Xiaozhen Zhang

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1 Education

Beijing Institute of Technology, China 2021.9 – present

Ph.D. candidate, School of Automation, supervisor: Qingkai Yang

Nanyang Technological University, Singapore 2025.2 – 2025.8

visting Ph.D. student, School of Electrical & Electronic Engineering, supervisor: Lihua Xie

Northwestern Polytechnical University, China 2018.6 – 2021.4

M.S. degree, School of Astronautics, supervisor: Panfeng Huang

Northwestern Polytechnical University, China 2014.9 – 2018.6

B.S. degree, honor college

2 Research Interests

- **Multi-agent systems**
- **Networked control and estimation**
- **Cooperative aerial transportation**
- **Swarm robotics**
- **Networked flow for solving linear equations**

3 Publications

1. **Xiaozhen Zhang**, Qingkai Yang*, Xianlin Zeng, Hao Fang, and Jie Chen, "Cooperative Shape-Translation Estimation and Control for Time-Varying Linear Formation," ***IEEE Transactions on Automatic Control***, 2025. **(Full Paper)**
2. **Xiaozhen Zhang**, Qingkai Yang*, Fan Xiao, Hao Fang, and Jie Chen, "Linear Formation Control of Multi-agent Systems," ***Automatica***, 2025. **(Regular Paper)**
3. Qingkai Yang*, **Xiaozhen Zhang**, Hao Fang, Ming Cao, and Jie Chen, "Joint Estimation and Planar Affine Formation Control with Displacement Measurements," ***IEEE Transactions on Control Systems Technology***, 2024. **(Full Paper)**
4. **Xiaozhen Zhang**, Qingkai Yang*, Jingshuo Lyu, Xinyue Zhao, and Hao Fang, "Distributed Variation Parameter Design for Dynamic Formation Maneuvers With Bearing Constraints," ***IEEE Transactions on Automation Science and Engineering***, 2024.
5. **Xiaozhen Zhang**, Fan Zhang*, Panfeng Huang, "Formation Planning for Tethered Multirotor UAV Cooperative Transportation With Unknown Payload and Cable Length", ***IEEE Transactions on Automation Science and Engineering***, 2024.
6. **Xiaozhen Zhang**, Fan Zhang*, Panfeng Huang, Jiale Gao, Hang Yu, Chongxu Pei, Yizhai Zhang, "Self-Triggered Based Coordinate Control With Low Communication for Tethered Multi-UAV Collaborative Transportation", ***IEEE Robotics and Automation Letters***, 2021.
7. Zeming Zhao, **Xiaozhen Zhang**, Hao Fang, and Qingkai Yang*, "Distributed Formation Planning for Unmanned Aerial Vehicles", ***Drones***, 2025.
8. Ya Liu, Fan Zhang*, Panfeng Huang, **Xiaozhen Zhang**, "Analysis, planning and control for cooperative transportation of tethered multi-rotor UAVs", ***Aerospace Science and Technology***, 2021.

4 Conferences

1. **Xiaozhen Zhang**, Qingkai Yang, Haijiao Wei, Wei Chen, Zhihong Peng, and Hao Fang, "A Distributed Algorithm for Solving A Time-Varying Linear Equation" in ***62nd IEEE Conference on Decision and Control (CDC)***, 2023.

2. **Xiaozhen Zhang**, Qingkai Yang, Rui Yu, Delong Wu, Shaozhun Wei, Jingqiang Cui, and Hao Fang, "Design and Analysis of Truss Aerial Transportation System (TATS): The Lightweight Bar Spherical Joint Mechanism", in ***IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)***, 2022.
3. **Xiaozhen Zhang**, Jingshuo Lv, Shaolei Wei, and Qingkai Yang, "Distributed Decision Making on Scaling Size for Obstacle Avoidance in Affine Formation Control", in ***37th Youth Academic Annual Conference of Chinese Association of Automation (YAC)***, 2022.
4. **Xiaozhen Zhang**, Fan Zhang, Panfeng Huang, Chen Wang, and Ya Liu,"Distributed Control for Cooperative Transportation in Presence of Unknown Disturbance", in ***IEEE International Conference on Real-time Computing and Robotics (RCAR)***, 2019.
5. **Xiaozhen Zhang**, Qingkai Yang, and et al., "How Do Swarms Behave Compliantly?" ***ICCA2025***. (under review)

5 Principal Awards

- The inaugural Young Elite Scientists Sponsorship Program by CAST, Doctoral Student Special Plan, 2025
- **National Scholarship**, 2024
- **CSC Scholarship**, 2024
- **Outstanding Master's Degree Thesis of Northwestern Polytechnical University**, 2021
- **Outstanding Master Graduates of Northwestern Polytechnical University**, 2021
- **Ministry of Industry and Information Technology Scholarship**, Third Prize, 2017

6 Talks

1. Linear Formation Control of Multi-agent Systems
   The 13th Forum of Young Scientists of China Command and Control Society, Zhuhai, China, April 2025.
2. Research on Motion Control of Swarm Robotics
   The 8th Graduate Forum of Beijing Institute of Technology, Beijing Institute of Technology, Beijing, China, November 2024.
3. Linear Formation Control for Swarm Robots
   International Doctoral Academic Forum on Mechanics and Interdisciplinary Subjects, Peking University, Beijing, China, October 2024.
4. A Distributed Algorithm for Solving A Time-Varying Linear Equation
   AI Future-The 5th Academic Forum on Artificial Intelligence in Beijing Universities, Beijing, China, April 2023.
5. Distributed Decision Making on Scaling Size for Obstacle Avoidance in Affine Formation Control
   The Fourteenth Japan-China International Workshop on Information Technology and Control Applications, Online, November 2022.

7 Academic Service

- **Conference Reviewer**: IROS2019, IROS2021, IROS2022, ACC2022, CDC2023, ICIT2024, ICLR2025.
- **Journal Reviewer**: IEEE Transactions on Automatic Control, IEEE Transactions on Automation Science and Engineering, IEEE Transactions on Fuzzy Systems, IEEE Transactions on Control Systems Technology, International Journal of Robust and Nonlinear Control, IEEE Transactions on Signal and Information Processing over Networks, Journal of Advanced Computational Intelligence and Intelligent Informatics, Autonomous Intelligent Systems.

8 Others

- **Google scholar**: https://scholar.google.com/citations?user=rcMx3LUAAAAJ
- **Personal page**: https://mkb9559.github.io/zxz-main/
- **GitHub**: https://github.com/mkb9559