Original Problem: Tracking problem for nonlinear system subject to disturbances (7):  $\tilde{\mathbf{y}}_{r} - \tilde{\mathbf{y}}_{r}^{d} \rightarrow \mathbf{0}$   $ASD: \tilde{\mathbf{y}}_{r} = \tilde{\mathbf{y}}_{r,p} + \tilde{\mathbf{y}}_{r,s}$ 

**Problem 1:** Tracking problem for an LTI system subject to disturbances (11): 
$$\tilde{\mathbf{y}}_{r,p} - \tilde{\mathbf{y}}_r^d \rightarrow \mathbf{0}$$

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**Problem 2:** Stabilization problem for a deterministic nonlinear system (12):  $\tilde{\mathbf{x}}_{rs} \rightarrow \mathbf{0}$ 

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