```
def solve_hull(self, points): # n log n time and space complexity

if len(points) > 3:
    m = math.floor(len(points) / 2)
    leftHalf = points[:m]
    rightHalf = points[m:]
    leftHull = self.solve_hull(leftHalf)
    rightHull = self.solve_hull(rightHalf)
    upperTan = find_upper_tangent(leftHull, rightHull) # n time
    lowerTan = find_lower_tangent(leftHull, rightHull) # n time
    hull = merge(leftHull, rightHull, upperTan, lowerTan) # n time
    return hull
else:
    hull = make_hull(points)
    return hull
```

### **Divide and Conquer Solve Hull Function:**

Time Complexity:

- O(n) from Finding Upper Tangent (see below)
- O(n) from Finding Lower Tangent (see below)
- O(n) from the Merge Function (see below)
- O(log n) from the recursive call that cuts the hull in half each time
- Overall we get  $O((3n) * log n) \Rightarrow O(nlog(n))$

Space Complexity:

- O(n) from the array that gets made for the hull in the merge function
- O(n) from the starting array
- O(2n) => **O(n)**

# **Theoretical Analysis for the Entire Algorithm:**

The worst case time complexity for this divide and conquer algorithm is O(nlog(n)). The recursion is related to this time complexity because at each level of recursion you'll split the points in half until you cannot anymore. By splitting into two at each level of recursion, you end up having log(n) levels to deal with. At each level you have a complexity of O(n), which you do O(log(n)) times, which overall makes the entire algorithm O(nlog(n)).

```
find_upper_tangent(leftHull, rightHull):
rightMostIndex = find_right_most(leftHull)
leftMostIndex = find_left_most(rightHull)
currentIndexLeft = rightMostIndex
currentIndexRight = leftMostIndex
previousLeftHullIndex = rightMostIndex
previousRightHullIndex = leftMostIndex
isTopForLeft = False
isTopForRight = False
currentSlope = find_slope(leftHull[rightMostIndex], rightHull[leftMostIndex])
while not isTopForLeft or not isTopForRight: # n time
        if currentIndexLeft == 0:
            currentIndexLeft = currentIndexLeft - 1
        tempSlope = find_slope(leftHull[currentIndexLeft], rightHull[currentIndexRight])
            currentSlope = tempSlope
            isTopForRight = False
```

```
currentIndexLeft = previousLeftHullIndex
    isTopForLeft = True

while not isTopForRight:
    if currentIndexRight == len(rightHull) - 1:
        currentIndexRight == 0
    else:
        currentIndexRight = currentIndexRight + 1

tempSlope = find_slope(leftHull[currentIndexLeft], rightHull[currentIndexRight])

if tempSlope > currentSlope:
    previousRightHullIndex = currentIndexRight
        currentSlope = tempSlope
    isTopForLeft = False
    isTopForRight = False
    else:
        currentIndexRight = previousRightHullIndex
        isTopForRight = True

return [leftHull[currentIndexLeft], rightHull[currentIndexRight]]
```

#### **Find Upper Tangent Function:**

Time Complexity:

- n is the number of points in the left hull
- m is the number of points in the right hull
- Say n is bigger than m, than worse case complexity is O(2n) =>O(n)
- O(n) from find\_right\_most(lefthull)
- O(n) from find\_left\_most(righthull)
- O(n)+O(n)+O(n) => O(n)

### Space Complexity:

- Nothing is stacked onto each other in memory as you go from iteration to iteration
- O(1)

```
lef find_lower_tangent(leftHull, rightHull):
   rightMostIndex = find_right_most(leftHull)
   leftMostIndex = find_left_most(rightHull)
  currentIndexLeft = rightMostIndex
  currentIndexRight = leftMostIndex
  previousLeftHullIndex = rightMostIndex
  previousRightHullIndex = leftMostIndex
  isBotForLeft = False
  isBotForRight = False
   currentSlope = find_slope(leftHull[rightMostIndex], rightHull[leftMostIndex])
   while not isBotForLeft or not isBotForRight:
       while not isBotForLeft:
              currentIndexLeft = 0
           tempSlope = find_slope(leftHull[currentIndexLeft], rightHull[currentIndexRight])
           if tempSlope > currentSlope:
              currentSlope = tempSlope
              previousLeftHullIndex = currentIndexLeft
              isBotForRight = False
               isBotForLeft = True
```

```
while not isBotForRight:
    if currentIndexRight == 0:
        currentIndexRight = len(rightHull) - 1
else:
        currentIndexRight = currentIndexRight - 1

tempSlope = find_slope(leftHull[currentIndexLeft], rightHull[currentIndexRight])

if tempSlope < currentSlope:
    previousRightHullIndex = currentIndexRight
        currentSlope = tempSlope
    isBotForRight = False
    isBotForLeft = False
else:
    currentIndexRight = previousRightHullIndex
    isBotForRight = True</pre>

return [leftHull[currentIndexLeft], rightHull[currentIndexRight]]
```

## **Finding Lower Tangent Function:**

Time Complexity:

- n is the number of points in the left hull
- m is the number of points in the right hull
- Say n is bigger than m, than worse case complexity is O(2n) =>O(n)
- O(n) from find\_right\_most(lefthull)
- O(n) from find\_left\_most(righthull)
- O(n)+O(n)+O(n) => O(n)

## Space Complexity:

- Nothing is stacked onto each other in memory as you go from iteration to iteration
- O(1)

```
def merge(leftHull, rightHull, upperTan, lowerTan):
    mergedHull = []
    foundTopRight = False
    TopRightIndex = 0
    while not foundTopRight:
        if rightHull[TopRightIndex] == upperTan[1]:
            foundTopRight = True
        else:
            TopRightIndex = TopRightIndex + 1

    foundBottomRight = False
    BotRightIndex = 0
    while not foundBottomRight:
        if rightHull[BotRightIndex] == lowerTan[1]:
            foundBottomRight = True
        else:
            BotRightIndex = BotRightIndex + 1
```

```
foundBottomLeft = False
BotLeftIndex = 0
    if leftHull[BotLeftIndex] == lowerTan[0]:
       BotLeftIndex = BotLeftIndex + 1
while TopRightIndex != BotRightIndex:
   mergedHull.append(rightHull[TopRightIndex])
    if TopRightIndex == len(rightHull) - 1:
        TopRightIndex = 0
        TopRightIndex = TopRightIndex + 1
mergedHull.append(rightHull[BotRightIndex])
while BotLeftIndex != TopLeftIndex:
   mergedHull.append(leftHull[BotLeftIndex])
    if BotLeftIndex == len(leftHull) - 1:
       BotLeftIndex = 0
       BotLeftIndex = BotLeftIndex + 1
mergedHull.append(leftHull[TopLeftIndex])
return mergedHull
```

### **Merge Function:**

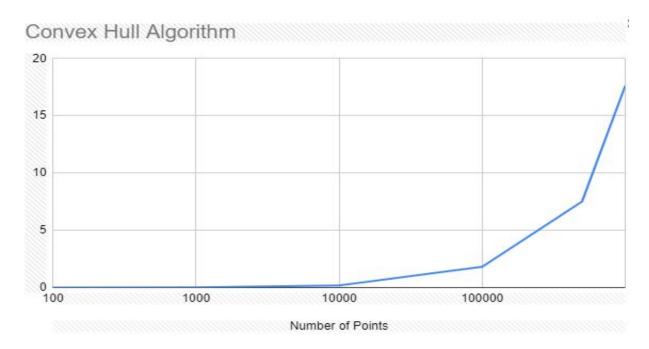
Time Complexity:

- n is the number of points in the left and right hull
- O(n) is worst case as we travel around each while loop in case we have to hit every point before the while loop stops
- O(5n) from all the while loops => O(n)

## Space Complexity:

- n is the number of points in the hulls
- O(n) is the worst case because we are storing an array of all the points

	10	100	1000	10000	100000	500000	1000000
1	0.0001	0.001	0.018	0.204	1.667	7.642	15.051
2	0.0001	0.002	0.026	0.211	1.702	8.501	13.759
3	0	0.001	0.015	0.151	1.48	8.107	25.766
4	0	0.001	0.014	0.122	2.085	6.425	19.561
5	0	0.001	0.014	0.196	2.12	6.906	13.936



#### **Discussion on the Pattern of the Plot:**

I believe that the order of growth that fits best is something more linear than the expression O(nlog(n)). My graph does not relate very well proportionately to the graph of nlog(n). In fact, as the number of points increases, the proportion between what theoretically is happening with the nlogn time and the actual time increases as well.

For example, the ratio between nlogn and the empirical time at 100 points was around 500,000. But at 1,000,000 points the ratio was over a million. This means that the empirical results performed much better than the theoretical results (which makes sense, because nlogn is worst case scenario. If I had to make an estimate of what the proportion constant would be, it about 1/800,000.

The biggest difference between what is empirically happening and what we theorized would happen is that the order of growth is a lot smaller in our algorithm. This is because we theorized the Big O to be what our worst-case scenarios would be. This is a safe claim, but is also unlikely because it would be very rare to have the worst-case scenarios happen, especially with a larger number of points (which is also why the constant of proportionality gets bigger as the amount of points gets larger).

