Project 0 - Legged Locomotion Robot

EECS 464 - Winter 2018

**README for ZIP file**

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Team Blue:

Royce Chung

Anne Gu

Mukai Wang

Ali Yassine

Course Instructor:

Prof. Shai Revzen

The following files are contained in the HowTo\_P0\_18Blue.zip:

1. AssemblyInstructions\_P0\_18\_Blue.pdf

* Specific instructions for building our robot, including descriptions of materials used and code used.

2. p0blue.py

* Source code for robot controls. Reads values from left.csv, right.csv, and leap.csv to determine plan for turning left or right and moving forward

3. runrobot.py

* Bash script for executing p0blue without having to enter command line arguments. Stores servo assignments

4. left.csv

* Contains the three servo motions to turn left

5. right.csv

* Contains the three servo motions to turn right

6. leap.csv

* Contains the three servo motions to leap forward