

Polyhedral Geometry of simplex method.

"Extreme point" — notion from convex geometry.
 }

vertices — as 0-dimensional faces
 of a polyhedron.

In the context of feasible region of a problem
 in std. equation form: $\max_{\substack{m \times n \\ \text{std. eqn. form}}} C^T X$ $A \in \mathbb{R}^{m \times n}$
 $x \in \mathbb{R}^{m+n}$
 $x \geq 0$.

In any basic solution: Choose a basis $B \subseteq \{1, \dots, m+n\}$

a subset of card. m
 so that the columns of A indexed by B
 are { linearly indep. }
 { Spanning }
 { a basis of \mathbb{R}^m }
 form an invertible sq. matrix

determines nonbasic $N = \{1, \dots, m+n\} \setminus B$.

Rewrite the std. equation form:

$$(A_B \mid A_N) \begin{pmatrix} x_B \\ x_N \end{pmatrix} = b, \quad \begin{pmatrix} x_B \\ x_N \end{pmatrix} \geq 0.$$

Submatrices
 formed by
 columns indexed
 $= (B \mid N)$

$$A_B x_B + A_N x_N = b$$

$$A_B x_B = b - A_N x_N$$

"equation solving
= rewriting as
an dictionary"

$$x_B = A_{B3}^{-1}(b - A_N x_N)$$

$$\left[\begin{array}{l} x_B = A_{B3}^{-1} b - A_{B3}^{-1} A_N x_N \end{array} \right]$$

$$\max C^T x = C_{B3}^T x_B + C_N^T x_N$$

$$= C_{B3}^T \left(A_{B3}^{-1} b - A_{B3}^{-1} A_N x_N \right) + C_N^T x_N$$

... a function of x_N

$$= C_{B3}^T A_{B3}^{-1} b - \underbrace{C_{B3}^T A_{B3}^{-1} A_N x_N}_{= -(A_{B3}^{-1} A_N)^T C_{B3}} + \underbrace{C_N^T x_N}_{= (C_N - (A_{B3}^{-1} A_N)^T C_{B3})^T}$$

$$\text{Max} = \underbrace{C_{B3}^T A_{B3}^{-1} b}_{\bar{c}} + \underbrace{(C_N - (A_{B3}^{-1} A_N)^T C_{B3})^T}_{\bar{C}} x_N$$

$$\text{s.t. } x_B = \underbrace{A_{B3}^{-1} b}_{\bar{b}} - \underbrace{A_{B3}^{-1} A_N x_N}_{\bar{A}}$$

Primal dictionary in matrix form.

Take a feasible basis \mathcal{B} :
 $\bar{b} \geq 0$.

\Rightarrow The basic feasible solution (BFS) of \mathcal{B} is $x = \begin{pmatrix} x_{\mathcal{B}} \\ x_N \end{pmatrix} = \begin{pmatrix} \bar{b} \\ 0 \end{pmatrix}$.

Count inequalities that are "tight" at this point... in addition to all the equations.

\rightarrow In the dictionary, have the nonnegativity constraints:

$$x \geq 0.$$

All the nonnegativity constraints $x_j \geq 0, j \in N$ are tight at this point (BFS)

Nonnegativity constraints

$$x_i \geq 0, i \in \mathcal{B}$$

either tight or loose at this point (BFS).

If $\bar{b}_i > 0$ for all $i \in \mathcal{B}$

\rightarrow BFS is (primal) "nondegenerate"
 \rightarrow exactly $m+n$ (indep.) tight constraints
 \rightarrow BFS uniquely determined by these equations

If some $\bar{b}_i = 0$ for some $i \in \mathcal{B}$.

\rightarrow BFS is (primal) "degenerate"

"too many tight inequalities"
 \rightarrow more than $m+n$ tight constraints.
 \Rightarrow BFS is overdetermined

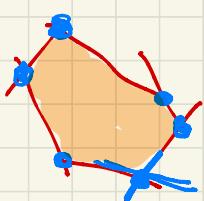
\mathbb{R}^{m+n}

forget about basic variables

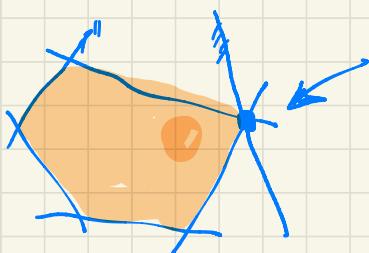
tight inequalities (≥ 0)
+ equations of the dictionary

$$\mathbb{R}^m = \mathbb{R}^{|N|}$$

If $m=2$



2 tight inequalities



overdetermined point
(3 tight inequalities
in dimension 2)

If $m > 2$, e.g., $m=3$:

4 tight
inequalities
(all non-
redundant)

Square pyramidal



3 tight inequalities.
(nondegenerate)

but the apex is overdetermined:

Any 3 of the 4 equations determining the triangular sides determine it.

⇒ only finitely many vertices



⇒ only finitely many BFS



⇒ only finitely many bases



⇒ only finitely many m -subsets of
 $\{1, \dots, m+n\}$, $\binom{m+n}{m}$.



We never see the same basis again in simplex method,
it has to terminate in finitely many steps.