

Bayesian Statistics

Model Assessment

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Prediction

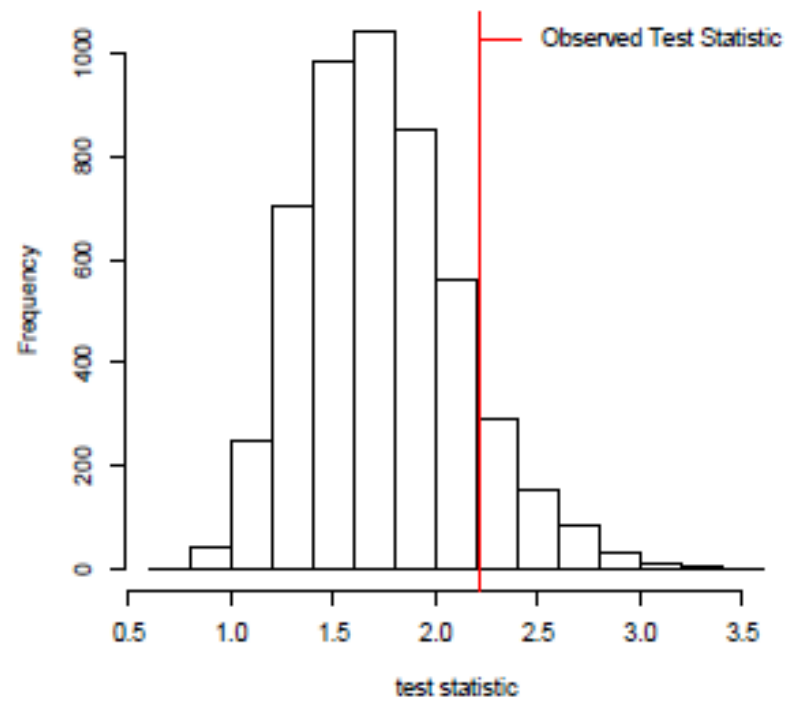
- ▶ Given a model and draws from the posterior distribution, we make prediction for future data points by simulating from the posterior predictive distribution.
- ▶ Consider making prediction for some future data point(s) \tilde{y} based on the observed data y , the posterior predictive distribution is then $p(\tilde{y}|y) = \int p(\tilde{y}|\theta, y)p(\theta|y)d\theta$
 - ▶ If we assume that \tilde{y} and y are conditionally independent given θ , then $p(\tilde{y}|y) = \int p(\tilde{y}|\theta)p(\theta|y)d\theta$
- ▶ Simulating from the posterior predictive distribution
 1. Sample m values of θ from the posterior distribution $p(\theta|y)$
 2. For each simulated value of θ , sample a \tilde{y} from $p(\tilde{y}|\theta)$

Model assessment by predictive checks

- ▶ Suppose that the data set contains some covariates, one may make predictions at
 - ▶ the observed values of the covariates → assess model accuracy
 - ▶ or at some hypothetical values → prediction the future

Posterior predictive checks

- ▶ Define a test statistic T that has power to diagnose violations of the assumption to be tested
 - ▶ Assume that a large value of T indicates violation
- ▶ Calculate T for the observed data y : $T(y)$
- ▶ Calculate $T(\tilde{y}|y)$ for each \tilde{y} drawn from the posterior predictive distribution
- ▶ Calculate the fraction of $T(\tilde{y}|y) > T(y)$. This is an estimate of the **posterior predictive p-value**.
 - ▶ If our posterior predictive p-value is close to 0 or 1 (say 0.05 or 0.95), then it suggests that our observed data has an extreme test statistic and that something in our model may be inadequate.



Possible Problems

- ▶ Choice of test statistic is very important.
 - ▶ Test statistic must be meaningful and pertinent to the assumption you want to test.
 - ▶ Test statistics often have low power
 - ▶ Test statistics should not be based on aspects of the data that are being explicitly modeled (for example, the mean of y in a linear model).
- ▶ If the model passes posterior predictive check, it does not necessarily mean there are no problems with the model.
 - ▶ Test statistic may have low power.
 - ▶ May be testing the wrong assumption.
- ▶ It is not always clear how to correct the incorrect model assumptions.

Example

- ▶ Model: Bayesian logistic regression with multivariate normal prior
 - ▶ $y_i | p_i \sim \text{Bin}(n_i, p_i)$ and $\log \frac{p_i}{1-p_i} = \mathbf{x}_i^T \boldsymbol{\beta}$
- ▶ Simulating from the posterior predictive distribution
 1. Create model matrix of covariates X .
 2. Get linear predictors by multiplying X and our m draws from the posterior.
 3. Convert linear predictors into probabilities with the inverse logit function.
 4. Draw m samples of \tilde{y} from the binomial likelihood.
- ▶ Output: a $n \times m$ matrix

Test statistic

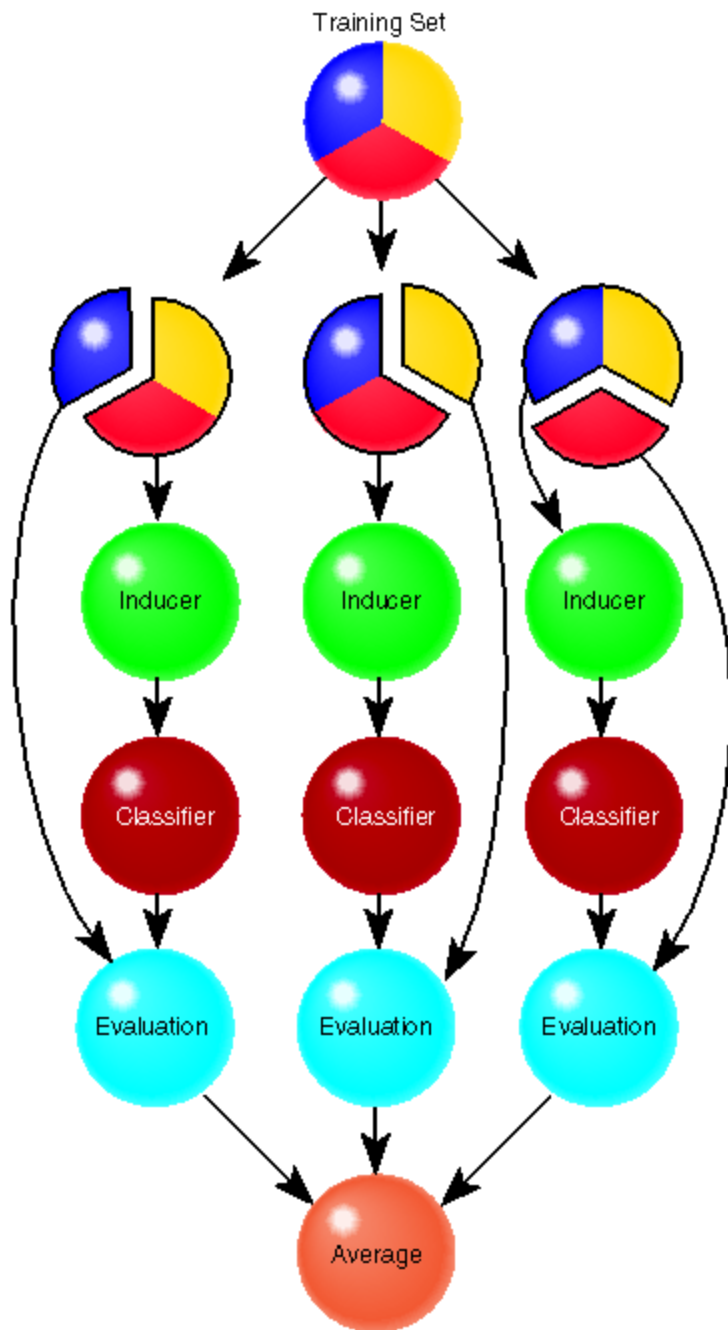
- ▶ Suppose we want to check the assumption that no clustering effect within levels of a covariate x^*
- ▶ T_1 = the fraction of y 's that take on the value of 1
 - ▶ Unclear what assumption are we testing.
 - ▶ The fraction of 1s is explicitly being modeled in the logit model.
 - ▶ The test will never show anything is wrong regardless of how bad our model is.
- ▶ T_2 = the variance of the number of 1s in each level of x^*
 - ▶ When clustering effect exists, the variance within clusters tends to be small

- Assume modelling data as $\mathbf{y} = (y_1, \dots, y_n) \sim N(\mu, \sigma^2)$
- Set priors on μ and σ^2
- Run WinBUGS and obtain samples: $\theta_t = \{\mu_t, \sigma_t^2\}$, $t = 1, \dots, M$
- For each sampled data point θ_t , replicate n data points: $y_{rep,i}^t \sim N(\mu_t, \sigma_t^2)$, $t = 1, \dots, M$ and $i = 1, \dots, n$.
- For each sampled value, (μ_t, σ_t^2) , we obtain M replicated data set $\mathbf{y}_{rep}^t = (y_{rep,1}^t, \dots, y_{rep,n}^t)$.
- Does our model represent our data adequately? Choose a discrepancy measure, say

$$T(\mathbf{y}; \theta) = \sum_{i=1}^n \frac{(y_i - \mu)^2}{\sigma^2}$$

Compute $T(\mathbf{y}, \theta_t)$ and the set of $T(\mathbf{y}_{rep}^t, \theta_t)$ and obtain “Bayesian p-values”:

$$P(T(\mathbf{y}_{rep}, \theta) > T(\mathbf{y}, \theta) | \mathbf{y}) = \frac{1}{M} \sum_{t=1}^M 1[T(\mathbf{y}_{rep}^t, \theta_t) > T(\mathbf{y}, \theta_t)].$$



Cross validation

- ▶ Leave-one-out cross validation
- ▶ g -fold cross validation

Basic tools for model assessment

- ▶ Cross-validation residual: $r_i = y_i - E(y_i | \mathbf{y}_{(i)})$, where $\mathbf{y}_{(i)} = (y_1, \dots, y_{i-1}, y_{i+1}, \dots, y_n)^T$
- ▶ Outliers are indicated by large standardized residuals $d_i = r_i / \sqrt{\text{Var}(y_i | \mathbf{y}_{(i)})}$
- ▶ Conditional predictive ordinate (CPO):
- ▶ $p(y_i | \mathbf{y}_{(i)}) = \int p(y_i | \theta, \mathbf{y}_{(i)}) p(\theta | \mathbf{y}_{(i)}) d\theta$
 - ▶ Height of the conditional density at the observed value of y_i
 - ▶ Large values indicates good prediction of y_i

Approximate method

- ▶ Given Monte Carlo (MC) samples $\theta^{(g)} \sim p(\theta|y)$,

$$\begin{aligned} E(y_i|\mathbf{y}_{(i)}) &= \int \int y_i f(y_i|\boldsymbol{\theta}) p(\boldsymbol{\theta}|\mathbf{y}_{(i)}) dy_i d\boldsymbol{\theta} \\ &= \int E(y_i|\boldsymbol{\theta}) p(\boldsymbol{\theta}|\mathbf{y}_{(i)}) d\boldsymbol{\theta} \\ &\approx \int E(y_i|\boldsymbol{\theta}) p(\boldsymbol{\theta}|\mathbf{y}) d\boldsymbol{\theta} \\ &\approx \frac{1}{G} \sum_{g=1}^G E(y_i|\boldsymbol{\theta}^{(g)}) . \end{aligned}$$

- ▶ Usually, the approximation works well unless the data set is small or y_i is an extreme outlier
- ▶ In practice, one can use the same $\{\theta^1, \dots, \theta^G\}$ for calculating all $E(y_i|\mathbf{y}_{(i)}), i = 1, \dots, n$

Approximate method

- ▶ To obtain the standardized residual $d_i = r_i / \sqrt{\text{Var}(y_i | \mathbf{y}_{(i)})}$, one can use a further approximation.
- ▶ Compute $d_i^* = \frac{y_i - E(y_i | \theta)}{\sqrt{\text{Var}(y_i | \theta)}}$
- ▶ Then find $E(d_i^* | y)$, the posterior average of the ratio

Exact method

- ▶ Evaluate $E(y_i|\mathbf{y}_{(i)})$ and $Var(y_i|\mathbf{y}_{(i)})$ separately.
- ▶ For $Var(y_i|\mathbf{y}_{(i)})$, use the fact that

$$Var(y_i|\mathbf{y}_{(i)}) = E(y_i^2|\mathbf{y}_{(i)}) - [E(y_i|\mathbf{y}_{(i)})]^2,$$

$$\begin{aligned} E(y_i^2|\mathbf{y}_{(i)}) &= \int E(y_i^2|\boldsymbol{\theta})p(\boldsymbol{\theta}|\mathbf{y}_{(i)})d\boldsymbol{\theta} \\ &= \int \{Var(y_i|\boldsymbol{\theta}) + [E(y_i|\boldsymbol{\theta})]^2\}p(\boldsymbol{\theta}|\mathbf{y}_{(i)})d\boldsymbol{\theta} . \end{aligned}$$

- ▶ For example, call the WinBUGS program n times, each time leaving one observation out
 - ▶ Use the R package BRugs

Example: stack loss data

- ▶ An oft-analyzed dataset, featuring the stack loss Y (ammonia escaping), and three covariates X_1 (air flow), X_2 (temperature), and X_3 (acid concentration).

- ▶ Linear regression with noninformative priors

$$Y_i \sim N(\beta_0 + \beta_1 z_{i1} + \beta_2 z_{i2} + \beta_3 z_{i3}, \tau),$$

- ▶ WinBUGS code and data for approximate method:
www.biostat.umn.edu/~brad/data/stacks BUGS.txt

- ▶ BRugs code and data for exact method:
www.biostat.umn.edu/~brad/software/BRugs

- ▶ an R program that organizes the dataset, contains all the BRugs commands, and summarizes the output
- ▶ a piece of BUGS code that is sent by R to OpenBUGS

Approximate vs Exact results

obs	sresid		CPO	
	approx	exact	approx	exact
1	0.948	1.098	0.178	0.124
2	-0.566	-0.628	0.224	0.188
3	1.337	1.461	0.122	0.084
4	1.672	1.851	0.078	0.047
5	-0.504	-0.477	0.251	0.244
⋮	⋮	⋮	⋮	⋮
21	-2.126	-3.012	0.046	0.005

- ▶ Approximate residuals are too small, especially for the most outlying observations
- ▶ Approximate CPOs also tend to understate lack of fit