

Consequences of ignoring dispersal variation in network models for landscape connectivity

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Abstract

Habitat loss and fragmentation can negatively impact population persistence and biodiversity, but these effects can be mitigated if species successfully disperse between isolated habitat patches. Network models are the primary tool for quantifying landscape connectivity, yet as practiced, they take an overly simplistic view of species dispersal. These models often ignore individual variation in dispersal ability, assuming all individuals move the same fixed distance with equal probability. Here we develop a modeling approach to address this problem. We incorporate dispersal kernels into network models to determine how individual variation in dispersal alters our understanding of landscape-level connectivity, and test our approach on a fragmented grassland landscape in Minnesota. We show that ignoring dispersal variation consistently overestimates a population’s robustness to local extinctions while simultaneously underestimating its robustness to local habitat loss. Furthermore, a simplified view of dispersal underestimates the amount of habitat sub-structure for small populations but overestimates habitat sub-structure for large populations. Our results demonstrate that considering biologically realistic dispersal alters our understanding of landscape connectivity for ecological theory and conservation practice.

Introduction

Loss of habitat due to land-use alteration is one of the largest anthropogenic threats to Earth’s planetary systems (Rockström 2009), contributing to major declines in biodiversity (Newbold et al. 2016) and other ecosystem services (Haddad et al. 2015). Habitat loss fundamentally alters landscapes by simultaneously decreasing the overall amount of native habitat, and changing how the remaining habitat patches are arranged with respect to each other

through fragmentation *per se* (Fahrig 2017). The negative effects of fragmentation (Fletcher et al. 2018) can be mitigated if species are still able to move between physically isolated habitat patches, maintaining connectivity. However, the extent of species' movement among patches remains an open question (Fahrig 2017). Thus, a complete understanding of the degree to which current (Haddad et al. 2015) and ongoing (Wright & Wimberly 2013) fragmentation disrupts connectivity requires accounting for potential species movement among patches.

Recent work examining how organisms move among fragmented patches draws on network modelling (e.g. Saura & Rubio 2010; Fletcher et al. 2013; Ziółkowska et al. 2014; Wimberly et al. 2018). This approach converts spatial data on habitat locations to networks (or graphs), where nodes represent habitat patches and two patches are connected by an edge if organisms can disperse between them (Urban & Keitt 2001). These networks can be analyzed to inform conservation decisions by calculating patch-based or network-based 'connectivity' metrics, and identifying sets of patches that are connected via dispersal and thus function as a unit (termed components). Network modelling has enabled researchers and managers to infer connectivity, identify habitat patches with high conservation value, and quantify the scale of dispersal necessary to maintain connectivity (e.g. O'Brien et al. 2006; Saura & Rubio 2010; Creech et al. 2014; Wimberly et al. 2018). Generally, while models that infer connectivity tend to take into account detailed information about matrix quality between habitat patches and potential ease-of-flow through this matrix (Moilanen & Hanski 1998; McRae et al. 2008; Wimberly et al. 2018), they often make simplistic assumptions about species' movement dynamics. Specifically, network models, particularly unweighted or binary networks that simply consider whether or not patches are connected, tend to define species' dispersal as a single fixed distance, effectively assuming that all individuals are equally able to disperse up to that distance,

and unable to disperse past that distance. Building network models with the same sets of simplifying assumptions limits our ability to understand how a broad range of biological factors (such as dispersal behavior) influence connectivity, which is especially problematic since dispersal variation can have many consequences (Snell et al. 2019; Shaw 2020). Simplified dispersal assumptions may over- or under-estimate the degree of connectivity, or fail to capture important connectivity patterns altogether, thereby preventing accurate estimations of landscape-level habitat use.

An alternative to viewing dispersal as fixed, is to account for variation in dispersal, thus more accurately representing movement behavior. Inherent variation among individuals (e.g. sex, personality, body condition), populations (e.g. density), and the environment (e.g. habitat quality, habitat configuration, and season) can cause differences in dispersal ability (Snell et al. 2019; Shaw 2020). This dispersal variation can be captured with a dispersal kernel, that describes the proportion of individuals traveling any given distance (Shoemaker et al. 2020). Dispersal kernels thus account for variation in distance traveled as well as variation in the proportion of the dispersing population traveling each distance (Kot et al. 1996). In most species, the majority of dispersing individuals travel short distances, remaining close to their source location and thus contributing to local population dynamics (Moles & Westoby 2004). Simultaneously, few individuals move longer distances and they drive processes like colonization (Soons et al. 2004b), range expansions (Kot et al. 1996) and range shifts (Davis & Shaw 2001). This ‘long-distance dispersal’ is often defined by the distance travelled by the farthest 1% of individuals (Nathan 2006). Finally, population size can influence dispersal; populations with more dispersing individuals will more fully ‘realize’ the dispersal kernel – thus being more likely to successfully reach farther distances. Although network models have the potential to account for

variation in dispersal (i.e. via weighted edges, Shanafelt et al. 2017), most either assume fixed dispersal (e.g. Minor et al. 2009), or use weighted edges to describe how easily an organism can move through a given matrix, ignoring dispersal variation (e.g. Ziolkowska et al. 2014; Wimberly et al. 2018). Those network models that do consider dispersal as a function of distance tend to do so by using simulated draws from dispersal kernels (Fletcher et al. 2011, 2013). Models that more fully explore weighted networks using dispersal kernels would allow for a more nuanced representation of species' movement capacity, and provide a better understanding of habitat connectivity and the impacts of fragmentation. A deeper understanding of connectivity would influence both the conservation of rare and threatened species that have had natural movement patterns altered by fragmentation, as well as the control of invasive species that have strong movement abilities that are unaltered by fragmentation (Damschen et al. 2008).

Here, we create a series of deterministic network models to ask the question: how does variation in dispersal alter estimates of landscape connectivity? First, we generate networks based on fixed dispersal distances, allowing us to compare our results to previous studies (e.g. Urban & Keitt 2001; O'Brien *et al.* 2006; Wimberly *et al.* 2018). Then, we generate networks based on dispersal kernels, which incorporate variation in dispersal and include the effect of population size. By comparing networks created either with fixed dispersal distances or with dispersal kernels, we explore how variation in dispersal alters our understanding of aspects of landscape connectivity including: habitat sub-structure, robustness to habitat loss, and robustness to local extinction. Our approach provides a starting point for conservation managers interested in understanding how traditional methods might over- or under-estimate connectivity based on simplified assumptions about dispersal. We apply these models to the fragmented grasslands in Minnesota (Fig. 1), where there is renewed interest from state and local managers in considering

connectivity in their restoration efforts. Minnesota managers have created plans for protecting existing grasslands and building future restorations to promote connectivity through the creation of grassland corridors (Minnesota Prairie Plan Working Group 2018), yet these plans were designed with very minimal information on species movement because little is known. Thus, Minnesota grasslands are an excellent study system to demonstrate the utility of our broader approach because prior knowledge of, and interest in, connectivity exists, and managers there are open to considering how to incorporate more realistic information on species' dispersal into future conservation plans (Minnesota Prairie Plan Working Group 2018; Wimberly et al. 2018; Sperry et al. 2019).

Materials and Methods

We created deterministic network models with and without dispersal kernels in order to draw conclusions about how including biologically meaningful knowledge of dispersal alters predictions about connectivity as compared to ignoring dispersal variation. We assumed that dispersal kernels more accurately represent species movement than the assumption of fixed models where all individuals travel all distances with equal likelihood. Our models are general, and thus could apply to any species of interest, including Minnesota grasslands species across a range of dispersal distances: prairie coneflower (~9m; Ison et al. 2014), ground squirrels (53-80m; Rongstad 1965), dickcissels (222m; Walk et al. 2004), and burrowing owls (2802m; Catlin & Rosenberg 2008) – all indicating mean dispersal distances.

Habitat Selection

We developed our models for the prairie region of western and southern Minnesota (also called the prairie parkland region). This region was historically grassland but has been fragmented and reduced to ~1% of its original area (Minnesota Prairie Plan Working Group 2018). The spatial locations of the remaining grasslands are well documented, and exist in a matrix of mostly agriculture. We refer to each separate grassland fragment as a ‘patch’ throughout. To build our networks, we used a comprehensive spatial grassland habitat database for the region (The Nature Conservancy 2015). This dataset combined the Minnesota Department of Natural Resources’ native prairie layer, the United States Fish and Wildlife Services’ (USFS) Habitat and Population Evaluation Team’s (HAPET) 2014 reclassification dataset, and the United States Department of Agriculture’s Cropland Data Layer (CDL) dataset. The USFS National Wetlands Inventory layer was used for corrections in classifying wetland and open water areas. The resulting database consisted of all grassland types, including native remnant prairie, reconstructed or disturbed grasslands, and hay/pasture fields. We included all of these grassland types in our network analysis because they represent potentially suitable habitat for grassland species (e.g. birds, insects, mammals, plants). Similar to Wimberley et al. (2018) we used ArcGIS 10.4 to select patches that were five acres (2.023 ha) or larger. This resulted in ~37,000 grasslands ($N=37,091$ patches in the network, see Appendix S1 for all parameters) to use in our connectivity analysis (Fig. 1a,b).

Networks Using Fixed Dispersal Distances

First, we generated networks for our grasslands assuming that organisms had no dispersal variation (i.e. all individuals traveled a fixed dispersal distance). To do this, we calculated the nearest-edge distance (i.e. the distance between the closest points) of all pairs of patches in

ArcGIS using the geodesic method, and a max search radius of 4000m (Fig. 1c). We chose this radius, which is within the range used in similar studies (Wimberly et al. 2018), for computational simplification, but note that it is smaller than the movement ability of extremely vagile Minnesota grassland species (e.g. the red fox disperses on average ~31,000m; Storm et al. 1976). We then generated 2000 networks, one for each fixed dispersal distance (d') that we considered (1,...,2000m). For each dispersal distance d , we generated a binary adjacency matrix A (of size $N \times N$) where each element described whether (1) or not (0) the distance between a pair of patches was less than d (i.e., whether an individual traveling that distance could move between these two patches). This generated 2000 binary adjacency matrices A (of size $N \times N$) where each element described whether (1) or not (0) two patches were connected for each dispersal distance. We then used each matrix to create a non-directed network using the igraph package in R (Csardi & Nepusz 2006). To guide readers through our methods, we also created a ‘toy’ network (Fig. 2a).

Networks Using Dispersal Kernels

We also generated networks for our grasslands assuming that individual organisms varied in their dispersal ability (i.e. their movement was described by a dispersal kernel, Fig. 1d). Specifically, we used the exponential distribution (Fig. 3a), where the proportion of individuals traveling any distance d is

$$e^{-bd} \tag{1}$$

with rate parameter, b . This distribution is commonly used as a dispersal kernel since it often matches empirical data (Hovestadt et al. 2011; Shaw et al. 2019). As with the fixed distance networks, here we also considered 2000 dispersal distances. However instead of considering

these to be the exact distances traveled, we considered these to be the farthest 1% value (d^*) for defining ‘long-distance dispersal’ for our dispersal kernels. Thus we established a dispersal kernel for each d_x^* value ($x = 1, \dots, 2000\text{m}$) as follows. We determined the proportion of individual dispersing each distance d or more, given by the complementary cumulative distribution function (CCDF) for the exponential kernel (Fig. 3a). We set this proportion f to be 0.01, plugged in each d_x^* , and solved for the corresponding b_x value (Fig. 3c), that is

$$b_x = \frac{-\ln(0.01)}{d_x^*}. \quad (2)$$

This b_x value describes a dispersal kernel where only 1% of individuals dispersed a distance of d_x^* or further. Next, we calculated the nearest-edge distance between all pairs of patches up to a maximum distance of 4000m, resulting in a Euclidian distance matrix, \mathbf{D} (Fig. 3b). Setting a maximum distance for these calculations (rather than calculating all pairwise distances) saved computational time while ensuring we calculated all relevant distances needed for our kernels below. Finally, for each dispersal distance d_x^* we converted the distance matrix, \mathbf{D} , into a matrix \mathbf{M}_x , describing the proportion of the modelled population that disperses between each patch (Fig. 3c). To do this, for each d_x^* value, we used the CCDF to calculate the proportion of individuals $m(i,j)$ with dispersal kernel defined by b_x that would travel at least the distance $d(i,j)$ between each patch i and j . We then used these \mathbf{M}_x matrices to generate weighted non-directed networks, where the weight of each edge corresponds to the proportion of dispersing individuals that can move between the two patches the edge connects.

Finally, we explored the influence of population size on connectivity metrics. A dispersal kernel describes the distribution of distances that would be observed across a very large number of dispersal events. However, since species vary in population size and fecundity, they will also vary in how well the kernel is ‘realized’. These differences will appear most strongly for the low-

probability longer distances (the dispersal kernel tail); a species with a smaller population size or lower fecundity will have fewer realized dispersal events and thus across the population there will be fewer dispersal distances represented by the tail of the kernel. To mimic different population sizes with our models, we thresholded the matrix M at three values, by keeping the 75% highest dispersal probabilities (i.e. setting to zero all dispersal probabilities less than 25%; ‘75%-realized’, representing a small population), 99% (‘99%-realized’, medium population), and 99.99% (‘99.99%-realized’, large population). This is equivalent to truncating the dispersal kernel at three increasingly long maximum distances, but does not incorporate uncertainty and represents the simplifying assumption that small populations are less likely to reach longer distances than large populations. Imposing a maximum dispersal distance also kept the dispersal kernel from becoming infinite (i.e. there is a very small proportion of individuals dispersing infinitely far). We note that an alternative approach to examining population size is to multiply all weighted edges within the network by these proportions (for large populations, 0.9999, for medium populations 0.99, for small populations 0.75), and then conduct network analyses. This approach leads to qualitatively similar results for patch-level metrics to those we present here (Appendix S2).

In total, we considered 2000 different measures of ‘long-distance dispersal’ and 3 different measures of population size, generating 6000 weighted networks. As above, we calculated network and patch-level metrics for each network, some of which were modified to accommodate the weighted network structure.

Connectivity Metrics

Network-level Metrics

For each network generated with fixed dispersal (non-weighted) and dispersal kernels (weighted), we calculated three network-level metrics (Fig. 2b), to quantify different aspects of network structure and connectivity. The first two metrics do not take into account weights and thus were calculated the same way for both non-weighted (binary) and weighted networks. (1) Number of components, (see Appendix S3 for igraph functions): two patches are in the same component if they are connected by an edge; fully isolated patches are their own component. Patches in different components are isolated from each other, thus the number of separate components in a network provides a rough sense of overall fragmentation across the network (Calabrese & Fagan 2004). (2) Maximum component size: the number of patches in the largest component of the network provides a measure of effective network size (Urban & Keitt 2001). Both the number of components and the size of the largest component represent an estimate of the amount of habitat sub-structure present. (3) Average clustering coefficient: this metric quantifies the extent to which a network contains well-connected clusters of patches and thus provides an estimate of local landscape connectivity. In non-weighted networks, for a given patch i , that is connected to k_i neighboring patches (see patch-level metrics below), there can be at most

$$(1/2) k_i (k_i - 1) \quad (3)$$

connections among its neighboring patches. The clustering coefficient for this patch is the fraction of those possible connections that actually occur (Watts & Strogatz 1998), a metric used to quantify the local connectivity for landscape networks (Wimberly et al. 2018). Average clustering coefficient can be considered a measure of robustness to habitat loss, as networks with higher clustering will more easily maintain their sub-structure even as habitat fragmentation removes either edges or patches. For weighted networks, we used weighted distances between

patches based on dispersal proportion (Csardi & Nepusz 2006). This weighted clustering coefficient is calculated as

$$\frac{1}{s_i(k_i - 1)} \sum_{j,h} \left\{ \frac{1}{2} [m(i,j) + m(i,h)] a(i,j) a(i,h) a(j,h) \right\} \quad (4)$$

where s_i is the strength of patch i (see below), k_i is the degree of patch i , $m(i,j)$ are the elements of the weighted matrix \mathbf{M} , and $a(i,j)$ are the elements of the adjacency matrix \mathbf{A} . We note that there was little difference between the mean and median values for clustering coefficient, except for small to moderate dispersal distances in the ‘75%-realized’ kernels where the mean value was larger than the median value (Appendix S4).

Patch-level Metrics

For each patch within each network, we also calculated two patch-level metrics (Fig. 2c), and summarized them by looking at the 25th, 50th, and 75th quantiles of all values for patches within each network. (1) Degree centrality: for non-weighted networks, this metric is calculated as the number of connected neighbors each patch has (k_i), i.e. the number of patches that an individual could potentially reach via dispersal as defined by the model (Wimberly et al. 2018). For weighted networks we calculated strength, the weighted version of degree centrality, as

$$s_i = \sum_j m(i,j) \quad (5)$$

where $m(i,j)$ are the elements of the weighted matrix \mathbf{M} for all connected neighbors j of patch i . Degree centrality or strength quantifies the number of colonization opportunities to or from each patch and represents a measure of short-term robustness to local (patch-level) extinction. Patches with low degree/strength are likely to be isolated and vulnerable to reductions in species richness as any local extinction would be unlikely to be recovered by recolonization from other patches.

(2) Closeness centrality: for non-weighted networks, this metric quantifies the importance of each patch i for overall connectivity in the network as

$$\frac{1}{\sum_{i \neq j} p_{ij}} \quad (6)$$

where p_{ij} is the shortest path, or the number of steps (i.e. sequential dispersal events) it takes to reach every other patch j in the network from the focal patch. If two patches are not connected (i.e. p_{ij} is infinite), the total number of patches (N) is used instead of p_{ij} for this pair. Thus closeness is a measure of the average number of sequential dispersal events required to recolonize the network, and represents a measure of long-term robustness to local extinction. We chose closeness as our centrality metric (rather than ‘betweenness’ as used by Minor and Urban (2007)) because closeness more accurately represents dispersing organisms that do not always take the most efficient route between patches (Borgatti 2005). For weighted networks, we calculated a weighted version of closeness, as

$$\frac{1}{\sum_{i \neq j} q_{ij}} \quad (7)$$

where q_{ij} is the sum of inverse probabilities m^{-1} along the shortest path between patch i and patch j . Since the inverse of the proportion of dispersers gives an expected number of events needed (e.g., a 0.5 proportion of dispersers would take about 2 dispersal events), weighted closeness is again a measure of long-term robustness to local extinction because it tallies the expected number of sequential dispersal events required to recolonize the entire network. As for non-weighted networks, if two patches are not connected, the total number of patches (N) is used instead of q_{ij} for that pair. Note that this correction for unconnected patches (while a suitable approximation for non-weighted networks) is actually an underestimate of the number of sequential dispersal events for weighted networks. Since the degree to which it underestimates dispersal events (and thus overestimates weighted closeness) interacts with the different

population sizes we considered, there is no meaningful way to compare across different truncations of the dispersal kernels for this metric. Thus, we only calculated weighted clustering coefficient for the networks based on the ‘99%-realized’ dispersal kernels.

All analyses were run in R v3.4.4 (R Core Team 2017), data and code are available at the Dryad Digital Repository xxxxx.

Results

Network-level Metrics

Networks were less fragmented (had less habitat sub-structure) for larger dispersal distances, with fewer components (Fig. 4a) and larger largest components (Fig. 4b). These relationships were starkest for networks created from dispersal kernels with longer realized kernel tails (i.e. larger population size or higher fecundity). In other words, the ‘99.99%-realized’ kernel showed the fastest drop in the number of components, and the fastest increase in size of largest component with increasing d^* , while the ‘75%-realized’ dispersal kernel showed a markedly slower decrease in the number of components and slower increase in maximum component size with increasing d^* . The fixed dispersal distance produced accurate estimates for populations of intermediate size (the ‘99%-realized’ dispersal kernel, Fig. 4a-b). Intuitively, this result occurs because a network from a fixed dispersal distance of d' is structurally equivalent to a network with a ‘99%-realized’ dispersal kernel with distance d^* (the same patches are connected in both when considering non-weighted (or binary) network metrics like the number of components and largest component size). However, fixed dispersal distance underestimated habitat sub-structure for smaller populations (‘75%-realized’) and overestimated habitat sub-structure for larger populations (‘99.99%-realized’).

Networks were also more connected for larger dispersal distances, with higher clustering coefficients (Fig. 4c). In other words, populations with larger dispersal distances are more robust to habitat loss leading to lost patches or connections. However, the fixed dispersal distance consistently underestimated robustness to habitat loss compared to all three populations sizes ('75%-, 99%-, 99.99%-realized' dispersal kernels, Fig. 4c), with the largest difference for the largest population sizes ('99.99%-realized' kernel). The fixed network and the '75%-realized' kernel produced similar results for low dispersal distances, but the clustering coefficient then plateaued for the fixed distance while the '75%-realized' kernel continued to increase for larger dispersal distances.

Patch-level Metrics

Patches in networks with larger dispersal distances were on average connected to more neighbor patches (higher degree centrality, Fig. 5a), representing a higher short-term robustness to local extinctions. Networks from fixed dispersal distances consistently overpredicted robustness compared to networks from dispersal kernels, a gap that increased with dispersal distance. In other words, fixed kernel networks systematically overpredict the number of neighbors (and thus expected number of recolonization opportunities) each patch has, compared to dispersal kernel networks. Within the dispersal kernel networks, smallest populations ('75%-realized' kernel) had patches with the lowest robustness, followed by medium ('99%-realized') and large ('99.99%-realized') population sizes, however these ranges overlapped substantially. Similarly, patches in networks with larger dispersal distances had higher closeness values (Fig. 5b). Fixed dispersal distances consistently overpredicted closeness, and thus underpredicted the

number of sequential dispersal events needed to recolonize a network following extinction, compared to the networks created with dispersal kernels.

Discussion

We built deterministic network models from fixed dispersal distances and dispersal kernels, and contrasted them to more fully explore how weighted networks that use dispersal kernels affect estimates of landscape connectivity. As with other simulation-based connectivity models that incorporate dispersal variation (Palmer et al. 2014), we found that network models based on dispersal kernels generated a markedly different understanding of population connectivity than network models based on a fixed dispersal distance (Figs. 4-5, Appendix S5). Specifically, using fixed dispersal consistently overestimated a population's robustness to local extinctions while simultaneously underestimating robustness to habitat fragmentation. Our results from fixed dispersal distances qualitatively match similar network analyses for other grasslands (Wimberly *et al.* 2008) and for forests (Urban & Keitt 2001), suggesting that current habitat management using fixed dispersal networks is based on inaccurate estimates of population connectivity. As there is ample evidence that most organisms have substantial variation in dispersal (e.g. Baguette 2003; Krkošek et al. 2007; Sullivan et al. 2018), connectivity models must account for such variation by using dispersal kernels. Other network models that use dispersal kernels to match empirical movement data find these methods to be a good approximation of movement ability (Fletcher et al. 2011, 2013). These findings have implications for managers that plan for conservation based on connectivity metrics. Some species of concern may need more total habitat, while others rely on continual recolonization and thus would differ in whether fixed models over- or underestimated their connectivity.

The magnitude of differences between fixed and dispersal kernel connectivity metrics depended on how we modeled the tail of the dispersal kernel, which reflected a examining different population sizes of organisms. The underestimate of robustness to habitat fragmentation (clustering) was the largest for large populations ('99.99%-realized' dispersal kernel, Fig. 4c). In contrast, the overestimate of robustness to local extinction (degree centrality) was similar for all population sizes, but slightly larger for small populations ('75%-realized', Fig. 5a). Degree centrality estimates the expected number of patches that can be colonized with a single set of dispersal events. Since fixed dispersal effectively assumes 'perfect' dispersal (patches within a fixed distance will always be reached), networks with fixed dispersal will always overestimate colonization ability.

In light of our results, explicit consideration of conservation goals can help guide the appropriate use of dispersal kernels for management and planning. Inherent in the use of dispersal kernels is the understanding that most individuals move shorter distances, and few individuals move farther distances. Therefore, the conservation goals at the heart of maintaining connectivity should take population size into account when appropriate. For example, often the goal of promoting connectivity between patches is to build a functioning meta-population for rare species where individuals can move freely and breed between patches (Hanski 1998). As rare or threatened species are often dispersal-limited due to small population sizes and low fecundity (Baur 2014), considering a less realized dispersal kernel (i.e. '75%-realized') could more accurately represent likely connectivity outcomes for this particular goal. Moreover, if small population sizes are of serious concern, other methods might need to be incorporated, including individual based models (Grimm & Railsback 2005). Another goal of maintaining connectivity might be to allow for the possibility of species' response to climate change via

range shifts (Krosby et al. 2010). Range expansions often proceed through the dispersal of a few individuals over a long distance (Davis & Shaw 2001). To successfully track climate change, large populations must produce the few individuals that disperse long distances, thus a more realized dispersal kernel (i.e. '99.99%-realized') would be more appropriate to include in network models to achieve this goal. Consideration of these highly realized dispersal kernels is also appropriate for controlling invasive species like the cane toad, which have high movement ability (Perkins et al. 2013). Finally, for sessile organisms like plants, managers might be interested in distinguishing between maintaining high genetic diversity to decrease the probability of inbreeding depression - which requires the movement of gametes (i.e. pollen), versus allowing for species recolonization to increase species diversity - which requires the movement of individuals (i.e. seeds) (Elistrand 1992; Brudvig et al. 2009). In this case managers should consider defining dispersal kernels that represent pollen and seed dispersal separately in order to match their management goals. When looking to define dispersal kernels, managers can use measurement-based (e.g. Stevens et al. 2010), trait-based (e.g. Soons et al. 2004a), or genetic-based approaches (e.g. Bacles et al. 2006) to estimate kernels.

Grasslands are globally important, yet they are among the most threatened due to land use conversion and fragmentation (Soons et al. 2005; Newbold et al. 2016). Our network models help elucidate how likely species are able to move between grassland patches and maintain connectivity at a broader scale. Our results are comparable to Wimberly et al. (2018), which determined connectivity of the grasslands in the Prairie Coteau region of Minnesota and the Dakotas, but use a fixed dispersal distance. Extrapolating their results based on our findings from network models with dispersal kernels, we might expect that for species with large population sizes there might be increased connectivity, with fewer, larger components that are more robust

to fragmentation than what Wimberly et al. (2018) found, but we might expect the opposite for species with smaller populations. To aid Minnesota grassland managers, we have created a web-based app to allow for the direct application of network models to existing grasslands in Minnesota (Sperry et al. 2019). This approach could be easily updated to incorporate known dispersal kernel information for species of interest (e.g. grassland plant species - Sullivan et al. 2018), patch prioritization, or matrix quality between patches (Castillo et al. 2016), which would afford a more targeted understanding of which species can maintain connectivity, and which might require assistance moving between patches.

Conclusions

In order to understand if and where connectivity is maintained between isolated habitat fragments, we must account for how organisms move in a biologically meaningful way. We take steps toward this goal by considering variability in dispersal in network models by incorporating fully explored dispersal kernels, to determine how this alters our view of network-based connectivity as compared to standard methods that use a fixed dispersal distance. Since interspecific dispersal variation is also common, future work should examine how dispersal varies across species (e.g., when different species have different dispersal kernel shapes), and when there is directionality in dispersal to understand more fully how interspecific variation affects connectivity. We find that models ignoring dispersal variation simultaneously overestimate robustness to local extinctions while underestimating robustness to habitat loss, compared to models that account for dispersal variation. The magnitude of these differences depends both biological traits of the species of interest, particularly population size, and dispersal distance.

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Figure Legends

Figure 1. (a) Map of the location of the ~37,000 grassland patches across Minnesota used in our network analysis, as well as (b) the histogram showing distances between patches up to 4000m (the max our models examined). Examples of a subset of the network (from Clay County, MN) showing patches and connections under (c) the fixed distance (with $d^* = 2000$) and (d) dispersal kernel (with $d^* = 2000$ and ‘99%-realized’). In panel (d) thicker lines correspond to a higher proportion of dispersers between patches.

Figure 2. (a) Toy network with nine patches (points labeled A-I) and two components, where numbers along edges indicate the probability that two patches are connected via dispersal – used for calculating weighted metrics. When calculating non-weighted metrics, the probability values along connections become 1. (b) Network-level metrics calculated for this network. (Since clustering coefficient only counts nodes with degree > 1, the only nodes used for these calculations are B, G, H and I). (c) Patch-level metrics as calculated for two example patches (A and B, within component #1).

Figure 3. Methods schematic for building networks from dispersal kernels. (a) Use the dispersal kernel (the proportion of individuals traveling a distance d) to calculate the complementary cumulative density function (CCDF, f , the proportion of individuals traveling a distance d or more). Very few (1%) individuals travel a distance d^* or more, considered “long-distance dispersal”. (b) Use the landscape of N patches to calculate a distance matrix (\mathbf{D} , the physical distance between all pairs of patches i and j). (c) Use the CCDF to map from each “long” distance (d_x^*) to corresponding dispersal kernel parameter (b_x) by setting f_x to 0.01, then use both

the CCDF and the distance matrix to create a corresponding weighted matrix (\mathbf{M}_x , the proportion of individuals dispersing between all pairs of patches i and j), where x is the dispersal distance index $x=1 \dots n$, ($n=2000$). See Appendix S1 for full definitions of parameters.

Figure 4. Network-level metric values for networks with fixed dispersal distances (red) and using the exponential dispersal kernel at various tail truncations ‘75%-realized’ (dark gray), ‘99%-realized’ (medium gray) and ‘99.99%-realized’ (light gray), which represent increasing abilities for long-distance dispersal. Panels show the (a) number of components, (b) size of the largest component, which represent measures of habitat sub-structure and (c) the clustering coefficient, which represents robustness to habitat loss.

Figure 5. Patch-level metric values for networks with fixed dispersal distances (red), and networks with dispersal kernels, ‘75%-realized’ (dark gray), ‘99%-realized’ (medium gray) and ‘99.99%-realized’ (light gray). Panels show the 25th, 50th and 75th quantiles for (a) patch degree centrality, and (b) patch closeness which represent measures of robustness to local extinction. In panel (a), the ‘99%-realized’ (medium gray) and ‘99.99%-realized’ (light gray) are nearly overlapping with the ‘99.99%-realized’ kernel having a slightly higher degree. For clarity, asterisks represent the 50th quantile for each kernel.

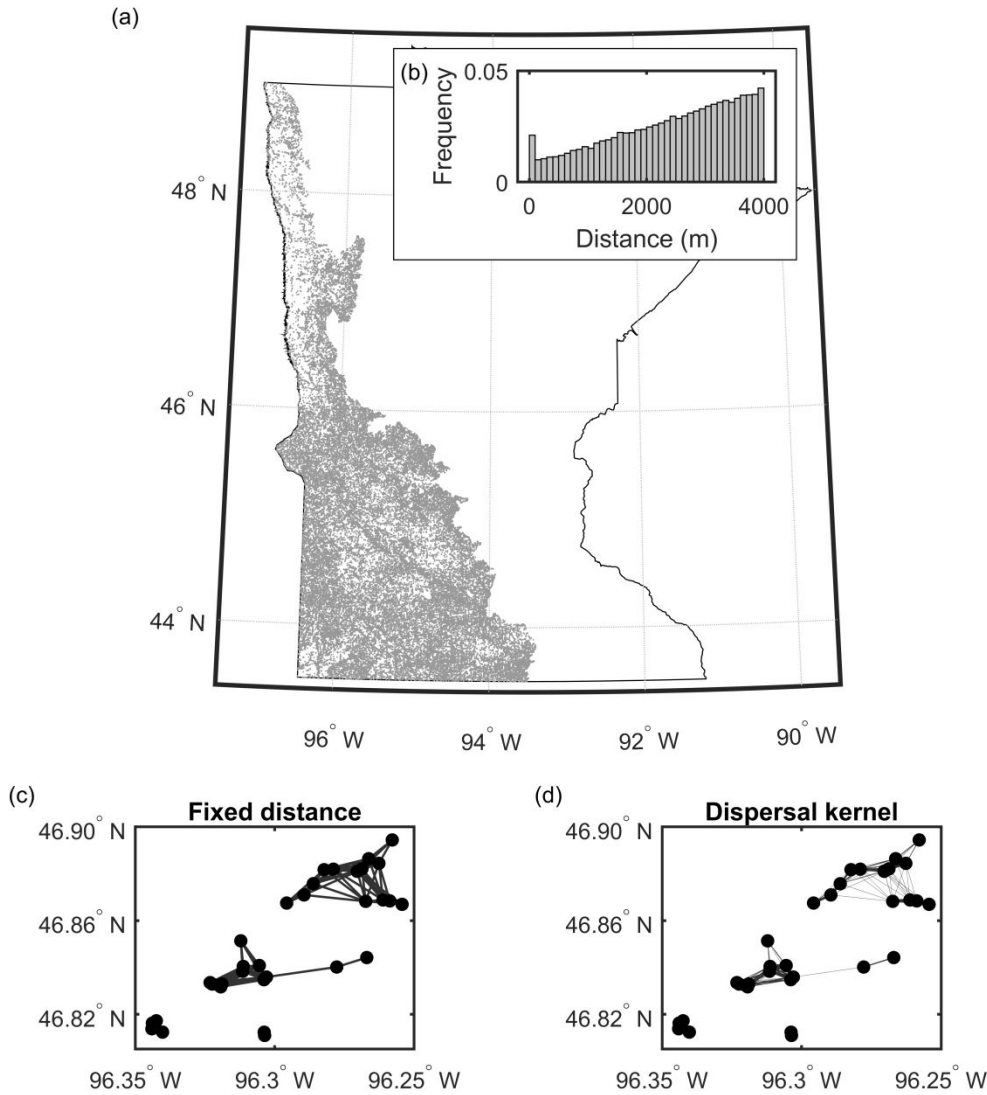


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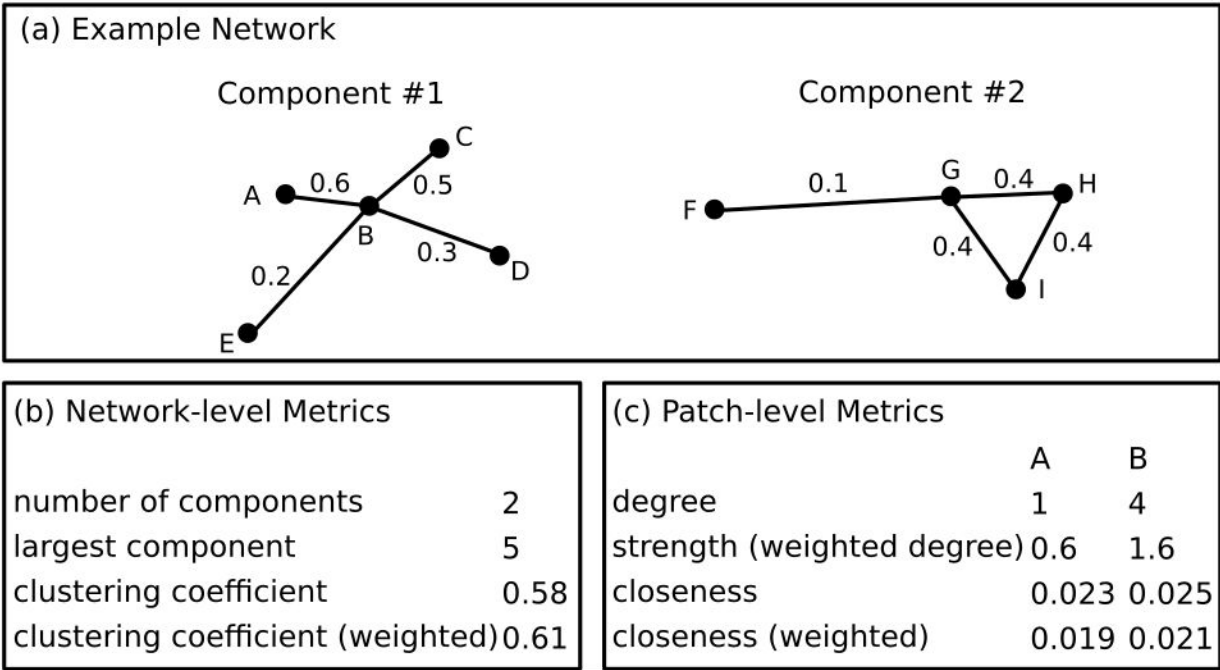


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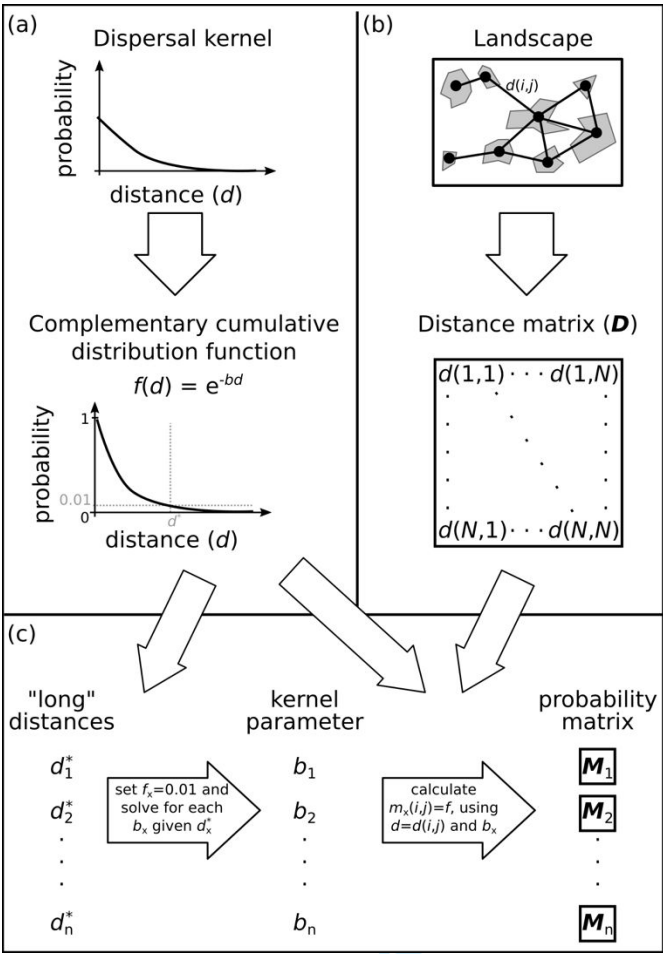


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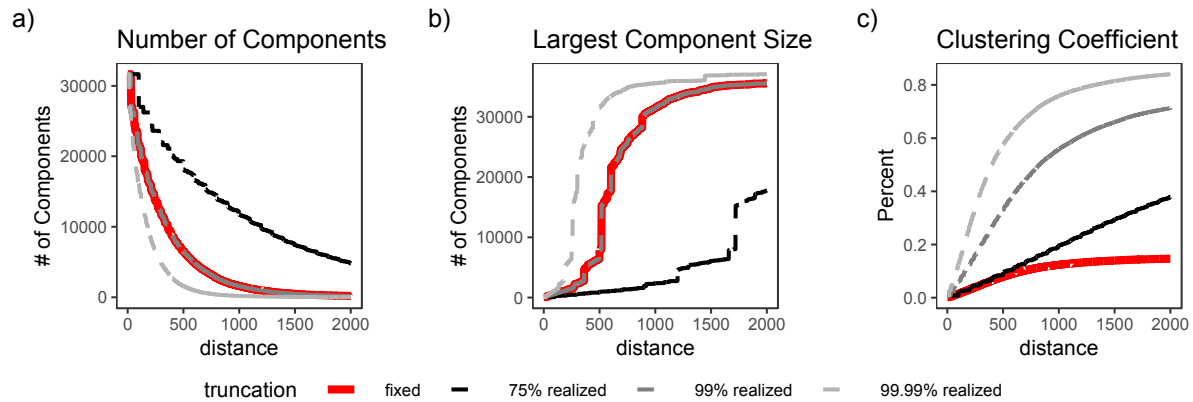


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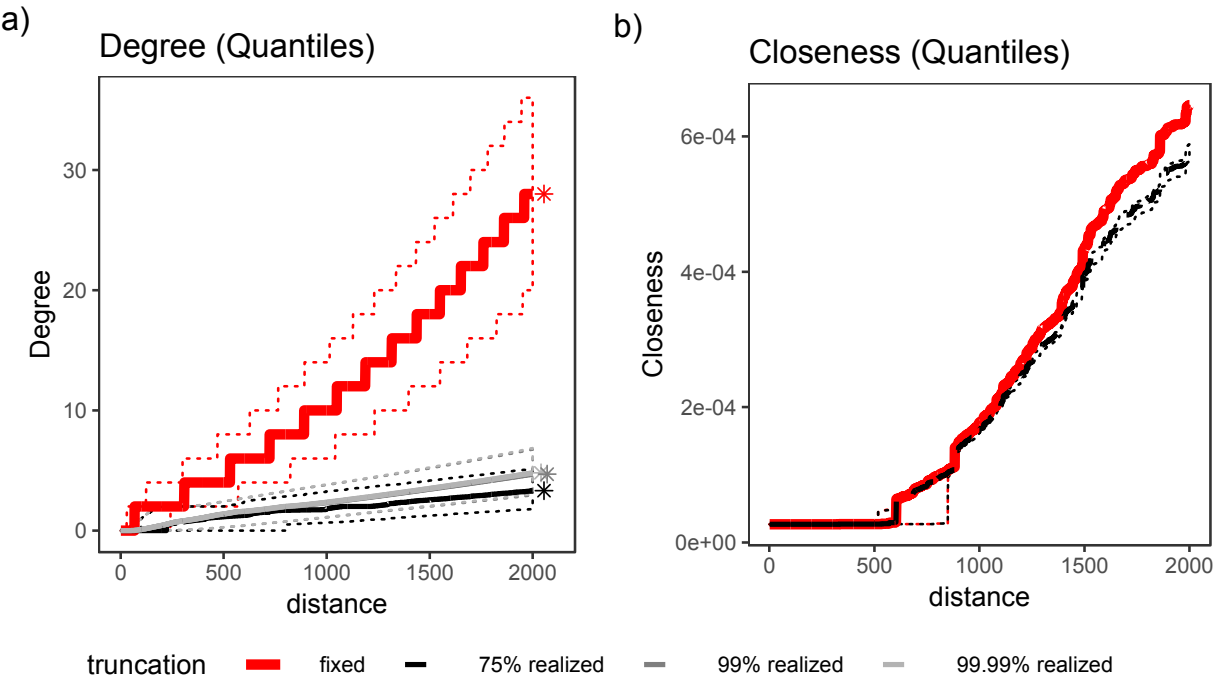


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