# Time-lapse Full-Waveform Inversion using Hamiltonian Monte Carlo: A proof of concept

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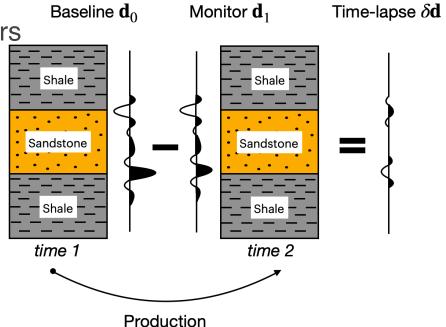


## Time-Lapse Seismic Imaging

Over a reservoir's life its parameters will change

 <u>Time-lapse or 4D seismic</u>: same location but different time

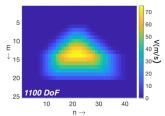
 Full–Waveform Inversion (FWI): delivers a velocity model of the subsurface

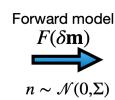




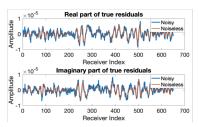
## Bayesian Time-Lapse Inversion







 $\delta \mathbf{d}$ : Observed data residual



**Goal**: estimate distribution of time-lapse models given data residuals  $p(\delta m \mid \delta d)$ 

#### **Challenges:**

- Large dimensionality (visualization, covariance)
- Expensive forward solvers (finite difference, finite element)
- Non-linear forward model (multi-modal or non-Gaussian model distribution)

Solution: Markov Chain Monte Carlo with a fast forward solver



### Outline

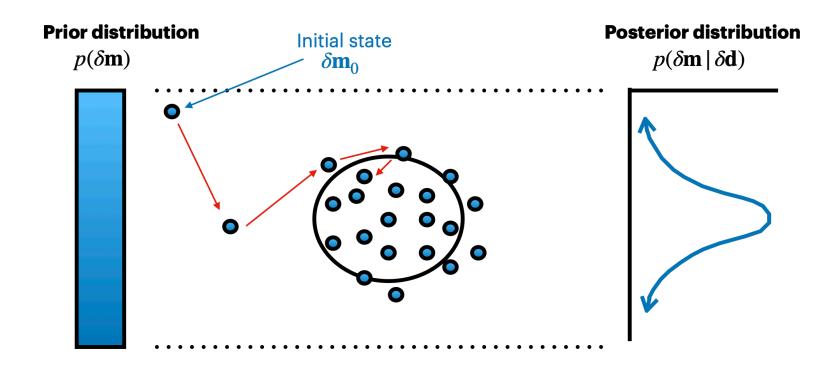
- Motivation
- Markov Chain Monte Carlo



- Hamiltonian Monte Carlo
- Local solver
- Numerical Example
- Summary



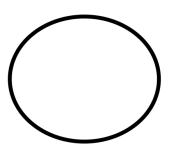
### Markov Chain Monte Carlo





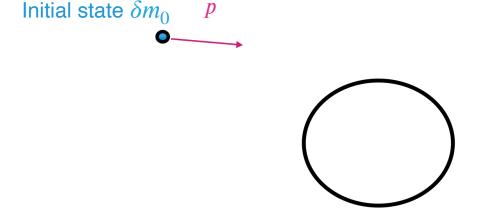
HMC treats a model as virtual Hamiltonian particle that moves along a trajectory.

Initial state  $\delta m_0$ 



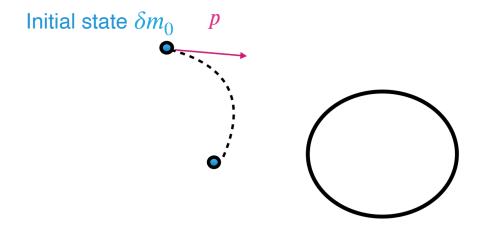
- Initial model
  - Associated potential energy  $U(\delta m)$





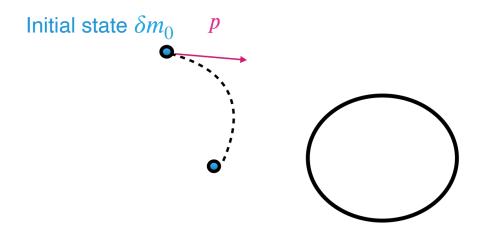
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- 2. Add auxiliary momentum
  - Associated kinetic energy K(p)





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  - $H(\delta m, p) = U(\delta m) + K(p)$
- 4. Get a new proposed model



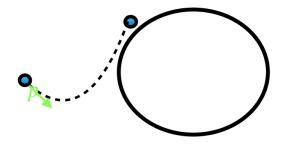


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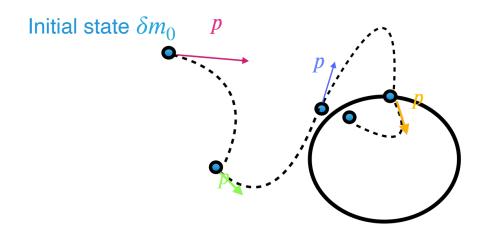
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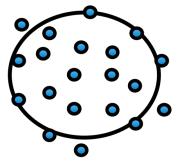


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	Metropolis Hastings	Hamiltonian Monte Carlo
DoF	1 - 10 <sup>2</sup>	10³ - 10 <sup>6</sup>
Iterations	104 - 106	10 <sup>3</sup> - 10 <sup>5</sup>
Computational cost	Low	High
Pixel-by-pixel UQ	No	Yes
Gradient calculation	No	Yes

- Metropolis Hastings algorithms are used to ground truth probability distribution.
  - Very slow to converge as the number of dimensions grows
  - Requires reduced parameterization techniques
- Hamiltonian Monte Carlo is more advanced
  - Use the geometry of the target distribution for faster exploration

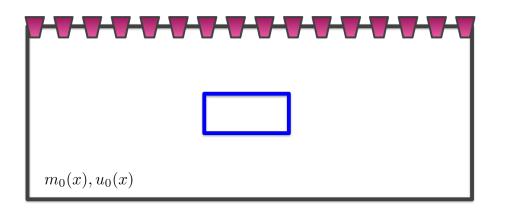


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#### Local Acoustic Solver

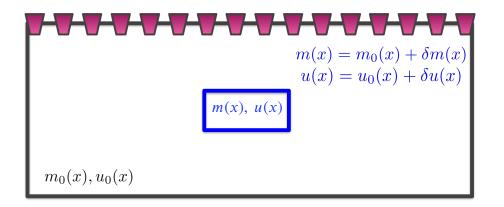


1) Split model to subdomain and exterior. Model in exterior & initial guess in local domain = background model  $m_0$ 

Willemsen et al. (2016); Malcolm & Willemsen (2017)



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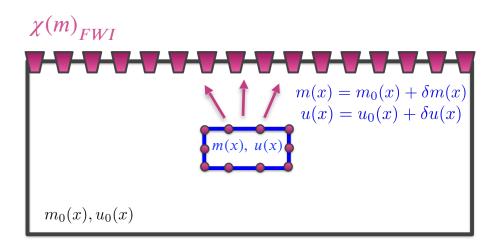


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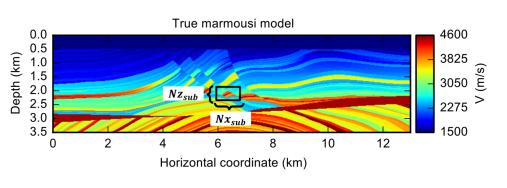
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- 3) Propagate u to the receivers

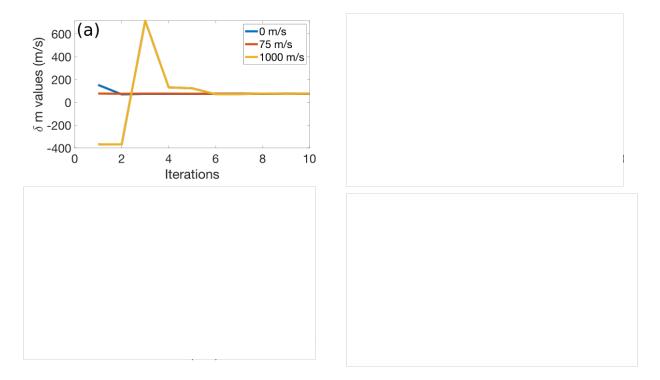
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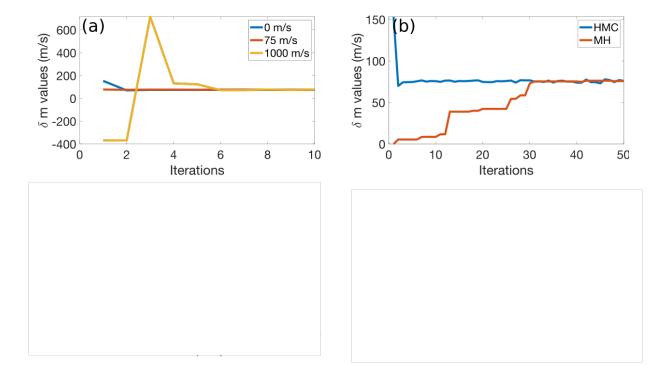


- Marmousi: background baseline model
- Time lapse change :  $\delta m = 75 \ m/s$
- 1 shot, 651 receivers
- Single frequency of 8 Hz
- Full domain grid points:
  Nz\*Nx = 113925
- Local domain grid points:
  Nz<sub>sub</sub>\*Nx<sub>sub</sub> = 1100

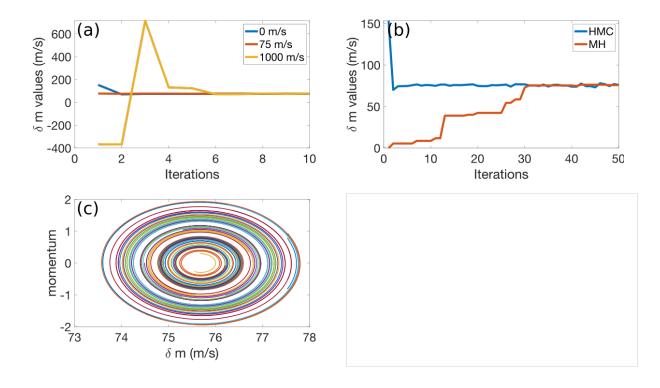




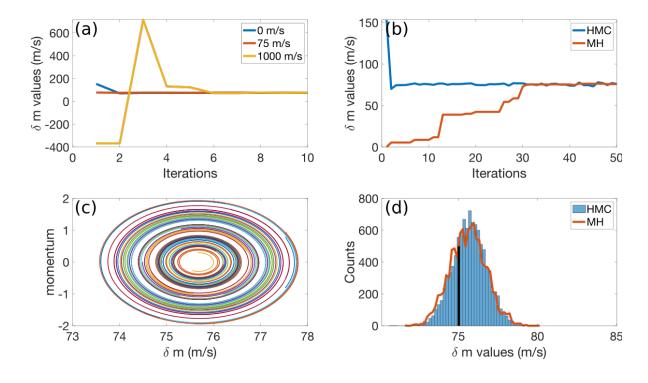




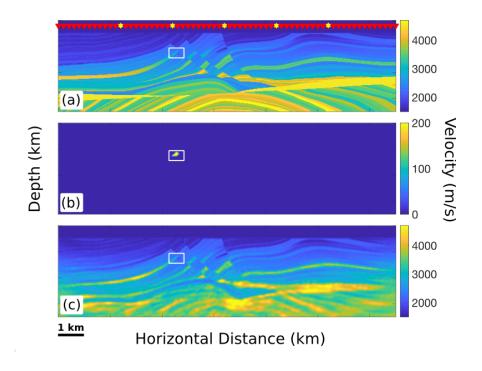






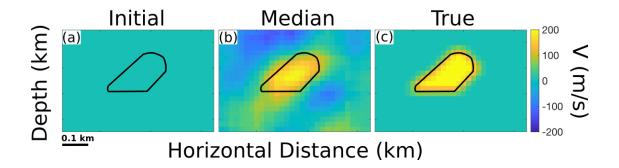






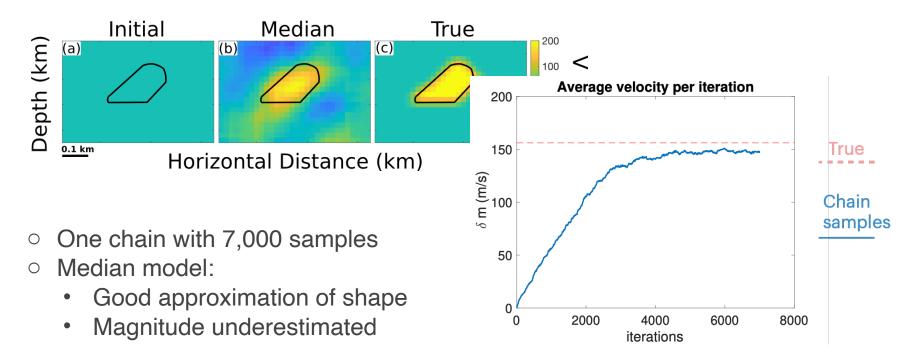
- Setup (a & b)
  - $> \delta m = 200 \, m/s$
  - > 600 DoF
  - > 5 shots, 651 receivers
  - ➤ Single frequency: 5 Hz
- Background model ( c )
  - > Inverted baseline
  - ➤ 64 shots, 651 receivers
  - > 3, 4, 5, 6.5, 8, 10 Hz sequentially for 15 iterations per frequency.





- One chain with 7,000 samples
- Median model:
  - Good approximation of shape
  - Magnitude underestimated







## Summary

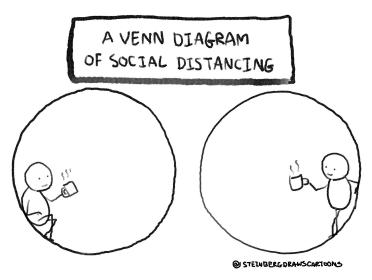
- We generated a framework for uncertainty quantification in a targeted way
- Use of local solver for fast gradient calculations

\_ Computational savings are 
$$\frac{t_{local}}{t_{full}} = 0.03$$

- Proof of concept of HMC on time-lapse scenario
  - Superior performance when compared to MH
- Future work:
  - Use of Mass Matrix in the kinetic energy formulation
  - Multiple frequencies



## ΤΗΑΝΚ ΥΟυ! ΕΥΧΑΡΙΣΤΩ!



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