

1 **layer** applies
before-stat mappings

$$t_v(\mu, \sigma) \rightarrow x_{DIST}$$
$$group \rightarrow y$$

<i>group</i>	<i>v</i>	<i>μ</i>	<i>σ</i>
b	60	1	1.1
a	8	6	1.6

2 **stat_slab** creates an *x* grid
and at each *x* calculates
f(x), *F(x)*, and the mass (*γ*)
of the smallest requested
interval containing that *x*

<i>y</i>	<i>x_{DIST}</i>
2	$t_{60}(1, 1.1)$
1	$t_8(6, 1.6)$

3 **layer** applies
after-stat mappings

$$f(x) \rightarrow thickness$$
$$\gamma \rightarrow fill$$

<i>y</i>	<i>x</i>	<i>f(x)</i>	<i>F(x)</i>	<i>γ</i>
2	-3
2	-2.9
...
1	-3
1	-2.9
...

4 **geom_slab** constructs
multiple polygons for each
slab, one for each block of
consecutive *x* values with the
same appearance (e.g. *fill*)

<i>y</i>	<i>x</i>	<i>thickness</i>	<i>fill</i>
2	-3	...	#E2E2E2
2	-2.9	...	#E2E2E2
...
1	-3	...	#E2E2E2
1	-2.9	...	#E2E2E2
...

