## 2.5 ANOVA

# Analysis of Variance – ANOVA

Analysis of variance is a method to *compare means of groups of continuous observations* where the groups are defined by the levels of the factors.

- Y: continuous variable
- **x**: categorical variable(s)

The element of  $\boldsymbol{X}$  (design matrix) are  $\boldsymbol{\text{dummy}}$  variables.

### Example: One-factor analysis

Genetically similar seeds are randomly assigned to be raised in either nutritionally enriched environment (treatment A or treatment B) or standard conditions (control group) using a **completely randomised experimental design**. After a predetermined time all plants are harvested, dried and weighted.

```
library(dobson)
data("plant.dried")
attach(plant.dried)
head(plant.dried)
```

**Remark:** if experimental units are randomly allocated to groups corresponding to J levels of a factor, this is called a **completely randomised experiment**.

The responses at level j, i.e.  $Y_{j1},\ldots,Y_{jn_j}$  are called **replicates**. In the example  $n_j=K$  for j=1,2,3, but this is not always true. We assume  $n_j=K$  throughout for simplicity.

The **response** vector (of length N=JK), is given by:

$$\mathbf{y} = [Y_{11}, Y_{12}, \dots, Y_{1K}, Y_{21}, \dots, Y_{2K}, \dots, Y_{J1}, \dots, Y_{JK}]$$

We consider three specifications of the model:

1. 
$$\mathbb{E}(\mathrm{Y}_{jk}) = \mu_j$$
 for  $k = 1, \ldots, K$ 

2. 
$$\mathbb{E}(\mathrm{Y}_{jk}) = \mu + lpha_j$$
 for  $k = 1, \ldots, K$ 

3. 
$$\mathbb{E}(\mathrm{Y}_{jk}) = \mu + lpha_j$$
 for  $k=1,\ldots,K$ , under constraint  $lpha_1=0$ 

#### Model 1

Model 1 - 
$$\mathbb{E}(\mathrm{Y}_{jk}) = \mu_j$$
 for  $k=1,\ldots,K$ 

Model (1) can be re-written as  $\mathbb{E}(Y_i) = \sum_{j=1}^J x_{ij} \mu_j$  for  $i=1,\ldots,N$  where  $x_{ij}$  represent an element of the **design matrix** through:

- ullet  $x_{ij}=1$  if response  $Y_i$  corresponds to level j
- $x_{ij}=0$  otherwise

This gives  $\mathbb{E}(\mathbf{y}) = \mathbf{X}\boldsymbol{\beta}$  where

$$oldsymbol{eta} = egin{pmatrix} \mu_1 \ \mu_2 \ dots \ \mu_J \end{pmatrix} \quad ext{and} \quad \mathbf{X} = egin{pmatrix} \mathbf{1} & \mathbf{0} & \cdots & \mathbf{0} \ \mathbf{0} & \mathbf{1} & \cdots & \mathbf{0} \ dots & dots & \cdots & dots \ \mathbf{0} & \mathbf{0} & \cdots & \mathbf{1} \end{pmatrix}.$$

The design matrix is given by

and the estimate  $\hat{m{\beta}}$  is the vector of sample means for each group

The disadvantage of this simple formulation of the model is that it *cannot be extended to consider* more than one factor.

#### Model 2

Model 2 - 
$$\mathbb{E}(\mathrm{Y}_{jk}) = \mu + lpha_j$$
 for  $k=1,\ldots,K$ 

In this model  $\mu$  is an **average effect** for all levels and  $\alpha_j$  is an **additional effect** due to level j. In this case we have:

$$oldsymbol{eta} = egin{pmatrix} \mu \ lpha_1 \ lpha_2 \ draingledown \ lpha_J \end{pmatrix} \quad ext{and} \quad \mathbf{X} = egin{pmatrix} \mathbf{1} & \mathbf{1} & \mathbf{0} & \cdots & \mathbf{0} \ \mathbf{1} & \mathbf{0} & \mathbf{1} & \cdots & \mathbf{0} \ \mathbf{1} & \mathbf{0} & \mathbf{0} & \cdots & \mathbf{0} \ \vdots & draingledown & draingledown \ \mathbf{1} & \mathbf{0} & \mathbf{0} & \cdots & \mathbf{1} \ \end{pmatrix}.$$

The design matrix as an additional column of elements equal to 1.

The first row (or column) of the  $(J+1)\times (J+1)$  matrix  $\mathbf{X}^{\top}\mathbf{X}$  is the sum of the remaining rows (or columns), therefore  $\mathbf{X}^{\top}\mathbf{X}$  is **singular** and there is **no unique solution**.

The general solution can be written

$$\hat{oldsymbol{eta}} = egin{bmatrix} \hat{eta} \ \hat{eta}_1 \ \vdots \ \hat{eta}_J \end{bmatrix} = rac{1}{K} egin{bmatrix} 0 \ Y_{1.} \ \vdots \ Y_{J.} \end{bmatrix} - \lambda egin{bmatrix} -1 \ 1 \ \vdots \ 1 \end{bmatrix}$$

where  $\lambda$  is an arbitrary constant and  $\mathbf{Y}_{j.} = \sum_{i=1}^{n_j} \mathbf{Y}_{ij}$ .

Usually a **sum-to-one constraint** is used, such that  $\sum_{j=1}^{J} lpha_j = 0$ , i.e.

$$rac{1}{K}\sum_{j=1}^J Y_{j.} - J\lambda = 0 \qquad \Longleftrightarrow \qquad \lambda = rac{1}{JK}\sum_{j=1}^J Y_{j.} = rac{Y_{..}}{N}$$

and therefore

$$\hat{\mu} = rac{Y_{..}}{N} \qquad ext{and} \qquad \hat{lpha}_j = rac{Y_{j.}}{K} - rac{Y_{..}}{N} \quad j = 1, \dots, J$$

library(dobson)
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attach(plant.dried)

#### Model 3

Model 3 - 
$$\mathbb{E}(\mathrm{Y}_{jk}) = \mu + lpha_j$$
 for  $k=1,\ldots,K$ , under constraint  $lpha_1=0$ 

In this case  $\mu$  represents the effect of the first level and  $\alpha_j$  measures the difference between the first level and the j-th level of the factor.

This is called a **corner point parametrization**. We have

$$m{eta} = egin{pmatrix} \mu \ lpha_2 \ dots \ lpha_J \end{pmatrix} \quad ext{and} \quad \mathbf{X} = egin{pmatrix} \mathbf{1} & \mathbf{0} & \mathbf{0} & \cdots & \mathbf{0} \ \mathbf{1} & \mathbf{1} & \mathbf{0} & \cdots & \mathbf{0} \ \mathbf{1} & \mathbf{0} & \mathbf{1} & \cdots & \mathbf{0} \ \vdots & dots & dots & \ddots & dots \ \mathbf{1} & \mathbf{0} & \mathbf{0} & \cdots & \mathbf{1} \end{pmatrix}.$$

Now  $\mathbf{X}^{\top}\mathbf{X}$  is **not singular**, so there a **unique solution** for

$$\hat{oldsymbol{eta}} = rac{1}{K}egin{bmatrix} \mathrm{Y}_{1.} \ \mathrm{Y}_{2.} - \mathrm{Y}_{1.} \ dots \ \mathrm{Y}_{J.} - \mathrm{Y}_{1.} \end{bmatrix}$$

In the analysis of the variance, it is important to *compare the alternative hypothesis* (means for each level differ) with the *null hypothesis* (means are all equal)

For the null model,  $\mathbb{E}(Y_{jk}) = \mu$  and the design matrix is a column vector of elements equal to 1, i.e.  $\mathbf{X}^{\top}\mathbf{X} = N$  and  $\mathbf{X}^{\top}\mathbf{y} = Y$ .

$$egin{aligned} D_1 &= rac{1}{\sigma^2} (\mathbf{y}^ op \mathbf{y} - \hat{oldsymbol{eta}}^ op \mathbf{X}^ op \mathbf{y}) \ D_0 &= rac{1}{\sigma^2} \left[ \sum_{j=1}^J \sum_{k=1}^K \mathrm{Y}_{jk}^2 - rac{Y_{..}^2}{N} 
ight] \end{aligned}$$

and the F-statistic

$$F = \frac{D_0 - D_1}{J - 1} / \frac{D_1}{N - J}$$

```
library(dobson)
data("plant.dried")
attach(plant.dried)
y <- matrix(weight, ncol=1)</pre>
X <- cbind( rep(1, nrow(plants)) ,</pre>
            c(rep(0,10), rep(1,10), rep(0,10)),
            c(rep(0,20),rep(1,10))
b.hat <- solve(t(X) %*% X) %*% t(X) %*% y
b.hat
D1 <- t(y) %*% y - t(b.hat) %*% t(X) %*% y
# Null model:
X0 <- matrix(rep(1,nrow(plant.dried)),ncol=1)</pre>
b0.hat <- solve(t(X0) %*% X0) %*% t(X0) %*% y
D0 <- t(y) %*% y - t(b0.hat) %*% t(X0) %*% y
Fstat \leftarrow ((D0 - D1)/(ncol(X)-1)) / (D1 / (nrow(X)-ncol(X)))
crit.val \leftarrow qf(0.95, df1 = ncol(X)-1, df2 = nrow(X)-ncol(X))
if(Fstat > crit.val){
  cat("There is enough evidence to reject HO")
}else{
  cat("There is NOT enough evidence to reject HO")
}
```

Similarly, we could have obtained the same results with the  $\mathtt{lm}()$  function

```
library(dobson)
data("plant.dried")
attach(plant.dried)

res.lm <- lm(weight ~ group)
summary(res.lm)</pre>
```

Have a look to the two-factor analysis of variance, which is a simple extension of this section (Dobson and Barnett, 2018, Section 6.4.2).