

# An Intentional AI for Hanabi: Reproduction

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## Introduction

In this reproduction, we consider the paper “*An intentional AI for hanabi*” (Eger, Martens, and Cordoba 2017) and propose the following research questions which reproduce and extend the findings of the prior paper:

- RQ1: Does an intentional AI agent perform better in a collaborative game with a human than a baseline AI agent? (as measured by score)
- RQ2: Is the player’s perception of the AI agent (e.g. perceived skill and/or enjoyment of playing together) correlated with higher score, regardless of implementation?
- RQ3: Can we use Machine Learning to predict human responses to improve game-playing AI for more compatible cooperation?

All code for this project is publicly available on GitHub: [https://github.com/mjohns2355/stat204\\_final](https://github.com/mjohns2355/stat204_final)

## Background and Motivation

Game-playing AI has proven to be a useful test-bed for exploring decision-making AI implementations, and has attracted a wide range of researchers and research interests (Yin et al. 2023; Hu et al. 2024). Similarly, AI within games offer a valuable opportunity to understand human perception of interacting, and collaborating, with AI (Laird 2002; Yannakakis 2005). As we rapidly approach a state where humans and AI interact and cooperate on a daily basis, it is becoming increasingly important to (1) develop AIs that meaningfully cooperate with humans, and (2) understand what aspects of human-AI interaction are enjoyable, challenging, or unpleasant for humans. With this paper, we aim to contribute to further understanding AI implementations and human-AI interaction through an analysis of an intentional AI for the game of hanabi. We used the following R packages: ggplot2, dplyr, patchwork, and vtable.

Table 1: Summary Statistics

Variable	N	Mean	Std. Dev.	Min	Pctl. 25	Pctl. 75	Max
Likability	213	2.7	1.2	1	2	4	5
Perceived.Skill	213	2.4	0.95	1	2	3	5
Perceived.Intention	213	3.1	0.85	1	3	4	5
Final.Score	213	12	5.4	0	8	16	21

## Dataset Description

We are using two datasets for our analysis. First is the results of 240 games along with survey information from participants, which is publicly available on GitHub: <https://github.com/yawgmoth/HanabiData/> The second dataset is the turn-by-turn game logs from all games scoring over 20 points. While this data is not publicly available, we were granted access by one of the original authors. The game logs use one-hot-encoding to store the current game state (e.g. cards in each players' hand, cards that have been played or discarded, and what the current player knows from hints) and for the player's action on that turn (e.g. play card 1, discard card 4, etc.). The data is a matrix with dimensions 192731 x 393. The first 373 features represent Game State, the last 20 represent Player Action.

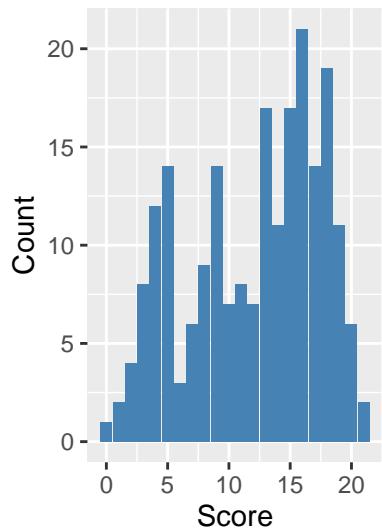
## Study Objectives

Our study has three objectives. First, to reproduce the results from the original paper using the extended dataset. Second, to extend the research to consider player perception of the AI (e.g. skill, likability). Lastly, to train a machine learning model on game logs to predict the player's next move from the current game state. This model could then be a proposed addition to the current AI implementation, offering a better collaborator with the human.

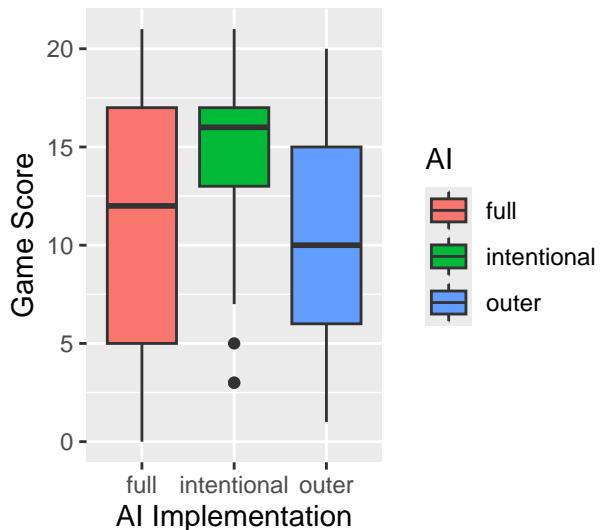
## Exploratory Data Analysis

We begin our reproduction by first exploring the data. The dataset consists of 240 rows/games and 14 columns, 10 of which being survey responses such as the player's perception of ai skill (1-5 scale) and enjoyment of playing with the ai (1-5 scale), while the others consist of game data, such as game score or the type of ai played with. We first checked for missing values and counted a total of 27 rows containing at least one missing value and thus decided to discard these rows for our subsequent analysis. Following this, we examined the distribution of scores, which can be seen in Figure 1. Inspecting this, we see that the distribution appears somewhat bimodal, with the most frequent score(s) being 17 and close to 17, and with distinct peaks at 5 and 9 as well. Table 1 shows a summary of the data.

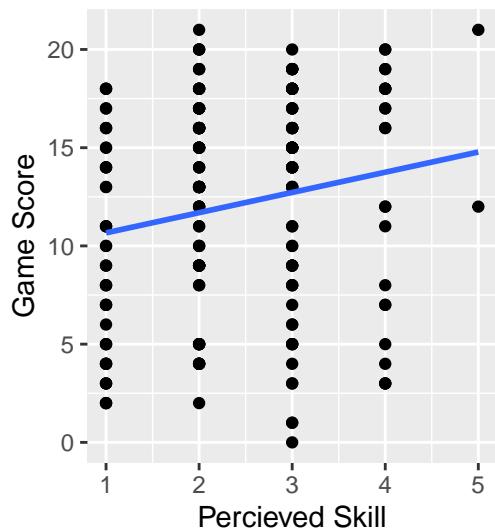
**Figure 1**  
Distribution of Scores



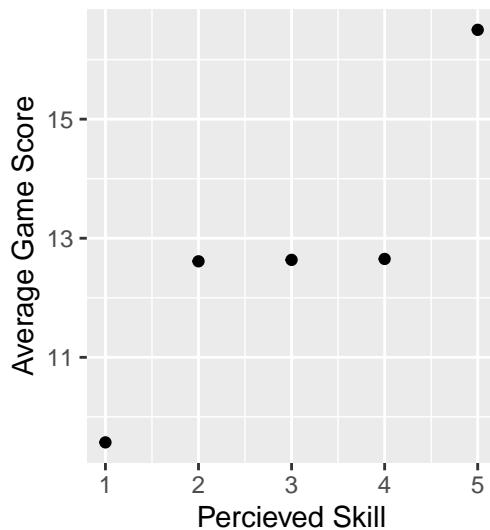
**Figure 2**  
AI Implementation Played With vs Game S



**Figure 3**  
Perceived Skill vs Game Score



**Figure 4**  
Average Perceived Skill by Game



## Methods

In the original study, participants were told they would be playing with an AI, but not which AI implementation they would be matched with. The original analysis involved an ANOVA comparing score based on AI implementation (Intentional, Outer, or Full). The original study's ANOVA resulted in ( $p < 0.0001$ ) showing statistical significance for a relation between AI implementation and final score. To compare the specific implementations, the original study used a Tukey test to determine that there was a statistically significant difference between the intentional AI and the outer state AI (baseline), as well as between the outer state AI and the full AI, however they did not find statistical significance when comparing the intentional to the full AI.

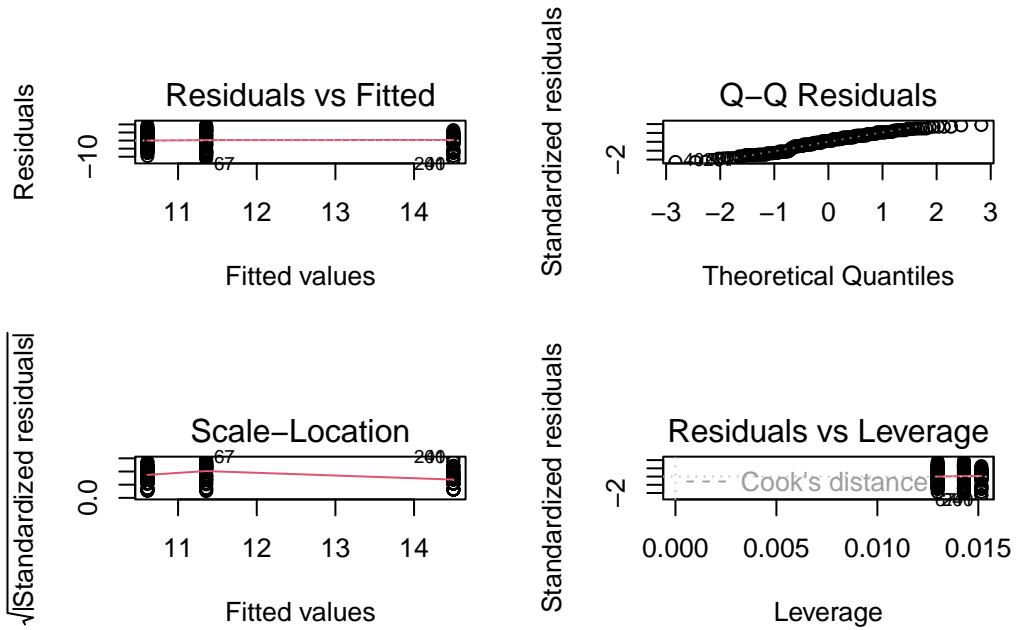
Beyond reproducing the original ANOVA and Tukey tests using the larger dataset, we extend this research by considering the potential correlation of player perception of AI on the resulting score regardless of AI implementation. To measure this correlation, we use Spearman's Rank considering the 5-point Likert responses to perceived AI Skill and how much the player liked their AI companion as potential variables. This method is used to test how strongly two sets of ranks are correlated, in this case we hypothesize that both perceived AI skill and likability will be correlated with higher game score.

Lastly, we used Machine Learning to train a model to predict player action based on current game state. Since the game log data was structured and labeled, we used XGBoost and a Neural Network to train two models and compare their performance.

## Results

To reproduce the original results, we conducted an ANOVA and Tukey Test. We verified the assumptions of the ANOVA with diagnostic plots. The Q-Q Residuals plot shows potential concern for skewness, however we have a large sample size and ANOVA is robust to mild normality violations.

```
Df Sum Sq Mean Sq F value    Pr(>F)
ai        2     589   294.66   11.19 2.42e-05 ***
Residuals 210   5531    26.34
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```



Tukey multiple comparisons of means  
95% family-wise confidence level

```
Fit: aov(formula = score ~ ai, data = survey_complete)
```

\$ai

	diff	lwr	upr	p adj
intentional-full	3.1428571	1.064447	5.221268	0.0012846
outer-full	-0.7467532	-2.747293	1.253786	0.6528219
outer-intentional	-3.8896104	-5.921657	-1.857564	0.0000309

Our results align with the findings of the original paper: we can be 95% confident that the Intentional AI implementation scores higher than either the Outer or Full implementations. There is no statistically significant difference between the Outer and Full implementations, as the original authors noted.

Spearman's rank correlation rho

```
data: perceived_skill and final_score
S = 1297231, p-value = 0.004373
alternative hypothesis: true rho is not equal to 0
```

```
sample estimates:  
rho  
0.1945487
```

```
Spearman's rank correlation rho  
  
data: perceived_like and final_score  
S = 1470958, p-value = 0.2077  
alternative hypothesis: true rho is not equal to 0  
sample estimates:  
rho  
0.08668117
```

The Spearman's Rank Correlation shows 95% confidence that Perceived Skill and Final Score are positively correlated, though the correlation is small (less than .3). There is no statistically significant correlation between Likability and Final Score.

**Machine Learning:** we used XGBoost and a Neural Network to train two potential models for predicting the next move based on current game state. We used 373 features, with One-Hot-Encoding to describe the current game state, at 20 output variables with One-Hot-Encoding representing the next move. The Nerual Network had a 41% success rate at correctly predicting the next move, while XGBoost had a 52% success rate. The code for both is available in the Appendix. One limitation of our approach is that we did not account for repeat players in the game logs, so one player who played many times may have had undue influence on the training data.

## Discussion & Conclusion

Based on our ANOVA and Tukey tests we are able to reproduce the results of the original study, and using the larger dataset provides evidence that the results are generalizable. This offers continued evidence to support the value of intentionality in AI design.

Based on our Spearman's Rank test, liking the AI companion was not statistically significantly correlated with higher score, however perceived AI skill was correlated with a higher score ( $p < .005$ ). This suggests that performing well in the game is not heavily reliant on the player *liking* their AI companion, and also that *liking* their companion is not heavily reliant on how well the AI is playing, however players who perceive the AI as more skillful were more likely to have high scoring games.

Lastly, our implementation of a Machine Learning model offers a proof-of-concept for future work that can integrate prediction into the intentional AI, allowing the AI to consider the likelihood of future moves based on the current game state.

## References

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