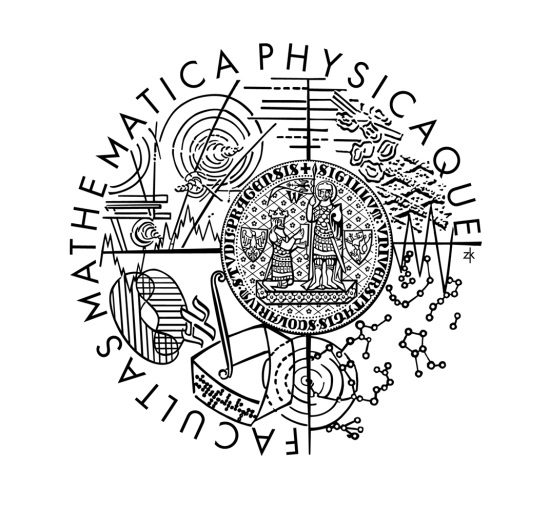
Charles University in Prague

Faculty of Mathematics and Physics

**MASTER THESIS**



Martin Koníček

**Debugger Frontent for the SharpDevelop IDE**

Department of Software Engineering

Supervisor: Mgr. Pavel Ježek

Study program: Computer science, Software systems

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I would like to thank my advisor Pavel Ježek for his time and his very helpful, constructive advice on this thesis.

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Last but not least, I thank Google for supporting students to work on interesting open source projects.

I hereby declare

Prague, Martin Koníček

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Autor: Martin Koníček

Katedra / Ústav: Department of Software Engineering

Vedoucí diplomové práce: Mgr. Pavel Ježek

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Author: Martin Koníček

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# Introduction

The ideas for this thesis are based on a desire for better debugging features in current IDEs. A vision about innovative ways of debugging, namely debugging object graphs and collections was implemented in form of new functionality for SharpDevelop – the open source IDE for .NET. This thesis first describes the motivation behind this functionality – i.e. why to build new features even though developers could live without them so far. Then, detailed analysis of the work is presented, including an overview of SharpDevelop architecture and means of integration of the work into SharpDevelop. Finally, the Implementation section describes the design and highlights interesting parts of the implementation.

## Style conventions

The following style conventions are used throughout the document:

* Text in italics denotes special terms and definitions.
* Fixed-width font is used for code and pseudocode listings and references to symbols.

## Terminology

Debugger – a program which controls execution and observes state of another program.

Debuggee – the process being debugged by the debugger.

IDE – Integrated development environment. A collection of software developments tools such as a code editor, a debugger etc.

By the term collection this thesis refers to .NET Lists, ObservableCollections, arrays, or any other IEnumerables. Similar classes exist in other environments and most ideas mentioned in this thesis would apply also to them.

## Context

This thesis is about debugging managed programs in the context of .NET environment. Therefore, whenever the text mentions classes and their instances, it refers to managed .NET instances, references etc. Likewise, the term object properties in the context of this thesis refers to standard .NET properties – i.e. a getter and/or a setter method usually with a backing field. Still, a lot of concepts and ideas described in this thesis can be directly applied to other managed environments, for example Java.

## Motivation

Debuggers and Integrated Development Environments are a very live topic in software engineering and they have seen a lot of improvement in the last years. However, current debuggers still do not solve some scenarios sufficiently – this section identifies such scenarios.

### Object graphs

Currently, most visual debuggers are similar in terms of presenting data from the debuggee (the program being debugged) to users. The most typical way of presenting such data are watches, which show variables in current scope in a tree view fashion - if an object contains references to other objects, these become its children in the tree. Debugger tooltips are a very similar feature to watches; the difference is that debugger tooltips allow users to explore values of expressions by pointing mouse cursor directly at expressions in code. This makes debugger tooltips easier to use than watches, since users do not have to look for the right variables in the watch window and switch their focus between the watch window and the code editor.

(screenshot Eclipse watch, tooltips)

But neither debugger tooltips nor watches are perfect for all scenarios – take, for instance, a structure of two objects having a reference to each other:

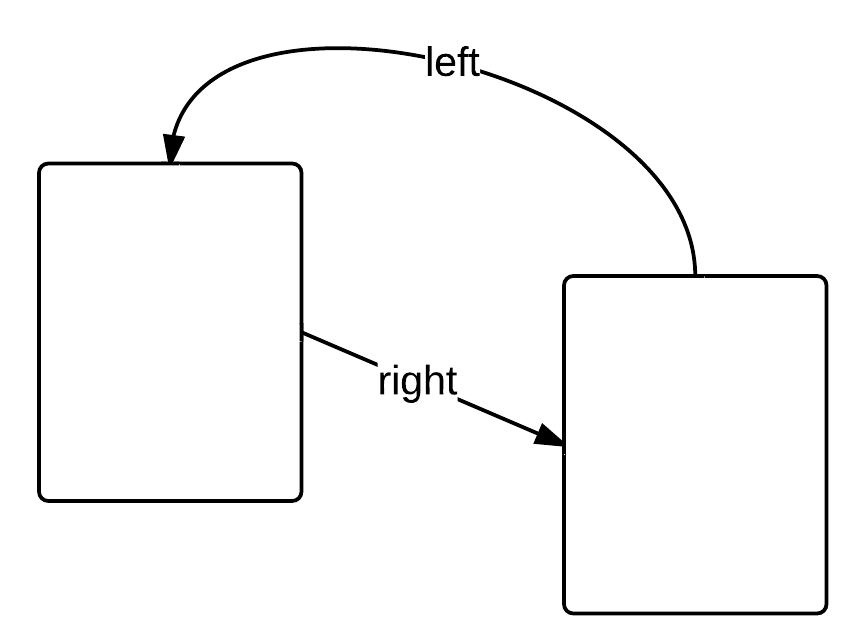


Figure – Two instances having a reference to each other

Figure 1 shows a simple data structure as usually depicted by people. However, the following figure shows how such structure is presented by watches or debugger tooltips:

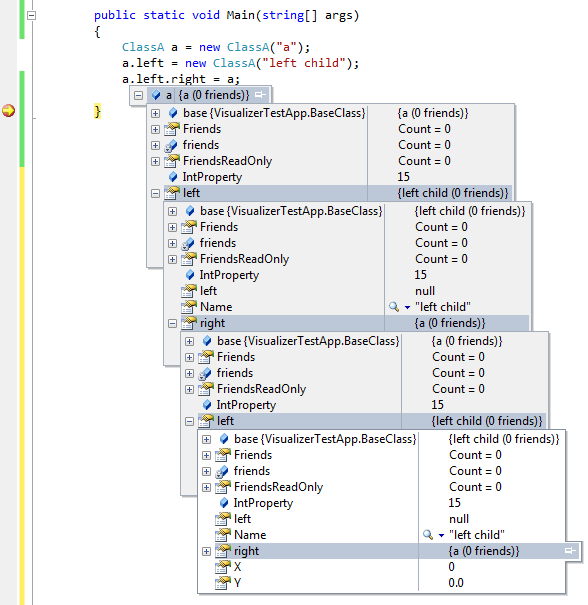


Figure – Data structure from Figure 1 presented by Debugger tooltips in Visual Studio 2010

The problem is that using current debugging tools, users have very little means of determining how the data structure actually looks in reality. In the example from Figure 2 the tooltips can be expanded infinitely.

Another problem which is not very well solved today is visualization of *changes*. If a user performs a step in the debugger how can he or she determine what changes occurred in the state of the program? Sometimes the change is easy to understand from the code, as in:

IFoo foo = **GetFooImplementation**(context);

But if the code being stepped over changes multiple variables, it is useful to see what just happened. This is solved in some IDEs by highlighting variables whose values were just changed.

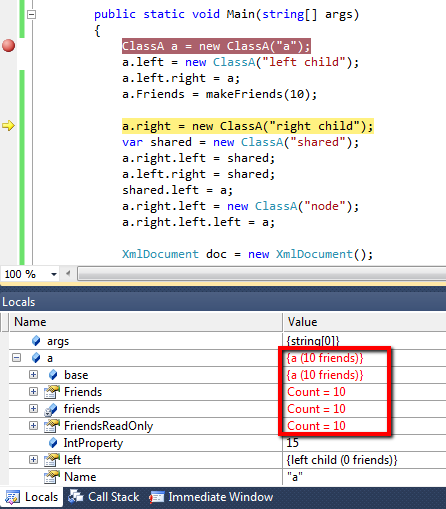


Figure – In the Visual Studio 2010 Locals window, values of variables changed by debugger step are highlighted automatically.

Unfortunately, this approach is not great for visualizing changes in data structures. What if an item was inserted into a linked list, or what if a tree rotation occurred? I realized this problem when teaching Introduction to programming to university freshmen. What I frequently observed was that there had been code on one side of the whiteboard and a drawing of a data structure on the other side. The teacher was explaining the code by pointing to the current “instruction pointer” with a finger and moving the finger from one line of the program to the next line. At the same time a student was updating the drawing of a data structure by erasing parts of it and drawing new parts, as the structure was being modified. By seeing how each statement modified the data structure the students could clearly see how the program works.

After several weeks of running this university class I had an idea – why not automate the process? The IDE could actually let users step through the code and draw and update data structures in a similar way we did in the class.

### Collections

The second issue with current debuggers are insufficient possibilities to explore and understand contents of collections of complex objects. For example, when debugging a program that works with a collection of objects of type Person, such collection is commonly visualized in the following way in current debuggers:

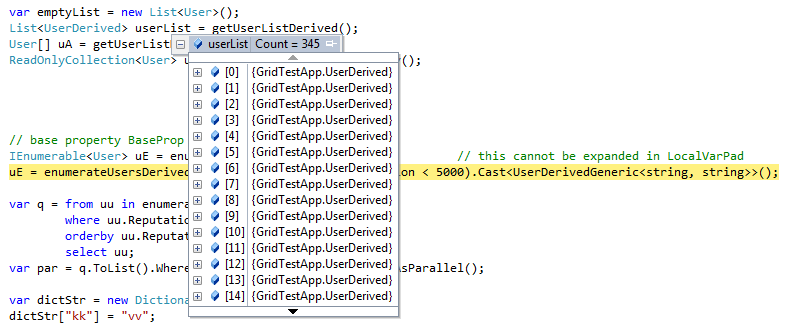


Figure – Debugger tooltip in Visual Studio 2010 showing contents of a collection of objects

The problem is that such view does not provide almost any information – there is no way to get an overview of the contents of the collection and there is also no way to quickly locate individual items based on their properties. The only possibility is to drill down the items of the collection, opening and closing them one by one, which takes a lot of time. Combined with the fact that collections are one of the most common data structures, this is a serious shortcoming of current debuggers.

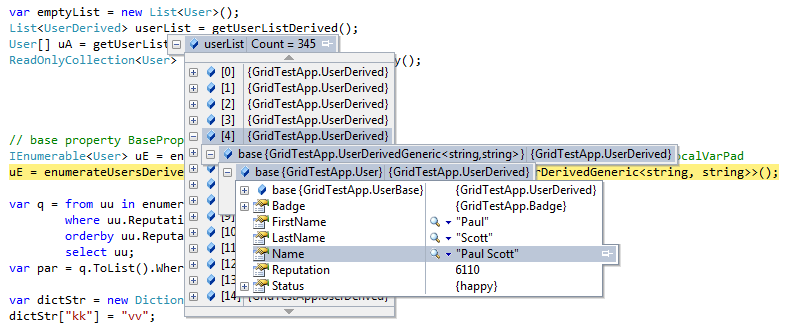


Figure – Debugger tooltip in Visual Studio with one collection item expanded. The interesting property was declared in a base class so expanding multiple times was needed to locate the desired property.

In Visual Studio, debugger support for DebuggerDisplayAttribute and DebuggerTypeProxyAttribute [1], [2] partially solves this problem but these attributes have to be included in the code being debugged and also provide only hard-wired view of individual fields or properties. SharpDevelop’s debugger currently does not support these attributes.

Apart from general issues with debugging collections, there are issues specific to SharpDevelop. SharpDevelop’s integrated debugger currently lacks support the IEnumerable type and does not support large collections efficiently (expanding contents of a large collection can block whole SharpDevelop for a long time, depending on the size of the collection).

### Debugger tooltips

Debugger tooltips are a feature similar to watches, as shown on the following screenshot:



Figure – Debugger tooltips in SharpDevelop 3

The advantage of debugger tooltips compared to watches is that users can just point a mouse cursor at anything they are interested in. They don’t have to look for variables in the watch window which typically contains more than a dozen of available variables. Debugger tooltips are a frequently used feature of Visual Studio’s integrated debugger and SharpDevelop implements them as well. However, the debugger tooltips in SharpDevelop 3 are missing two very important features: support for large collections, and support for the IEnumerable type. The importance of support for IEnumerable is very high since typical programs use IEnumerable extensively. Moreover, the UI of SharpDevelop 3 was built using Windows Forms and starting with SharpDevelop version 4.0, Windows Forms has been deprecated in and the UI of SharpDevelop has been rewritten to WPF, which means that completely new tooltips implemented in WPF are needed. This thesis covers a new implementation of debugger tooltips for SharpDevelop 4.0.

## Goals

To address the issues identified in section 1.4 (Motivation), this thesis sets the following goals:

* Provide a way for users to explore state of data structures in a debuggee in a similar way people draw data structures on a whiteboard.
* Make it possible for users to see how data structures are being changed by stepping in the debugger. The more understandable the visualization of the change, the better.
* Provide a way for users to get an overview of contents of collections of objects, in an easier, faster way than using watches and debugger tooltips.
* Add support for IEnumerable collections to SharpDevelop’s integrated debugger.
* Add efficient support for large collections (tens of thousands of items) to SharpDevelop’s integrated debugger.
* Reimplement SharpDevelop’s debugger tooltips in WPF, also adding support for IEnumerable collections and large collections.
* Make it possible to open debugger visualizers from the debugger tooltips; make the integration extensible, enabling users to implement new debugger visualizers.

## Preview

To give the reader a better overview of what this thesis is about, this section presents a short preview of some of the results of this thesis.

### Object graph visualizer

Our first addition to SharpDevelop’s integrated debugger is a visualizer of object graphs.



Figure – Object graph visualizer showing in-memory instances and references between them

While debugging, the Object graph visualizer lets users explore object graphs referenced by the variables in user code. For example, if there is an instance of a linked list in the program, the visualizer displays the linked list in a similar fashion it is commonly drawn on a whiteboard. The graph is updated live as the user steps in the debugger and the state of the data structure changes.

### Collection visualizer

The second addition to SharpDevelop’s integrated debugger is a collection visualizer – a new way to explore contents of collections of objects.

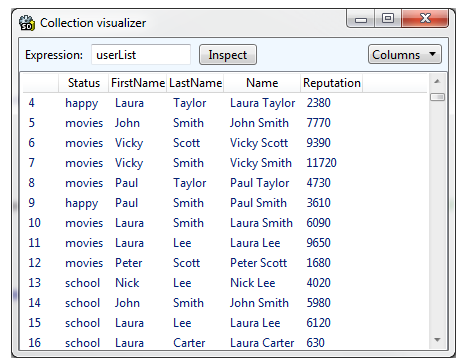


Figure – Collection visualizer showing contents of a collection of objects in the debugger

The Collection visualizer provides insight into the contents of collections of objects. The main point is that it displays properties of the collection items in a way which makes multiple properties of each item visible at once.

### Debugger tooltips

The third implemented as a part of this thesis are debugger tooltips for SharpDevelop.

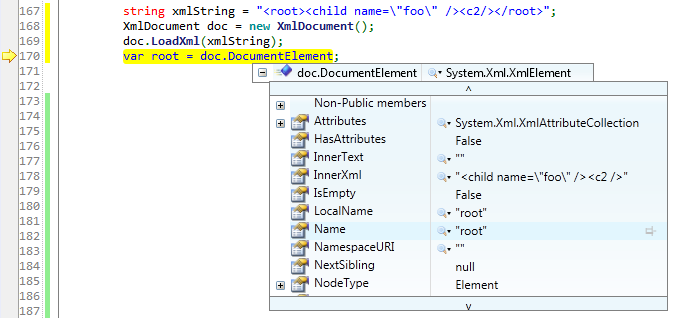


Figure – New debugger tooltips for SharpDevelop 4, with support for visualizers

Debugger tooltips are a popular feature of Visual Studio. SharpDevelop 3 has debugger tooltips but two important features were missing - support for IEnumerable collections, and support for large collections. As a part of this thesis the tooltips were reimplemented in WPF for SharpDevelop 4.0, including added support for IEnumerable collections and large collections.

## Contribution of this thesis

As a result of this thesis SharpDevelop is currently the only IDE to have the features described in the thesis and we are expecting user feedback to see how these features help users in their every-day development tasks. Some users have already provided positive feedback – for example, they expressed a need for a better Collection debugging support in their favorite IDEs.

Note that this thesis is not about implementation of a similar feature to Visual Studio’s debugger visualizers [3]. In Visual Studio, users can include custom debugger visualizers for custom types into their code and Visual Studio then offers these visualizers in its debugger tooltips. Since the approach used in Visual Studio would be too limiting for the visualizers described in this thesis, we rather implement visualizers directly in SharpDevelop and provide extensibility points for other visualizers to be added in form of SharpDevelop AddIns. Functionality similar to Visual Studio’s user defined visualizers is not supported in SharpDevelop yet but the SharpDevelop team welcomes contributors who would like to work on this (we would be glad to help with the implementation). There are also many other interesting areas to work on, for example background compilation or refactorings.

## Background

The first ideas for this thesis come from the beginning of 2009 when I was experimenting with visualizing object graphs using the Visual Studio debugger [4], thinking about improving the way people debug data structures. Then I found about the Google summer of code 2009 program. Seeing that SharpDevelop IDE was among the mentoring organizations and the team even wanted to improve their debugger, applying to SharpDevelop in Google summer of code was a no-brainer.

Google summer of code [5] is a program run by Google. Open source organizations apply to the program and Google selects the most attractive organizations to participate. Among participating organizations are such ones as Eclipse, Firefox, gcc, Haskell, Mono, Ogre3D, OpenOffice, Scala and many others. The students then apply to individual organizations with detailed proposals of their ideas. Google distributes approximately 1000 slots to the organizations, based on how popular the organization is (that is how many applications the organization received). For example, SharpDevelop had five slots in 2009. Then it is up to the mentoring organization members (that is, the long-term contributors to the open source project) to select the students they like the most. These students then work for 3 months fulltime on their projects and receive $5000 from Google, provided the mentoring organization confirms that the student did a good job. The not-so-unofficial goal of Summer of code is that students stay with the project after the summer and become contributors.

My experience with working on SharpDevelop has been very positive mainly because the SharpDevelop team is made by the best programmers I have had an opportunity to work with. They deserve a lot of respect not only for contributing their skills and free time, but also for the quality of their work. SharpDevelop is a very good source for learning about design, coding practices and technologies. Moreover, the team members are helpful and discussions with them are always effective.



Figure - SharpDevelop meeting in August 2009 in Bad Ischl, Austria. Left to right: Tomasz Tretkowski (Gsoc: C++ Backend Binding), Daniel Grunwald (Senior Developer, Architect), Martin Koníček (Gsoc: Debugger visualizers), Siegfried Pammer (Gsoc: Xaml Binding), David Srbecký (Debugger), Peter Forstmeier (SharpDevelop Reports), Christoph Wille (Project Management).

# Analysis

Having the motivation and high-level goals for the thesis set, this section provides necessary introduction to SharpDevelop IDE and debugging and provides detailed analysis of the possible ways of reaching the goals.

## Introduction to the SharpDevelop IDE

SharpDevelop [6] is a free open source IDE for .NET written almost entirely in C#. The development of SharpDevelop started in 2000 and as of April 2011 SharpDevelop supports C# 4, Visual Basic 10, F#, IronPython, Boo and C++.

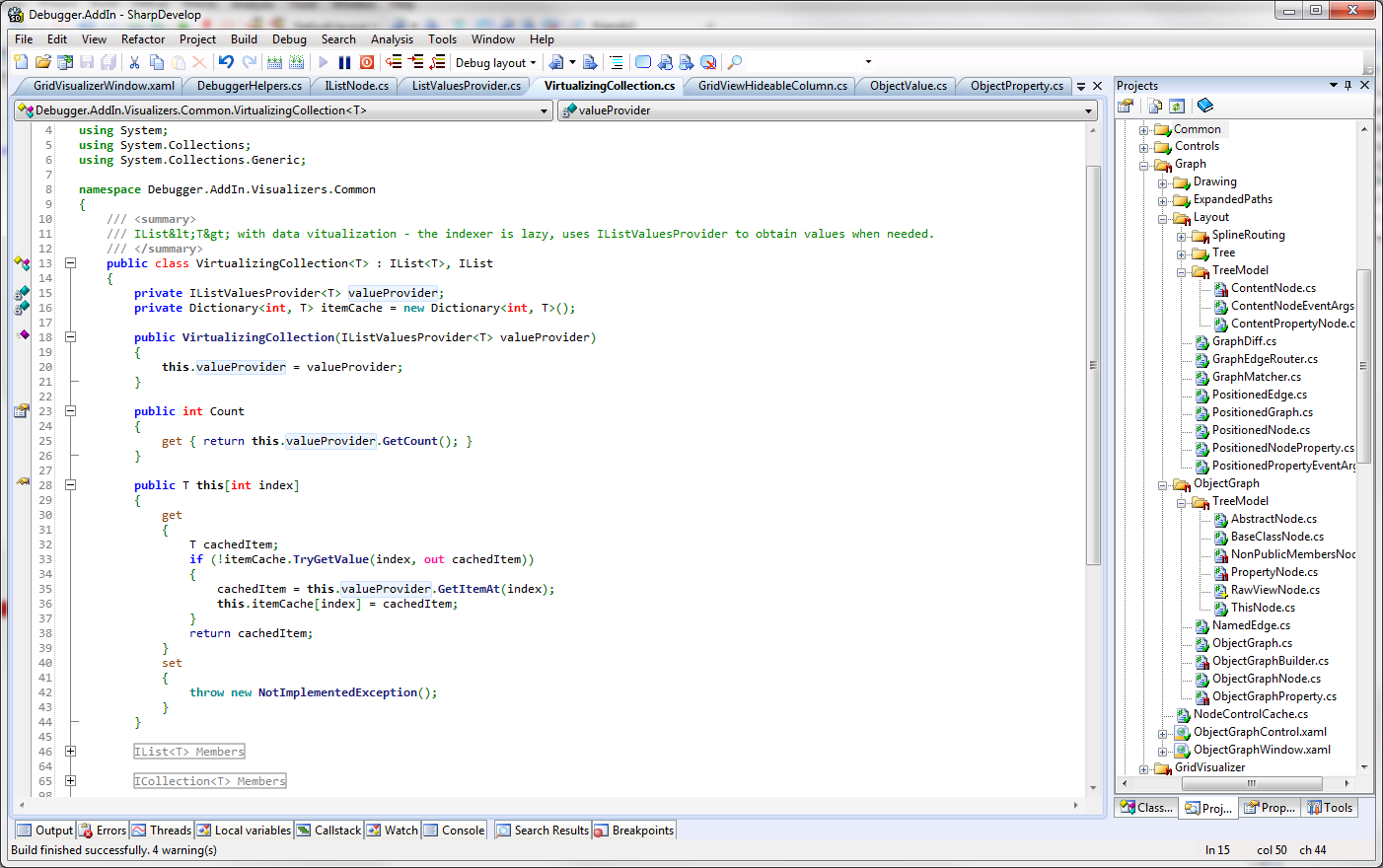


Figure – SharpDevelop IDE

The level of support for the individual languages varies. For example, F# code-completion is currently under development. Support for C# in SharpDevelop is well comparable to Visual Studio and in some areas, SharpDevelop surpasses Visual Studio. Regarding C++ support, Visual Studio definitely surpasses SharpDevelop, but C++ is not the main focus of SharpDevelop. All this information is for SharpDevelop 4.0 as of April 2011.

SharpDevelop runs on Windows (for Linux there is MonoDevelop which was forked from an early version of SharpDevelop). SharpDevelop uses .NET SDK for the build process (that is MSBuild and the compilers for individual languages). SharpDevelop 4.0 supports targeting .NET versions 2.0, 3.0, 3.5 and 4.0. SharpDevelop uses the project and solution file format of Visual Studio – therefore, it can be used side-by-side with Visual Studio.

SharpDevelop (as of April 2011) does not fully support the following functionality:

* Web application development. It is possible to build and debug an ASP.NET application using SharpDevelop [7]. However, the tooling (.aspx code completion etc.) is not implemented.
* WPF designer is work in progress.

As SharpDevelop is completely free, it makes sense to compare it to the Express version of Visual Studio. SharpDevelop has the following features which are not present in Visual Studio Express:

* Integrated profiler
* NUnit integration (with test runner in SharpDevelop)
* Subversion and Git integration out of the box
* Code coverage
* ILSpy integration (open source .NET decompiler, developed by the SharpDevelop team)
* Reports (developed as part of SharpDevelop)
* Debugger visualizers
* Productivity features (ReSharper-like context actions, navigation shortcuts, etc.) [8]
* Extensibility

Of course, there are many small differences on both sides, but the list should provide a basic overview.

The last mentioned feature, Extensibility, is important: SharpDevelop can be extended or modified in almost any way. Its API is well designed and in case there would be an extension point missing, the team is open to good contributions. Being an open source IDE written entirely in C# makes SharpDevelop a very interesting project for programmers interested in .NET who would like to learn advanced topics and have their work used by many people (SharpDevelop is currently being downloaded around two thousand times a day). SharpDevelop primary mailing list is sharpdevelop-contributors@lists.sourceforge.net.

## The architecture of SharpDevelop

This section provides a high-level look at the architecture of SharpDevelop, its extensibility model and how the Debugger visualizers fit into the picture.

### Reusable parts of SharpDevelop

Several parts of SharpDevelop are written as standalone libraries. These include:

* ICSharpCode.Core – the generic extensibility framework on which SharpDevelop is built
* NRefactory (C# and VB parser and AST)
* ICSharpCode.SharpDevelop.Dom (representation of type system)
* AvalonEdit (code editor with syntax highlighting and code completion window)
* Debugger
* Profiler
* Usage data collection (collecting data about how users interact with the application and uploading them to a server)
* Reports (reporting library)

All of these libraries are completely reusable. Most of them are integrated into SharpDevelop by AddIns which act as a “glue” to provide the functionality of the libraries in SharpDevelop. E.g. Debugger.Core is a managed debugger library and Debugger.AddIn contains user interface and SharpDevelop-specific logic. In the same fashion, AvalonEdit is a code editor with support for syntax highlighting and AvalonEdit.AddIn adds SharpDevelop-specific behavior, like split-view, context actions etc.

### ICSharpCode.Core

SharpDevelop is an application built using a generic extensibility framework called ICSharpCode.Core (further referred to as the Core). The Core provides an AddIn infrastructure, where AddIns can extend almost anything, including other AddIns. The main point of the Core is to allow users to provide extension points in their applications very easily.

The Core was developed for the purposes of SharpDevelop but it is a standalone framework on which SharpDevelop is built.

#### ICSharpCode.Core for WPF and Windows Forms applications

There are two versions of the Core: ICSharpCode.Core.WinForms and ICSharpCode.Core.Presentation, designed to be used in Windows Forms and WPF applications respectively. They both reference the assembly ICSharpCode.Core which contains all the common non-UI-specific functionality.

#### The AddIn tree

The extensibility infrastructure provided by the Core is called the AddIn tree. AddIns are defined in XML files with .addin extension. There are several standard tags, the basic one being a tag called Path which essentially enables adding extension points. In the following example three ToolBarItems are being added to the AddIn tree path called “SharpDevelop/Browser/Toolbar”:

<Path name = "/Browser/Toolbar">  
  <ToolbarItem id      = "Back"  
               icon    = "Icons.16x16.BrowserBefore"  
               tooltip = "${res:AddIns.HtmlHelp2.Back}"  
               class   = " SharpDevelop.BrowserDisplayBinding.GoBack"/>  
  <ToolbarItem id = "Separator1" type  = "Separator"/>  
  <ToolbarItem id      = "Home"  
               icon    = "Icons.16x16.BrowserHome"  
               tooltip = "${res:AddIns.HtmlHelp2.Homepage}"  
               class   = "SharpDevelop.BrowserDisplayBinding.GoHome"/>  
  [...]

Then the application built using the Core can use the following call which returns a ToolStrip object with three buttons and a separator, as defined in the .addin xml file :

var toolStrip = ToolbarService.**CreateToolStrip**(**this**, "/Browser/Toolbar");

Such functionality by itself wouldn’t be very interesting. The interesting part comes when someone else writes an AddIn for the application, specifying the following in the .addin definition file:

<Path name = "/Browser/Toolbar">  
  <Condition name="IsSolutionOpen" action="Disable">  
    <ToolbarItem id      = "SyncHelpTopic"  
                 icon    = "Icons.16x16.ArrowLeftRight"  
                 tooltip = "${res:AddIns.HtmlHelp2.SyncTOC}"  
                 class   = "HtmlHelp2.SyncTocCommand"  
                 insertafter = "Separator1"/>  
    [...]

Now, the call to ToolbarService.CreateToolStrip will return a ToolStrip with four buttons thanks to the fact that the AddIn tree combines all the AddIn definitions together. By creating the toolbar using the Core API, the host application has made its toolbar extensible. The more the host applications uses such calls, the more extensible it will be.

The second code listing also shows a standard construct called Condition. The Condition causes the ToolbarItem to be enabled only if the SolutionOpen condition evaluates to true. The Condition has custom logic implemented in a C# class, which has to be registered in the following way:

<Runtime>  
    <Import assembly=":HelpAddin">  
        <ConditionEvaluator name="IsSolutionOpen"   
 class="HelpAddin.IsSolutionOpenConditionEvaluator"/>  
[...]

In the listings one can also notice that each of ToolbarItem xml tags has a number of attributes. The attribute class determines the name of the class the toolbar button click. The insertafter attribute specifies at which position the item should be inserted. Insertafter refers to an id of another item. The final order of items is resolved from the insertafter relations by a topological sort algorithm.

So far the examples have shown two types of tags which can be inserted inside a Path in the AddInTree: Condition and ToolbarItem. These xml tags are called codons in SharpDevelop terminology. There are six types of default codons:

* Class - Creates object instances by invocating a type's parameterless constructor.
* FileFilter - Creates file filter entries for the OpenFileDialog or SaveFileDialog.
* Include - Includes one or multiple items from another location in the addin tree. You can use the attribute "item" (to include a single item) **or** the attribute "path" (to include all items from the target path).
* Icon - Used to create associations between file types and icons.
* MenuItem - Creates a menu item (WinForms on WPF depending on the version of Core used).
* ToolbarItem - Creates a toolbar item (WinForms on WPF depending on the version of Core used).

The class codon is very useful when providing extensibility not related to user interface. A typical usage is to register classes at a well-known Path, while all of these classes implement an interface provided by the host application:

<Path name="/SharpDevelop/Debugger/Visualizers">  
        <Class class="Debugger.AddIn.Visualizers.ObjectGraphVisualizer" />  
</Path>

Then the host application can obtain all the available implementations:

AddInTree.BuildItems<IVisualizer>("/SharpDevelop/Debugger/Visualizers");

Such call assumes that all the classes registered at the Path /SharpDevelop/ Debugger/Visualizers implement the IVisualizer interface.

##### Lazy loading

To improve application startup time, the parts of the AddIn tree are only loaded when needed. For example if an AddIn adds items to a menu, the AddIn assembly will not be loaded until the menu is opened for the first time.

##### Extensibility

So far, six default types of codons (Class, FileFilter, Include, Icon, MenuItem, Toolbar) were described. All the codons are actually not hardwired into the AddIn tree implementation. There is a generic mechanism of turning codons (i.e. the xml tags) into objects, and this mechanism is extensible. We will not go into details here because there is an excellent article by Daniel Grunwald [9] covering this topic and more.

#### Localization

ICSharpCode.Core provides support for localization. Localization strings are stored in standard .NET resource files with extensions denoting culture, such as “StringResources.de.resx”. The individual strings can have arbitrary identifiers but a namespace-like notation is usually used to prevent collisions. The strings are then accessible in XAML using a markup extension:

"${res: AddIns.Profiler.ProfilingView.CpuCyclesText}"

And in code using e.g.

StringParser.**Parse**("${res:AddIns.Profiler.ProfilingView.CpuCyclesText}")

In SharpDevelop itself, the resource files are being generated by a custom tool from a translation database filled by contributors using a translation website[[1]](#footnote-1).

#### Remarks

For more information about SharpDevelop.Core see [9] and [10].

### ICSharpCode.SharpDevelop

As said before, SharpDevelop is an application built using ICSharpCode.Core. The codebase of SharpDevelop itself consists of many AddIns. Even the IDE “itself” is an AddIn contained in the project ICSharpCode.SharpDevelop, with the AddIn definition file ICSharpCode.SharpDevelop.addin. The SharpDevelop AddIn contains the base of SharpDevelop UI and a part of functionality but it is not a working IDE - it rather provides interfaces to be implemented by other AddIns. For example, code editing, code completion, and debugger are all implemented as AddIns extending ICSharpCode.SharpDevelop.

### NRefactory

NRefactory is a standalone library providing object model for C# and VB code. NRefactory is important to this thesis because the debugger is using NRefactory extensively to represent expressions to be evaluated.

NRefactory contains a lexer and a parser of C# and VB languages[[2]](#footnote-2). The main use of NRefactory is parsing of source code and providing a Syntax tree of the code. There are many possible types of nodes in the syntax tree, for example ForStatement, SwitchStatement, MemberReferenceExpression, BinaryOperatorExpression etc. For example the following code snippet is parsed into the following syntax tree:

var foo = Foo.Size + 2;

tree lucidchart

The important fact to realize is that the syntax tree does not contain any semantic information – for example it is not known whether Foo is a class, a local variable, or a property.

#### Visitors

NRefactory uses the classical Visitor pattern for all operations on the syntax tree: the root of the class hierarchy, INode, defines a method AcceptVisitor and each specific type of node overrides AcceptVisitor to call a specific version – e.g. ForStatement.AcceptVisitor calls visitor.VisitForStatement(this). The logic of the tree traversal is implemented in AbstractAstVisitor from which users can derive new visitors to implement new operations, getting interesting information about the tree.[[3]](#footnote-3)

### ICSharpCode.SharpDevelop.DOM

Type system representation:

IEntity <- IClass (has members), IMember <- IMethod (which has parameters), etc. In SharpDevelop they represent both user’s types and types loaded from referenced assemblies.

IReturnType is a reference to a type. IReturnType.GetUnderlyingClass() returns the IClass this type represents. Can also be a ConstructedType, e.g. List<string> which doesn’t “exists” anywhere and then GetUnderlyingClass returns null.

Entities converted to string representation by IAmbience.

IExpressionFinder.FindExpression returns ExpressionResult: string + location + context (e.g. AttributeContext).

IResolver.Resolve takes the ExpressionResult and returns ResolveResult (e.g. TypeResolveResult which contains the resolved IClass, MemberResolveResult which contains the resolved IMember, UnknownIdentifierResolveResult, UnknownMethodResolveResult, etc).

### Future of NRefactory and DOM

Will replace NRefactory and DOM. Short explanation and link to github. Talk about Compiler as a service and the need to reimplement parsers and lexers. Mention Scala’s presentation compiler.

### Debugger

SharpDevelop’s integrated debugger consists of two components – Debugger.Core and Debugger.AddIn. Debugger.Core is a standalone debugging library for .NET and Debugger.AddIn integrates this library into SharpDevelop.

#### Debugger.AddIn

Debugger.AddIn is essentially SharpDevelop’s integrated debugger. It contains all the IDE-specific logic and user interface, including the Debugger tooltips and Debugger visualizers. Debugger.AddIn relies on Debugger.Core for most of its functionality, for example setting breakpoints, stepping, or evaluating expressions.

#### Debugger.Core

Debugger.Core is a standalone debugging library for .NET. It provides features typically present in debuggers: attaching to and controlling a user program, stepping, setting breakpoints, exploring state of the variables in the program etc. Debugger.Core uses a low-level debugging COM API provided by the .NET runtime [11]. Parts of this section build on information from David Srbecký, namely [12].

##### Architecture

Debugger.Core consists of four cleanly separated layers. Starting from the lowest layer, these layers are:

* COM API:  The low-level unmanaged debugging API of the .NET framework.  The API contains interfaces such as ICorDebug or ICorDebugManagedCallback.
* COM wrappers:  Auto-generated thin layer over the COM API which makes it a bit easier to use.  It converts 'out' parameters to return values and tracks returned COM objects so that they can be explicitly released (this is necessary so that the debugger does not lock assemblies).  The layer also contains several hand-written methods that handle marshaling of strings and other objects.
* NDebugger:  The debugging library itself.  It provides access to variables and types via reflection-like interface.  It provides commands for setting breakpoints, stepping and basically everything usually expected from a debugger.
* ExpressionEvaluator:  Extension on top of NDebugger which can evaluate C# expressions.  ExpressionEvaluator depends on SharpDevelop's NRefactory.

##### Fundamentals of debugging

The debugger can start a new debuggee process or it can attach to an existing one.  While the debuggee is running, there is not much the debugger can do.  Almost all operations are forbidden.  The debugger has to wait until the debuggee pauses - usually because user's breakpoint is hit.  Once the debuggee is paused, the debugger can investigate its state - it can look at the call stack, read local variables and so on.  Stepping or pressing "Continue" will put the debuggee into running state again. An important thing to realize is that the debugger and the debuggee are running in separate processes.

##### Sample

To demonstrate Debugger.Core in practice, let’s look at an example of its usage. Assume we have the following “Hello world” program:

class Program  
{  
    **public** static void **Main**(string[] args)  
    {  
        string message = "Hello World!";  
        System.Console.**WriteLine**(message);  
    }  
}

This program can be debugged using the following code:

NDebugger debugger = **new** **NDebugger**();  
Breakpoint breakpoint = debugger.**AddBreakpoint**("Program.cs", 6);  
breakpoint.Hit += delegate { Console.**WriteLine**("Breakpoint hit"); };  
// Start the debugee  
Process process = debugger.**Start**("HelloWorld.exe", "C:\\", **null**);  
// Waits until the breakpoint is hit if it did not  
// already happen.  
process.**WaitForPause**();  
// The breakpoint hit message should be shown now  
// Show the name of the current method on the stackframe  
Console.**WriteLine**("Current method = " + process.SelectedStackFrame.MethodInfo.FullName);  
// Get reference to the local variable  
Value localVariable =   
 process.SelectedStackFrame.**GetLocalVariableValue**("message");  
Console.**WriteLine**(string.**Format**("message = {0} (type: {1})",  
 localVariable.**AsString**(), localVariable.Type.Name));  
// Resume execution after the breakpoint  
process.**AsyncContinue**();

The program produces the following output:

Breakpoint hit  
Current method = Program.Main  
message = Hello World! (type: String)

##### Investigating state of variables

The sample code in the previous section showed that it is possible to obtain values of variables defined in the debuggee process. This section described how the process of obtaining values of variables works and what the design decision were when building this part of the debugger API.

###### Values

The sample code in the previous section (link) showed a statement for obtaining the value of a variable:

Value localVariable =   
 process.SelectedStackFrame.**GetLocalVariableValue**("message");  
Console.**WriteLine**(string.**Format**("message = {0} (type: {1})",  
 localVariable.**AsString**(), localVariable.Type.Name));

The object returned by the GetLocalVariableValue call is of type Debugger.Value. The Debugger.Value class has an AsString() method which returns a string representation of the value of the variable.

What exactly is the Debugger.Value? As said before, the debugger and the debuggee are running in separate processes. That means a Debugger.Value cannot hold a direct reference to an instance in the debuggee process (because memory spaces of individual processes are strictly separated by the operating system). Instead, some sort of interprocess communication must be used. The ICorDebug API used by the Debugger.Value class under the hood takes of this communication.

If the value in the debuggee is of primitive type like string or integer, its actual content can be requested.  However if the value is a class, we must enumerate its fields and properties and get the values for the ones that we are interested in.  We are of course free to get fields of the new values as well and drill down as much as we want to.

There is a good reason why this model is appropriate.  The debugger does not know that the user will create a field "myHelloWorldMessage" and therefore it cannot reference it.  Even if direct reference to the object in the other process was somehow available, the debugger would still have to use reflection to figure out what fields the object contains and then get their values one by one.  In fact, most of the debugger's API inherits from the abstract reflection classes (like Type, MethodInfo) so anyone familiar with reflection should have no problems using the debugger API.

###### Lifetime of Values

The .NET garbage collector (GC) presents a significant complication to the debugger.  When the debuggee is paused no code can be executed including the garbage collector so it is safe to investigate it as much and as long as we want.  However, if the debuggee is resumed even for just a few instructions, the GC might have been run and it might have moved all variables around in memory.  The GC takes care to update all references within the debuggee so that it does not even notice.  However, it unfortunately does not tell the debugger.  This means that whenever the debuggee is resumed, all debugger's Values become invalid because they might be pointing to wrong memory (Value holds a reference to the COM object identifying the value in the debuggee).  The next time the debuggee is paused, it has to obtain all values again.  This problem is more problematic than it might initially seem - getting a value of a property or calling Object.ToString() both require that the debuggee is resumed for a while so that the methods can be injected into the debuggee and executed.  Imagine that we are debugger tooltips to drill down to object "foo.bar.Person" which contains two properties - FirstName and Surname.  After we evaluate the "FirstName" property, all values will become invalid and we will have to obtain "foo.bar.Person" again just so that you we evaluate "Surname".

###### Permanent references

The ICorDebug API provides a facility to get around the problem with the lifetime of Values – it is possible to create a strong handle, which does not become invalid when the debuggee is resumed and always points to the right place in the memory where the debuggee instance resides, even after the target instance was moved by the garbage collector. This functionality is accessible using the Value.GetPermanentReference() method in Debugger.Core. In this thesis, we refer to Values returned from GetPermanentReference() as *Permanent references*.

It seems that the problem with the lifetime of Debugger.Values is solved by immediately obtaining a Permanent reference immediately when obtaining any Debugger.Value. However, the documentation states that user code should never keep many Permanent references (more than a few hundred). Therefore, the problem remains as we are allowed to create Permanent references and use them shortly but we cannot keep many of them as long as we need to.

###### Expressions

To get around the problem with Garbage collection invalidating Values, Debugger.Core provides Expressions, using NRefactory.Ast.Expression. An Expression is a tree which represents a way to obtain a Debugger.Value.

Expressions can be turned into their string representation (e.g. "foo.bar.Person“) and parsed from a string in C# format. This functionality is provided by NRefactory. Expressions can be evaluated by calling Expression.Evaluate(), producing a Debugger.Value. This is the main point of expressions in the debugger – instead of keeping a Debugger.Value and never knowing when it becomes invalid, we keep an Expression an evaluate it whenever we need its value. Indeed, this how all the UI of SharpDevelop’s integrated debugger uses Expressions: When the user has foo.bar open in a debugger tooltip and expands Person, the debugger tooltip generates an expression foo.bar.Person and then evaluates it.

At one point in the past, the Value class was designed so that it would remember the expression using which it was obtained and automatically reevaluate itself if needed.  However, this approach turned out to be quite difficult to debug since a relatively simple call could cause complicated chain of events.  The expression based approach is more explicit and thus allows better reasoning about the program - both in terms of behavior and performance.

###### Expression evaluation

Expression.Evaluate() is implemented in the ExpressionEvaluator class which acts as a visitor, traversing the syntax tree of the Expression. This design takes advantage of the fact that expression evaluation can be defined recursively:

For example, when evaluating expressions list[i+3].Name or person.Name, list[i+3] or person is evaluated first and then the field or property called Name is evaluated on the result of the evaluation. To evaluate list[i+3], i+3 is evaluated and the result is passed as a parameter to the indexer of list.

This is exactly how ExpressionEvaluator works. Methods calls are also supported (so „foo.Bar(foo).Foo“ can be evaluated).

Caching

Performance tricks

There are some clever tricks used to improve performance of the evaluation. For example, in .NET it is very common to have properties with getter methods just returning a backing field, such as (in C#).

string Name { get { return **this**.name; } }

or

string Name { get; set; }   // backing field is generated by the compiler

Exploiting the fact that getting values of fiels is much faster that using getters (which requires resuming the debuggee and waiting for result), the value of the field is returned directly when possible.

This is done by looking at IL of the getter method to see if it is a method in the form return field;. Such IL can have four different versions when generated by Microsoft’s C# compiler (depending on the property being instance/static and the backing field being explicit/generated). The pattern to recognize all four versions is the following (can be found in DebugMethodInfo.cs):

nop || nothing   
ldarg.0; ldfld || ldsfld  
 <field token>  
stloc.0; br.s; offset+00; ldloc.0 || nothing  
ret

##### The type system

The debugger can not only provide information about the values in the debuggee, but also about their types. In fact, to be able to obtain contents of a complex value (instance of a class) we must know the type of the value to be able to iterate its fields and properties and get their values one by one. This is a very common pattern used everywhere in SharpDevelop, including Debugger visualizers.

The API provided by the debugger to investigate the types in the debuggee is very easy to understand if one is familiar with Reflection. In fact, the API is exactly the same as the reflection API. The class DebugType implements the abstract class System.Type, so it has methods such as GetProperties() and GetMethods() which return System.Reflection.PropertyInfo, MethodInfo etc. They actually return debugger-specific implementations of these types but that is not a concern to the user.

Again, under the covers, the debugger uses the low level COM API provided by the .NET runtime (for example the IMetadataImport interface).

##### Multithreading

Unfortunately from the specification of the underlying ICorDebug API, all the debugger calls have to be invoked from the main thread. Evaluating multiple expressions at once would be a performance improvement for some parts of the code working with the Debugger API (including the Debugger visualizers) but it is unfortunately not possible.

##### Evaluating multiple values at once

In the code of SharpDevelop’s Debugger.AddIn, one can notice a very common pattern – the values of fields and properties

## Fundamental problem of debugging

There are several important facts to realize about debugging in general when properties are involved. The first fact is that the debugger is actually changing the state of the debuggee by observing it. This is because the only correct way to get a value of a property is to invoke its getter, and if the getter has some side effects it can change the state of the program.

Another fact to realize is that it is not always easy to correctly determine the values of all properties of an object. Take, for example, the following class:

**public** class Tricky  
{  
    **int** a;  
    **int** b;  
    **public** **int** A {   
        get    {  
            b++;  
            return a;  
        }  
    }  
    **public** **int** B {   
        get    {  
            a++;  
            return b;  
        }  
    }  
}

After creating an instance of this class, debugger tooltips in Visual Studio 2010 show an incorrect state of the instance:

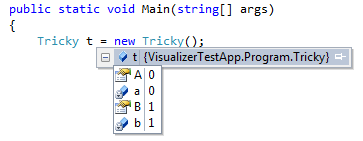


Figure – Debugger tooltip in Visual Studio 2010 showing „incorrect“ state of an instance

The state displayed in Figure 12 definitely does not correspond to reality – the debugger read both of the properties A and B so the actual values of the fields are a=1, b=1. But what are the actual values of properties A and B?

If a value of a property is defined by calling a getter of the property and reading the return value, then reading the value of A changes the value of B and vice versa, which means values of both A and B cannot be determined at the same time. The debugger could get around the problem with values of fields by first evaluating all properties and then all fields (here the evaluation was apparently done in aplhabetical order) but the debugger can never display „correct“ values for both properties A and B because such pair of values does not exist.

The problem might seem a little theoretical, but there are very practical scenarios which exhibit similar problems:

**public** class Caching  
{  
    object cachedInstance;  
          
    **public** object Instance {  
        get {  
         **if** (cachedInstance == **null**)  
                cachedInstance = **new** object();  
            return cachedInstance;  
        }  
    }  
}

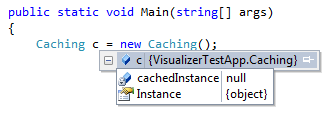


Figure – Debugger tooltip in Visual Studio 2010 showing incorrect state of an instance

The situation in Figure 13 could be solved by first evaluating properties and then fields. But what if there is another property which only reads cachedInstance? Then the value of such property would be shown incorrectly if it were evaluated before evaluating Instance. Next solution would then be evaluating all properties twice, which would incur a large performance overhead (especially concerning the expensiveness of the debugger API) and still would not solve all cases – when there are more instances shown at the same time (watch window, or multiple levels of a debugger tooltip expanded), all of them would have to be updated because a property getter could also change other instances.

Probably the only relatively reasonable solution to the problems with reading values of properties is evaluating properties first and fields after them, which would solve some common scenarios like the one in Figure 13, but such solution would have to evaluate all properties even when they would be out of view (scrolled away) which would again incur mostly unnecessary performance overhead. As seen on the screenshot, current debuggers do not try to solve these problems – the user has better understanding of the code and can reevaluate relevant parts as needed.

## Division of work

In the motivation section it was stated that this thesis aims to solve issues with the current state of debugging Object graphs and Collections and to improve SharpDevelop’s debugger tooltips in the direction of collection support. As visualizing changes in object graphs and visualizing contents of collections are distinct topics, it was decided (after a discussion with the SharpDevelop team) that there will be two new separate features in SharpDevelop – the Object graph visualizer and the Collection visualizer. The third feature are the debugger tooltips. The debugger tooltips will conceptually stay the same as they were in SharpDevelop 3, but will be re-implemented in WPF with added proper support for debugging collections. This thesis will analyze the Object graph visualizer, the Collection visualizer, and the Debugger tooltips mostly separately but it will also identify common functionality shared by these three features – such as collection support.

## Collections

From the goals set for the Collection visualizer and Debugger tooltips, it is clear that both of them will handle collections – the Debugger tooltips need support for IEnumerable collections and large collections and the Collection visualizer will handle the same types of collections as well. As for the Object graphs – the individual nodes in actual object graphs can, indeed, also be collections, therefore it would be best to support collections in the Object graph visualizer as well.

The common requirement for all of the visualizers is that large collections are supported without significant degradation in performance. In the previous version of SharpDevelop, when a collection variable was expanded in the debugger tooltips, the tooltips first obtained all of the collection items from the debugger and only then displayed first few items. Since the communication with the debugger has to be done on the main thread (as discussed in the section about the debugger), the whole IDE was blocked for up to minutes, depending on the size of the collection.

This thesis takes a lazy approach to getting items of collections from the debugger – only the first few items needed to be displayed are obtained and as the view is scrolled more items are being pulled from the debugger. This approach can be applied to all of the visualizers.

### Types of collections

The basic inheritance hierarchy of .NET collection interfaces is the following.



Figure - .NET collections inheritance hierarchy

As seen from the diagram, all the collection types in .NET framework implement IEnumerable. Also, when dealing with user-defined collection types (including enumerators implemented using the yield return construct in C#), it is safe to assume that any user type that has semantics of a collection will implement IEnumerable. Therefore by supporting IEnumerable, all possible types of collections would be supported.

However, the IEnumerable interface itself is very basic – it only enables sequential iteration over the collection, without random access. The following three sections analyze possible approaches to supporting collection types in the visualizers.

### First approach – treating all collections as IEnumerable

The starting point for all the visualizers is a Debugger.Value or NRefactory.Ast.Expression (which, when evaluated, yields a Debugger.Value). First, it must be verified that the debuggee instance represented by the Debugger.Value implements System.Collections.IEnumerable, which can be done by examining Value.Type.FullName. Then it is possible to obtain the individual Values representing the items: the method GetEnumerator() is invoked and the result is stored as a Permanent reference. Then, whenever the collection view is scrolled and more items are needed, the MoveNext() method and Current getter are invoked on the enumerator object to obtain a Value representing the next item. When MoveNext() returns false, there are no more items available.

A very important requirement in all of the visualizers is that the individual items of collections can be expanded further. To expand an item, an identification of the item is needed – either a Debugger.Value or an Expression. For Debugger.Values obtained from an enumerator, there are no corresponding Expressions – the instances returned from the enumerator can be new objects which cannot be reached through any variables in user code simply because the user code does not reference the instances. The only remaining possible identification of the Debugger.Values obtained from the enumerator are therefore the Values themselves, in form of Permanent references (because without Permanent references they would all become invalid immediately when obtaining the next item). The problem is that scrolling the view of the collection would cause more and more Permanent references to be kept and, by specification, holding many Permanent references is not allowed.

The only solution possible here would be not to hold any identification of the Debugger.Values and when an item at index i is expanded, iterate over the collection from the beginning (by obtaining a new enumerator) to the i-th item and expanding it. Such solution would not be very efficient and moreover, the item obtained by re-enumerating the collection could be a different instance from the one which is being expanded.

#### Pros

* One implementation supports all types of .NET collections.
* Supports infinite collections. It is not a problem if MoveNext() never returns false - first few items will be displayed immediately and more and more items will be obtained as needed.

#### Cons

* Expanding individual items is not really possible (only by re-enumerating the collection from the beginning).
* Fast scrolling (faster than items can be obtained from the debugger) is not possible due to the sequential nature of IEnumerable interface.
* If a collection only implements IEnumerable, the number of items (needed to display an accurate scrollbar) cannot be determined. The only possible solution would be evaluating MoveNext() and Current in loop, which is unacceptably slow. Evaluating System.Linq.Enumerable.Count(e) would count the items quickly but it cannot be guaranteed that the debuggee process references System.Core. The difference between evaluating MoveNext() in a loop and evaluating Count() is that each MoveNext() call needs an expensive interprocess debugger API call, while Count() is one debugger API call and all the work is done directly in the debuggee. Injecting a foreach loop into the debuggee to emulate missing System.Linq.Enumerable.Count() is not possible, as the debugger API only supports expressions, not statements (foreach is a statement).

#### Summary

The cons of the IEnumerable solution are significant and it can be observed that all of them are caused by the simple nature of the IEnumerable interface allowing only sequential access to the items. The problem with determining the length of the collection and fast scrolling cannot be resolved. Expanding can be solved only partially by re-enumerating the collection always from the beginning, possibly obtaining wrong instances. The Pros of this solution are outweighed greatly by its Cons.

### Second approach – special case for IList

In the .NET collection interface hierarchy there is an interface called IList which adds an indexer allowing random access to the items (the ICollection interface is not interesting in our scenario because it only adds the Count property and otherwise has exactly the same drawbacks like IEnumerable). This section explores the possibilities of dealing with collections that also implement IList. It can be verified that a Debugger.Value implements System.Collections.IList by examining Value.Type. The individual items from the IList can be obtained by invoking the indexer getter on the Debugger.Value representing the whole IList instance.

#### Pros

* Expanding individual items is not a problem: to expand an item at position i, it is sufficient to remember the Permanent reference representing the whole IList and invoke the indexer on this Permanent reference, passing i as a parameter.
* The length of the collection is immediately known by evaluating the “Count” property on the IList Value. A scrollbar of correct size can be displayed.
* There are no limitations on the speed of scrolling. If properly implemented, it will be possible to skip evaluation of items which are being scrolled over fast.

#### Cons

* Works for IList but not for IEnumerable.

#### Summary

The Pros of making a special case for IList are so significant that it is definitely worth it to support IList separately. When an instance does not implement IList and only implements IEnumerable, a fallback to the basic IEnumerable solution can be implemented.

### Third approach – converting IEnumerable to IList

There is another possible approach to IEnumerable which is not immediately obvious – having an expression e representing an IEnumerable<T>, by evaluating an Expression “new List<T>(e)“, the IEnumerable<T> gets fully enumerated directly in the debuggee (as if the debuggee itself called new List<T>(e)) and a Value representing the new List is returned. Then the visualizers can access the List items randomly and get the Count of the List, enabling expanding, accurate scrollbar, and fast scrolling. The constructor of List<T> is always available because List<T> resides in mscorlib.dll which is always loaded in any .NET process (mscorlib defines all the system types, like System.Int32 or System.String).

The solution is then to visualize ILists using the Second approach and visualize IEnumerable<T> by converting it into IList and then also using the Second approach.

#### Pros

* All the Pros of the Second approach hold not only for IList and IList<T>, but also for IEnumerable<T>.

#### Cons

* This solution cannot be applied to non-generic IEnumerable collections. Unfortunately, there is no method in .NET 2.0 mscorlib (we want to support .NET 2 programs) that accepts non-generic IEnumerable and returns an IList. Injecting a piece of code that would emulate this functionality into the debuggee is not possible using the debugger API, as the debugger API only supports expressions, not statements.
* Infinite IEnumerable<T> collections are not supported – the evaluation will timeout.

### Conclusion

From the three approaches, the last one was chosen to be used in both the visualizers and the Debugger tooltips. It has very strong Pros only at the cost of not supporting non-generic IEnumerable and infinite collections, which are both rare cases. To support these two cases, the fallback to the first approach can be implemented, but it was decided not to do so – it would mean maintaining more code only two support two uncommon cases which arguably most programmers almost never encounter (actually we had the First approach implemented but removed it for maintainability reasons – the First approach works with Debugger.Values while the Third approach enables working with Expression consistently everywhere).

Note: Experiments with Visual Studio 2008 show that its integrated debugger timeouts when expanding an infinite IEnumerable collection in a debugger tooltip. This indicates that the Visual Studio debugger is probably using an approach similar to our Third approach.

#### Expression caching

The visualizers will be getting the individual collection items by evaluating Expressions such as list[i].Name. In the section Expression evaluation, it was stated that the ExpressionEvaluator internally caches Permanent references of evaluated expressions. This means that when scrolling a view of a collection, more and more Permanent references would be held by the Expression cache. To solve this problem, after a discussion with David Srbecký a method to clear the Expression cache was added to Debugger.Core and the visualizers will call this method periodically to avoid holding many Permanent references when working with large collections.

This concludes the analysis of handling collections in the visualizers.

## Object graph visualizer

The high level idea of the Object graph visualizer is the following:

The user enters an expression to be visualized. The visualizer explores the object graph starting at this expression and presents it to the user in a similar way people draw data structures on a whiteboard. When a step in the debugger is performed, the drawing of the graph is updated using a transition from the old state to the new state. The transition should help users understand the changes that occurred during the debugger step.

### Existing work

There have been attempts to implement something similar. Probably the most significant effort so far has been the Data Display Debugger [13] which is a graphical frontent to the command line debuggers like GDB or a Python debugger pydb. Unfortunately, none of these debuggers support debugging managed .NET programs.



Figure – DiplayDataDebugger showing a graph of in-memory structures in a C program

### What needs to be done

The basic requirement for the Object graph visualizer is that an object graph for a given expression is presented to the user in a similar way people draw the object graphs on a whiteboard. Can the task be split into separate parts / steps? Yes it can, at least into these two independent steps:

1. Building the graph - given an expression, determine the vertices and edges of the graph
2. Drawing the built graph to the screen

The second step can be split into two independent steps:

* Determining the layout of the graph (that is the positions of nodes and edges on a plane)
* The actual drawing to the screen

The last required feature are Graph transitions which visualize the changes caused by steps in the debugger. This leaves us with:

1. Graph building
2. Graph layout
3. Graph drawing
4. Graph transitions

As said, the first three steps can be done independently; but what about the last step – Graph transitions? Will Graph transitions be a completely separate step or will they interact with Graph building / layout / drawing?

#### Graph transitions

To decide how Graph transitions integrate with the rest of the algorithm, one has to realize how debugger steps work. During a debugger step, a temporary breakpoint is placed at the location of the next code segment and the debuggee is resumed to run at full speed until it hits the breakpoint. When the temporary breakpoint is hit, the control is returned to the debugger.

Graph transitions should visualize the change caused by the debugger step, by moving existing nodes to their new positions, and making it clear which nodes have been added and removed. A natural idea would be to obtain some kind of a diff from the debugger describing the changes which occurred and based on this diff then produce the transition. Unfortunately, the debugger has no control over the debuggee while the debuggee is running and obtaining such state diff directly is not possible.

However, we propose that it is still possible to infer a diff based on observations of the debuggee state before and after the step. After the debugger step is finished and the control is returned to the debugger, a new Object graph is built, reflecting the current state. The instances found in this new Object graph are compared to the instances found in the old Object graph from before the step and as a result of this comparison a diff describing the changes is obtained. Using this diff a graphical transition explaining the changes can be produced.

The conclusion to this section is that Graph building, Layout and Drawing will not depend on Graph transitions. Graph transitions will use the information obtained in the Graph building phase to infer a diff between two Object graphs and produce a graphical transition from the first graph to the second one.

### Graph building

Definition: Object graph is an oriented graph, where vertices represent in-memory instances. Let vA and vB denote two vertices representing two instances A and B in the debuggee process. There is an oriented edge from vA to vB if and only if instance A has a direct reference to B (through a field or a property).

The problem: Given a reference to an instance in the debuggee, build an object graph representing all instances reachable from this instance (up to a maximum depth in case the graph is too large).

#### The algorithm

We propose the following algorithm to build an object graph given an expression e. The algorithm is quite straightforward – it does a DFS walk down the object graph in the debuggee, checking for already seen nodes. The checking for already seen nodes is done by the function GetSeenNode which is crucial because it enables detecting shared references and loops correctly. The result is a graph having the same “shape” as the object graph in the debuggee (in other words the graph built by this algorithm is isomorphic to the actual graph in the debuggee).

// evaluate the Expression e to obtain a Value              
value = **Evaluate**(e)  
// build the graph  
graph = **BuildGraph**(value)  
  
// value is a Debugger.Value representing an instance in the debuggee process  
**BuildGraph**(value):  
   If maximum recursion depth has been reached, return **null**.  
   node = create a new graph node representing this value  
   // get all instances this instance points to  
   **foreach** referencedValue **in** **GetReferencedValues**(value)       
     // do we already have a node reprenting this referenced instance?  
 existingNode = **GetSeenNode**(referencedValue)       
 // if yes, just add an edge to this node  
 **if** existingNode != **null** then **MakeEdge**(node, existingNode)  
     // otherwise continue recursively  
     **else** **MakeEdge**(node, **BuildGraph**(referencedValue))

Will this be possible to implement? The calls Evaluate and GetReferencedValues will need to access the debugger API. Both of them will be possible to implement: evaluating expressions as well as enumerating fields and properties of objects is supported. What actually makes the Object graph special is the function GetSeenNode. Without this function the algorithm would be equivalent to expanding debugger tooltips or watches recursively and wouldn’t follow the actual structure of the object graph. The main question therefore is whether and how GetSeenNode will be possible to implement.

#### Analysis of GetSeenNode

In our algorithm, the GetSeenNode function takes a reference to an instance in the debuggee (a Debugger.Value) and returns a graph node that has been already created for this instance, or null if such node doesn’t exist in the graph yet.

To be able to distinguish which Debugger.Values have been seen from those which haven’t, the algorithm will have to keep some unique identifiers of the Debugger.Values. One option would be to add some extra information directly to the instances in the debuggee, but that is not possible, as in .NET it is not possible to add fields to objects at runtime[[4]](#footnote-4). Not being able to add unique identifiers to the instances in the debuggee process means that unique identifiers have to be added to the Values living in the debugger process. Permanent references represent a possible unique identification. Expressions represent another possibility because when evaluated they also uniquely identify Values. As it will be shown, Permanent references and Expressions are mostly interchangeable for the purposes of building the Object graph.

A first solution using Expressions follows. The algorithm works with Expressions and keeps an Expression for every node in the graph. GetReferencedExpressions creates Expressions by appending all field and property names to given Expression, based on the actual type of the Expression (the Type is determined by evaluating the Expression). For example, by appending property name FooProp to object foo.bar we get an expression foo.bar.FooProp.

**BuildGraph**(expression):  
  If maximum recursion depth has been reached, return **null**.  
  node = create a new graph node representing this expression  
  **foreach** referencedExpression **in** **GetReferencedExpressions**(expression)       
    existingNode = **GetSeenNode**(referencedExpression)      
    **if** existingNode != **null** then **MakeEdge**(node, existingNode)  
    **else** **MakeEdge**(node, **BuildGraph**(referencedExpression))

In order to determine whether an Expression identifies an already seen instance, GetSeenNode queries the debugger to compare the Expression to all of the seen Expressions (by evaluating Expressions such as foo.bar.Name == e, where e is replaced by all the expressions seen so far, such as foo.bar etc.). This works because an expression a==b evaluates to true if an only if expressions *a* and *b* refer to the same instance in the debuggee, because evaluating an expression a == b is equivalent to executing a == b in the debuggee[[5]](#footnote-5). Pseudocode for GetSeenNode follows:

**GetSeenNode**(Expression exprToTest)  
**foreach** node **in** graphNodesSoFar  
    **if** **Evaluate**(**BinaryOpExpression**(op.Equals, node.Expression, exprToTest))  
      return node  
return **null**

As can be seen from the pseudocode, every call of GetSeenNode has to perform many Evaluate calls, which is the most significant problem of this algorithm because GetSeenNode will be called once per edge and it needs do up to n Evaluate calls, the total number of Evaluate calls in O(n.E) where n is the size of the resulting graph and E is the number of edges in the graph. We implemented this algorithm and found it to be too slow. Even though the graphs to visualize will usually not be very large, the Evaluate calls are unfortunately so expensive that this algorithm is unacceptable.

The algorithm using Permanent references would be exactly the same, including the needed calls to the debugger in a loop, expect it would work with Permanent references. Permanent references provide instance addresses (offsets in the memory space of the debuggee) but these are not usable as they can be changed by the garbage collector which moves the instances around during the run of the graph building algorithm when the debuggee is being resumed and paused again. Therefore, addresses cannot be used as unique instance identifiers and the only way to use Permanent references is the same way as using Expressions.

The conclusion is that the main problem with identifying debuggee instances by Expressions or Permanent references is that GetSeenNode has to compare all the unique identifiers one by one by querying the debugger. The best solution to this problem would be some different form of unique identification of instances in the debuggee such that GetSeenNode could run faster than in O(n), ideally in O(1) in average case.

##### .NET hash codes

Could standard .NET hash codes serve as unique identifiers in the Object graph building algorithm?

In CLR, the runtime representation of every instance has a data member which stores the hash code for the instance. This data member is assigned by the CLR and it is accessible from managed code through RuntimeHelpers.GetHashCode(Object) method which returns the same value as the default Object.GetHashCode(). While Object.GetHashCode() can be overridden to define equality semantics for structures and classes, RuntimeHelpers.GetHashCode(Object) always returns the original hash code assigned by the runtime. In the Object graph visualizer we are interested in instance equality to display actual state of objects in memory, not user defined equality. Therefore the default hash codes (accessible through RuntimeHelpers.GetHashCode) will be used. The default hash codes have a good property that they never change during the lifetime of an instance and, being integers, they can be used as keys for a hash table.

However, there is no guarantee that the hash codes will be unique – there is no guarantee that two different instances will have different hash codes. The “theoretical” reason behind this is that the hash code is a 32-bit integer (on a 32-bit system), hence the space of all hash codes is limited and it can be guaranteed that sooner or later two different objects with the same hash code will be encountered. There is, however, one very practical reason. One could think that 32-bit space is large enough and in practice different instances with same hash codes would almost never be encountered in a given small object graph. However, our tests on CLR (Microsoft’s implementation of CLI) are quite surprising. The following code generates new objects until two different objects with same hash code are encountered. It turns out that such case occurs very quickly, after creating as few a few thousand instances:

Hashtable hashCodesSeen = **new** **Hashtable**();    
LinkedList<object> l = **new** LinkedList<object>();    
**int** n = 0;  
**while** (**true**)    
{    
    object o = **new** object();    
    // remember instances to be sure they don't get collected  
    l.**AddFirst**(o);    
    **int** hashCode = o.**GetHashCode**();    
    n++;    
    **if** (hashCodesSeen.**ContainsKey**(hashCode))    
    {    
        // same hashCode seen twice for DIFFERENT instances  
        Console.**WriteLine**("Hashcode seen twice after „ + n + „steps“);    
        break;    
    }    
    hashCodesSeen.**Add**(hashCode, **null**);    
}

During our tests, the output of the program was Hashcode seen twice after 5322 steps, which means that the possibility of different objects having same hash codes is very real and must definitely be accounted for. The article [14], which was the original source for this experiment, gives very similar results.

Interestingly, during our tests, the output was always the same on a given machine. This shows that the hash code generation on the current implementation of the CLR is deterministic.

#### The final algorithm

The final Object graph building algorithm takes advantage of the .NET hash codes while correctly accounting for different instances having same hash codes. This is done by looking up graph Nodes by hash codes and comparing instance addresses[[6]](#footnote-6) in case of hash code collisions to be sure the hash code collision was not a coincidence. The main BuildGraph algorithm stays almost the same as in the first version, with the exception that graph Nodes are being added into a hashcode->Nodes hashtable. Ideally, when there are no hash code collisions, the hashtable will contain exactly one Node for every hash code.

hashtable: 'hashCode' -> (list of objects with hash code == 'hashCode')  
  
**BuildGraph**(**value**):  
   If a maximum recursion depth is reached, return **null**.  
   **node** = create a Node for this value (holding a Permanent reference)  
   add the **node** to the hashtable,  
 key=value.**HashCode**  // HashCode being the in-debuggee hash code

**foreach** referencedValue **in** **GetReferencedValues**(**value**)       
     existingNode = **GetSeenNode**(referencedValue)       
     **if** existingNode != **null** then **MakeEdge**(**node**, existingNode)  
     **else** **MakeEdge**(node, **BuildGraph**(referencedValue))

GetSeenNode then takes the advantage of the hashtable in the following way:

**GetSeenNode**(**value**) {  
    candidates = hashtable[**value**.HashCode] // instances with same hashCode  
    **if** no candidates, the object is new  
    **if** some candidates, compare their addresses to o.Address  
     **if** no address **equal**, o is new// hashCode collision was a coincidence  
       **if** some address equal, o already seen

GetSeenNode only works with addresses of Permanent references, which is safe because getting addresses of Debugger.Values does not resume the debuggee and therefore the addresses are guaranteed to be fixed during the execution of GetSeenNode.

Note: As said in the section .NET hash codes, the algorithm always obtains hash codes by invoking RuntimeHelpers.GetHashCode() in the debuggee. If the algorithm instead used Object.GetHashCode() and user code would override GetHashCode to always return zero (for example), the algorithm would still work. The whole algorithm would, however, run in O(n.E) (n being the number of vertices and E being the number of edges in the object graph) – the same as the original slow algorithm.

#### Expanding nodes

The graph building algorithm as described can be considered finished. It handles very large (up to infinite) graphs by limiting the maximum depth of recursion.

There is, however, one user experience aspect that deserves analysis - when the user enters an expression which evaluates to a very large object graph expanding the whole graph up to some maximum depth would be a bad user experience:

* If the maximum depth is small, nodes the user is actually interested in can be missing from the graph.
* If the maximum depth is large, too many nodes are shown while the user is not interested in most of them; the drawing is confusing. Visualization takes too much time to show nodes that are not needed.

Instead of always traversing the whole graph, a solution is proposed where users can choose which nodes to include in the graph by expanding them manually. The algorithm stays essentially the same but it is split into steps determined by user actions. The body of the Expand function called when a Node is being expanded is the same as the body of the original loop iterating over all Node properties.

// a property is being expanded on this node  
**Expand**(node, propertyName)          
    // get the value of the property being expande  
    targetValue = **EvaluateProperty**(node, propertyName)     
    // and add the value to the graph  
 // (either an edge to an existing node, or a new node)  
    existingNode = **GetSeenNode**(targetValue)  
    **if** existingNode != **null** then **MakeEdge**(node, existingNode)  
    **else** **MakeEdge**(node, **NewNode**(targetValue))  
}

The algorithm does not recalculate the whole Object graph on every Expand action it assumes that property getters don’t have any side effects on the rest of the graph, which is a reasonable tradeoff between graph correctness and expand performance. Having property getters modify other properties is rarely done in practice – the only reasonable use case is when a property getter caches a value in a field or a data structure. Such scenario would be solved by reevaluating all the properties of the instance instead of evaluating a single property. In principle, property getters could modify also anything in the any other instances of the graph, but that would a very bad programming practice and it is practically never done, therefore it was decided not to make the general case much slower in order to account for a theoretical edge case. After the graph is rebuilt completely (either when requested by user or after a debugger step) the graph is in correct state. See also the section 2.3 (Fundamental problem of debugging) for more general discussion on the problems with determining debuggee state.

Of course, apart from Expanding, there will be also a Collapse feature, which consists of removing the target Node and all its inbound and outbound edges from the graph.

### Graph layout

Having the Object graph (that is, a graph inside the debugger isomorphic to the actual graph in the debuggee) built, this section focuses on how to position the vertices and edges of the Object graph on a 2D plane so that it looks *natural* to users.

#### Dynamic graphs and incremental stability

There is one special requirement to the Graph layout – the Object graph visualizer deals with dynamic graphs, which directly relates to the Graph transitions feature.

There is a problem with calculating layout for dynamic graphs – if the layout algorithm does not account for graph dynamicity, a small change to the graph can cause drastic changes to the layout. Say for example that one node or edge is added to the graph and most nodes are rearranged completely in the new layout. In other words, such layout is incrementally unstable. In our scenario, incremental instability would mean large groups of nodes moving around randomly when a debugger step introduces only small changes to the graph, which would certainly mean bad user experience. The solution should therefore aim for incremental stability of the layout.

#### Existing layout engines

Graph layout is a not a new problem so naturally, existing solutions were researched. A good comprehensive list of graph layout engines can be found at [15]. The list does not include Dynagraph, which was also considered. As SharpDevelop is LGPL-licensed free software, any commercial solutions were out of question. Apart from being free, any code included in SharpDevelop must come from a live, maintained project.

Most of the layout engines also handle rendering of graphs. However, the Object graph visualizer has a special requirement for graph transitions, where existing nodes move to their new positions after the graph is changed. The visualizer needs to control these transitions and to be able to do so, the information about the positions of individual nodes is needed – if the layout engine acts as a black box producing images, it might be well usable in some scenarios but not for the Object graph visualizer.

Out of all the existing layout engines, only Graphviz and Dynagraph were considered an analyzed in detail. All the other layout engines were ruled out quickly – the reasons are summarized in the following table.

|  |  |  |  |
| --- | --- | --- | --- |
| **Layout engine** | **free** | **maintained** | **suitable** |
| Graphviz |  |  |  |
| MAGL | x |  |  |
| ILOG Diagram for .NET | x |  |  |
| Dynagraph |  | x |  |
| Diagram.NET |  | x |  |
| Omnigator |  | x |  |
| Pajek |  | x |  |
| Piccolo |  | x |  |
| Flare |  |  | x (Flash) |
| UbiGraph |  |  | x (client-server) |
| aiSee |  |  | x (low quality output) |
| Graph# |  |  | x (did not exist at the time of our research) |
| Circos |  |  | x (only circular layouts) |
| Cytoscape |  |  | x (standalone app, not a library) |
| Treemaps |  |  | x (Java) |
| QuickGraph |  |  | x (graph algorithm library, does not deal with graph layout) |
| NodeXL |  |  | x (implemented in Excel) |

Table –Graph layout engines considered during our research

##### Dynagraph

Dynagraph [16] is an incremental layout engine based on the code of Graphviz. Being an incremental layout engine means that it is actually designed to work with dynamic, incrementally changing graphs. Dynagraph is a standalone executable with an API which works by writing text commands to standard input and parsing responses from standard output (there is also a partial, undocumented COM interface).

###### Pros

Dynagraph is the only layout engine dealing with incremental layouts by accepting commands such as “add edges between nodes A and B” and responding in the terms of “node B moved down by 2cm, added edge A->B as a straight line” [17].

###### Cons

Dynagraph is an unmaintained library (last update from 2007), which makes it unfortunately not suitable for being used in SharpDevelop.

##### Graphviz

Graphviz [18] is a mature, widely used graph layout and visualization toolkit running on Linux and Windows. Graphviz consists of set of executables (dot, neato, etc.) where each of these implements one particular layout algorithm. All of the executables act as batches accepting command line parameters and standard input and returning results (text, image) using standard output or writing to a file.

Graphviz provides ways for users to control the layout to some degree using node clusters, explicitly specified edge endpoints etc. The following graph, which looks almost exactly like what the Object graph visualizer should look like, was rendered using Graphviz:



Figure – A graph rendered using Graphviz

###### Pros

The output of dot layout algorithm (Figure 16) seems suitable to the needs of the Object graph visualizer.

Graphviz separates layout calculation from rendering: a graph (plain vertices and edges) can be passed to Graphviz and the same graph with added position information is returned. There are several formats in which the result can be returned, configurable using command line switches.

Graphviz is fast – for the purposes of the Object graph visualizer where the graphs are not very large (up to 20 nodes and 60 edges), the time needed to calculate graph layout including launching the dot executable was under 200ms on a modest machine[[7]](#footnote-7).

###### Cons

As Graphviz does not have any notion of dynamic graphs, its layouts can suffer from incremental instability – when a graph is slightly changed by a debugger step and the layout is recalculated, the layout can differ a lot visually from the previous layout. Graphviz does not provide any option to calculate new layout incrementally based on old layout and a graph diff.

Including Graphviz binaries would add 10MB to the size of SharpDevelop installer, while the whole SharpDevelop setup is currently only 15MB. The problem is that the Graphviz executables statically link a lot of other libraries and even when dot.exe or neato.exe are given parameters specifying text-only input and output, these executables won’t start without libraries for image encoding. This point alone is enough to say no to Graphviz because adding 10MB of binaries to SharpDevelop to support a single feature is unacceptable. The solution would be either to modify Graphviz code or ask users to install Graphviz.

Graphviz API is text based – using Graphviz from an application means launching a separate executable, writing graph specification to the standard input, and parsing response from the standard output, which is not trivial. If a rendering of the graph is needed, Graphviz can write the output to a file and the host application can then read the image file.

#### Conclusion – Tree layout algorithm

The conclusion of our research of existing graph layout engines is that no existing solution fits the scenario of the Object graph visualizer for SharpDevelop and therefore a new solution will be implemented.

One option is to design an incremental layout algorithm which takes an existing layout and a graph diff as input and produces a new layout, trying to make only small changes to the layout when the diff is small. When designing such algorithm, methods used in Dynagraph would be studied as a starting point.

Another option is a solution which does not deal with graph diffs at all. We propose that it is possible to design a graph layout algorithm, specialized for dealing with object graphs (graphs of data structures), which has no notion of incremental layout but still produces layouts that behave well in terms of incremetal stability. The idea for the algorithm comes from two intial observations: first, object graphs are very often close to trees (the numbers of edges is not much larger than n-1, where n is the number of nodes), and second, the edges in object graphs have a special meaning – the edges represent named object fields and properties.

The algorithm is the following: when the input graph is a tree, layout it using a standard tree layout algorithm: Place the root to the top, order the child subtrees by names of properties they represent and place the child subtrees next to each other below the root. Example:

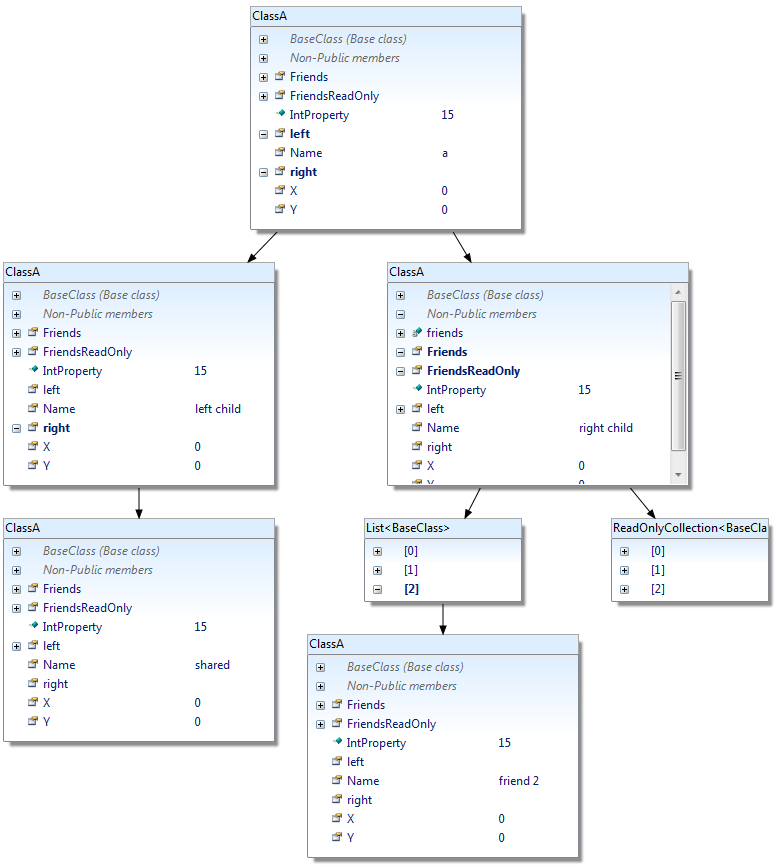


Figure – Example of a tree layout

A preudocode of the standard tree layout algorith follows. The algorithm is done in two recursive passes over the tree, which we call Measure and Arrange:

First pass: measure

**Measure**(node):  
    **foreach** child **in** node.Children  
        **Measure**(child)  
    subtreeW = node.Children.**Sum**(n => n.Width)  
    node.treeW = **max**(node.ownW, subtreeW);

Second pass: arrange

**Arrange**(node, position)      
    subtreeW = node.Children.**Sum**(n => n.treeW)  
    node.Pos = **CenterHorizontally**(position, node.ownW, subtreeW)   
    currentChildPos = position  
    **foreach** child **in** node.Children  
        **Arrange**(node, currentChildPos)  
        // place next child subtree next to this child subtree  
        currentChildPos.X += child.treeW

The important case is when the input graph is not a tree. In such case, select some subset of n-1 edges to obtain a tree, layout it using the tree layout algorithm, fix the layout, and then add the remaining edges to the layout. Example:

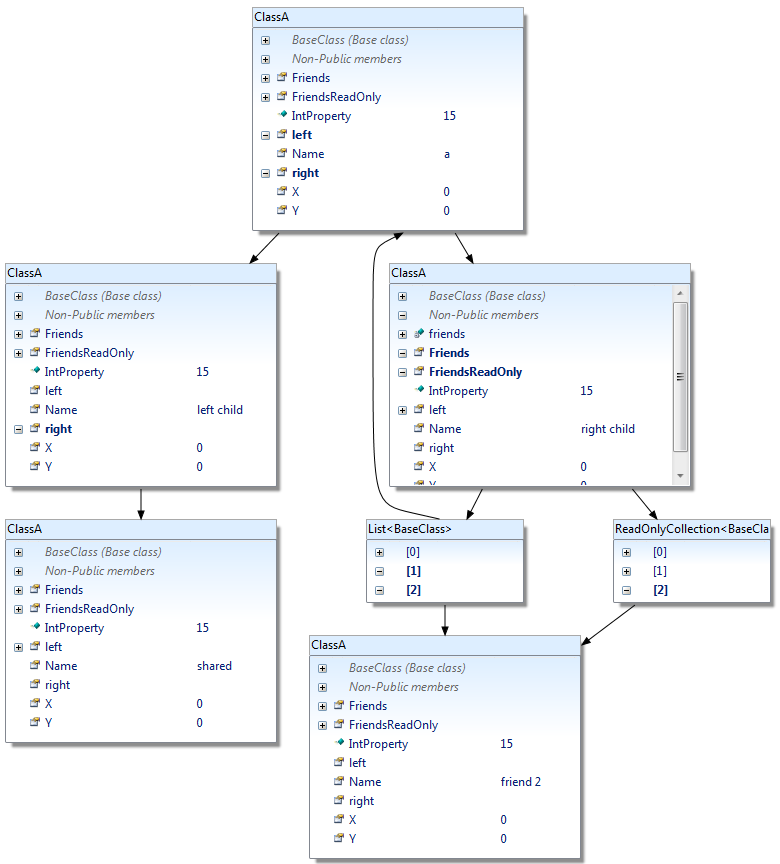


Figure – Example of a tree layout when the input graph is not a tree. The graph is the graph from Figure 17 with two edges added.

The only thing remaining to be resolved is how to select the subset of the n-1 edges when the graph is not a tree.

##### Selecting tree edges

One possible approach is to start in the root of the graph and do a standard DFS[[8]](#footnote-8). The edges traversed by the DFS are declared tree edges. Because the DFS enters and leaves every node exactly once, the subgraph formed by the selected edges will indeed be a tree. Pseudocode follows: in the beginning, Traverse(root) is called which traverses the whole graph and marks n-1 edges as tree edges. There is a helper structure called nodeAlreadySeen used to mark visited nodes.

**Traverse**(node):  
    nodeAlreadySeen[node] = **true**  
    **foreach** edge **in** node.OutgoingEdges  
    **if** not nodeAlreadySeen[edge.target]  
        edge.IsTreeEdge = **true**  
        **Traverse**(edge.target)

This approach works, but unfortunately does not behave well in terms of incremental stability – here is an example:

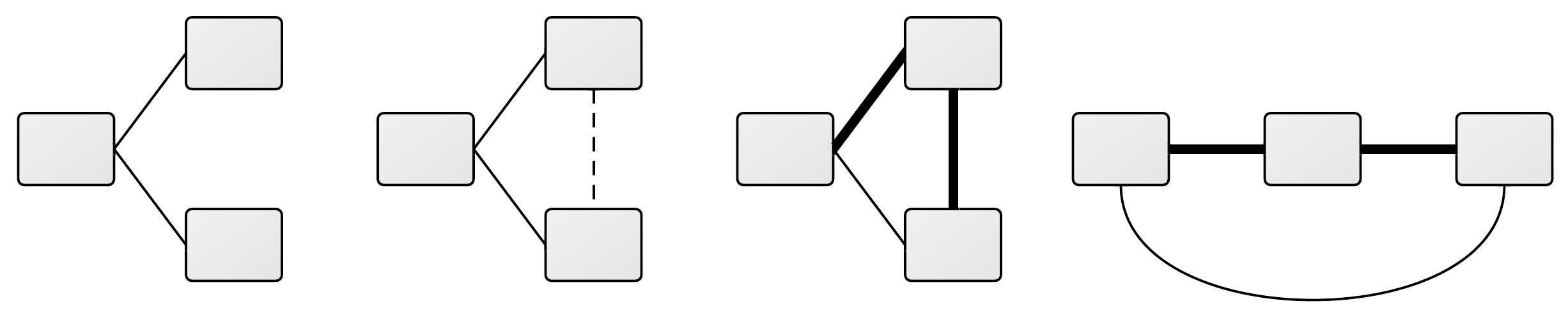


Figure – From left to right: an edge is being added to a tree, tree edges are selected using DFS, and new Tree layout is calculated based on the selected tree edges.

The problem is that when a node has multiple possible parents, DFS selects one of the parents quite arbitrarily – the paths in the graph are traversed in alphabetical order, given by the names of edges. This problem can be resolved by replacing DFS by BFS[[9]](#footnote-9) (using a queue instead of a stack to traverse the graph) because BFS selects the parent based on the distance from the root. BFS prefers short paths, not arbitrary paths. For comparison, here is the exact same situation as in Figure 19, now using BFS to select the tree edges:

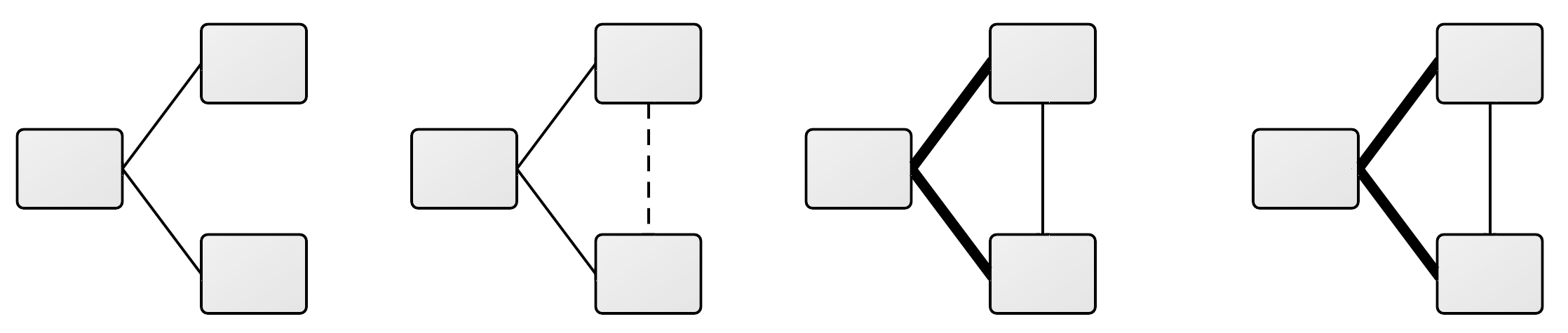


Figure – The same situation as in Figure 19, but different set of tree edges is selected using BFS, resulting in much more intuitive behavior.

There is no strict proof that the layout generated by the tree layout algorithm using BFS for edge selection is incrementally stable because there is no strict definition of “small change of the layout proportional to the change of the object graph”. However, our tests show that in practice this is a good algorithm when dealing with incrementally changing data structures. This specific version of the tree layout algorithm also has a good property of fixed alphabetical ordering of outgoing references which is a familiar concept to users.

##### Edge routing

In the layout, not all edges are drawn as straight lines. When an edge drawn as straight line between two nodes would cross other nodes, it is routed as a curved line avoiding the nodes. Calculating the curved paths for edges is called edge routing. Graphviz provides a good edge routing algorithm but again, including 10MB of binaries into SharpDevelop is unacceptable and moreover the communication with Graphviz is done via standard input and output so a parser of edge routes returned from Graphviz would have to be implemented. We decided to implement an edge routing algorithm ourselves – the details are provided in the Implementation section.

### Graph transitions

In the previous section a layout algorithm was presented which is sufficiently incrementally stable even while not accounting for incremental graph updates explicitly. This section discusses how to produce smooth transitions between two layouts of two object graphs, visually explaining changes caused by a debugger step.

The transitions should move existing nodes from the old layout to their new positions in the new layout and visually indicate which nodes were added and removed. To be able to produce such transition it must be known which nodes from the old layout and the new layout represent the same debuggee instances, which nodes were added and which nodes were removed. We call this information a graph diff and the process of producing a graph diff is called graph matching.

To realize the matching, hash codes, Permanent references and addresses can be used, in a similar way to how they are used in Graph building. For every node in the old and the new graph, a Permanent reference and a hash code of the debuggee instance is stored. Then for every node in the new graph a matching node in the old graph can be found quickly using the stored hash code and comparing instance addresses to make sure the hash code equality was not a coincidence (like in the Object graph building algorithm). Pseudocode follows:

**FindMatchingNodeInOldGraph**(Node nodeInNewGraph):  
    find a node **in** the old graph by nodeInNewGraph.hashCode  
    **if** found, compare found.PermRef.Address and nodeInNewGraph.PermRef.Address  
    **if** the addresses are the equal, return the found node

This algorithms works because the hash codes of instances never change during their lifetime (using RuntimeHelpers.GetHashCode). The nodes from the new graph without matching nodes are marked added. The nodes from the old graph without matching nodes are marked removed. The graph diff then consists of a list of pairs of matching nodes, a list of removed nodes, and a list of added nodes. Given such diff and two graph layouts, a transition can be produced in the following way: fade out removed nodes, fade in added nodes and move matched nodes from their old positions to their new positions. The same technique can be applied to edges: edges connecting matched nodes are moved to their new positions, all the remaining edges from the old layout are faded out and the edges from the new layout are faded in.

## Collection Visualizer

The Collection visualizer should provide a new way to explore collections of objects in the debugger. It should help users understand contents of collections more easily than watches or debugger tooltips. The following solution is proposed: Display a grid where rows represent individual items of the collection and columns represent properties of individual items.

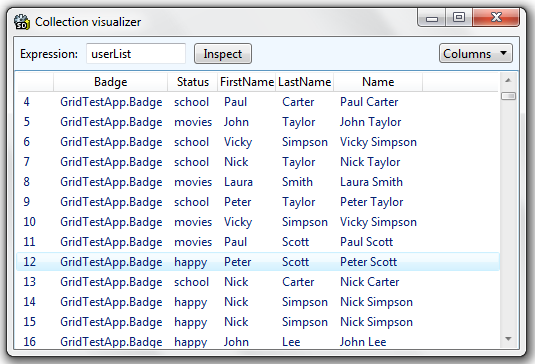


Figure – The Collection visualizer – rows represent collection items and each column represents one public property.

This advantage of this approach is that users get a good overview of the contents of the collection and can locate individual items quickly. Compare this to using watches or debugger tooltips, where individual items have to be expanded and collapsed one by one to accomplish the same goal.

The Collection visualizer will use the same approach to accessing individual items of collections described in the section 2.5 (Collections) – a special case for IList plus conversion of IEnumerable<T> to IList<T>. Therefore, the Collection visualizer inherits the properties of the solution – non-generic IEnumerable as well as infinite IEnumerable will not be supported but the number of items will be known, scrolling will be fast, and it will be possible to further expand individual rows.

### Existing work

There are some existing tools to visualize collections in the debugger in a way similar to our proposition, for example [19] (a debugger visualizer for Visual Studio). However, this visualizer is designed only to visualize one type of objects specific to one application – e.g. a ShoppingCart. In other words, the visualizer is not generic. A generic visualizer for List and Dictionary types exists [20] but due to the architecture of Visual Studio Visualizers, the collection items need to marked with the [Serializable] attribute which can’t be always guaranteed and requires users to change their code in order to view data. Also, if the visualizer wanted to support IEnumerable, every IEnumerable class would have to be registered manually by users as Visual Studio debugger visualizers can't be registered for interfaces [21].

Our collection visualizer should be completely generic – it should work for collections containing any types of objects out of the box, and it shouldn’t need to transfer the whole collection from the debuggee to the debugger in order to display first few items. We haven’t found any existing generic solution which accomplishes this.

### What needs to be done

Summarizing the previous thoughts, here are the requirements for the Collection visualizer:

* Display contents of a collection of objects: rows represent objects, columns represent their properties.
* Support IEnumerable<T>, IList, IList<T> and one-dimensional arrays.
* Should not suffer a noticeable slowdown for collections containing thousands of items.
* Should work out of the box, without any need to manually register types or modify code.
* Will be a standard part of the IDE so no additional downloads are needed.

### Grid columns, generic vs. non-generic collections

The main difference between the Collection visualizer and the Debugger tooltips is that the Collection visualizer presents values of multiple properties of all the items at once, using one column for each property. This brings us to an important question: Given a collection, how to determine what the columns will be?

If all the items of the collection were guaranteed to be of same type, it would be certainly a correct solution to make one column per each public property of this type (possibly also including properties from base classes). The problem is that the collection can, in fact, contain items of various types and it is not possible to know all these types in advance because determining them is too expensive due to the expensiveness of the debugger API calls. Realizing that it is not possible to have full information about types of all the items, there are three options:

1. Look at the first item in the collection and use its public properties.

Pros:

* None.

Cons:

* + The columns for the whole collection are determined only by the type of the first item.
  + When subsequent items have additional properties, these properties will not be shown.
  + When subsequent items miss some of the properties, the cells will be empty.

1. When scrolling and evaluating new items, add columns to the grid dynamically when new properties are encountered.

Pros:

* + All of the properties of every item are always shown.

Cons:

* + When items miss some of the properties, the cells will be empty.
  + A complicated solution.
  + Columns being added when scrolling are not a good user experience.

1. Look at the generic parameter of the collection (IList<T>, IEnumerable<T>) and use the public properties of the parameter type T.

Pros:

* + The columns represent the type of the whole collection.
  + Collection can contain only subclasses; therefore no cells will be empty.

Cons:

* + Does not support non-generic IList (non-generic IEnumerable was decided not to be supported in general).
  + When the items are subclasses of T, the properties defined in the subclass are not shown.

From the three solutions, the third one was chosen because its Cons are the least significant – non-generic ILists are not a common case (a fallback to the first solution could be implemented for non-generic ILists). Regarding the second Con: If the collection is of type IEnumerable<ICar> and the user knows that all the items are actually of type Truck, the user can add a cast to (IEnumerable<Truck>) which will cause all properties of the Truck type to be shown.

## Debugger tooltips

The third feature we built as a part of this thesis are the debugger tooltips for SharpDevelop 4. The goal is to re-implement the existing debugger tooltips in WPF and add support for IEnumerable collections and large collections.

### Existing work

SharpDevelop 3 has debugger tooltips implemented using Windows Forms and there is also a very similar feature in Visual Studio and other IDEs.

Screenshot SharpDevelop 3, VS, Eclipse.

### What needs to be done

The debugger tooltips in SharpDevelop 3 have cleanly separated user interface code from the underlying data model, which means the data model can be reused. Support for IEnumerable collections will be added to the data model according to the section 2.5 (Collections). The user interface implemented in Windows Forms will be removed from SharpDevelop and re-implemented using WPF.

Integration of the Debugger visualizers with the Debugger tooltips will be implemented so that the visualizers can be opened directly from tooltips. This integration should be extensible so that new visualizers become available in the tooltips.

# Implementation

This section highlights interesting parts of the implementation of Debugger visualizers for SharpDevelop and documents the codebase and design decisions.

In the SharpDevelop codebase [22], most of the Debugger visualizers code is located in the Debugger.AddIn project (AddIns/Debugger/Debugger.AddIn folder), specifically in subfolders Visualizers and Tooltips. The code of SharpDevelop and Debugger.Core is very well designed and needed only minor modifications to integrate the debugger visualizers and debugger tooltips. The directory structure of the code is the following (namespaces mostly follow directory structure):

Debugger.AddIn

Tooltips – logic and UI of debugger tooltips

TreeModel – data model for the debugger tooltips

Visualizers

Commands – opening visualizers from debugger tooltips

Common – code shared by multiple visualizers (such as collections support)

GraphVisualizer –Object graph visualizer

Drawing – rendering of the graph using WPF

ExpandedPaths – remembering expand state between debugger steps

Layout – calculation and representation of layout

SplineRouting – reusable implementation of edge routing

Object graph – building and representation of the Object graph

CollectionVisualizer – Collection visualizer

Presentation – WPF-related reusable code

Utils –generic reusable code

AvalonEdit.AddIn

CodeEditorView.cs – integration of debugger tooltips with the code editor

## Common base for visualizing collections

All of the visualizers are dealing with collections in essentially the same way, described in the Analysis in the section 2.5 (Collections). Each of the visualizers has a different data model for collection items (tooltips show a tree of Expressions, the Object graph visualizer has edges outgoing from property trees, and the Collection visualizer uses a grid) but they all essentially handle collections as described in the Collections section of the Analysis - converting IEnumerable to IList by constructing a List in the debuggee by evaluating an expression such as “new List<T>(enumerable)” where T is the generic parameter of the type of the enumerable variable in debuggee. If an instance already implements IList, the conversion is skipped (this check is implemented in TypeResolver). The conversion of IEnumerable to IList is implemented in DebuggerHelpers.

## Object graph visualizer

In section 2 (Analysis), the high level architecture of the Object graph visualizer was outlined. It was decided that building and layout of the graph will be separate steps, and a Tree layout algorithm, which does not work incrementally but behaves well in terms of incremental stability, was proposed. The following diagram shows a design following the decisions from section 2.6 (Object graph visualizer):



Of course, constructing a static ObjectGraph and presenting it to users is only half of the picture. As further discussed in section 2 (Analysis), the changes which occur during debugger steps are being visualized by smooth transitions between graphs. The transitions are produced using graph diffs which are inferred by comparing graph state before and after each debugger step. The following diagram explains the design of the Object graph visualizer the best:

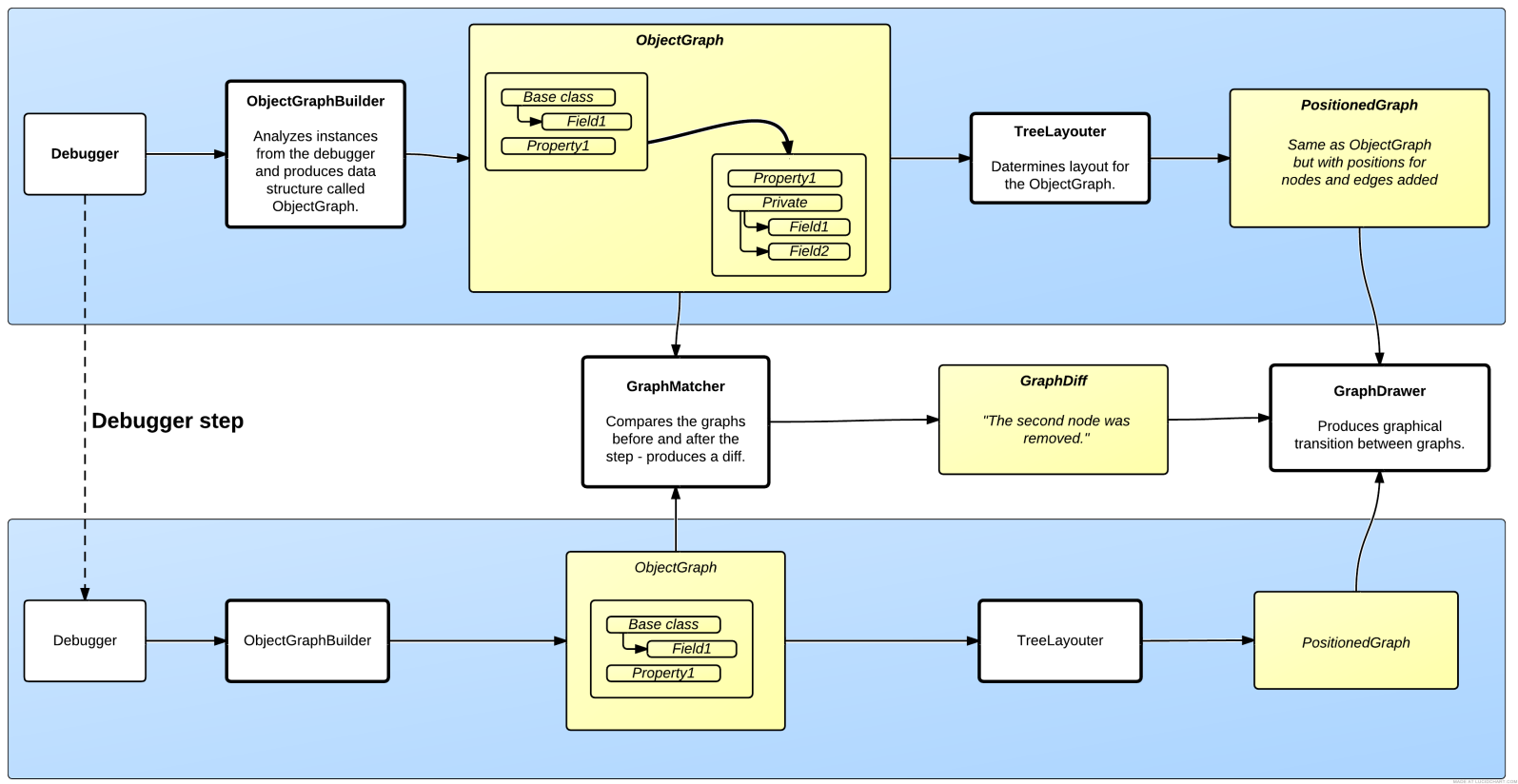
The main window of the Object graph visualizer, from where all the processes outlined in the diagram are coordinated, is implemented in ObjectGraphControl.

Figure - Design of the Object graph visualizer

diagram: Debugger.Addin -> Debugger.Core -> ICorDebug and around it the boundaries of SharpDevelop and the CLR (with JITted program in it)

### Graph building

The graph building algorithm including the decisions behind it was largely described in the Analysis section. In the implementation, this algorithm resides in the ObjectGraphBuilder class. Its method BuildGraphForExpression takes an NRefactory.Ast.Expression and produces an ObjectGraph.

### The ObjectGraph

The ObjectGraph is composed of a collection of ObjectGraphNodes. An ObjectGraphNode represents one debuggee instance and contains a tree of properties of this instance, grouping the properties by their visibility and class where they were declared. The properties are represented by PropertyNodes, each containing an ObjectGraphProperty, pointing to a target ObjectGraphNode, thus representing a named edge. There also also special nodes in the property tree used to group PropertyNodes into subtrees, like BaseClassNode or NonPublicMembersNode.

#### Lazy evaluation of properties

The ObjectGraphProperties inside ObjectGraphNodes are lazily-evaluated. When a node contains many properties, only the first few are evaluated and when the contents of the node are scrolled, the properties coming into view are being evaluated as needed.

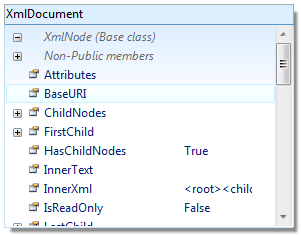


Figure – UI for ObjectGraphNode (implemented by PositionedGraphNodeControl). The properties out of view have not been evaluated yet and will be evaluated when they are scrolled into view.

This saves a lot of performance especially when objects have a lot of properties. The lazy evaluation is controlled by user interface because only the UI has exact information about which properties are currently in view. The implementation exploits the fact that WPF ListView pulls items from its ItemsSource as the items come into view. As the ItemsSource for the ListView, an instance of VirtualizingObservableCollection is supplied. VirtualizingObservableCollection adds on-demand evaluation support to an existing ObservableCollection (Decorator pattern).

Class diagram

#### Collections

When an ObjectGraphNode represents a collection, the collection is converted to a List using the common approach, the Count property of the List is evaluated and a flat list of empty ObjectGraphProperties is generated quickly – each ObjectGraphProperty representing one item of the List (with Expressions list[0] up to list[Count-1]) – this logic is implemented in ObjectGraphBuilder. The lazy evaluation then works using exactly the same mechanism as the lazy evaluation of properties described in the previous section.

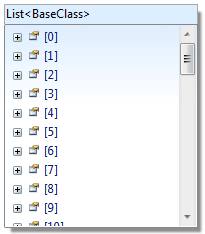


Figure – ObjectGraphNode representing a collection.

#### Expanding nodes

As discussed in section 2.6.3 (Graph building), the ObjectGraph returned from the ObjectGraphBuilder is not fully expanded up to some given maximum depth but users control which individual nodes are expanded by clicking a plus button next to fields and properties.

When a field or property is being expanded, its target is evaluated and either a new node is added to the graph, or only an edge to an existing node is added in case the target was already present in the graph. Then the layout for the whole graph is recalculated. When a field or property is collapsed, its target is removed from the graph including all its inbound and outbound edges. Expanding and collapsing is implemented in ObjectGraphControl – PositionedNodeControls raise events and ObjectGraphControl reacts to them by implementing the logic just described.

##### Remembering expanded nodes between debugger steps

A large part of the design of the Object graph visualizer focuses on debugger steps. The expanding of nodes must also fit into the picture – namely, when some nodes are expanded, these nodes must also stay expanded after a debugger step. Considering the fact that after the debugger step the ObjectGraph is being rebuilt from scratch, the information about expanded nodes must be kept somewhere separately. The structure holding this information is called simply Expanded. The Expanded structure holds the information about expanded nodes by holding a set of string expressions describing expanded paths in the graph, such as a[0].left, a[0].left.right etc. After a debugger step, the same paths are expanded again, which is equivalent to the user manually clicking the same plus buttons on the same nodes. Of course, these nodes might not represent the same debuggee instances anymore but this approach is quite intuitive and behaves as expected.

An implementation detail is that re-expanding of the right paths after a debugger step is not implemented by repeatedly invoking an Expand function but instead the expanding is incorporated right into the graph building algorithm. The ObjectGraphBuilder gets the Expanded data structure and when recursively exploring the graph, it only follows the paths which are present in the Expanded set.

### Graph layout

This section describes our Tree layout algorithm in detail. The whole layout algorithm consists of two separate steps:

* Calculating the positions of nodes (node layout)
* Calculating the paths of edges (edge routing)

Naturally, edge information is involved in the first step as well. The separation into two steps means that after the node positions are determined, the positions are fixed and only then edge paths are being added to the layout. The dot algorithm implemented in Graphviz uses exactly the same separation into two steps.

As the calculation of node positions was largely described in section 2.6.4 (Graph layout), this section focuses mainly on the algorithm for calculating edge paths.

#### TreeLayouter, PositionedGraph

The algorithms described in this section and section 2.6.4 (Graph layout) are implemented in classes TreeLayouter (responsible for node layout) and EdgeRouter (responsible for edge routing). The TreeLayouter takes an ObjectGraph as input, calculates node positions, calls EdgeRouter to calculate edge routes, and produces a PositionedGraph.

The difference between ObjectGraph and PositionedGraph is that ObjectGraph is an UI-independent model of a graph of debuggee instances and PositionedGraph also contains position information for nodes and positioned paths for edges. The PositionedGraph is not produced by copying an ObjectGraph; it rather wraps the ObjectGraph and adds position and UI information.

To be able to work with real sizes, the PositionedGraph is WPF-dependent and contains the WPF user interface elements for graph nodes (PositionedGraphNodeControl) and edges (System.Windows.Shapes.Path).

#### Node layout

It the section 2.6.4 (Graph layout), the Tree layout algorithm for calculating positions of nodes was proposed. The algorithm is implemented exactly as described, by selecting a tree subgraph of the input graph using BFS and then recursively traversing the tree twice – first to calculate the areas needed for the subtrees and then arranging the subtrees next to each other. The implementation can be found in the TreeLayouter class.

##### Similarity to WPF’s “Measure-Arrange” layout algorithm

The two recursive passes over the tree are named Measure and Arrange in our algorithm. The fact that the two layout passes in WPF are named the same is not a coincidence – the layout algorithms in WPF and many other UI frameworks work on exactly the same principle.

In WPF the user interface elements are organized into a tree called the Visual tree. When an UIElement is asked for its size (Measure() method) it asks its children for their desired sizes so that it can determine its own desired size. When an UIElement is told its new position (Arrange() method) it also repositions its children, knowing their sizes because Measure() is called before Arrange() for any element.

In WPF the users can define their own user interface elements and completely control the layout by subclassing FrameworkElement and overriding the MeasureOverride() and ArrangeOverride() methods. This is also how existing UIElements are implemented. For example, StackPanel is a panel which stacks its children next to each other – this logic is implemented in the ArrangeOverride method of the StackPanel.

#### Edge routing

After the node positions are calculated and fixed, the paths for graph edges are determined.

The problem: Given a set of positioned rectangles on a 2D plane and a set of directed edges between pairs of rectangles, find paths for the edges so that the paths avoid the rectangles and look *natural*.

Example of a solution (Graphviz):



Figure – Edges routed using Graphviz

As discussed in the section 2.6.4 (Graph layout), after researching available solutions it was decided that a custom solution would be implemented for the purposes of the Object graph visualizer. The implementation presented in this section is not WPF-dependent and can be reused as-is in other applications; this is achieved by following a common practice of programming against interfaces.

##### Our algorithm

The first decision that has to be made when designing an edge routing algorithm is whether the edges will be routed globally or independently (one by one):

* Global routing tries to minimize the total number of edge overlaps while making the individual edge paths look natural.
* One-by-one routing calculates each edge path independently from others, trying to make each edge path look natural.

Like the edge routing algorithm used by Graphviz [23] [24], our algorithm processes edges one by one, treating each edge as separate input. The Graphviz paper [23] also mentions a possibility of a global algorithm that would try to make edges avoid each other or emphasis routing edges in parallel but does not provide any ideas for such algorithm.

When designing the algorithm, two important observations were made:

* The most natural path is a straight line and when there is a rectangle blocking the straight line, the path must be broken around some corners of the rectangle. There is no need to break paths in open space. Therefore, the interesting points in the plane are the corners of the rectangles.
* To make edge paths look natural to users, the edge paths should be relatively close to closest possible paths, while not bending too sharply.

The algorithm works in the following way: First a visibility graph is built, where vertices represent the corners of all the rectangles and edges connect pairs of vertices which can be connected by straight lines without intersecting any rectangles (each edge endpoint is visible from the opposite edge endpoint). The pairs of vertices where the edge would be blocked by a rectangle are not connected. Then, to find routes for edges, shortest path are found in the visibility graph.

Determine edge start and end points in the plane:

For each edge e in G:  
 Determine edge start and end point of edge e:   
 take a straight line from the center of edge’s source rectangle   
 to the center of edge’s target rectangle.  
 Where this line intersects the source rectangle is the start point es  
 analogically end point et

Build the visibility graph:

Build the following graph Gv (visibility graph):

V = (every 4 corners of all rectangles on input[[10]](#footnote-10)) + (all start and end points of all edges)

E = (pairs (u, v) from V where u is visible from v: straight line can be drawn from u to v without crossing the body of any rectangle)

Find edge routes (each edge independently):

For each edge e in G:  
 In Gv find shortest path from es to et (using A\* or Dijkstra’s algorithm)  
 Smoothen the path by replacing each sharp join by a bend (join smoothing)

Our implementation has time complexity of O(n3) where n is the number of rectangles due to the construction of visibility graph: O(n2) vertex pairs are tested for visibility and each test needs O(n) line-rectangle intersections. The time complexity could be probably reduced but for our needs this is sufficient (note that Graphviz also uses an O(n3) implementation).

The following figure shows an example of a result of our implementation:

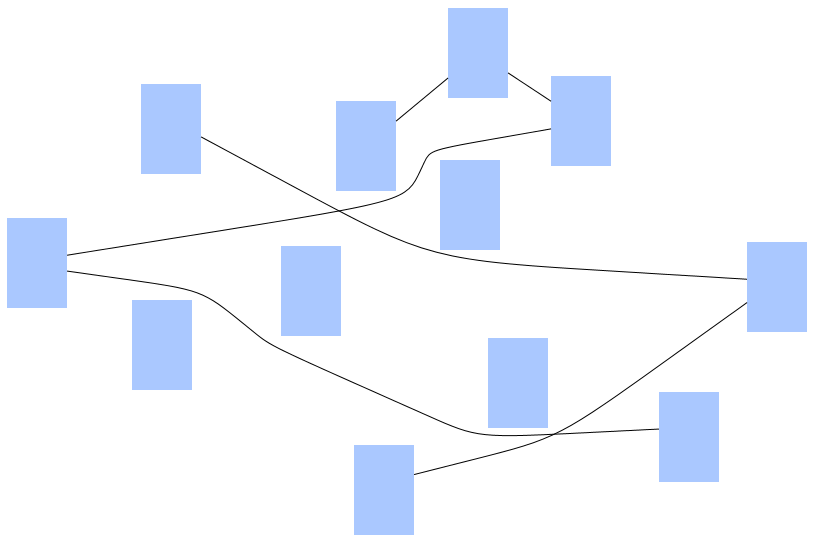


Figure – Edge paths calculated using our implementation.

The implementation is completely reusable and can be found in the namespace Debugger.AddIn.Visualizers.Graph.SplineRouting. The reusability is achieved by defining simple interfaces such as IPoint, IRect, IEdge and programming against them. Any representation of a graph implementing these simple interfaces is then a suitable input to the algorithm.

##### Join smoothing

The last step of the algorithm, join smoothing, is used to replace sharp joins on shortest paths in the visibility graph by smooth bends. As a result, the output is visually much more appealing. The following two figures show a comparison of an edge path with and without join smoothing used:

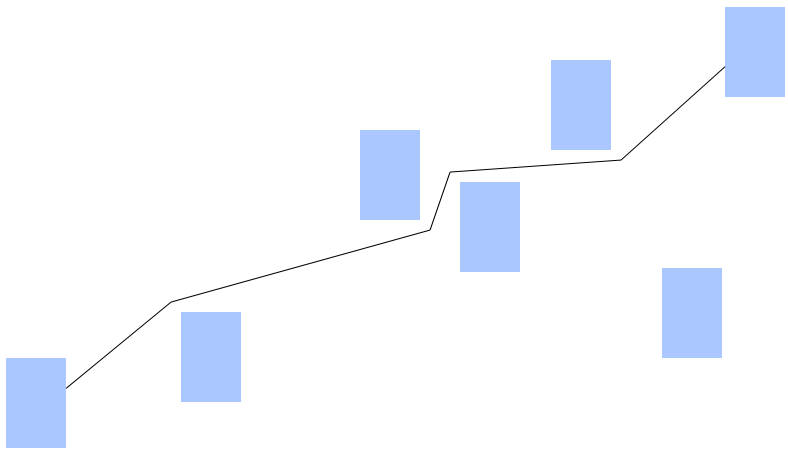


Figure – Edge path without smoothing (a shortest path in the Visibility graph).

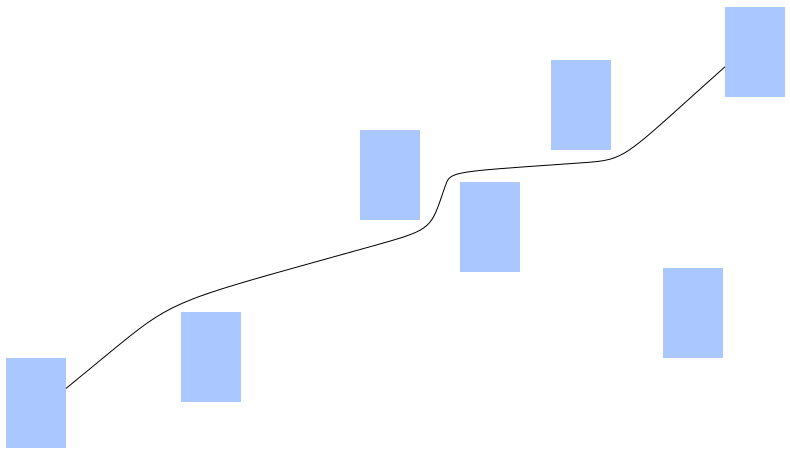


Figure – The path from Figure 27 with smoothing applied.

The principle of the join smoothing method is the following: Given two consecutive line segments, replace the segments by a Bezier curve of order 3 extended by a straight line segments at each end:

Screenshot original broken line and the bend following it

The control points of the Bezier curve lie on the original lines. The distance of the control points from the original points determines the “smoothness” of the curve:

(Screenshot) two distances next to each other

##### Edge overlaps

Routing edges independently can result in edge crossings and overlaps. To deal with possible confusion caused by edge overlaps, highlighting of edges under cursor is implemented in the GraphDrawer.

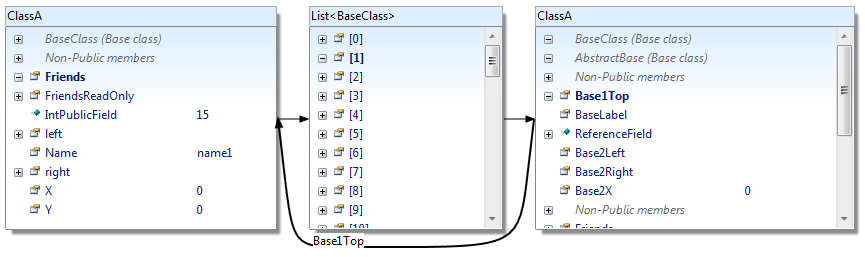


Figure – Edge under mouse cursor is highlighted in bold and a tooltip is displayed.

##### Multiple edges, self-edges

The implementation also deals with situations when there are multiple edges between one pair of rectangles. This is solved by distributing the edge start and end points along the border of the rectangles. Self-edges are solved in the same way.

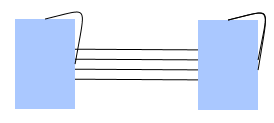


Figure – Multiple edges between two rectangles and self-edges.

##### Explicitly determined start and end points

Some layout engines (including Graphviz) let users specify starting and ending points of edges. This feature could be useful in the Object graph visualizer because the edge outgoing from an object property could start directly next to the title of the property. We considered this and concluded that the layout would get problematic when the contents of nodes are scrolled – the edge point would have to move and the edge would have to be re-routed when scrolling. Therefore it was decided not to implement this feature for now.

### Graph matching

Graph matching is used to produce graph transitions between two graph states. Graph matching is implemented as described in the Analysis section in the class GraphMatcher which accepts two ObjectGraphs and produces a GraphDiff object containing a list of pairs of matched nodes, a list of nodes which were added in the new graph, and a list of nodes which were removed from the old graph. Figure 22 explains this process the best.

### Graph drawing and transitions

After the layout of ObjectGraph is calculated by the TreeLayouter producing a PositionedGraph where nodes and edges are already represented by WPF elements, graph drawing is the final step which actually draws the PositionedGraph to screen. Graph drawing is implemented in the GraphDrawer class, which positions graph nodes and edges on a WPF Canvas. GraphDrawer also produces the transitions by creating a set of WPF Animation objects (one animation per each node and edge) based on a GraphDiff. The animations transform existing graph drawing to its new state.

While positioning the edges on the Canvas, GraphDrawer also adds tooltips to the edges, which appear when mouse cursor is hovered over the edges.

### The result

The following two figures show the final state of the Object graph visualizer in context of SharpDevelop:

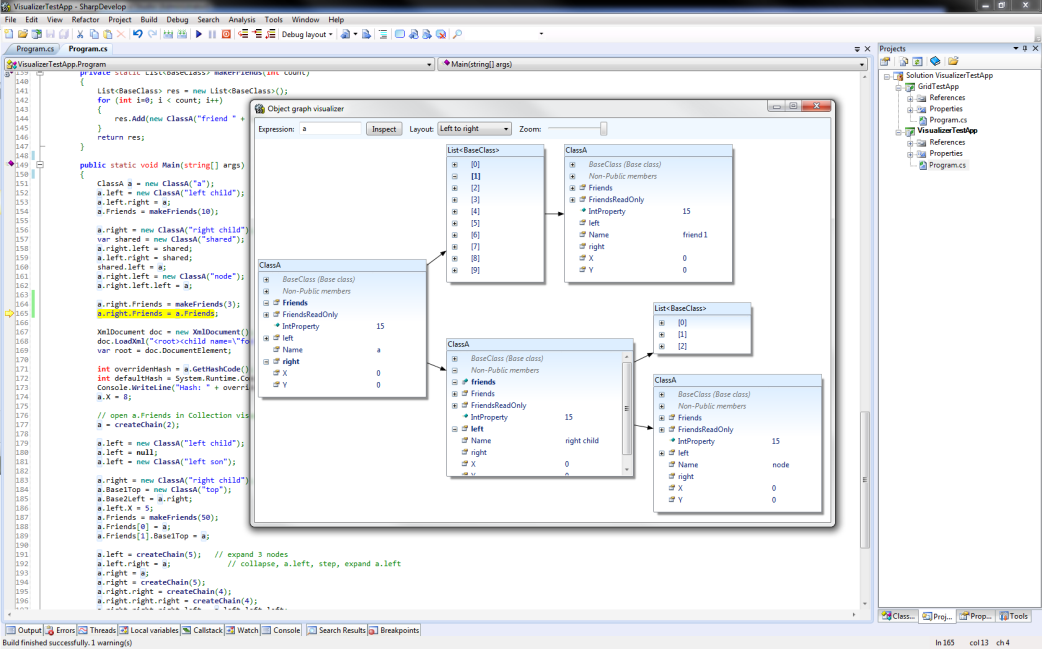


Figure – Object graph visualizer showing the state of the debuggee.

The next figure shows the changed state of the object graph after a debugger step is performed:

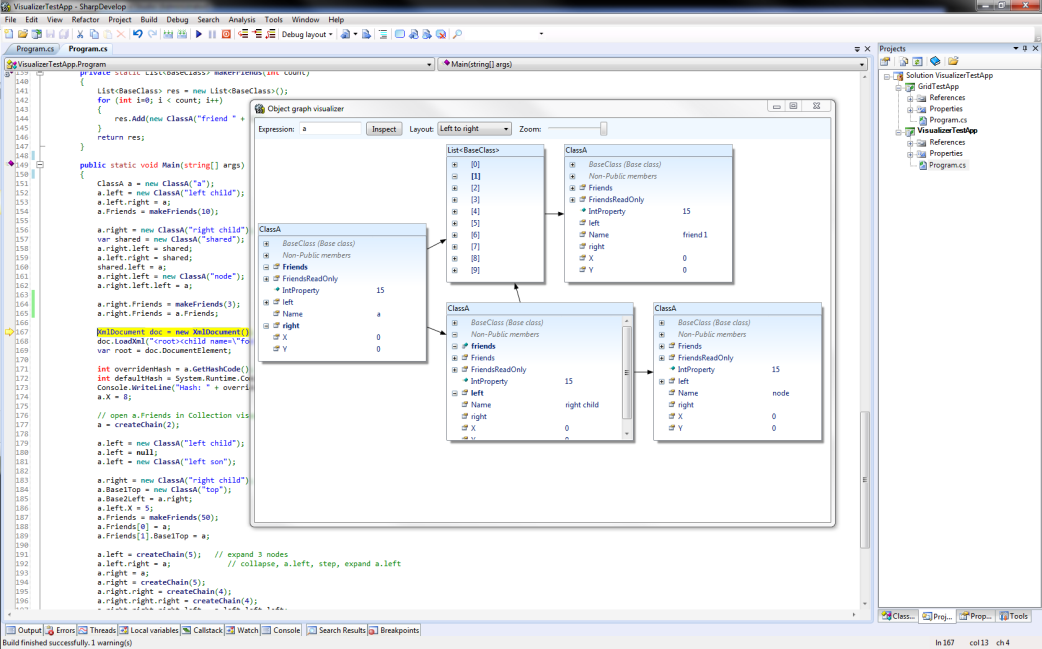


Figure – Object graph updated after a step in the debugger.

All of the work described in this thesis is included in standard releases of SharpDevelop 4.x. The easiest way to try the Object graph visualizer is to download a stable release link or a nightly build of SharpDevelop. link

## Collection Visualizer

Section 2.5 (Collections) identified the conceptual difference between IList and IEnumerable collections and the need for obtaining collection items lazily. An important question of how to determine the columns for the Collection visualizer’s grid was also resolved. The Collection visualizer, implemented in CollectionVisualizerWindow, follows these decisions. This section covers the data model of the visualizer, the implementation in WPF and explains how not only rows, but also columns of the grid are evaluated lazily for best possible performance.

### Lazy loading items when scrolling

Following the common approach to collections, any collection which is not an IList is converted to a List prior to being visualized. The implementation uses a WPF ListView and exploits the way in which ListView accesses items from its ItemsSource. When the ItemsSource is an IList, the ListView accesses the items which are needed to be rendered using the IList’s indexer.

Our implementation supplies a special collection, called VirtualizingCollection, as the ListView.ItemsSource. This collection is a wrapper around some data source (in our case the debuggee collection) and when asked for an item at index *i* it queries its underlying data source for item *i*, returns it and caches it. This principle is often referred to as *data virtualization*.



Figure (Class diagram) – Data virtualization using VirtualizingCollection<T>.

The top half of the class diagram in Figure 33 is a generic data virtualization implementation. The bottom half is specific to debugging. The items returned by the indexer of ListValuesProvider are instances of ObjectValue – a representation of a collection item specific to the Collection visualizer. ObjectValue contains the index of the item in the collection and a map of values of item’s properties.

The map is used to provide indexing by property name, which is used by the data binding of dynamically created ListView columns. The following listing shows how columns are created dynamically and prepared to be bound to ObjectValues.

**foreach** (var member **in** itemTypeMembers)    {  
 var memberColumn = **new** **GridViewColumn**();  
    memberColumn.Header = member.Name;  
    // "{Binding Path=[Name].Value}"  
    memberColumn.DisplayMemberBinding=**new** **Binding**("["+member.Name+"].Value");  
    gridView.Columns.**Add**(memberColumn);  
}

#### Note on generic data virtualization

Note that in our case, the only way to get a set of items from the debugger is to query items one by one. However, there are scenarios where querying a range of items at once is faster than obtaining items one by one (for example relational databases). In such scenario it is reasonable to implement paging mechanism in the concrete value provider so that when the provider is asked for an item at position *i* it queries and caches a number of items around index *i* (because it is very likely that these items will be needed soon).

### Expanding items in the grid – from here rewrite!

Because the properties of each collection item, shown in the individual grid cells, can be complex objects themselves, we implemented a way to explore their contents - each item of the collection has an expand button which opens a standard debugger tooltip for the item.

Screenshot

We implemented the expanding in the following way: Each item is represented by an ObjectValue which holds its index. To expand the tooltip, we pass an expression representing the item (like “list[12]”) to a debugger tooltip and open it at a right position.

### Generic vs. non-generic collections

There is an important question when designing the collection visualizer – when given a collection, what should be the columns of the grid? We already discussed this in the Analysis section. We decided that the grid columns represent the properties of the single generic parameter of the collection. That means when we get IEnumerable<Person> we make one column for each public property of the class Person and its base classes.

When the collection contains subclasses of the generic parameter type, their properties are not shown. Showing properties of subclasses would mean leaving the cells empty for some rows, since they would miss the properties, and adding columns dynamically on scrolling. We are not doing this.

Mockup of how it would look (in Excel)

Using the generic parameter also means that we do not support non-generic collections.

Building the columns is implemented in GridVisualizerWindow.

### Lazy loading columns (object properties)

In the collection visualizer, we are evaluating rows on-demand, as the user scrolls down (this was described in the section Lazy loading items when scrolling link). But we are also loading the individual cells lazily - the user can select which columns to show and which to hide. When a column is hidden, it is not being evaluated. When the user decides to show the column later, the values in the column are only evaluated for the few items which are currently in view. In other words, the visualizer is as lazy as it can be.

The implementation exploits the way the WPF ListView evaluates databinding expressions. We bind ObjectValue[propertyName] to each column, and when a column is hidden, we remove it, so the ListView stops evaluating it. When we add the column back, the ListView only asks for the values which are currently in view. The laziness is implemented in ObjectValue and the databinding can be seen in where.

### The result

The following figure shows the final state of the Collection visualizer:



Figure – Final state of Collection visualizer.

The Collection visualizer has been successfully tested on the following types: array, List<T>, ArrayList, Dictionary<K,V>, HashSet<T>, IEnumerable<T>, IQueryable<T>, ObservableCollection<T>, ReadOnlyCollection<T> and IParallelEnumerable<T>. The types of collection items tested were various classes and structures (including a class with inheritance hierarchy of depth 4 containing generic classes). We are also using the Collection visualizer while working on SharpDevelop.

## Debugger tooltips

Talk about how tooltips are integrated with vispicker – show .addin.

Unlike with the two previous visualizers, the data model for the tooltips was already there in SharpDevelop. It didn’t support large collections so we had to add this to the data model.

The main part of work on the debugger tooltips was to implement the user interface and integrate it in into SharpDevelop’s code editor. We wanted the tooltips to work for C# and VB.

### The result

# Conclusion and future work

Great idea – integrate collection visualizer into tooltips. When a collection is expanded in the tooltip, clicking a small arrow adds columns.

In tooltip button to include properties from all base classes, so that user does not have to search. Or add type-to-search feature.

Draw a forest – all the local variables for example, with markers to show which node is which variable.

Special case for Dictionaries.

Plot visualizer (for someone interested).



# References

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# Appendices

## User manual

## Content of CD

1. From a personal point of view, it is a great feeling to add a new string into the UI and see it translated into ten languages by people from around the world. [↑](#footnote-ref-1)
2. The lexer and parser are kept up to date with most recent language specifications changes. [↑](#footnote-ref-2)
3. AbstractAstVisitor is intented for read-only operations. If an operation needs to modify the parse tree, it should subclass AbstractAstTransformer. [↑](#footnote-ref-3)
4. It would be possible to create a Dictionary directly in the debuggee by evaluating an expression “dict=new Dictionary<object, int>()“ and track instances using this Dictionary by evaluating dict[o] and dict.Add(o, new\_id). However, a Dictionary uses user defined instance equality (overridden GetHashCode and Equals methods) while in the Object graph visualizer we are interested in instance equality. [↑](#footnote-ref-4)
5. Evaluating a==b does not execute a==b directly in the debuggee, but is evaluated recursively using the ExpressionEvaluator (see the section Expression evaluation), which must be implemented correctly so that the expected behavior is met. [↑](#footnote-ref-5)
6. Each graph Node holds a Permanent reference to be able to access the address of the in-debuggee instance it represents. [↑](#footnote-ref-6)
7. Laptop with 1.6Ghz Pentium CPU, 2GB RAM. [↑](#footnote-ref-7)
8. Depth-first search. [↑](#footnote-ref-8)
9. Breadth-first search. [↑](#footnote-ref-9)
10. Note: the vertices of the visibility graph do not lie exactly in the corners of the rectangles but further from the rectangles by a small offset so that the paths go around the rectangles, not directly through their corners. [↑](#footnote-ref-10)