



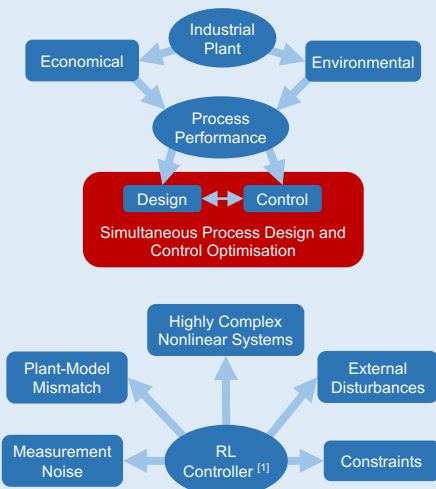
Simultaneous Process Design and Control Optimisation using Reinforcement Learning

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IMPORTANCE



OBJECTIVES

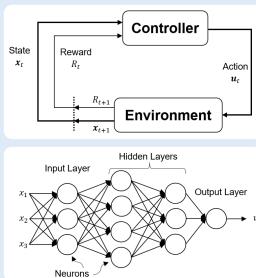
1. Propose a new approach using reinforcement learning (**policy gradient**).
2. Showcase the control performance using two case studies from [2].

METHODOLOGY

Formulate bi-level problem

$$\begin{aligned} \min_{\mathbf{p}} C_p(\mathbf{p}) + \kappa C_u(\mathbf{x}(t), \mathbf{y}(t), \mathbf{u}(t), \mathbf{p}, \theta^p(t)) \\ \text{s.t. } f_p(\mathbf{p}, \theta^p(t)) = 0 \\ g_p(\mathbf{p}, \theta^p(t)) \leq 0 \\ \min_{\mathbf{u}(t)} C_u(\mathbf{x}(t), \mathbf{y}(t), \mathbf{u}(t), \mathbf{p}, \theta^p(t)) \\ \text{s.t. } \dot{\mathbf{x}} = f_u(\mathbf{x}(t), \mathbf{y}(t), \mathbf{u}(t), \mathbf{p}, \theta^p(t)) \\ g_u(\mathbf{x}(t), \mathbf{y}(t), \mathbf{u}(t), \mathbf{p}, \theta^p(t)) = 0 \\ h_u(\mathbf{x}(t), \mathbf{y}(t), \mathbf{u}(t), \mathbf{p}, \theta^p(t)) \leq 0 \end{aligned}$$

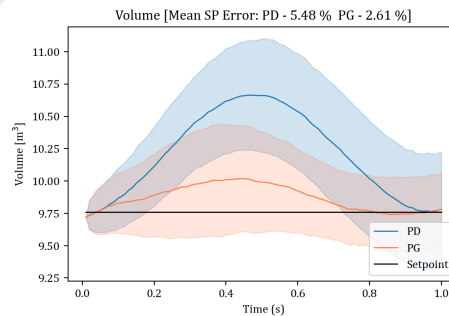
Prepare controller



Solve the bi-level problem

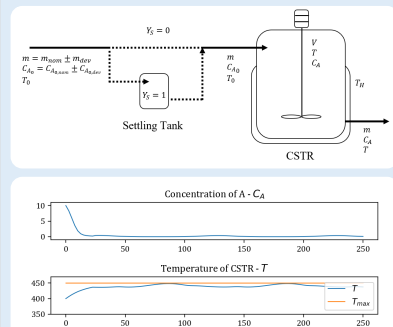
$$\mathbf{u}_t = \pi_\theta(\mathbf{x}_t^{obs}, \mathbf{x}_{t-1}^{obs}, \mathbf{y}_t^{obs}, \mathbf{y}_{t-1}^{obs}, \mathbf{p}^{obs}) \forall t$$

CASE STUDY 1: Tank



- Disturbance on inlet flow.
- **OCF**: Maintain **dynamic** setpoint.
- **Design**: Maximum flow **disturbance**.

CASE STUDY 2: CSTR



- Minimise reactant concentration.
- **OCF**: **Constrained** control.
- **Design**: Cost related optimisation with **binary decision making**.

CONCLUSIONS

Control Performance ✓

Constraints ✓

High Non-linearity [2] ✓

Bi-linear Problem ✓

REFERENCES

- [1] Petsagkourakis, P., et al. (2020) Reinforcement learning for batch bioprocess optimization. Computers & Chemical Engineering. [Online] 133, 106649. Available from: doi:10.1016/j.compchemeng.2019.106649.
- [2] Diangelakis, N.A., et al. (2017) Process design and control optimization: A simultaneous approach by multi-parametric programming. AIChE Journal. [Online] 63 (11), 4827–4846. Available from: doi:10.1002/aic.15825.