



# Looking Beyond the Local Neighbourhood: dynamic kernel topographic indices (KTPI)

Presentation for **FOSS4G 2016**  
302A - Wednesday, May 4, 2016 - 17:00 to 17:15 | [tesera.com](http://tesera.com)

# Introductions

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Presenting: Michael Kieser

Key collaborators (stuck at home working):

Matt Zandstra, Boris Cosic, Yves Richard

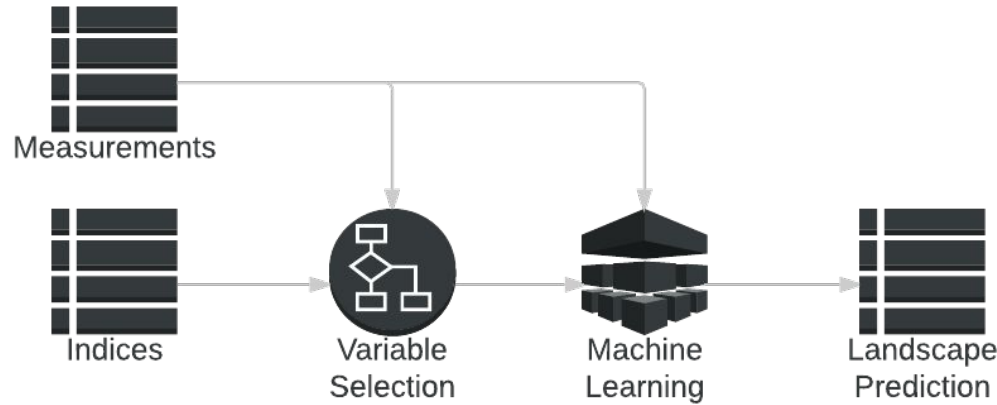
# Agenda

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- Why** KTPI for prediction
- What** Capabilities
- How** Cloud based task distribution

# Why KTPI

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- **Indices** are used as inputs for landscape prediction / imputation processes for Forestry and Insurance clients.
- **Multi-scale** kernels improve the predictive power for each measurement (target).
- Process at multiple-scales and let the models decide which scale is best for each measurement (target)
- Processing is **CPU Intensive**



<https://github.com/tesera/ktpi>

Kernel Topographic Indices (KTPI) is a R based utility to classify topography using raster focal and zonal analysis based to derive elevation statistics, terrain indices, topographic position indices, and kernel aspect indices from DEM (digital elevation model) data.

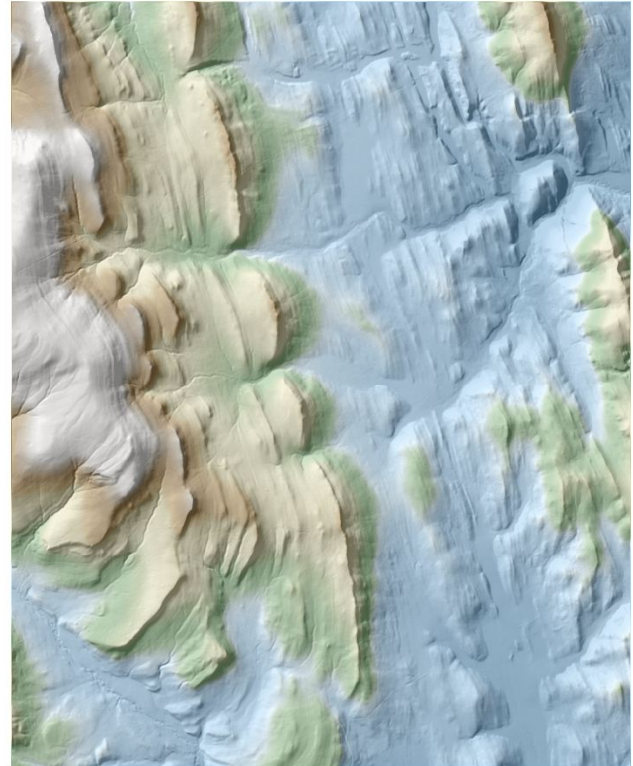
**Hijmans, R. + Weiss, A. + Stage, A.**

# What

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## INPUT

**feature data** (unique id): rasterized point, line, polygon  
**digital elevation model**



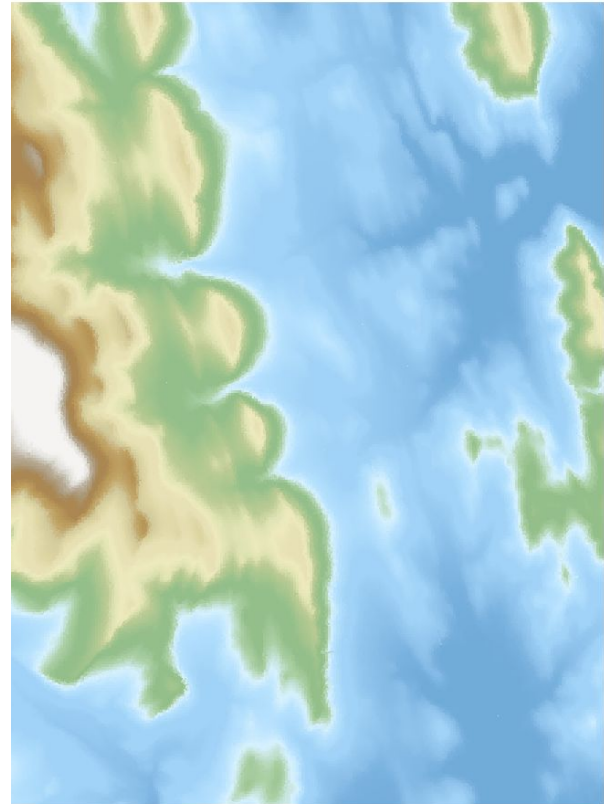
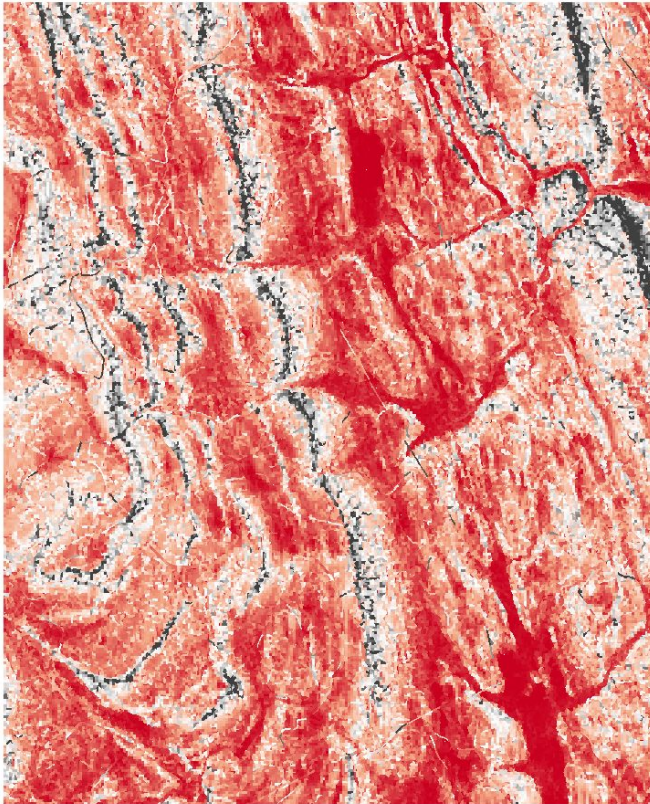


# What

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## **ktpi.R** STATISTIC

zonal analysis of elevation value statistics for each feature

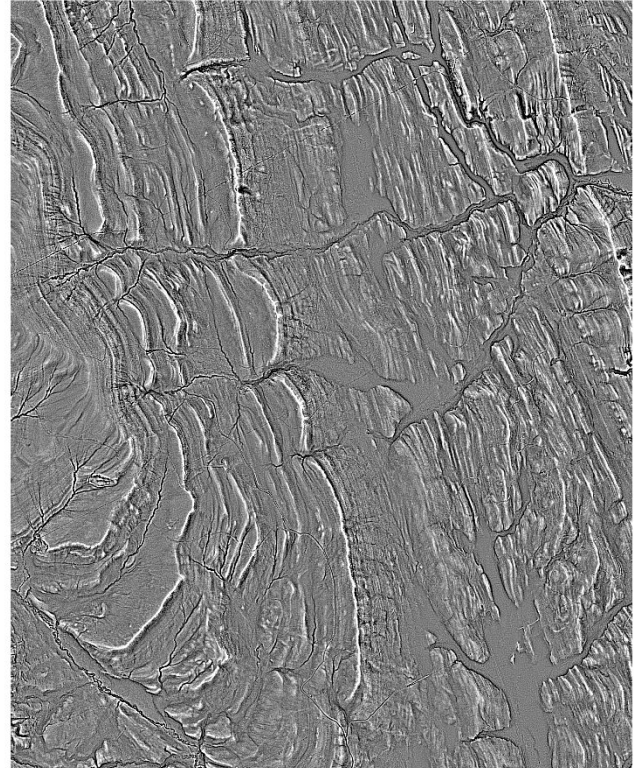
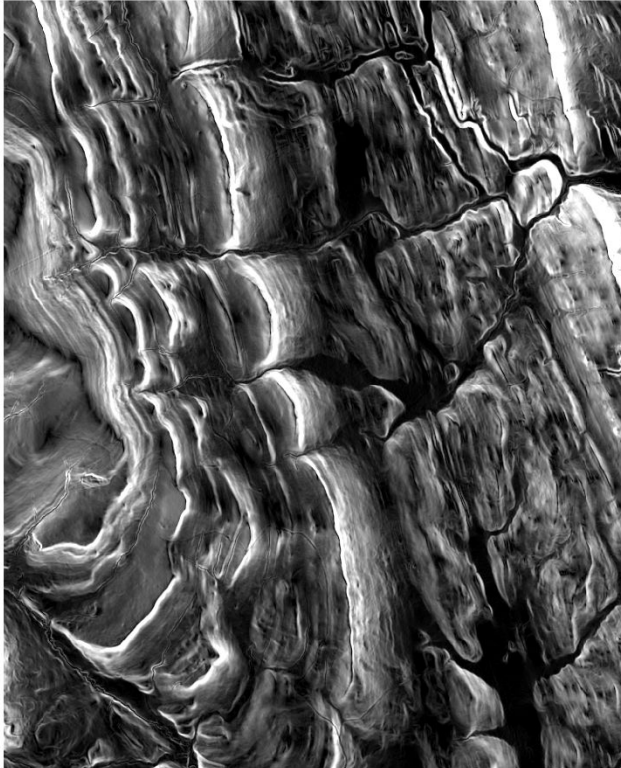


# What

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## ktpi.R TERRAIN

zonal analysis of “terrain” function (Robert J. Hijmans **R raster** library) outputs for each feature



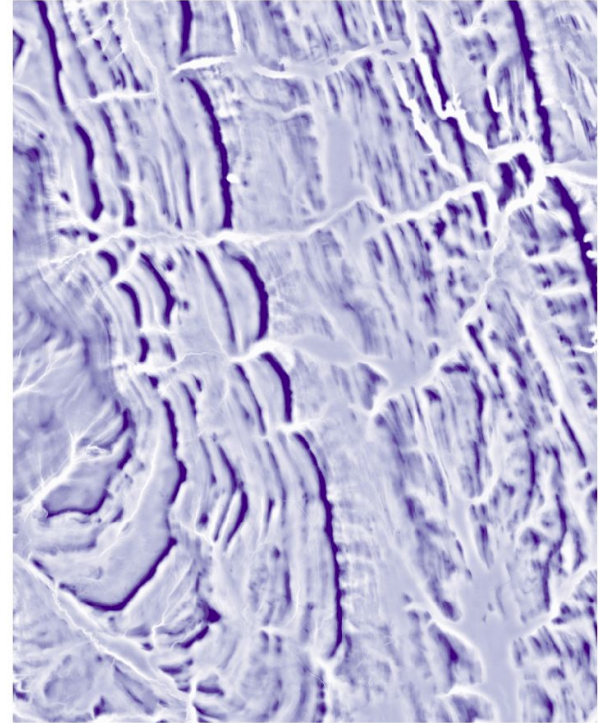
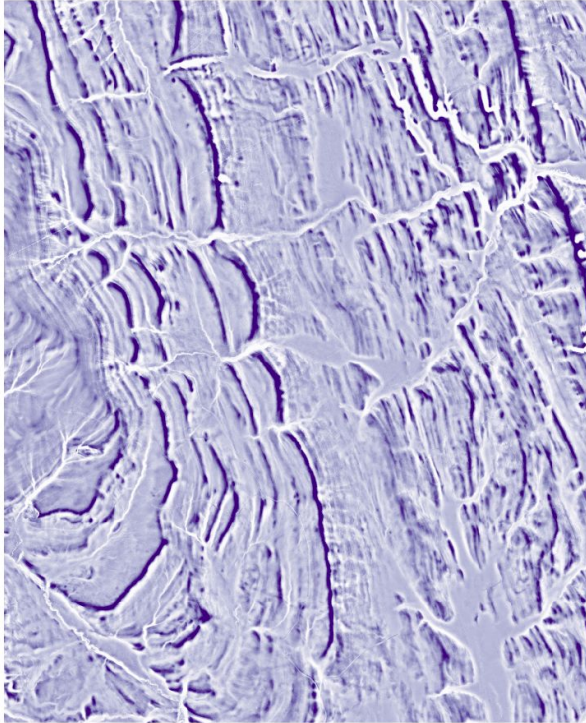


# What

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## **ktpi.R** **KTPi**

zonal analysis of, a focal analysis of difference from mean and standard deviation within a given kernel (Andrew D. Weiss, 2001), for each feature

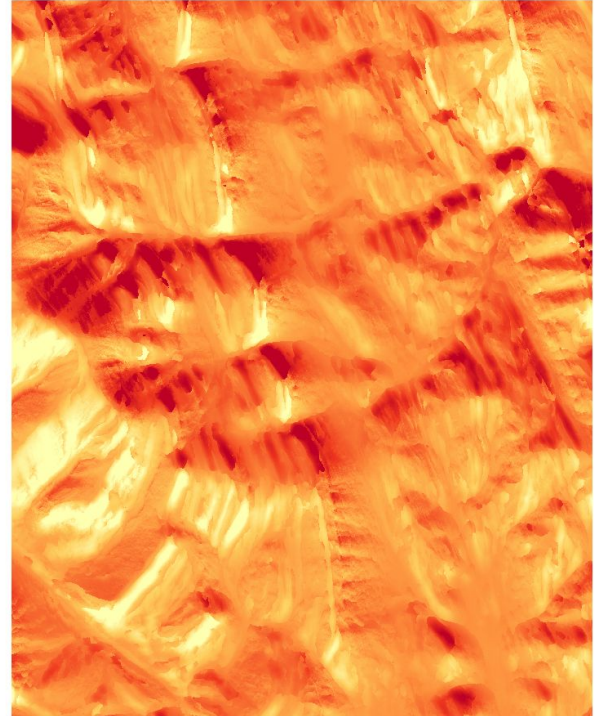
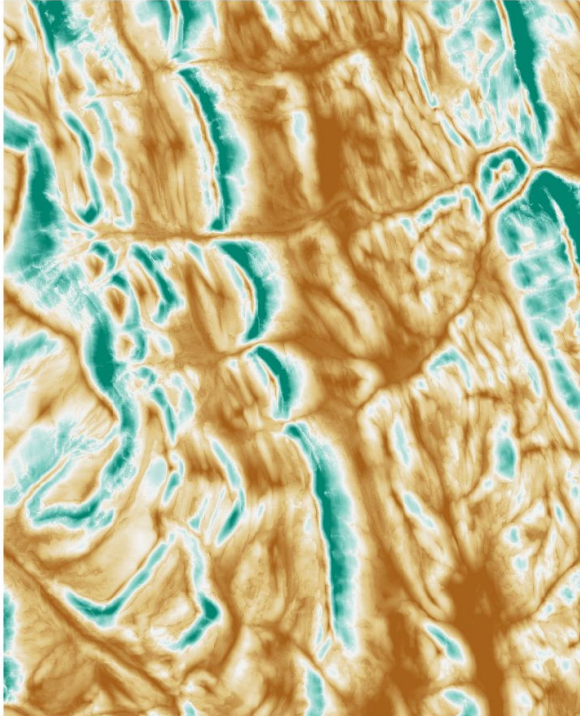


# What

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## **ktpi.R** KASP

zonal analysis of, a focal analysis of the interactions of direction and slope of aspect and elevation within a given kernel (Albert R. Stage, 2007), for each feature



# How

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## Option 1: Run a single CLI command:

```
ktpi.R statistic /input/feature/6/7.tif /input/dem /output --dem-cell-size 10
```

## Option 2: Run batch on a single machine:

a. Use CLI Generator to generate commands:

```
./ktpi.R ktpi-cli --ktpi-function statistic --ktpi-function terrain ../input/features ../input/dems ../output --tile-col-min 0 --tile-col-max 10 --tile-row-min 0 --tile-row-max 10 --raster-cells 500 --raster-cell-size 5 -d 5 -l none
```

b. Run CLI commands generated:

```
ktpi.R statistic /input/feature/6/7.tif /input/dem /output --dem-cell-size 10
ktpi.R terrain /input/feature/6/7.tif /input/dem /output --dem-cell-size 10
ktpi.R ktpi /input/feature/6/7.tif /input/dem /output --dem-cell-size 10 --kernel-size 400
...
```

# How

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## Option 3: Prepare tasks for AWS ECS Cluster

a. Use SQS Generator to generate SQS messages:

```
./ktpi.R ktpi-sqs --ktpi-feature feature --ktpi-function statistic --ktpi-function terrain --tile-col-min 0 --tile-col-max 10 --tile-row-min 0 --tile-row-max 10 --raster-cells 500 --raster-cell-size 5 -d 5 -l none
```

b. Push messages to SQS

c. Push data to S3

d. Configure AWS Elastic Compute Service (ECS): tools/run-instances.sh

e. Start ECS tasks: tools/start-task.sh + Dockerfile (r-spatial-raster + ktpi.R)

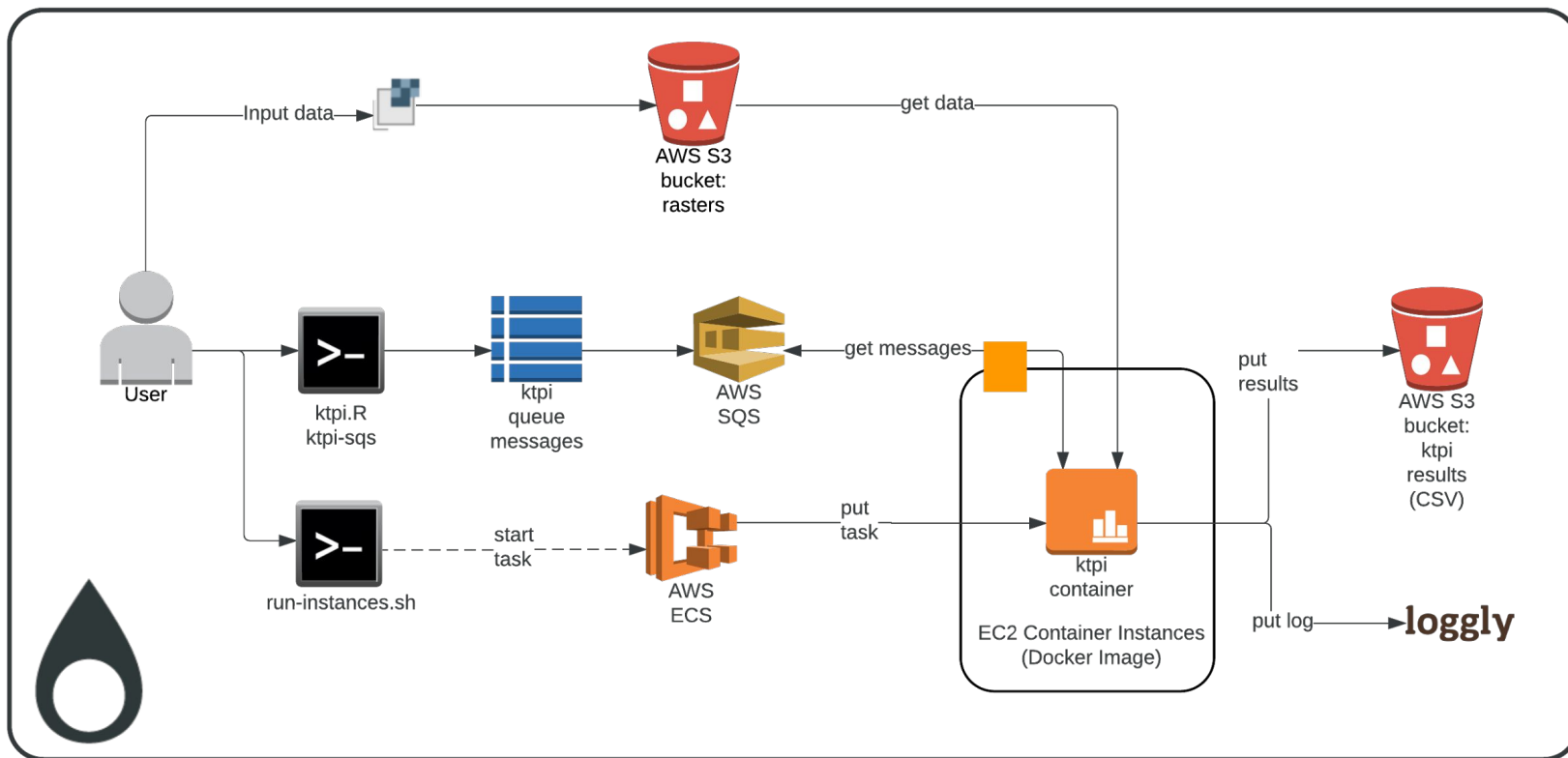
f. ECS instance retrieves messages: tools/client.js

g. ECS instance generates commands: tools/runner.sh

h. ECS instance runs ktpi.R command

i. ECS checks output & writes to S3: tools/runner.sh

# Distributed in Amazon Web Services





# Results

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- **ECS / Docker** used to overcome challenges with deploying geospatial dependencies (R, gdal, geos, sp, raster, rgdal, rgeos, docopt)
- **SQS** as a task repository with built in failure handling
- **Isolated self contained tasks** enables graceful degradation and retry.
- **User friendly** frontend under development.

Over and out

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Thank you for your time :)



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