

$$CC_t = \begin{bmatrix} p_t \\ v_t \end{bmatrix} = \begin{bmatrix} p_{t-1} + v_{t-1} \Delta t = 1 \\ v_{t-1} \end{bmatrix} = \begin{bmatrix} p_{t-1} + v_{t-1} \\ v_{t-1} \end{bmatrix}$$

$$= M CC_{t-1} = M \begin{bmatrix} p_{t-1} \\ v_{t-1} \end{bmatrix}$$

$$\Rightarrow M = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$\Rightarrow M CC_{t-1} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} p_{t-1} \\ v_{t-1} \end{bmatrix} = \begin{bmatrix} p_{t-1} + v_{t-1} \\ v_{t-1} \end{bmatrix}$$

$$CC_t = M CC_{t-1}$$

$$CC_t \sim N(M CC_{t-1}, \sigma_{cc}^2)$$

Initial CC

$$CC_0 \sim N(\mu_{CC_0}, \sigma_{CC}^2)$$

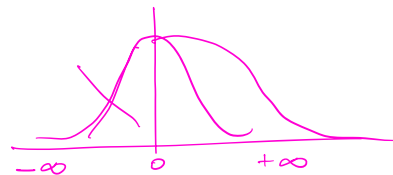
mean-CC
 Sd-CC

$$\mu_{CC} \sim N(\mu_{\mu_{CC_0}}, \sigma_{\mu_{CC_0}}^2)$$

Trainable
 Fixed Fixed
 Hyper-prior distribution

$$\sigma_{CC} \sim HN(\sigma_{\sigma_{CC}})$$

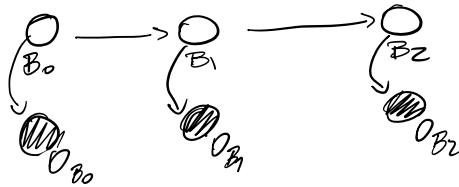
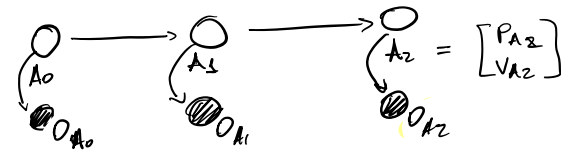
Trainable
 Fixed



Sd-Sd-CC

Latent System component

No coordination



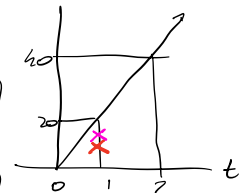
$$A_t = \begin{bmatrix} P_{A_{t-1}} + V_{A_{t-1}} \\ V_{A_{t-1}} \end{bmatrix}$$

$$F_{A_t} = P_{A_t}$$

$$A_0 = \begin{bmatrix} 0 \\ 20 \end{bmatrix}$$

$$A_1 = \begin{bmatrix} 20 \\ 20 \end{bmatrix}$$

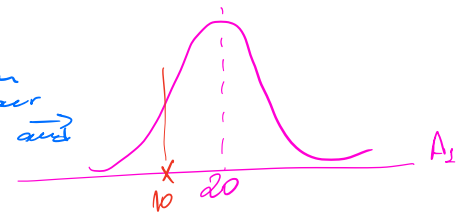
$$A_2 = \begin{bmatrix} 40 \\ 20 \end{bmatrix}$$



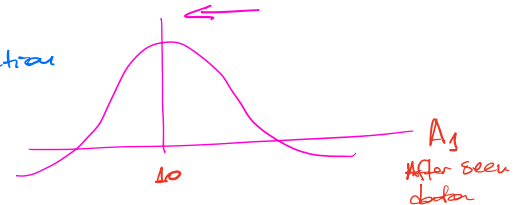
$$O_1 = \begin{bmatrix} 10 \end{bmatrix}$$

$$A_1 = N\left(\begin{bmatrix} 20 \\ 20 \end{bmatrix}, \frac{\sigma_{cc}}{2}\right)$$

Expectation based on our assumptions and dynamics

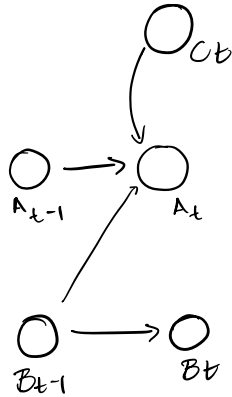


Correction



$$O_t \approx N(A_t, \frac{\sigma_o^2}{2})$$

with coordination



No coordination

$$A_t = \begin{bmatrix} P_{A_{t-1}} + V_{A_{t-1}} \\ V_{A_{t-1}} \end{bmatrix}$$

w/ coordination

$$A_t = \begin{bmatrix} P_{A_{t-1}} + V_{A_{t-1}} \\ (1-c_t)V_{A_{t-1}} + c_t V_{B_{t-1}} \end{bmatrix}$$

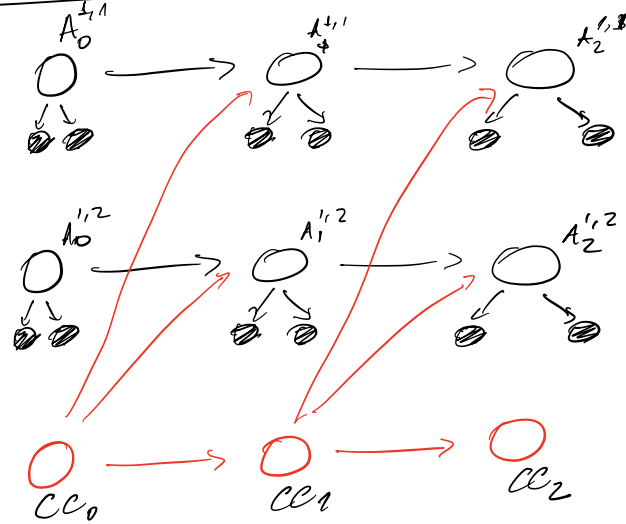
$$A_t = U A_{t-1} + F B_{t-1}$$

$$A_t = \begin{bmatrix} 1 & 1 \\ 0 & (1-c_t) \end{bmatrix} A_{t-1} + \begin{bmatrix} 0 & 0 \\ 0 & c_t \end{bmatrix} B_{t-1}$$

$$O_{A_t} = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} P_{A_t} \\ V_{A_t} \end{bmatrix} = P_{A_t}$$

$$O_{A_t} = \begin{bmatrix} 1 & 0 \\ \vdots & \vdots \\ 1 & 0 \end{bmatrix} \begin{bmatrix} P_{A_t} \\ V_{A_t} \end{bmatrix} = \begin{bmatrix} P_{A_t} \\ \vdots \\ P_{A_t} \end{bmatrix} \quad \left. \vphantom{\begin{bmatrix} P_{A_t} \\ \vdots \\ P_{A_t} \end{bmatrix}} \right\} \text{\# channels}$$

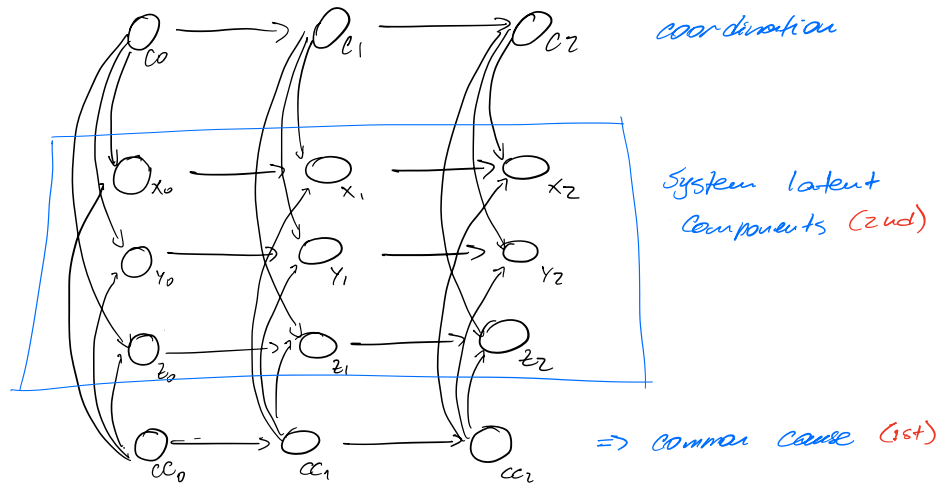
Adding the common cause



w/ coordination and common cause

$$A_t = \begin{bmatrix} PA_{t-1} + VA_{t-1} \\ (1-c_t)VA_{t-1} + c_t \cancel{VA_{t-1}} \end{bmatrix}$$

VA_t



1st test case

$$P(cc_0, cc_1, cc_2) = P(cc_0) P(cc_1 | cc_0) P(cc_2 | cc_1)$$

$$\log P = \log P(cc_0) + \log P(cc_1 | cc_0) + \log P(cc_2 | cc_1)$$

2nd test case

$$P(x_{0:2}, y_{0:2}, z_{0:2}) = P(x_0 | c_0, cc_0) P(y_0 | c_0, cc_0) P(z_0 | c_0, cc_0)$$

$$P(x_1 | x_0, cc_1, c_1) P(y_1 | x_0, cc_1, c_1) P(z_1 | z_0, cc_1, c_1)$$

$$P(x_2 | x_1, cc_2, c_2) P(y_2 | x_1, cc_2, c_2) P(z_2 | z_1, cc_2, c_2)$$

$$P(x_0 | c_0, cc_0) = N(c_0 cc_0 + (1 - c_0) \mu_x, \sigma_A^2)$$

$$P(x_1 | c_1, cc_1) = N(c_1 cc_1 + (1 - c_1) x_0, \sigma_A^2)$$

$$P(x_t | c_t, cc_t) = N(c_t cc_t + (1 - c_t) x_{t-1}, \sigma_A^2)$$

$$\begin{aligned}
p(x_1 | c_1, cc_1^{x_0}) &= p\left(\begin{bmatrix} x_1^p \\ x_1^v \end{bmatrix} \middle| c_1, \begin{bmatrix} cc_1^p \\ cc_1^v \end{bmatrix}, \begin{bmatrix} x_0^p \\ x_0^v \end{bmatrix}\right) \\
&= p\left(\begin{bmatrix} x_1^p \\ x_1^v \end{bmatrix} \middle| \begin{bmatrix} x_0^p + x_0^v \\ (1-c_1)x_0^v + c_1 cc_1^v \end{bmatrix}\right) \\
&= p\left(\begin{bmatrix} x_1^p \\ x_1^v \end{bmatrix} \middle| \underbrace{\begin{bmatrix} 1 & 1 \\ 0 & (1-c_1) \end{bmatrix}}_{\substack{\mathbb{F} = \begin{bmatrix} 1 & 1 \\ 0 & \frac{1}{\gamma} \end{bmatrix}}} \begin{bmatrix} x_0^p \\ x_0^v \end{bmatrix} + \underbrace{\begin{bmatrix} 0 & 0 \\ 0 & c_1 \end{bmatrix}}_U \begin{bmatrix} cc_1^p \\ cc_1^v \end{bmatrix}\right)
\end{aligned}$$