1 EchoSafeletExecuter

```
1 package scjlevel2examples.echo;
3 import javax.safetycritical.Safelet;
 4 import javax.safetycritical.SafeletExecuter;
   //Application\ entry\ point\,,\ runs\ the\ Safelet
   public class EchoSafeletExecuter extends SafeletExecuter
8
9
      public EchoSafeletExecuter(Safelet arg0)
10
11
        \mathbf{super}(\arg 0);
12
13
14
      public static void main (String [] args)
15
16
        System.out.println("EchoSafeletExecuter");
//Run the safelet which starts the whole application
EchoSafeletExecuter.run(new EchoApplication());
17
18
19
20
21 }
```

2 EchoApplication

```
package scjlevel2examples.echo;
3 import javax.realtime.PriorityParameters;
  import javax.safetycritical.*;
  import javax.safetycritical.annotate.Level;
  public class EchoApplication implements Safelet
8
9
    @Override
10
    public Level getLevel()
11
12
13
       return Level.LEVEL_2;
14
15
    @Override
16
    public MissionSequencer getSequencer()
17
18
       System.out.println("EchoApplication");
19
20
       //Create and return the main mission sequencer
       return new EchoMissionSequencer(new PriorityParameters(5),
21
           new StorageConfigurationParameters(1048576, 1048576, 1048576));
22
23
24
25
    @Override\\
26
    public void setup()
27
28
29
30
    @Override\\
    public void teardown()
31
32
33
34
35
36 }
```

3 EchoMissionSequencer

```
package scjlevel2examples.echo;
3 import javax.realtime.PriorityParameters;
  import javax.safetycritical.Mission;
  import javax.safetycritical.MissionSequencer;
6 import javax.safetycritical.StorageConfigurationParameters;
9
   public class EchoMissionSequencer extends MissionSequencer
10
11
     private boolean returnedMission;
12
13
     public EchoMissionSequencer (PriorityParameters priorityParameters,
         Storage Configuration Parameters\ storage Configuration Parameters)
14
15
       super(priorityParameters , storageConfigurationParameters);
16
17
       returnedMission =false;
18
19
20
     @Override\\
21
     protected Mission getNextMission()
22
23
       System.out.println("EchoMissionSequencer");
24
25
       //As this sequencer only delivers one mission,
26
       //if it has not been returned yet then return it,
       //else return null which will terminate the sequencer
27
28
29
       if (!returnedMission)
30
         System.out.println("EchoMissionSequencer returns mission");
31
         returned Mission = true;
32
         return new EchoMission();
33
34
35
       else
36
37
         return null;
38
39
40
41
42
43 }
```

4 EchoMission

```
package scjlevel2examples.echo;
 3 import javax.realtime.PeriodicParameters;
 4\big|\,\mathbf{import}\,\,\,\mathbf{javax}\,.\,\mathbf{realtime}\,.\,\mathbf{PriorityParameters}\,;
  import javax.realtime.RelativeTime;
 6 import javax.safetycritical.Mission;
  import javax.safetycritical.PriorityScheduler;
  import javax.safetycritical.StorageConfigurationParameters;
10
   public class EchoMission extends Mission
11
12
     private volatile String buffer;
13
14
15
     @Override
     protected void initialize()
16
17
18
       //start the two submission sequencers, note a reference to this object is
            passed to both so that they can access the buffer
19
       EchoInputMissionSequencer\ echoInputMissionSequencer\ =\ \textbf{new}
            EchoInputMissionSequencer (new PriorityParameters (5),
20
                             new StorageConfigurationParameters (1048576, 1048576,
                                  1048576), this);
21
       EchoOutput Mission Sequencer \ echoOutput Mission Sequencer \ = \ \textbf{new}
22
            EchoOutput Mission Sequencer \  \, (\textbf{new} \  \, Priority Parameters \, (5) \, ,
23
                               new StorageConfigurationParameters (1048576, 1048576,
                                    1048576), this);
       buffer = "These are words in the buffer"; //though they are never read
24
25
26
       System.out.println("EchoMission");
27
28
29
     public void put(String words)
30
       buffer \, = \, words \, ;
31
32
33
34
     public String get()
35
36
       return buffer;
37
38
     @Override\\
39
40
     public long missionMemorySize()
41
       return 100000;
42
43
44
45
```

${\bf 5} \quad {\bf EchoInput Mission Sequencer}$

```
package scjlevel2examples.echo;
3 import javax.realtime.PriorityParameters;
  import javax.safetycritical.Mission;
  import javax.safetycritical.MissionSequencer;
  import javax.safetycritical.StorageConfigurationParameters;
9
   public class EchoInputMissionSequencer extends MissionSequencer
10
11
     private boolean returnedMission;
     private final EchoMission echoMission;
12
13
     public EchoInputMissionSequencer(PriorityParameters priorityParameters ,
14
15
         Storage Configuration Parameters\ storage Configuration Parameters\ ,\ Echo Mission
             echoMission)
16
17
       super(priorityParameters , storageConfigurationParameters);
       returnedMission = false;
18
19
       \mathbf{this}.\ \mathtt{echoMission}\ =\ \mathtt{echoMission}\ ;
20
       System.out.println("EchoInputMissionSequencer constructor");
21
22
23
     @Override
24
     protected Mission getNextMission()
25
26
       System.out.println("EchoInputMissionSequencer getNextMission");
27
       /\!/As \ this \ sequencer \ only \ delivers \ one \ mission \, ,
28
29
       //if it has not been returned yet then return it,
       //else return null which will terminate the sequencer
30
31
32
       if (!returnedMission)
33
       {
34
         System.out.println("EchoInputMissionSequencer returns mission");
35
         returned Mission = true;
36
         return new EchoInputMission(echoMission);
37
38
39
40
         return null;
41
42
     }
43
```

6 EchoInputMission

```
package scjlevel2examples.echo;
3 import javax.realtime.PeriodicParameters;
4 import javax.realtime.PriorityParameters;
  import javax.realtime.RelativeTime;
6 import javax.safetycritical.Mission;
  import javax.safetycritical.PriorityScheduler;
  import javax.safetycritical.StorageConfigurationParameters;
10
11
   public class EchoInputMission extends Mission
12
13
     private final EchoMission echoMission;
14
15
     public EchoInputMission(EchoMission echoMission)
16
17
       super();
18
       this.echoMission= echoMission;
19
20
21
     protected void initialize()
22
23
24
       //Start this mission's handler
       EchoInputter echoInputter = new EchoInputter (new PriorityParameters (10),
25
26
           new PeriodicParameters (new RelativeTime (100, 0)),
27
           new StorageConfigurationParameters(1000, 1000, 1000),
28
           1000,
29
           echoMission);
30
31
32
33
     @Override
34
     public long missionMemorySize()
35
36
       \textbf{return} \quad 100000;
37
38
39
```

7 EchoInputter

```
package scjlevel2examples.echo;
3 import javax.realtime.PeriodicParameters;
4\big|\,\mathbf{import}\,\,\,\mathbf{javax}\,.\,\mathbf{realtime}\,.\,\mathbf{PriorityParameters}\,;
  import javax.safetycritical.PeriodicEventHandler;
6 import javax.safetycritical.StorageConfigurationParameters;
  import java.io.*;
10
11
   public class EchoInputter extends PeriodicEventHandler
12
13
     private final EchoMission echoMission;
14
     private int i;
     15
16
17
18
19
20
     \textbf{public} \ \ EchoInputter (Priority Parameters \ priority \ , \ Periodic Parameters \ periodic \ ,
21
         StorageConfigurationParameters storage, long size, EchoMission echoMission)
22
23
       super(priority , periodic , storage , size);
24
25
       this.echoMission = echoMission;
26
       i = 0;
27
28
29
     @Override\\
     public void handleEvent()
30
31
       /\!/Put the next word from the array into the buffer in the main mission (
32
           EchoMission)
33
       echoMission.put(words[i]);
34
       //if the end of the array has been reached, reset the index; else increment the
35
36
       if(i < 18)
37
38
         i = i+1;
39
40
       else
41
         i = 0;
42
43
44
45
46 }
```

8 EchoOutputMissionSequencer

```
package scjlevel2examples.echo;
 3 import javax.realtime.PriorityParameters;
  import javax.safetycritical.Mission;
   import javax.safetycritical.MissionSequencer;
  {\bf import} \ \ javax.\ safety critical.\ Storage Configuration Parameters;
9
   public class EchoOutputMissionSequencer extends MissionSequencer
10
11
     private boolean returnedMission;
     private final EchoMission echoMission;
12
13
     \textbf{public} \hspace{0.2cm} \textbf{EchoOutputMissionSequencer} (\hspace{0.2cm} \textbf{PriorityParameters} \hspace{0.2cm} \textbf{priorityParameters} \hspace{0.2cm},
14
15
          Storage Configuration Parameters\ storage Configuration Parameters\ ,\ Echo Mission
               echoMission)
16
17
       super(priorityParameters , storageConfigurationParameters);
        returnedMission = false;
18
19
        \mathbf{this}.\ \mathtt{echoMission}\ =\ \mathtt{echoMission}\ ;
20
        System.out.println("EchoOutputMissionSequencer constructor");
21
22
23
     @Override
24
     protected Mission getNextMission()
25
26
        System.out.println(" EchoOutputMissionSequencer getNextMission");
27
        /\!/As\ this\ sequencer\ only\ delivers\ one\ mission\,,
28
29
        //if it has not been returned yet then return it,
        //else return null which will terminate the sequencer
30
        if (!returned Mission)
31
32
          System.out.println("EchoOutputMissionSequencer returns mission");
33
34
          returned Mission = true;
          return new EchoOutputMission(echoMission);
35
36
37
        else
38
39
          return null;
40
41
42
43
```

9 EchoOutputMission

```
package scjlevel2examples.echo;
3 import javax.realtime.PeriodicParameters;
4 import javax.realtime.PriorityParameters;
  import javax.realtime.RelativeTime;
6 import javax.safetycritical.Mission;
  import javax.safetycritical.PriorityScheduler;
  import javax.safetycritical.StorageConfigurationParameters;
10
   public class EchoOutputMission extends Mission
11
12
13
     private final EchoMission echoMission;
14
15
     public EchoOutputMission(EchoMission echoMission)
16
17
       super();
18
       this.echoMission= echoMission;
19
20
21
     protected void initialize()
22
23
24
       //Start this mission's handler
       EchoOutputter echoOutputter = new EchoOutputter(new PriorityParameters(10),
25
26
           new Periodic Parameters (new Relative Time (100, 0)),
27
           new StorageConfigurationParameters(1000, 1000, 1000),
28
           1000,
29
           echoMission);
30
31
32
33
     @Override
34
     public long missionMemorySize()
35
36
       \textbf{return} \quad 100000;
37
38
39
```

10 EchoOutputter

```
package scjlevel2examples.echo;
 3 import javax.realtime.PeriodicParameters;
 4 import javax.realtime.PriorityParameters;
   import javax.safetycritical.PeriodicEventHandler;
 6 import javax.safetycritical.StorageConfigurationParameters;
9
   {\bf public\ class\ EchoOutputter\ extends\ PeriodicEventHandler}
10
11
      private final EchoMission echoMission;
12
      \begin{array}{ll} \textbf{public} \;\; E choOutputter (\,PriorityParameters \;\; priority \;, \;\; PeriodicParameters \;\; periodic \;, \\ StorageConfigurationParameters \;\; storage \;, \;\; \textbf{long} \;\; size \;, \;\; E choMission \;\; echoMission \;) \end{array}
13
14
15
16
         super(priority , periodic , storage , size);
17
         this.echoMission = echoMission;
18
19
      }
20
21
      @Override\\
      public void handleEvent()
22
23
24
         //Print the contents of the buffer
         System.out.println(echoMission.get());
25
26
27
28
29 }
```