

# Miltiadis Kofinas

DEEP LEARNING RESEARCH SCIENTIST

Cornelis Lelylaan 5B12, 1062HD, Amsterdam, The Netherlands

+31 (0)6 44772467 | [mkofinas@gmail.com](mailto:mkofinas@gmail.com) | [mkofinas.github.io](https://github.com/mkofinas) | [mkofinas](https://www.linkedin.com/company/mkofinas) | [mkofinas](https://www.youtube.com/channel/UCmKofinas) | [miltiadiskofinas](https://www.instagram.com/multiadiskofinas) | [MiltosKofinas](https://twitter.com/MiltosKofinas)

## Education

### PhD in Computer Science

*Amsterdam, The Netherlands*

UvA (UNIVERSITY OF AMSTERDAM)

*April 2020 - present*

- Title: Deep Future Spatio-temporal Forecasting
- Supervisor: Efstratios Gavves

### Diploma in Electrical and Computer Engineering (M.Sc. Equivalent)

*Thessaloniki, Greece*

AUTH (ARISTOTLE UNIVERSITY OF THESSALONIKI)

*Oct. 2010 - Nov. 2018*

- Specialization Field: Electronics and Computer Engineering
- GPA: 7.57/10
- ECTS: 307
- Thesis: Scene Graph Generation using Message Passing Neural Networks and Graph Convolutional Networks (see Diploma Thesis)

## Research Experience

### Scene Graph Generation using Graph Transformer Networks

*University of Amsterdam*

RESEARCH ASSISTANT · SUPERVISORS: ASSISTANT PROFESSOR EFSTRATIOS GAWVES & PROFESSOR CEES G.M. SNOEK

*Mar. 2019 - May 2019*

- Mathematical formulation of a novel abstract Graph Network layer for visual scene graph generation that explicitly utilizes both local and global information on the graph space.
- Experiments on various architectures to maximize relevant information propagation across graph vertices and edges.
- Implementation of a multilayer Graph Network that effectively stacks Graph Network layers to increase network performance.
- Use of global information via Transformer blocks that attentively gather global context.
- Introduction of a self-attentive relationship pruning network that effectively samples meaningful relationships.

### P.A.N.D.O.R.A. Robotics Team

*Aristotle University of Thessaloniki*

COMPUTER VISION & MACHINE LEARNING ENGINEER

*Oct. 2014 - Oct. 2015*

- Development of a general-purpose image classification API using RGB-D sensor data to tackle victim detection.
  - Classification using a combination of HOG features, color histogram features from different color spaces (e.g. HSV, CIELab) and SIFT features with bag-of-words models.
  - Data augmentation using affine transformations, random sampling and color jittering.
  - Training and evaluation using support-vector machines (linear and non-linear), random forests and multilayer perceptrons.
- Motion detection using Gaussian mixture-based background/foreground segmentation algorithms.
- Soft obstacle detection from RGB-D sensor data using Haar wavelets and Hough transform.
- Hard obstacle detection from RGB-D sensor data using point cloud transformations for the creation of local elevation maps and various convolutional kernels for the creation of traversability maps.
- Development of a benchmark testing API for performance evaluation of computer vision algorithms under various environmental conditions (e.g. room lighting).

## Diploma Thesis

### Scene Graph Generation using Message Passing Neural Networks and Graph Convolutional Networks

*Aristotle University of Thessaloniki*

SUPERVISORS: POSTDOCTORAL RESEARCH ASSOCIATE CHRISTOS DIOU & ASSOCIATE PROFESSOR ANASTASIOS DELOPOULOS

*May 2017- Oct. 2018*

- Image semantic content representation using scene graphs that model objects and their relationships.
- Scene graph generation using an end-to-end model that incorporates a message passing scheme, propagating contextual information between objects and their relationships to iteratively refine its predictions.
- Experiments on message propagation architectures, including a modified version of Graph Convolutional Networks.
- Introduction of a relationship pruning network that learns to identify and dismiss unlikely relationships.
- Performance evaluation on scene graph generation and other auxiliary evaluation tasks using Visual Genome dataset.

Links to thesis:

- [Greek \(Original\)](#), [English \(Translated\)](#)

## Technical Skills

<b>Programming Languages</b>	Python, C++, C, MATLAB/Octave, Java
<b>Deep Learning Frameworks</b>	PyTorch, TensorFlow
<b>Deep Learning Tools</b>	PyTorch Lightning, PyTorch Geometric, WandB, Tensorboard, Hydra
<b>Computer Vision Libraries</b>	OpenCV
<b>Robot Software Development Frameworks</b>	ROS

## Publications

---

### CONFERENCE PAPERS

- **Miltiadis Kofinas**, Boris Knyazev, Yan Zhang, Yunlu Chen, Gertjan J Burghouts, Efstratios Gavves, Cees GM Snoek, and David W Zhang. “Graph Neural Networks for Learning Equivariant Representations of Neural Networks”. In: *12th International Conference on Learning Representations (ICLR)*. 2024 ([OpenReview](#)) [[Oral](#)]
- **Miltiadis Kofinas**, Erik J Bekkers, Naveen Shankar Nagaraja, and Efstratios Gavves. “Latent Field Discovery in Interacting Dynamical Systems with Neural Fields”. In: *Advances in Neural Information Processing Systems 36 (NeurIPS)*. 2023 ([ArXiv](#)) ([OpenReview](#)) ([Github](#))
- Yongtuo Liu, Sara Magliacane, **Miltiadis Kofinas**, and Efstratios Gavves. “Graph Switching Dynamical Systems”. In: *International Conference on Machine Learning (ICML)*. 2023 ([ArXiv](#)) ([Github](#))
- **Miltiadis Kofinas**, Naveen Shankar Nagaraja, and Efstratios Gavves. “Roto-translated Local Coordinate Frames For Interacting Dynamical Systems”. In: *Advances in Neural Information Processing Systems 34 (NeurIPS)*. 2021 ([ArXiv](#)) ([OpenReview](#)) ([Github](#))

### WORKSHOP PAPERS

- Aviv Shamsian†, David W Zhang†, Aviv Navon, Yan Zhang, **Miltiadis Kofinas**, Idan Achituve, Riccardo Valperga, Gertjan Burghouts, Efstratios Gavves, Cees Snoek, Ethan Fetaya, Gal Chechik, and Haggai Maron. “Data Augmentations in Deep Weight Spaces”. In: *Workshop on Symmetry and Geometry in Neural Representations (NeurReps), NeurIPS*. 2023 ([ArXiv](#)) [[Oral](#)]
- Samuele Papa, David M. Knigge, Riccardo Valperga, Nikita Moriakov, **Miltiadis Kofinas**, Jan-jakob Sonke, and Efstratios Gavves. “Neural Modulation Fields for Conditional Cone Beam Neural Tomography”. In: *SynS and ML Workshop, International Conference on Machine Learning (ICML)*. 2023 ([ArXiv](#))
- David W Zhang, **Miltiadis Kofinas**, Yan Zhang, Yunlu Chen, Gertjan J Burghouts, and Cees GM Snoek. “Neural Networks Are Graphs! Graph Neural Networks for Equivariant Processing of Neural Networks”. In: *Workshop on Topology, Algebra, and Geometry in Machine Learning (TAG-ML), ICML*. 2023 ([OpenReview](#))
- Piyush Bagad†, Floor Eijkelboom†, Mark Fokkema†, Danilo de Goede†, Paul Hilders†, and **Miltiadis Kofinas**. “C-3PO: Towards Rotation Equivariant Feature Detection and Description”. In: *3rd Visual Inductive Priors for Data-Efficient Deep Learning Workshop*. 2022 ([OpenReview](#)) [[Oral](#)]
- **Miltiadis Kofinas**, Erik J Bekkers, Naveen Shankar Nagaraja, and Efstratios Gavves. “Neural Fields for Latent Force Field Discovery in Interacting Systems”. In: *ICLR 2023 Neural Fields across Fields Workshop*. 2023

## Teaching Experience

---

### TEACHING ASSISTANT

<b>Machine Learning I</b>	University of Amsterdam, MSc AI	2020 & 2021
<b>Deep Learning</b>	University of Amsterdam, MSc AI	2020
<b>Deep Learning II</b>	University of Amsterdam, MSc AI	2022 & 2023

### THESIS SUPERVISION

<b>Daniël (Stijn) Hamerslag</b>	University of Amsterdam, BSc AI
DRIVING ON DATA, OBJECT DETECTION IN URBAN DRIVING SCENES	Oct. 2020 - Jan. 2021
<b>Daniel Perez Jensen</b>	University of Amsterdam, MSc AI
PREDICTING RIVER FLOW IN ATACAMA REGION WATERSHEDS	Nov. 2021 - July 2022
<b>Victor Kyriakou</b>	University of Amsterdam, MSc AI
EQUIVARIANT TRAJECTORY FORECASTING WITH LATENT ORIENTATION GRAPH NETWORKS	Nov. 2022 - July 2023

## Talks

---

<b>Geometric Deep Learning Study Visit</b>	Vrije Universiteit, Amsterdam
ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS	2 June, 2022
– <a href="#">Slides</a>	
<b>Amsterdam Applied ML Meetup</b>	Hyperion Lab, Amsterdam
ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS	6 Apr, 2022
– <a href="#">Slides</a>	
<b>LoGaG: Learning on Graphs and Geometry Reading Group</b>	Virtual
ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS	1 Feb, 2022
– <a href="#">Video</a> , <a href="#">Slides</a>	

## Honors & Awards

---

### 2nd Best Autonomous Robot

P.A.N.D.O.R.A. ROBOTICS TEAM

*Robocup Rescue Competition, Hefei, China*

*July 2015*

## Languages

---

**Greek** Native Language

**English** Certificate of Proficiency in English, University of Michigan

*Level C2*

**French** Diplôme d'études en langue française B2, Centre international d'études pédagogiques (CIEP)

*Level B2*

## Academic References

---

Available upon request.