Final Comments

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**Result**

Result of my work is that we have working and tested traction of hand, calculations required and simulation on python side. Also finished system of communicating coordinates to Arduino but this part was tested at all in other ways then getting x data on display that was tripping as hell.

Otherwise Jaakko had first version of mechanical arm that still needed a lot of modifications to make is durable and Daniel had some working version of motors rotations depending on the angle given to them.

Overall we had three separately working parts but we didn’t had any time to put them together and at least try to make them work.

**What to remember**Firstly to really introduce Git to people working on project, it’s amazing to have all files in one place where everyone can access them. For example, while Daniel was sleeping I had time to work on the motors but really couldn’t cause I hadn’t access to his code that was already working and it felt silly to start from scratch when other one has at least somehow working version. With bigger and longer project this will have even more weight.

Have solid plan on first. It was really hard to hold horses from excitement, so we just all started working before we really knew what are we doing. Having good plan would helped with helping each other, because on this time we needed to explain everything to each other before we could help. Also we couldn’t work on other’s member problems without them, because we hadn’t had any idea what are they trying to achieve. Also some problems would be probably noticed earlier.

Don’t try to freestyle mechanical design. That’s it☺