Assignment 4: Heap Data Structures - Implementation, Analysis, and Applications

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Course Title: Algorithms and Data Structures (MSCS-532-B01)

Heapsort Implementation and Analysis

1. Implementation

```
Python Code for Heapsort:
def heapify(arr, n, i):
  largest = i
  1 = 2 * i + 1
  r = 2 * i + 2
  if 1 < n and arr[1] > arr[largest]:
     largest = 1
  if r < n and arr[r] > arr[largest]:
     largest = r
  if largest != i:
     arr[i], arr[largest] = arr[largest], arr[i]
     heapify(arr, n, largest)
def heapsort(arr):
  n = len(arr)
  for i in range(n // 2 - 1, -1, -1):
     heapify(arr, n, i)
  for i in range(n - 1, 0, -1):
     arr[i], arr[0] = arr[0], arr[i]
     heapify(arr, i, 0)
  return arr
```

The Heapsort algorithm was implemented using a Max-Heap data structure built within a Python list. The key steps include building the heap from the array, repeatedly swapping the root (maximum element) with the last element, and reducing the heap size while restoring the heap property.

2. Time and Space Complexity Analysis

Time Complexity:

Worst-case: O(n log n)
Average-case: O(n log n)
Best-case: O(n log n)

All cases result in $O(n \log n)$ time complexity due to heap construction in O(n) and repeated heapify calls on $\log(n)$ levels.

Space Complexity: O(1) (in-place algorithm, no auxiliary arrays used).

3. Empirical Comparison

Heapsort was compared with Quicksort and Merge Sort across varying sizes of arrays (sorted, reverse, random). While Quicksort often performs faster due to better cache locality, Heapsort provides consistent performance and better worst-case guarantees.

Priority Queue Implementation and Applications

Part A: Priority Queue Design

Python Code for Priority Queue Implementation:

```
class Task:
  def init (self, task id, priority, arrival time, deadline):
     self.task id = task id
     self.priority = priority
     self.arrival time = arrival time
     self.deadline = deadline
  def lt (self, other):
     return self.priority < other.priority
class PriorityQueue:
  def init (self):
     self.heap = []
  def is empty(self):
     return len(self.heap) == 0
  def insert(self, task):
     self.heap.append(task)
     self. sift up(len(self.heap) - 1)
  def extract min(self):
     if self.is empty():
       return None
     self. swap(0, len(self.heap) - 1)
```

```
min task = self.heap.pop()
  self. heapify(0)
  return min task
def decrease key(self, index, new priority):
  self.heap[index].priority = new priority
  self. sift up(index)
def sift up(self, idx):
  parent = (idx - 1) // 2
  while idx > 0 and self.heap[idx] < self.heap[parent]:
     self. swap(idx, parent)
     idx = parent
     parent = (idx - 1) // 2
def heapify(self, idx):
  smallest = idx
  left = 2 * idx + 1
  right = 2 * idx + 2
  if left < len(self.heap) and self.heap[left] < self.heap[smallest]:
     smallest = left
  if right < len(self.heap) and self.heap[right] < self.heap[smallest]:
     smallest = right
  if smallest != idx:
     self. swap(idx, smallest)
     self. heapify(smallest)
def swap(self, i, j):
  self.heap[i], self.heap[j] = self.heap[j], self.heap[i]
```

A min-heap was used to implement the priority queue, ideal for task scheduling based on priority. The Python list represents the heap, allowing efficient insertions and deletions.

Each task is modeled using a Task class containing task ID, priority, arrival time, and deadline.

Core Operations

- insert(task): O(log n) Inserts a task and restores heap property via sift-up.
- extract min(): O(log n) Removes the task with the lowest priority and re-heapifies.
- decrease_key(): O(log n) Updates priority and performs sift-up to maintain the heap.
- is empty(): O(1) Checks if the heap is empty.

Conclusion

This assignment provided a comprehensive understanding of heap-based algorithms and their real-world applications in sorting and priority scheduling. The implementations demonstrate efficient time complexities and validate theoretical expectations.