



11

$$E_{totalmax} = \sqrt{E_{syst}^2 + E_{stat}^2}$$

$E_{totalmax} = 0.0360555127546$

12



$$-r_{hor} - l_{safetyoffset} \leq y \leq r_{hor} + l_{safetyoffset} \left\{ -x_{lidar} - r_{ver} - l_{safetyoffset} \leq x \leq l_{safetyoffset} + r_{ver} - x_{lidar} \right\}$$

13



$$-r_{slowdown} - x_{lidar} < x < r_{slowdown} - x_{lidar} \left\{ -l_{sidedist} - r_{hor} \leq y \leq l_{sidedist} + r_{hor} \right\}$$

14



$$-r_{normal} - x_{lidar} < x < r_{normal} - x_{lidar} \left\{ -l_{normalsidedist} - r_{ver} \leq y \leq l_{normalsidedist} + r_{ver} \right\}$$

15



$$-r_{hor} < y < r_{hor} \left\{ -r_{ver} \leq x \leq r_{ver} \right\}$$

16



$$(-x_{lidar}, 0)$$

17



$$(0, 0.0)$$

18



$$(0, 0.08)$$

19



$$(0, 0.2)$$

20



$$(0, 0.32)$$

21



$$(0, 0.46)$$