

1. DISCRETIZATION

Clearly, the solution of the problem

$$a(u, v) = (f, v) \text{ for all } v = (v_1, v_2)^T \in \mathbf{V} = V_1 \times V_2,$$

is equivalent to the solution of

$$\begin{aligned} a(u, (v_1, 0)^T) &= (f, (v_1, 0)^T), \text{ for all } v_1 \in V_1, \\ a(u, (0, v_2)^T) &= (f, (0, v_2)^T), \text{ for all } v_2 \in V_2. \end{aligned}$$

Thus, the variational formulation (??) can be rewritten as a system of two equations:

$$\begin{aligned} i\theta \int_{-L}^H (E'_2 - \imath\theta E_1) \overline{\tilde{E}_1} - \int_{-L}^H ((\epsilon_0 + \imath\nu \text{Id})\mathbf{E})_1 \overline{\tilde{E}_1} &= 0, \\ \int_{-L}^H (E'_2 - \imath\theta E_1) \tilde{E}_2 - \int_{-L}^H ((\epsilon_0 + \imath\nu \text{Id})\mathbf{E})_2 \overline{\tilde{E}_2} - \imath\sqrt{\alpha(-L)} E_2(-L) \tilde{E}_2(-L) &= -g_{inc}(-L) \overline{(\tilde{E}_2(-L))}, \\ \text{for all } \tilde{E}_1 &\in L_2(\Omega), \tilde{E}_2 \in H_1(\Omega). \end{aligned}$$

Inserting an explicit expression for the dielectric permittivity tensor

$$\epsilon_0(x) = \begin{pmatrix} \alpha(\mathbf{x}) & \imath\delta(\mathbf{x}) \\ -\imath\delta(\mathbf{x}) & \alpha(\mathbf{x}) \end{pmatrix} \quad (1)$$

into the above, we obtain

$$\begin{aligned} i\theta \int_{-L}^H (E'_2 - \imath\theta E_1) \overline{\tilde{E}_1} - \int_{-L}^H ((\alpha + \imath\nu)E_1 + \imath\delta E_2)_1 \overline{\tilde{E}_1} &= 0, \\ \int_{-L}^H (E'_2 - \imath\theta E_1) \tilde{E}_2 - \int_{-L}^H (-\imath\delta E_1 + (\alpha + \imath\nu)E_2)_2 \overline{\tilde{E}_2} - \imath\sqrt{\alpha(-L)} E_2(-L) \tilde{E}_2(-L) &= -g_{inc}(-L) \overline{(\tilde{E}_2(-L))}, \\ \text{for all } \tilde{E}_1 &\in L_2(\Omega), \tilde{E}_2 \in H_1(\Omega). \end{aligned} \quad (2)$$

Introducing two basis spaces, $V_{E_1} = \{\psi_j\}_{j=1}^{N_1}$ and $V_{E_2} = \{\phi_i\}_{i=1}^{N_2}$, we look for the solution of the problem (??) in the form:

$$E_1 = \sum_{k=1}^{N_1} e_{1k} \psi_k, \quad E_2 = \sum_{k=1}^{N_2} e_{2k} \phi_k.$$

Substituting $\tilde{E}_1 = \psi_m$, $m = 1, \dots, N_1$ and $\tilde{E}_2 = 0$ into the variational formulation (??), we obtain:

$$\begin{aligned} i\theta \sum_{k=1}^{N_2} e_{2k} \int_{-L}^H \phi'_k \bar{\psi}_m dx + \theta^2 \sum_{k=1}^{N_1} e_{1k} \int_{-L}^H \psi_k \bar{\psi}_m dx \\ - \sum_{k=1}^{N_1} e_{1k} \int_{-L}^H (\alpha(x) + \imath\nu) \psi_k \bar{\psi}_m dx - i \sum_{k=1}^{N_2} e_{2k} \int_{-L}^H \delta(x) \phi_k(x) \bar{\psi}_m dx = 0. \end{aligned}$$

Similarly, for $\tilde{E}_1 = 0$ and $\tilde{E}_2 = \phi_\ell$, $\ell = 1, \dots, N_2$:

$$\begin{aligned} & \sum_{k=1}^{N_2} e_{2k} \int_{-L}^H \phi'_k(x) \bar{\phi}'_\ell(x) dx - i\theta \sum_{k=1}^{N_1} e_{1k} \int_{-L}^H \psi_k(x) \bar{\phi}'_\ell(x) dx \\ & + i \sum_{k=1}^{N_1} e_{1k} \int_{-L}^H \delta(x) \psi_k \bar{\phi}_m dx - \sum_{k=1}^{N_2} e_{2k} \int_{-L}^H (\alpha(x) + i\nu) \phi_k \bar{\phi}_m dx \\ & - i\lambda \sum_{k=1}^{N_2} e_{2k} \phi_k(-L) \bar{\phi}_m(-L) = -g_{inc}(x) \bar{\phi}_m(-L). \end{aligned}$$

After introduction

$$\begin{aligned} (K^{\psi, \phi'})_{mk} &= \int_{-L}^H \bar{\psi}_m \phi'_k dx, & (M^\psi)_{mk} &= \int_{-L}^H \psi_k \bar{\psi}_m dx, \\ (M^{\alpha, \psi})_{mk} &= \int_{-L}^H (\alpha(x) + i\nu) \psi_m \bar{\psi}_k dx, & (M^{\delta, \psi, \phi})_{mk} &= \int_{-L}^H \delta(x) \bar{\psi}_m \phi_k dx, \\ K_{\ell k} &= \int_{-L}^H \phi'_k(x) \bar{\phi}'_\ell(x) dx, & (M^{\alpha, \phi})_{\ell k} &= \int_{-L}^H (\alpha(x) + i\nu) \bar{\phi}_\ell \phi_k dx, \\ & & I_{km}^\Gamma &= \bar{\phi}_m(-L) \phi_k(-L), \\ \mathbf{e}_1 &= (e_{11}, \dots, e_{1N_1})^T, & \mathbf{e}_2 &= (e_{21}, \dots, e_{2N_1})^T, \\ \mathbf{0}_n &\text{ is an } n\text{-dimensional zero column vector.} \end{aligned}$$

the above system of equations can be rewritten in an antisymmetric block form:

$$\begin{pmatrix} \theta^2 M_\psi - M^{\alpha, \psi} & i\theta K^{\psi, \phi'} - iM^{\delta, \psi, \phi} \\ -i\theta(K^{\psi, \phi'})^* + i(M^{\delta, \psi, \phi})^* & K - M^{\alpha, \phi} - i\lambda I^\Gamma \end{pmatrix} \begin{pmatrix} \mathbf{e}_1 \\ \mathbf{e}_2 \end{pmatrix} = -g_{inc}(-L) \begin{pmatrix} \mathbf{0}_{N_1} \\ \bar{\phi}_1(-L) \\ \bar{\phi}_2(-L) \\ \vdots \\ \bar{\phi}_{N_2}(-L) \end{pmatrix}.$$

This expression greatly simplifies when choosing $V_{E_1} = V_{E_2} = (\phi_m)_{m=1}^{N_2}$ and in the case $\theta = 0$:

$$\begin{pmatrix} M^{\alpha, \phi} & iM^{\delta, \phi, \phi} \\ i(M^{\delta, \phi, \phi})^* & K - M^{\alpha, \phi} - i\lambda I^\Gamma \end{pmatrix} \begin{pmatrix} \mathbf{e}_1 \\ \mathbf{e}_2 \end{pmatrix} = -g_{inc}(-L) \begin{pmatrix} \mathbf{0}_{N_1} \\ \bar{\phi}_1(-L) \\ \bar{\phi}_2(-L) \\ \vdots \\ \bar{\phi}_{N_2}(-L) \end{pmatrix}. \quad (3)$$

In all numerical experiments, we make use of the above variational formulation. We apply permutation to the above system to obtain a 7-diagonal Hermitian matrix and solve the system with the Gauss back substitution algorithm.

Let us assume that the operator

$$M\psi = \frac{i\delta}{(\alpha + i\nu)}\psi$$

defines an isomorphism from $L_2(\Omega)$ to $L_2(\Omega)$. Given $E_1, E_2 \in L_2(\Omega)$, the function $\mathcal{F} = \frac{i\delta}{(\alpha + i\nu)} ((\alpha + i\nu)E_1 + i\delta E_2)$ also belongs to $L_2(\Omega)$. If E_1, E_2 satisfy the problem (2) for $\theta = 0$, the function $\mathcal{F} = 0$, i.e.

$$(\mathcal{F}, \tilde{E}_2)_{L_2} = \int_{-L}^H (i\delta E_1 - \delta^2(\alpha + i\nu)^{-1}E_2) \overline{\tilde{E}_2} = 0,$$

for all $\overline{\tilde{E}_2} \in H_1(\Omega)$. Adding this to the second expression of (2), we obtain the variational formulation for E_2 , which coincides with the variational formulation for the Helmholtz equation. The well-posedness of this problem had been studied in [1]. Hence, we can add the second expression (??) to

$$\int_{-L}^H (i\delta E_1 - \delta^2(\alpha + i\nu)^{-1}E_2) \overline{\tilde{E}_2} = 0$$

to obtain the variational formulation for E_2 , which will coincide with the variational formulation for the Helmholtz equation, and thus will be well-posed (see the thesis [?]). The estimates from this thesis, and $\|E_1\|_{L_2}$ can be estimated in terms of $\|E_2\|_{L_2}$.

2. NUMERICAL EXPERIMENTS

This section is organized as follows. The first part is dedicated to the numerical implementation of the frequency domain formulation (??). We study the convergence of this formulation and the behaviour of the numerical solution as the absorption parameter ν tends to zero. The experiments in this section were performed on a laptop with 2.6GHz Intel Core i5 CPU, with the help of the code written in Octave (compatible with Matlab).

The second part of the section deals with the question of the equivalence of the limiting absorption and limited amplitude principle. We compare the solutions obtained as $\nu \rightarrow 0$ with the help of our frequency domain code and of the time domain code (computed for large values of time). The time-domain code implements the scheme described in Section ?? and is written in Fortran.

2.1. Frequency Domain Problem

2.2. Discretization of the Frequency Domain Problem

Let us consider the case of the resonance, more precisely, we consider sufficiently smooth α, δ , s.t. $\alpha(0) = 0$ and $\delta(0) \neq 0$, and the solvability conditions of Theorem ?? are satisfied. For simplicity, let us consider

$$\alpha(x) = -x \text{ in some neighbourhood of } 0. \quad (4)$$

Given the space $\mathbf{V}_h = S_h^1 \times S_h^1$, with S_h^1 consisting of piecewise-linear (hat) functions, we look for a ratio $h(\nu)$ that would ensure that the absolute error

$$\|E_1^\nu - E_1^{\nu,h}\|_{L_2(\Omega)} < \epsilon, \quad (5)$$

given a fixed value of $\epsilon > 0$.

We use the following well-known facts:

- The C ea's lemma applied to the problem (??); here C_c is the continuity and C_i is the coercivity constants:

$$\|\mathbf{E}^\nu - \mathbf{E}^{h,\nu}\|_V \leq \frac{C_c}{C_i} \min_{\mathbf{v} \in V_h} \|\mathbf{E} - \mathbf{v}\|_V \leq \nu^{-1} \min_{\mathbf{v} \in V_h} \|\mathbf{E} - \mathbf{v}\|_V. \quad (6)$$

The last inequality follows from Theorem ??.

- The form of the exact solution to the problem (??):

$$E_1^\nu = E_2^\nu \frac{\delta}{\alpha + i\nu} = \frac{f(x)}{\alpha(x) + i\nu}, \quad (7)$$

for some $f(x) \in L_2(\Omega)$.

- The estimate from [?, Chapter 0] on the rate of convergence of the interpolation

$$\|v - I^h v\|_{L_2(\Omega)} \leq Ch^2 |v''|_{L_2(\Omega)}, \quad C > 0, \quad (8)$$

$$(9)$$

where $I^h v$ is an interpolation operator onto S_h^1 .

For E_1^ν , $f(x)$ in (7) being sufficiently smooth,

$$\frac{d^2}{dx^2} E_1^\nu = \frac{f''}{\alpha + i\nu} - 2 \frac{f' \alpha'}{(\alpha + i\nu)^2} + \frac{f \alpha''}{(\alpha + i\nu)^3},$$

from which, together with (4), it follows that there exists $c > 0$ s.t. for all sufficiently small ν

$$\left| \frac{d^2}{dx^2} E_1^\nu \right|_{L_2}^2 \leq c \int_{\Omega} \frac{1}{(x^2 + \nu^2)^3} dx \leq C \nu^{-5},$$

where $C > 0$ does not depend on ν . This, together with the estimates (6) and (8), results in

$$\|E_1^\nu - E_1^{\nu,h}\|_{L_2(\Omega)} \leq C \nu^{-\frac{7}{2}} h^2,$$

from which it follows that to ensure (5) h should be chosen as $\alpha_\epsilon \nu^{\frac{7}{4}}$, where $\alpha_\epsilon > 0$ depends on ϵ but does not depend on ν .

Let us check whether this holds true. To do so, we conduct the following numerical experiment.

We can show that

$$\|E_1^\nu\|_{L_2(\Omega)} \leq \frac{C}{\sqrt{\nu}}, \quad C > 0,$$

and thus the relative error control

$$\frac{\|E_1^\nu - E_1^{\nu,h}\|_{L_2(\Omega)}}{\|E_1^\nu\|_{L_2(\Omega)}} \leq \epsilon$$

can be ensured by choosing h as $\beta_\epsilon \nu^{\frac{3}{4}}$.

2.3. Discretization of the Time Domain Problem

3. NUMERICAL EXPERIMENTS

3.1. Frequency Domain

3.2. Time Domain