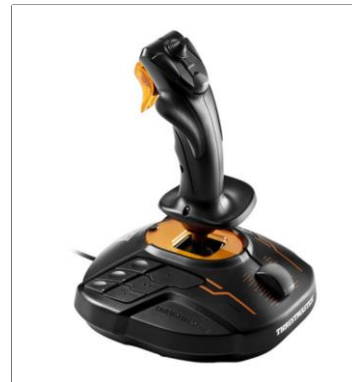




Joystick Controller



Pilot

Controls



F16 Nonlinear Model

F16_state

Altitude

F16_state

Pos_dr2tx

C2m

ft

m

$U \cdot K_c$

Scope

Navigator

Delta position

EstimatePos

Clock

T