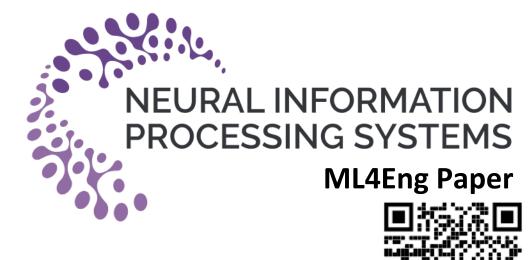


# On the Effectiveness of Bayesian AutoML methods for Physics Emulators

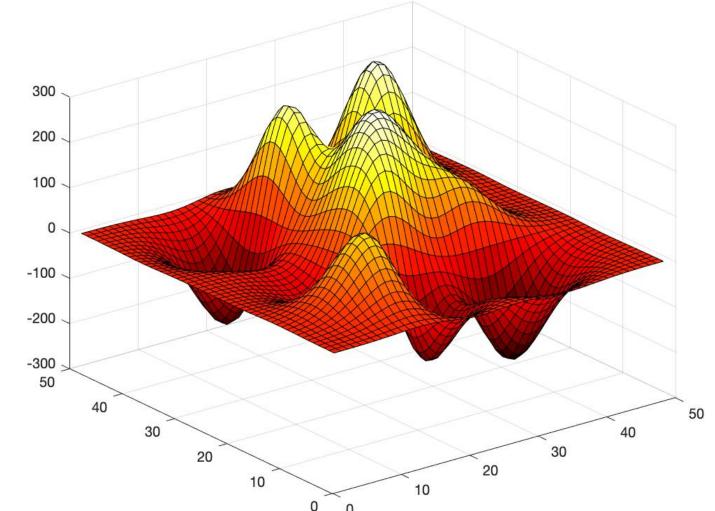






## Motivation

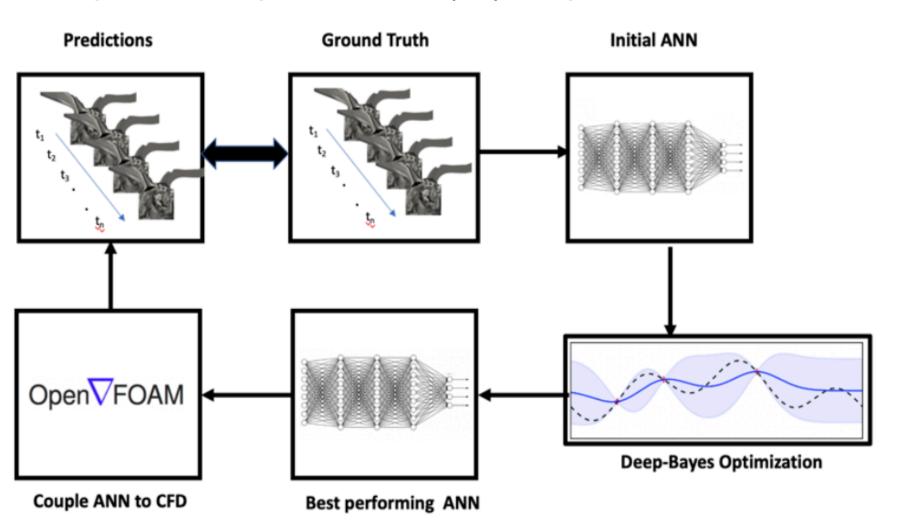
- Scientific data is often high-dimensional, complex, structured, sparse → Complicated loss manifold!
- Best practices in setting up network/hyperparameters translate poorly to scientific data
- Automatic ML methods are promising alternative to robustly train DNNs!



A translating, scaling Gaussian distribution-based loss manifold shows many peaks/troughs

### Workflow

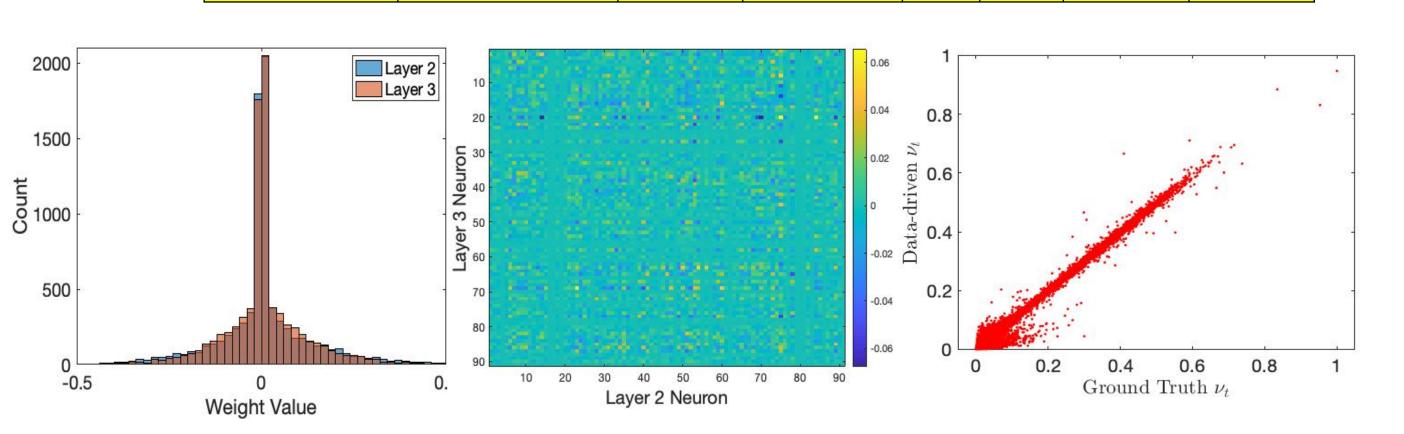
- Bayesian Optimization based AutoML explores parameter space to identify best performing settings, starting with an initial guess
- BayesOpt modeled as Gaussian Process (GP) with Expected Improvement (EI) acquisition function



Workflow for AutoML for a physics emulation task. While the final goal of this work is to incorporate machine-learnt model to non-linear PDE solver OpenFOAM, this study will limit to understanding the learning process

## Results

| Optimizer | Initialization | Batch<br>Size | LR       | W  | D  | æ     | N     |
|-----------|----------------|---------------|----------|----|----|-------|-------|
| ADAM      | Glorot         | 1426          | 9.56e-04 | 91 | 10 | 1e-05 | 84904 |
| ADAM      | He             | 12719         | 3.77e-04 | 50 | 7  | 2e-04 | 18207 |
| SGDM      | Glorot         | 6814          | 0.0098   | 91 | 9  | 2e-03 | 75812 |
| SGDM      | He             | 1161          | 0.0098   | 89 | 6  | 1e-03 | 48778 |
| RMSProp   | Glorot         | 291           | 1e-04    | 78 | 4  | 8e-04 | 25432 |
| RMSProp   | He             | 11630         | 1.86e-05 | 55 | 9  | 1e-03 | 28004 |



### **Weight Space Similarity**

Network checkpointed after every epoch

$$\cos(\theta_1, \theta_2) = \frac{\theta_2 \theta_1^T}{\|\theta_2\| \|\theta_1\|}$$

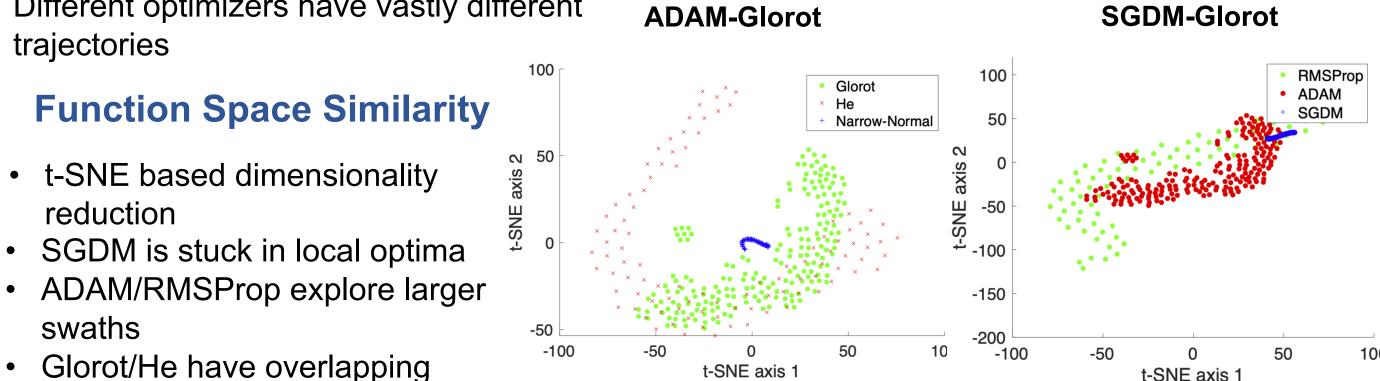
t-SNE based dimensionality

SGDM is stuck in local optima

reduction

swaths

Self-similar training evolution Different optimizers have vastly different trajectories

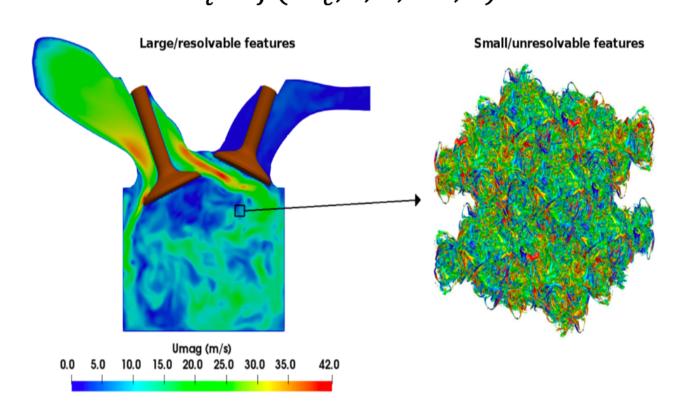


#### Glorot/He have overlapping exploration TL;DR

- AutoML methods are successfully in robustly identifying best performing settings for a complicated physics problem
- Network training evolution is heavily dependent on choice of optimizers, adaptive LR optimizers outperform
- Layer-by-Layer learnt weight comparisons reveals complicated nature of network learning

## **Physics**

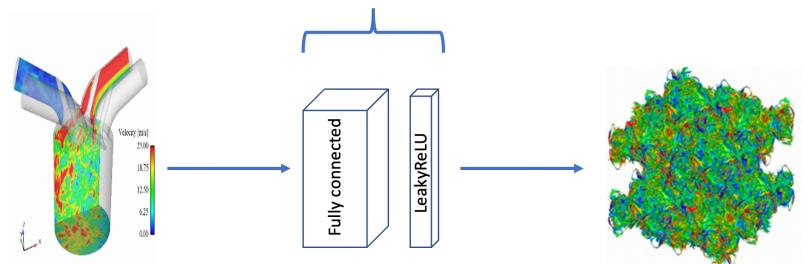
- Accurate turbulence closure is critically important for LES models
- Most methods involve some form of data-fitting, so why not a purely data-driven method!
- Eddy viscosity modeled as a function of large scale filtered variables  $\nu_t = f(Re_c, S, \Omega, VK, Y)$



ature of a typical Internal Combustion Engine (ICE) simulation. Adopted from Dias Riberio et al

## **Network Architecture Search**

NAS, Including optimize for weight initialization and solver D repetitions of layer blocks



W width of network

| <b>Hyper-parameter</b> | Min. Range | Max. Range | Interpolation |
|------------------------|------------|------------|---------------|
| Initial LR             | 1e-6       | 1e-2       | Logarithmic   |
| LR Drop Factor         | 10         | 1000       | Integer       |
| Batch Size             | 100        | 16000      | Logarithmic   |
| Network Depth          | 2          | 10         | Integer       |
| Network Width          | 10         | 100        | Integer       |

#### References

Dias Ribeiro, Mateus, Alex Mendonça Bimbato, Maurício Araújo Zanardi, José Antônio Perrella Balestieri, and David P. Schmidt. "Large-eddy simulation of the flow in a direct injection spark ignition engine using an open-source framework." International Journal of Engine Research (2020): 1468087420903622. Marge Simpson (2010).

#### **Acknowledgements**









