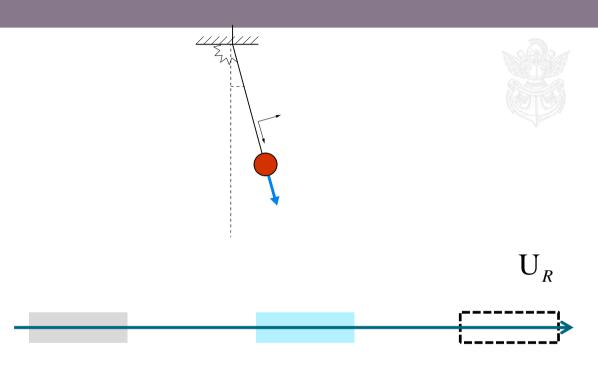
FLUID-CONVEYING PENDULUM



Added mass

Added damping

No effect

ANGULAR ROTATION THEOREM

$$T_{Solid-Fluid} = \frac{\partial}{\partial t} \int_{\text{Fluid domain}} x^2 M \dot{\theta} dV + \int_{\text{Fluid boundaries}} (x^2 M \dot{\theta}) (\underline{U}.\underline{\mathbf{n}}) dS$$



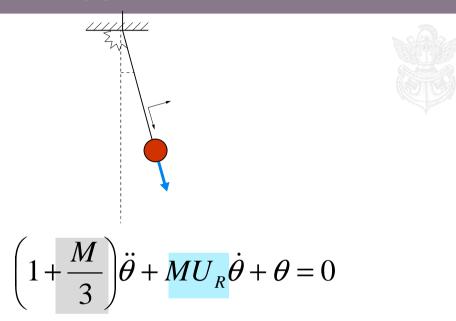
Intermediate velocity: $\dot{ heta}$ Frozen in time 0

Any velocity:
$$\dot{\theta}(t)$$
 $\frac{M}{3}\ddot{\theta}$



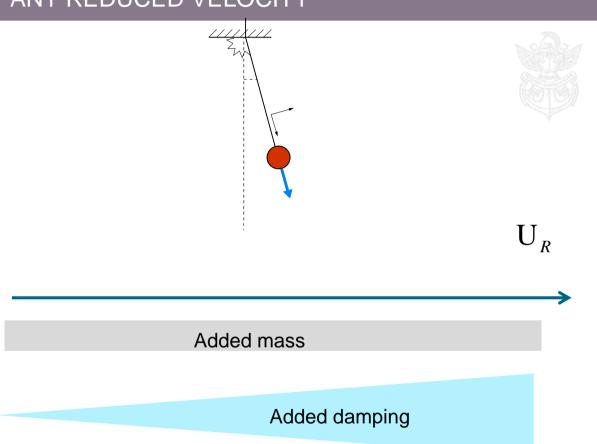
$$T_{Solid-Fluid} = \frac{M}{3}\ddot{\theta} + MU_R\dot{\theta}$$

THE FLUID-CONVEYING PENDULUM AT **ANY** REDUCED VELOCITY

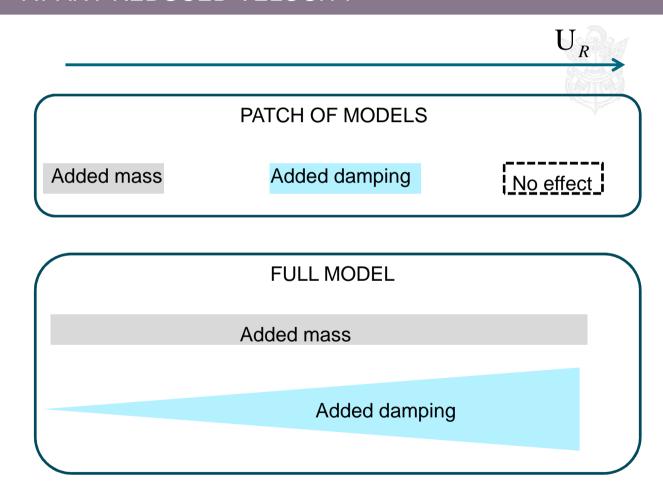


Added mass Added Coriolis damping

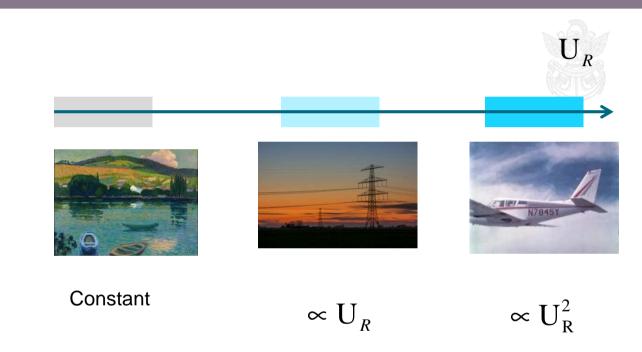
THE FLUID-CONVEYING PENDULUM AT ANY REDUCED VELOCITY



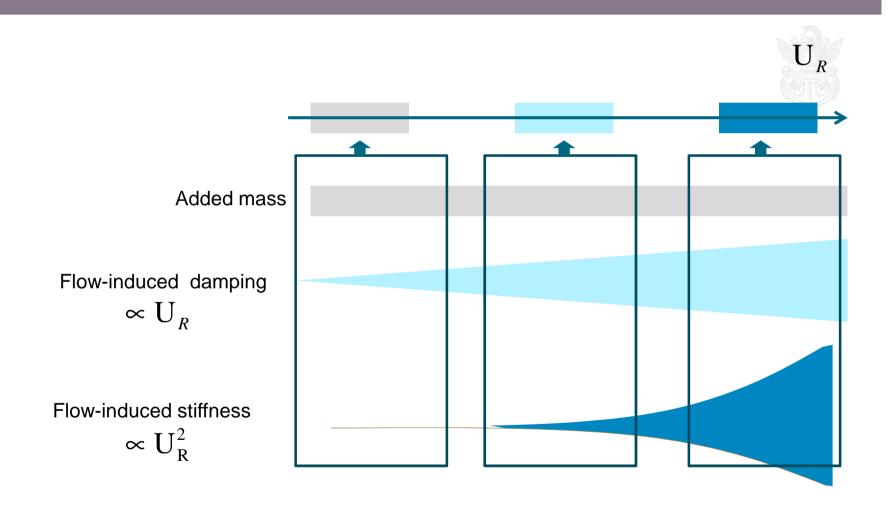
FLUID-CONVEYING PENDULUM AT ANY REDUCED VELOCITY



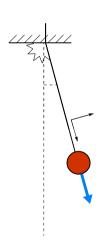
MODELS FOR FLUID SOLID INTERACTIONS

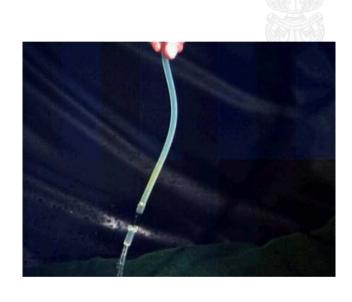


MODELS FOR FLUID SOLID INTERACTIONS



THE FLUID-CONVEYING PENDULUM : ANY REDUCED VELOCITY





THE FLUID-CONVEYING PENDULUM : ANY REDUCED VELOCITY

