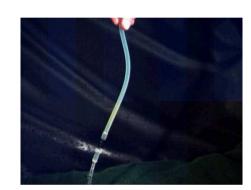
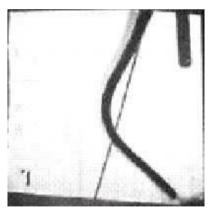
THE FLUID-CONVEYING PIPE INSTABILITY

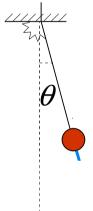




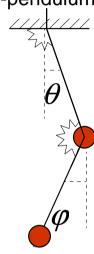


THE FLUID-CONVEYING BI-PENDULUM

Single pendulum model



Bi-pendulum model



Without fluid

$$\ddot{\theta} + \theta = 0$$

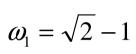
Without fluid

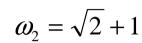
$$2\ddot{\theta} + \ddot{\varphi} + 2\theta - \varphi = 0$$
$$\ddot{\theta} + \ddot{\varphi} - \theta + \varphi = 0$$

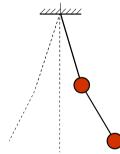
THE FLUID-CONVEYING BI-PENDULUM

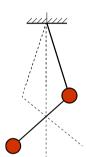
Mode 1







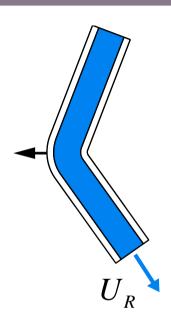




$$\begin{bmatrix} \theta(t) \\ \varphi(t) \end{bmatrix} = q_1(t) \begin{bmatrix} 1 \\ \sqrt{2} \end{bmatrix} + q_2(t) \begin{bmatrix} 1 \\ -\sqrt{2} \end{bmatrix}$$

$$\ddot{q}_1 + \omega_1^2 q_1 = 0$$

$$\ddot{q}_2 + \omega_2^2 q_2 = 0$$







Dimensional elbow force.

$$F = \rho SU^2(\theta - \varphi)$$

Cauchy number

$$C_{Y} = \frac{\rho SU^{2}L}{C}$$

Dimensionless elbow force.

$$F = C_{Y}(\theta - \varphi)$$

$$f = C_Y(\theta - \varphi)$$

$$\ddot{q}_1 + \omega_1^2 q_1 = -C_Y \frac{\sqrt{2} - 1}{4 + 2\sqrt{2}} q_1 + C_Y \frac{\sqrt{2} + 1}{4 + 2\sqrt{2}} q_2$$

$$\ddot{q}_2 + \omega_2^2 q_2 = -C_Y \frac{\sqrt{2} - 1}{4 - 2\sqrt{2}} q_1 + C_Y \frac{\sqrt{2} + 1}{4 - 2\sqrt{2}} q_2$$

$$\ddot{q}_{1} + \left[\omega_{1}^{2} + C_{Y} \frac{\sqrt{2}-1}{4+2\sqrt{2}}\right] q_{1} = C_{Y} \frac{\sqrt{2}+1}{4+2\sqrt{2}} q_{2}$$

$$\ddot{q}_{2} + \left[\omega_{2}^{2} - C_{Y} \frac{\sqrt{2}+1}{4-2\sqrt{2}}\right] q_{2} = -C_{Y} \frac{\sqrt{2}-1}{4-2\sqrt{2}} q_{1}$$

