Masaad Khan

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WORK EXPERIENCE

Intel Xeon SoC Pre-silicon Verification Intern (Full-time) May 2022 - August 2022

Remote

- Completed working voltage sensor and SPI drivers despite a complicated bug in Tesla's SPI silicon
- Implemented and rigorously tested a software architecture designed to funnel temperature and voltage data over SPI
- Created a python script able to generate QSPI images working around the LittleFS library, which used linux-like commands

January 2022 - May 2022

Design Verification Intern - RISC-V CPU Team (Full-time)

Austin, TX

- Compiled Google's open-source System Verilog RISC-V DV toolkit and modified it to generate tests useful to Tenstorrent
- familiarized myself with UVM
- Migrated Tenstorrent's enhancements to the vector, floating point, and more units to Google's head commit
- Produced testbenches using RISC-V DV and ran them in VCS and whisper (RISC-V ISS) to ensure no system breaking changes
- Generated diagrams in React using Python and data from SQL to describe our RTL interfaces; streamlines testbench gen-

Tesla

January 2021 - August 2021

Silicon Development Intern – Autopilot Hardware Group (Full-time)

Palo Alto, CA

- Completed working voltage sensor and SPI drivers despite a complicated bug in Tesla's SPI silicon
- Implemented and rigorously tested a software architecture designed to funnel temperature and voltage data over SPI
- Improved a python script to recursively parse generated protobuf, automated sending protobuf messages by filling a
- .JSON/.proto file, and synced this script as well as the hardware based on messages received over UART
- Created a python script able to generate QSPI images working around the LittleFS library, which used linux-like commands
- Gained experience writing firmware running ARM CMSIS RTOS wrapper for FreeRTOS, including drivers, interrupt handlers, etc

RESEARCH

Wireless Networking and Communications Group - UT Austin

August 2021 – Present

Undergraduate Researcher

Austin, TX

- Generated image datasets of Airsim drone simulations in Unreal Engine using C++ and Python; made to help train a CV model
- Coordinated with another undergraduate student to deliver object-detection using MobilenetV2 on the Jetson Nano
- Provided a networking stack to detect latency for a center-less cloud of Jetson Nanos using ZeroMQ and Google Protobuf
- Worked closely with a PhD student under researching In/Out of Distribution inputs to neural networks

PROJECTS

Cycle-level CPU Simulation

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SKILLS

- Programming Languages: System Verilog, Verilog, C, Python, C++, Perl, ARM Thumb/Risc-V Assembly
- Libraries: ARM CMSIS RTOS, FreeRTOS, Protobuf, Nanopb, Threading (Python), PySerial, PyFTDI, LittleFS (Python), PyTest
- Computer Science: Object Oriented Programming, Data Structures, Machine Learning, Operating Systems, Agile
- Software Applications: VCS, UVM, Whisper, Vivado, Git, Lauterbach, Linux, MATLAB, KiCad, Autodesk Eagle, Latex