

Efficient Algorithm for Mode- k Update in Tensor Completion

Summary

a. Verdict

I have successfully solved the problem. The final answer is a complete algorithm using the Preconditioned Conjugate Gradient (PCG) method to solve the mode- k update efficiently.

b. Method Sketch

The problem requires solving a linear system $\mathcal{A}\text{vec}(W) = \mathbf{b}$ of size $nr \times nr$, where $\mathcal{A} = (Z \otimes K)^T SS^T (Z \otimes K) + \lambda(I_r \otimes K)$.

1. **Implicit Matrix-Vector Multiplication:** We compute the product $\mathcal{A}\text{vec}(W)$ without forming \mathcal{A} . By exploiting the sparsity of the selection matrix S , we calculate the term $(Z \otimes K)^T SS^T (Z \otimes K)\text{vec}(W)$ using a sparse MTTKRP (Matricized Tensor Times Khatri-Rao Product) operation on the q observed entries. The cost is $O(qr + n^2r)$.
2. **Preconditioner:** We approximate the sampling operator SS^T with its expectation ρI_N , where $\rho = q/N$. This yields a structured preconditioner $\mathcal{M} = \rho(Z^T Z \otimes K^2) + \lambda(I_r \otimes K)$.
3. **Efficient Preconditioner Solve:** The system $\mathcal{M}\mathbf{z} = \mathbf{r}$ is equivalent to a generalized Sylvester equation $\rho K^2 W_{\text{new}}(Z^T Z) + \lambda K W_{\text{new}} = R$. We solve this by simultaneously diagonalizing the kernel K and the Gram matrix $Z^T Z$. The cost per iteration is dominated by basis transformations, $O(n^2r)$.

The total complexity per PCG iteration is $O(qr + n^2r)$, which avoids any $O(N)$ computation and is significantly faster than the $O(n^3r^3)$ direct solver.

Detailed Solution

We wish to solve the linear system for the unknown matrix $W \in \mathbb{R}^{n \times r}$:

$$\mathcal{A}\text{vec}(W) = \mathbf{b},$$

where the system matrix and right-hand side are defined as:

$$\mathcal{A} = (Z \otimes K)^T S S^T (Z \otimes K) + \lambda(I_r \otimes K), \quad \mathbf{b} = (I_r \otimes K) \text{vec}(B).$$

Here, n is the size of mode k , r is the rank, q is the number of observed entries, and $K \in \mathbb{R}^{n \times n}$ is the positive semi-definite RKHS kernel matrix. The matrix $S S^T$ is a diagonal matrix of size $N \times N$ (where $N = \prod n_i$) with ones at indices corresponding to observed entries and zeros otherwise.

Since \mathcal{A} is symmetric and positive definite (assuming $\lambda > 0$ and K is positive definite), we use the Preconditioned Conjugate Gradient (PCG) method. The efficiency of PCG depends on two components: a fast matrix-vector multiplication and an effective preconditioner.

1. Efficient Matrix-Vector Multiplication

We need to compute $\mathbf{y} = \mathcal{A}\mathbf{x}$ for an arbitrary vector $\mathbf{x} = \text{vec}(W)$ efficiently. The operation decomposes into two terms:

$$\mathbf{y} = \underbrace{(Z \otimes K)^T S S^T (Z \otimes K) \text{vec}(W)}_{\text{Term 1}} + \underbrace{\lambda(I_r \otimes K) \text{vec}(W)}_{\text{Term 2}}.$$

Computing Term 2: Using the identity $\text{vec}(AXB) = (B^T \otimes A) \text{vec}(X)$, we have:

$$\lambda(I_r \otimes K) \text{vec}(W) = \text{vec}(\lambda KW).$$

Computing KW costs $O(n^2r)$.

Computing Term 1:

1. **Forward Projection:** First, compute $(Z \otimes K) \text{vec}(W) = \text{vec}(KWZ^T)$.

Let $U = KW \in \mathbb{R}^{n \times r}$. The full product UZ^T is an $n \times M$ matrix, which is too large to form explicitly ($M \approx N/n$).

However, the matrix $S S^T$ selects only the entries corresponding to the observed set Ω . Let \mathcal{V} be the sparse matrix containing the values of UZ^T at indices in Ω :

$$\mathcal{V}_{i,\mu} = \begin{cases} (UZ^T)_{i,\mu} & \text{if } (i, \mu) \in \Omega \\ 0 & \text{otherwise} \end{cases}$$

For each observed entry indexed by $(i, \mu) \in \Omega$, we compute the dot product of the i -th row of U and the μ -th row of Z :

$$\mathcal{V}_{i,\mu} = \sum_{j=1}^r U_{i,j} Z_{\mu,j}.$$

Note that $Z_{\mu,j}$ corresponds to the row of the Khatri-Rao product associated with the multi-index of the other modes.

Cost: $O(qr)$.

2. **Backward Projection:** We now compute $(Z \otimes K)^T \text{vec}(\mathcal{V}) = (Z^T \otimes K) \text{vec}(\mathcal{V})$.

Using the vectorization property again, this is $\text{vec}(K\mathcal{V}Z)$.

Let $Y = \mathcal{V}Z \in \mathbb{R}^{n \times r}$. Since \mathcal{V} is sparse, we compute Y using a sparse MTTKRP operation:

$$Y_{i,j} = \sum_{\mu:(i,\mu) \in \Omega} \mathcal{V}_{i,\mu} Z_{\mu,j}.$$

Cost: $O(qr)$.

3. **Final Multiplication:** Compute KY .

Cost: $O(n^2r)$.

Total MatVec Algorithm:

1. $U \leftarrow KW$ ($O(n^2r)$).
2. Calculate sparse values \mathcal{V} on Ω using U and Z ($O(qr)$).
3. Calculate $Y \leftarrow \mathcal{V}Z$ ($O(qr)$).
4. Result $\leftarrow \text{vec}(K(Y + \lambda W))$ ($O(n^2r)$).

Total Complexity: $O(qr + n^2r)$.

2. Preconditioner Design

The matrix \mathcal{A} is ill-conditioned and unstructured due to SS^T . We construct a preconditioner \mathcal{M} by approximating SS^T with a scaled identity matrix. Assuming the observed entries are sampled uniformly at random with probability $\rho = q/N$, we have $\mathbb{E}[SS^T] = \rho I_N$. Replacing SS^T with ρI_N in \mathcal{A} :

$$\mathcal{M} = \rho(Z \otimes K)^T(Z \otimes K) + \lambda(I_r \otimes K).$$

Using the mixed-product property $(A \otimes B)(C \otimes D) = (AC \otimes BD)$:

$$(Z \otimes K)^T(Z \otimes K) = (Z^T Z \otimes K^T K) = (Z^T Z \otimes K^2).$$

Thus, the preconditioner is:

$$\mathcal{M} = \rho(Z^T Z \otimes K^2) + \lambda(I_r \otimes K).$$

3. Solving the Preconditioner System

In each PCG iteration, we solve $\mathcal{M}\mathbf{z} = \mathbf{r}_k$, where $\mathbf{z} = \text{vec}(W_{new})$ and $\mathbf{r}_k = \text{vec}(R)$. The equation is:

$$\rho(Z^T Z \otimes K^2) \text{vec}(W_{new}) + \lambda(I_r \otimes K) \text{vec}(W_{new}) = \text{vec}(R).$$

In matrix form:

$$\rho K^2 W_{new} (Z^T Z) + \lambda K W_{new} = R.$$

Let $G = Z^T Z \in \mathbb{R}^{r \times r}$. This is the Hadamard product of the Gram matrices of the other modes.

$$\rho K^2 W_{new} G + \lambda K W_{new} = R.$$

To solve this efficiently, we use the eigendecompositions of K and G .

1. Spectral Decompositions (Precomputed):

- $K = U_K \Sigma_K U_K^T$, where $\Sigma_K = \text{diag}(\sigma_1, \dots, \sigma_n)$.
- $G = Q_G \Lambda_G Q_G^T$, where $\Lambda_G = \text{diag}(\gamma_1, \dots, \gamma_r)$.
- Setup Cost: $O(n^3 + r^3)$.

2. Diagonalization Step:

Substitute the decompositions into the Sylvester equation. Let $\tilde{W} = U_K^T W_{new} Q_G$ and $\tilde{R} = U_K^T R Q_G$. Multiplying the equation by U_K^T from the left and Q_G from the right, and using $K^2 = U_K \Sigma_K^2 U_K^T$:

$$\rho \Sigma_K^2 \tilde{W} \Lambda_G + \lambda \Sigma_K \tilde{W} = \tilde{R}.$$

This system is diagonal. For each element (i, j) :

$$(\rho \sigma_i^2 \gamma_j + \lambda \sigma_i) \tilde{W}_{ij} = \tilde{R}_{ij}.$$

We solve for \tilde{W}_{ij} :

$$\tilde{W}_{ij} = \frac{\tilde{R}_{ij}}{\sigma_i(\rho \sigma_i \gamma_j + \lambda)}.$$

(If $\sigma_i = 0$, we set $\tilde{W}_{ij} = 0$ assuming R is in the range of K).

3. Reconstruction:

Recover $W_{new} = U_K \tilde{W} Q_G^T$.

Preconditioner Solve Complexity:

- Compute \tilde{R} : $O(n^2 r + n r^2)$.
- Element-wise division: $O(nr)$.
- Compute W_{new} : $O(n^2 r + n r^2)$.
- Total per iteration: $O(n^2 r)$.

4. Complexity Analysis

Let k_{iter} be the number of PCG iterations.

- **Setup:** $O(n^3)$ to diagonalize K and G .
- **Per Iteration:**
 - MatVec: $O(qr + n^2r)$.
 - Preconditioner Solve: $O(n^2r)$.
- **Total Complexity:** $O(n^3 + k_{iter}(qr + n^2r))$.

Given $n, r < q \ll N$, this approach is highly efficient and avoids any computation scaling with the full tensor size N .

References

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