

DEEP LEARNING RESEARCH SCIENTIST

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Education

PhD in Computer Science

Amsterdam, The Netherlands

April 2020 - present

UvA (University of Amsterdam)

• Title: Deep Future Spatio-temporal Forecasting

• Supervisor: Efstratios Gavves

Diploma in Electrical and Computer Engineering (M.Sc. Equivalent)

Thessaloniki, Greece

Oct. 2010 - Nov. 2018

AUTH (ARISTOTLE UNIVERSITY OF THESSALONIKI)

- Specialization Field: Electronics and Computer Engineering
- GPA: 7.57/10
- ECTS: 307
- Thesis: Scene Graph Generation using Message Passing Neural Networks and Graph Convolutional Networks (see Diploma Thesis)

Research Experience _____

Scene Graph Generation using Graph Transformer Networks

University of Amsterdam

RESEARCH ASSISTANT · SUPERVISORS: ASSISTANT PROFESSOR EFSTRATIOS GAVVES & PROFESSOR CEES G.M. SNOEK

Mar. 2019 - May 2019

- Mathematical formulation of a novel abstract Graph Network layer for visual scene graph generation that explicitly utilizes both local and global information on the graph space.
- · Experiments on various architectures to maximize relevant information propagation across graph vertices and edges.
- · Implementation of a multilayer Graph Network that effectively stacks Graph Network layers to increase network performance.
- Use of global information via Transformer blocks that attentively gather global context.
- · Introduction of a self-attentive relationship pruning network that effectively samples meaningful relationships.

P.A.N.D.O.R.A. Robotics Team

Aristotle University of Thessaloniki

COMPUTER VISION & MACHINE LEARNING ENGINEER

Oct. 2014 - Oct. 2015

- Development of a general-purpose image classification API using RGB-D sensor data to tackle victim detection.
 - Classification using a combination of HOG features, color histogram features from different color spaces (e.g. HSV, CIELab) and SIFT features with bag-of-words models.
 - Data augmentation using affine transformations, random sampling and color jittering.
- Training and evaluation using support-vector machines (linear and non-linear), random forests and multilayer perceptrons.
- · Motion detection using Gaussian mixture-based background/foreground segmentation algorithms.
- Soft obstacle detection from RGB-D sensor data using Haar wavelets and Hough transform.
- Hard obstacle detection from RGB-D sensor data using point cloud transformations for the creation of local elevation maps and various convolutional kernels for the creation of traversability maps.
- Development of a benchmark testing API for performance evaluation of computer vision algorithms under various environmental conditions (e.g. room lighting).

Diploma Thesis _____

Scene Graph Generation using Message Passing Neural Networks and Graph Convolutional Networks

Aristotle University of Thessaloniki

Supervisors: Postdoctoral research associate Christos Diou & Associate Professor Anastasios Delopoulos

May 2017- Oct. 2018

- · Image semantic content representation using scene graphs that model objects and their relationships.
- Scene graph generation using an end-to-end model that incorporates a message passing scheme, propagating contextual information between objects and their relationships to iteratively refine its predictions.
- Experiments on message propagation architectures, including a modified version of Graph Convolutional Networks.
- Introduction of a relationship pruning network that learns to identify and dismiss unlikely relationships.
- · Performance evaluation on scene graph generation and other auxiliary evaluation tasks using Visual Genome dataset.

Links to thesis:

Greek (Original), English (Translated)

Technical Skills __

Programming Languages Python, C++, C, MATLAB/Octave, Java

Deep Learning Frameworks PyTorch, TensorFlow

Deep Learning Tools PyTorch Lightning, PyTorch Geometric, WandB, Tensorboard, Hydra

Computer Vision Libraries OpenCV **Robot Software Development Frameworks** ROS

JANUARY 24, 2024 MILTIADIS KOFINAS · CURRICULUM VITAE

Publications

CONFERENCE PAPERS

- Miltiadis Kofinas, Boris Knyazev, Yan Zhang, Yunlu Chen, Gertjan J Burghouts, Efstratios Gavves, Cees GM Snoek, and David W Zhang. "Graph Neural Networks for Learning Equivariant Representations of Neural Networks". In: 12th International Conference on Learning Representations (ICLR). 2024 (OpenReview) [Oral]
- Miltiadis Kofinas, Erik J Bekkers, Naveen Shankar Nagaraja, and Efstratios Gavves. "Latent Field Discovery in Interacting Dynamical Systems with Neural Fields". In: Advances in Neural Information Processing Systems 36 (NeurIPS). 2023 (ArXiv) (OpenReview) (Github)
- Yongtuo Liu, Sara Magliacane, Miltiadis Kofinas, and Efstratios Gavves. "Graph Switching Dynamical Systems". In: International Conference on Machine Learning (ICML). 2023 (ArXiv) (Github)
- Miltiadis Kofinas, Naveen Shankar Nagaraja, and Efstratios Gavves. "Roto-translated Local Coordinate Frames For Interacting Dynamical Systems". In: Advances in Neural Information Processing Systems 34 (NeurIPS). 2021 (ArXiv) (OpenReview) (Github)

WORKSHOP PAPERS

- Aviv Shamsian†, David W Zhang†, Aviv Navon, Yan Zhang, Miltiadis Kofinas, Idan Achituve, Riccardo Valperga, Gertjan Burghouts, Efstratios Gavves, Cees Snoek, Ethan Fetaya, Gal Chechik, and Haggai Maron. "Data Augmentations in Deep Weight Spaces". In: Workshop on Symmetry and Geometry in Neural Representations (NeurReps), NeurIPS. 2023 (ArXiv) [Oral]
- Samuele Papa, David M. Knigge, Riccardo Valperga, Nikita Moriakov, Miltiadis Kofinas, Jan-jakob Sonke, and Efstratios Gavves. "Neural Modulation Fields for Conditional Cone Beam Neural Tomography". In: SynS and ML Workshop, International Conference on Machine Learning (ICML). 2023 (ArXiv)
- David W Zhang, Miltiadis Kofinas, Yan Zhang, Yunlu Chen, Gertjan J Burghouts, and Cees GM Snoek. "Neural Networks Are Graphs! Graph Neural Networks for Equivariant Processing of Neural Networks". In: Workshop on Topology, Algebra, and Geometry in Machine Learning (TAG-ML), ICML. 2023 (OpenReview)
- Piyush Bagad†, Floor Eijkelboom†, Mark Fokkema†, Danilo de Goede†, Paul Hilders†, and Miltiadis Kofinas. "C-3PO: Towards Rotation Equivariant Feature Detection and Description". In: 3rd Visual Inductive Priors for Data-Efficient Deep Learning Workshop. 2022 (OpenReview) [Oral]
- · Miltiadis Kofinas, Erik J Bekkers, Naveen Shankar Nagaraja, and Efstratios Gavves. "Neural Fields for Latent Force Field Discovery in Interacting Systems". In: ICLR 2023 Neural Fields across Fields Workshop. 2023

Teaching Experience

TEACHING ASSISTANT

Machine Learning I University of Amsterdam, MSc Al 2020 & 2021 Deep Learning University of Amsterdam, MSc Al Deep Learning II University of Amsterdam, MSc Al 2022 & 2023

THESIS SUPERVISION

Daniël (Stijn) Hamerslag University of Amsterdam, BSc Al DRIVING ON DATA, OBJECT DETECTION IN URBAN DRIVING SCENES Oct. 2020 - Jan. 2021

Daniel Perez Jensen

University of Amsterdam, MSc Al PREDICTING RIVER FLOW IN ATACAMA REGION WATERSHEDS Nov. 2021 - July 2022

Victor Kyriakou University of Amsterdam, MSc Al

EQUIVARIANT TRAJECTORY FORECASTING WITH LATENT ORIENTATION GRAPH NETWORKS Nov. 2022 - July 2023

Talks

Learning on Graphs Conference Amsterdam Meetup

NEURAL NETWORKS ARE GRAPHS! GRAPH NEURAL NETWORKS FOR EQUIVARIANT PROCESSING OF NEURAL NETWORKS

Geometric Deep Learning Study Visit

ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS Slides

Amsterdam Applied ML Meetup

ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS - Slides

Elsevier, Amsterdam 29 November, 2023

Vrije Universiteit, Amsterdam

2 June, 2022

Hyperion Lab, Amsterdam

6 Apr, 2022

ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS

1 Feb, 2022

Video, Slides

Honors & Awards

2nd Best Autonomous Robot

Robocup Rescue Competition, Hefei, China

P.A.N.D.O.R.A. ROBOTICS TEAM

July 2015

Languages_

Greek Native Language

English Certificate of Proficiency in English, University of Michigan

Level C2

French Diplôme d'études en langue française B2, Centre international d'études pédagogiques (CIEP)

Level B2

Academic References _____

Available upon request.