**Project 4 – Report** 

#### **Device Drivers**

## **Connecting to the ChompApp Device**

Using the 'libusb' library, a session is created, and a list of devices is populated using the 'libusb\_get\_device\_list()' function. From this list the function 'libusb\_open\_device\_with\_vid\_pid()' is used to open the ChompApp device using the known 'vendorID' and 'productID' for the device. The list is then freed and the devices in it are unreferenced using 'libusb\_free\_device\_list()'.

### Read ChompApp data

First, a buffer is created to store the ChompApp data e.g. 'unsigned char\* data =  $(char^*)malloc(1)$ ;'. The device is claimed (because you must claim the interface before you do any operation on the device) using 'libusb\_claim\_interface()' and a bulk transfer is initiated with 'libusb\_bulk\_transfer()'. The bulk transfer reads in data from the device, in this case a single byte of data, and stores it into the buffer for consumption by the joystick driver.

#### **Creating the Virtual Joystick Device**

Using the 'uinput' library, a new virtual device is opened e.g. 'int fd = open("/dev/uinput", O\_WRONLY | O\_NONBLOCK); '. For Linux to recognize this device as a joystick, a button and two absolute axes are created using 'ioctl()'. Events are also created for the button and axes e.g. 'ioctl(fd, UI\_SET\_EVBIT, EV\_KEY); 'and 'ioctl(fd, UI\_SET\_EVBIT, EV\_ABS); 'respectively. Once the settings for the device are written, it is created e.g. 'ioctl(fd, UI\_DEV\_CREATE);'. The device now appears as '/dev/input/jsX' in Linux.

#### Routing ChompApp data into the Linux Input System

Finally, the data from the bulk transfer is parsed into *emit* statements for the button and axes. *Emits* are a simple struct containing a *timestamp*, the *event type* (button or stick press), *identifier* (name of the button or axis), and *value*. For button presses, a *value* of 1 indicates the button was pressed, 0 indicates it was released. Axis movements *values* are signed shorts, ranging from -32768 to 32767. After all updates have been made, a *sync report* is emitted which routes the state of the joystick to the Linux Input System.

#### **Testing**

The driver was tested using 'jstest' which was run in a separate window from the ChompApp device and driver. ChompApp was run in the first terminal, a second terminal was connected to the USB subsystem e.g. 'sudo usbip -a 127.0.0.1 1-1' and the device was started, and then 'jstest' was run in a third terminal e.g. 'jstest /dev/input/js0'. As the joystick state changed in the ChompApp device, the output for the 'jstest' changed accordingly. The driver has no way of exiting and assumes the ChompApp device is always running.

# Code and other information were referenced from the following links on 12/4/2018:

- 1. https://blog.marekkraus.sk/c/linuxs-uinput-usage-tutorial-virtual-gamepad/
- 2. <a href="https://www.dreamincode.net/forums/topic/148707-introduction-to-using-libusb-10/">https://www.dreamincode.net/forums/topic/148707-introduction-to-using-libusb-10/</a>
- 3. https://stackoverflow.com/questions/16032982/getting-live-info-from-dev-input/