

The Dataset

So far, we have introduced our simulator

The rest of our plan is as follows

- We learn an ML model
- We embed the model in a larger optimization problem
- We obtain a solution, i.e. a set of action to control the epidemics

But which data are we going to use for training?

The Dataset

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But which data are we going to use for training?

Since we have a simulator, we can build our dataset

- This means we can generate as much data as we wish
- ...But also that we are responsible for how to generate it

Building Our Dataset

We need to define the structure of the dataset

- We will focus on Non-Therapeutic Interventions (NPI)
 - E.g. mask mandates, social distancing...
- NPIs affect the β parameter in a SIR model
 - We will assume to have constant γ in our setup
- We will focus on making predictions at weekly intervals

Therefore, we can cover our needs with...

For the input part:

■ The initial state (S, I, R) and the value of β

For output part:

lacktriangle The state after one week (S, I, R)

Given an input (S, I, R, β) , we can get the output via simulation

Building Our Dataset

Which input configurations should we generate?

A training set should be representative of the test distribution

- We do not have a fixed test distribution (no test set)
- ...But we know that the ML model will be used by an optimizer

The optimizer will seek to minimize the total infections

So, we will need:

- High accuracy on the best configurations, so as to find them
- High accuracy on the worst configurations, so as to avoid them

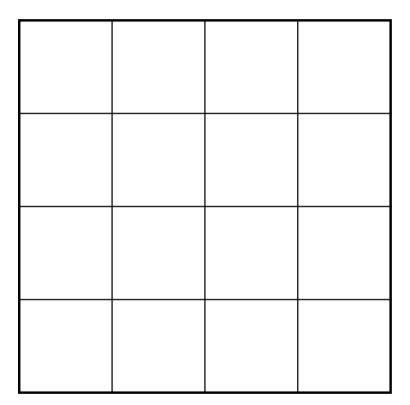
I.e. to be safe the model should work all across the board

Hence, we need a method that can cover well a given input space

- The simplest approach would be use use a regular grid
- ...But that approach does not scale well

The method we will use is called Latin Hypercube Sampling

Suppose we want to sample m points for n attributes with fixed ranges

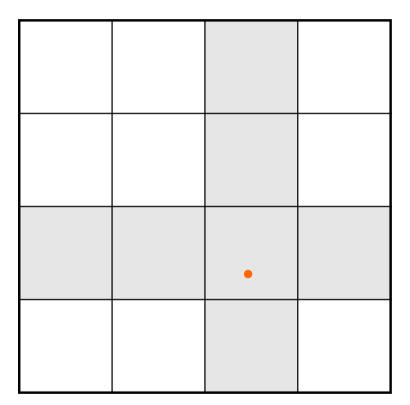


- We can view the sampling space as a hypercube
- ... Then we divide each dimension in n segments

In the example we want to sample 4 points for 2 attributes

The method we will use is called Latin Hypercube Sampling

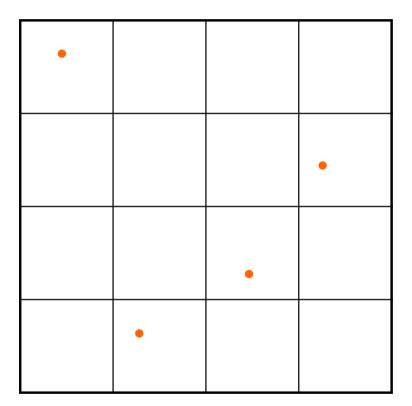
Suppose we want to sample m points for n attributes with fixed ranges



- We sample the first point uniformly at random
- ...Then we "cover" the row and column that contain the sample

The method we will use is called Latin Hypercube Sampling

Suppose we want to sample m points for n attributes with fixed ranges



- When we take additional samples, we exclude all covered row/columns
- ...So we end up with a pattern similar to that of the figure

LHS can cover quite uniformly a given space with relatively few samples

Let's see a practical example

Here is the result of uniform sampling, for reference

```
In [2]: test_nsamples, test_ranges = 12, [(0., 1.), (0., 1.)]
        X = util.sample_points(test_ranges, test_nsamples, mode='uniform', seed=42)
         util.plot_2D_samplespace(X, figsize=figsize)
          0.8
          0.7
          0.6
          0.5
          0.4
          0.3
          0.2
                                0.2
                                                   0.4
                                                           x_1
```

Let's see a practical example

...And here is the result of classical LHS:

```
In [3]: test_nsamples, test_ranges = 12, [(0., 1.), (0., 1.)]
        X = util.sample_points(test_ranges, test_nsamples, mode='lhs', seed=42)
        util.plot_2D_samplespace(X, figsize=figsize)
          0.8
          0.6
          0.4
          0.2
            0.0
                                0.2
                                                                     0.6
                                                          x_1
```

The process can be further improved

E.g. after sampling we can try to maximize the minimum distance

```
In [4]: test_nsamples, test_ranges = 12, [(0., 1.), (0., 1.)]
        X = util.sample_points(test_ranges, test_nsamples, mode='max_min', seed=42)
         util.plot_2D_samplespace(X, figsize=figsize)
          0.8
          0.6
          0.4
          0.2
                             0.2
                                                0.4
                                                                    0.6
                                                                                       0.8
                                                                                                          1.0
                                                           x 1
```

Dataset Input

We are now ready to generate our dataset input

- We sample S, I, R, β from $[0, 1]^3 \times [0, .4]$
- ...Then S, I, R are normalized so that their sum is 1

This will reduce in some redundancy in the dataset

Dataset Output

We obtain the corresponding output via simulation

```
In [6]: %%time
         qamma = 1/14
         sir_tr_out = util.generate_SIR_output(sir_tr_in, gamma, 7)
         sir ts out = util.generate SIR output(sir ts in, gamma, 7)
         sir tr out.head()
         CPU times: user 1.2 s, sys: 53.3 ms, total: 1.25 s
         Wall time: 1.2 s
Out[6]:
         0 0.201814 0.425756 0.372430
          1 0.115945 0.474359 0.409696
         2 0.019150 0.511369 0.469481
          3 0.078295 0.196566 0.725139
          4 0.453265 0.148189 0.398546
```

- We picked $\gamma = 1/14$ (this will be fixed in our use case)
- We simulate one week

Training a Model

We try with Linear Regression

```
In [7]: nn0 = util.build_ml_model(input_size=4, output_size=3, hidden=[], name='LR')
         history0 = util.train_ml_model(nn0, sir_tr_in, sir_tr_out, verbose=0, epochs=100)
         util.plot_training_history(history0, figsize=figsize)
         util.print_ml_metrics(nn0, sir_tr_in, sir_tr_out, 'training')
         util.print ml metrics(nn0, sir ts in, sir ts out, 'test')
          0.175
                                                                                                       val loss
          0.150
          0.125
          0.100
          0.075
          0.050
          0.025
          0.000
                                                  15
                                                                        25
                                                             20
                                                           epochs
         Model loss: 0.0012 (training) 0.0013 (validation)
```

R2: 0.95, MAE: 0.023, RMSE: 0.03 (training)

Training a Model

...And with a shallow Neural Network

R2: 0.99, MAE: 0.0081, RMSE: 0.01 (training)

```
In [8]: nn1 = util.build_ml_model(input_size=4, output_size=3, hidden=[8], name='MLP')
        history1 = util.train_ml_model(nn1, sir_tr_in, sir_tr_out, verbose=0, epochs=100)
        util.plot_training_history(history1, figsize=figsize)
        util.print_ml_metrics(nn1, sir_tr_in, sir_tr_out, 'training')
        util.print_ml_metrics(nn1, sir_ts_in, sir_ts_out, 'test')
         0.05
                                                                                                     val loss
         0.04
         0.03
         0.02
         0.01
         0.00
                           10
                                     20
                                                                                60
                                                                                          70
                                                         epochs
        Model loss: 0.0002 (training) 0.0002 (validation)
```

Considerations and Next Steps

We will save both models for later

```
In [9]: util.save_ml_model(nn0, 'nn0')
util.save_ml_model(nn1, 'nn1')
```

- The network is much better in terms of accuracy
- ...But the Linear Regressor is simpler!

Hence, the approaches provide different trade offs

We are halfway there

We now have our ML model(s)!

- We need to understand how they can be embedded in an optimization model
- ...And we need to define our optimization model itself