```
\mathcal{R}_{v}
(1)
\mathcal{R}_{v}
\mathcal{C}_{\mathcal{R}_{v}}
\mathcal{D}_{v}
d_{(s,k)}
R_{d_{t}}
                                                                                 \mathcal{R}_{v} = \{r_{(v,i)} | 1 \le i \le R_{v}, i \in Z^{+}\}, \mathcal{C}_{\mathcal{R}_{v}} = \{c_{r_{(v,j)}} | 1 \le j \le R_{v}, j \in Z^{+}\}, \mathcal{D}_{v} = \{d_{(v,k)} | 1 \le k \le D_{v}, k \in Z^{+}\},
                                                                                 R_{d_{(s,k)}}^{(s,n)} = B \log_2(1 + \gamma_{d_{(s,k)}}),
(2) \\ \begin{matrix} P_{d_{(s,k)}} \\ k \end{matrix}
                                                                                                                                                                                                                                         \frac{p_{d_{(s,k)}}|h^H_{\mathcal{R}_s,d_{(s,k)}}w_{\mathcal{R}_s,d_{(s,k)}}|^2}{I_{d_{(s,k)}}+BN_0}.
     (3) I_{d_{(s,k)}} BN_0 h_{\mathcal{R}_s,d_{(s,k)}} L
                                                                              \overset{k}{w}_{\mathcal{R}_{s},d_{(s,k)}}
                                                                           \begin{cases} k_s, a_0 \\ k_s \\ y_{d(s,k)} \\ y_{\mathcal{D}_s} \\ 1 \\ y_{\mathcal{D}_s} \\ y_{\mathcal{D
                                                                           y_{\mathcal{D}_s} = \sum_{v=1}^S H_{\mathcal{R}_v, \mathcal{D}_s}^H \hat{x}_{\mathcal{R}_v} + z_{\mathcal{D}_s},
(4) \\ \hat{x}_{\mathcal{R}_{v}} = \\ [\hat{x}_{r_{(v,1)}}, ..., \hat{x}_{r_{(v,\mathcal{R}_{v})}}]^{T} \in \\ \mathcal{C}^{R_{v}} \\ z_{\mathcal{D}_{s}} \mathcal{N}(0, N_{0}I_{D_{s}}) \\ N_{0} \\ H_{\mathcal{R}_{v}, \mathcal{D}_{s}} = \\ {}^{\Gamma_{L_{\mathcal{D}_{s}}, \mathcal{D}_{s}}} \\ {}^{\Gamma_{L_{\mathcal{D}_{s}}, \mathcal{D}_{s}}} = \\ {}^{\Gamma_{L_{\mathcal{D}_{s}}, \mathcal{D}_{s}}} \\ (4) \\ \mathcal{C}^{R_{v}} \\ \mathcal{C}^{R
                                                                         \begin{bmatrix} h_{\mathcal{R}_v, D_s} - \\ [h_{\mathcal{R}_v, d_{(s,1)}}, \dots, h_{\mathcal{R}_v, d_{(s,\mathcal{D}_s)}}]^T \in \\ C^{R_v \times D_s} \\ \mathcal{R}_v \\ \mathcal{D}_s \\ k \\ h_{\mathcal{R}_v, d_{(s,k)}} \in \\ C^{R_v} \\ \vdots \\ \vdots \\ C^{R_v} \end{bmatrix} 
                                                                                 h_{\mathcal{R}_v,d_{(s,k)}} = \beta_{\mathcal{R}_v,d_{(s,k)}}^{\frac{1}{2}} g_{\mathcal{R}_v,d_{(s,k)}},
                                                                                 g_{\mathcal{R}_v,d_{(s,k)}}\mathcal{N}(0,N_0I_{\mathcal{D}_s})
                                                                                    \beta_{\mathcal{R}_v,d_{(s,k)}} =
                                                                              diag(a_{r_{(v,1),d_{(s,k)}}}, \dots, a_{r_{(v,\mathcal{R}_v),d_{(s,k)}}})
\hat{x}_{\mathcal{R}_v} = \tilde{x}_{\mathcal{R}_v} + Q_{\mathcal{R}_v},
                          Q_{\mathcal{R}_v} =
                                                                              \begin{bmatrix} q_{r_{(v,1)}}, \dots, q_{r_{(v,R_v)}} \end{bmatrix}^T \\ q_{M_{(t,i)}} \mathcal{N}(0, \sigma_{q_{(t,i)}}^2) \end{bmatrix}
                                                                                 \tilde{x}_{\mathcal{R}_v} = \mathbf{W}_{\mathcal{R}_v, \mathcal{D}_v} \mathbf{P}_{\mathcal{D}_v}^{\frac{1}{2}} x_{\mathcal{D}_v},
                                                                              \hat{h}_{\mathcal{R}_v,d_{(s,k)}} = h_{\mathcal{R}_v,d_{(s,k)}} +
                                                                              \Delta h_{\mathcal{R}_v, d_{(s,k)}}, \\ \Delta h_{\mathcal{R}_v, d_{(s,k)}}
```

 $\Delta h_{\mathcal{R}} \to \mathcal{N}(0, \phi_{\mathcal{R}}^2)$ .