

COMBINATORIAL TESTING

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PLAN

- > Need for testing and verification
- > Combinatorial testing
- >Test example
- > Model checking
- > State space explosion







NEED FOR TESTING & VERIFICATION

- > The Ariane 5 rocket exploded on June 4, 1996, less than forty seconds after it was launched.
- > The investigation committee found a software error in the computer responsible to calculate movement.
- > An exception occurred when a large 64-bit floating point number was converted to a 16-bit integer.
- > This conversion was not protected by code for handling exceptions and caused the computer to fail, incorrect attitude data was transmitted.



NEED FOR TESTING & VERIFICATION

- > No longer feasible to shut down a malfunctioning system in order to restore it.
- > Systems need to be analyzed not only for compiling and static errors.
- > The principal validation methods for complex systems are simulation, testing, and verification (model checking, deduction).



NEED FOR TESTING & VERIFICATION

- > The analysis is expensive to be performed on the actual software.
- > Huge state space, combinatorial explosion
- > Combining different techniques to achieve V&V: Cheap to expensive (small hummer, big hummer)

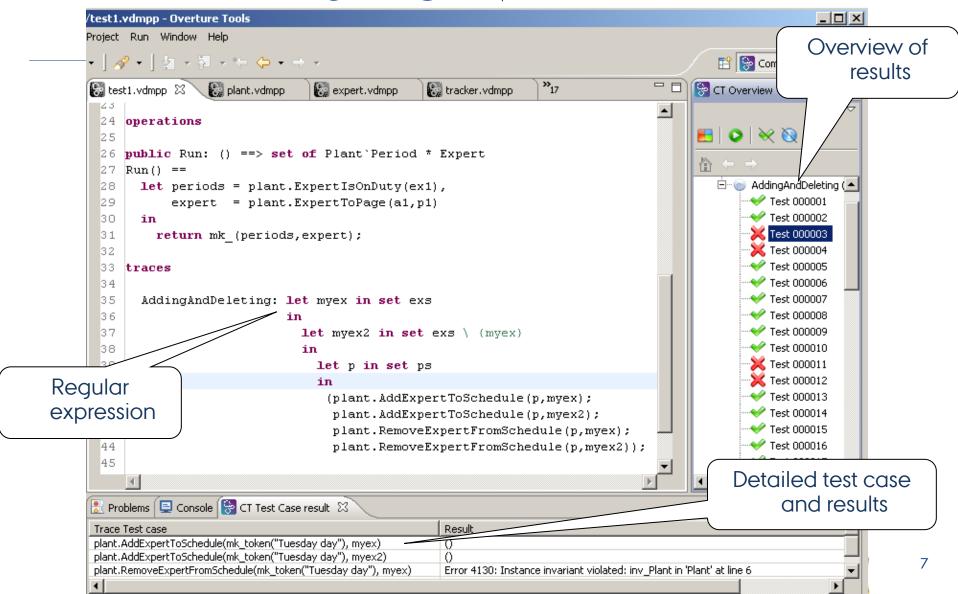


TESTING

- > Testing involves making experiments before deploying the system in the field.
- > Can be performed on a model or the actual system
- > Typically inject signals/inputs at certain points in the system and observe the resulting signals/outputs at other points.
- > Testing is a cost-efficient way to find many errors
- > However, checking all potential executions and interleaving using testing is rarely possible.



COMBINATORIAL TESTING PERSPECTIVE





EXAMPLE

Trace:

```
TTest: (let x in set \{1, 2\}
        in t.Insert(x)){3}
```

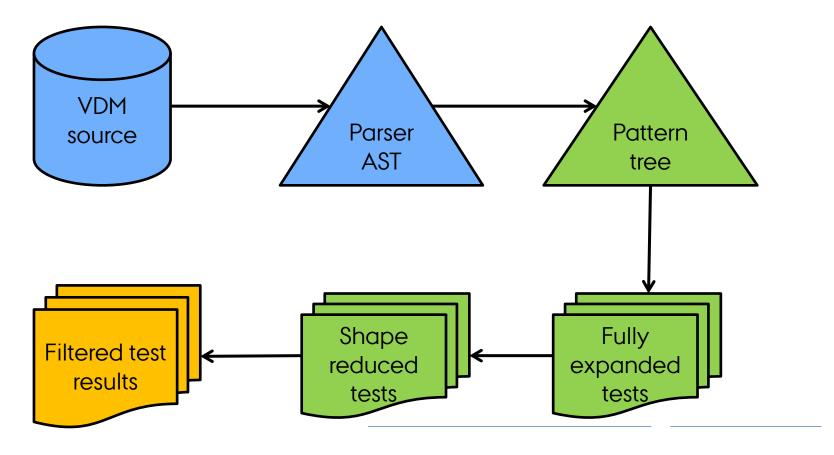
Generated Testcases:

```
TC1: t.Insert(1); t.Insert(1); t.Insert(1)
TC2: t.Insert(1); t.Insert(1); t.Insert(2)
TC3: t.Insert(1); t.Insert(2); t.Insert(1)
TC4: t.Insert(1); t.Insert(2); t.Insert(2)
TC5: t.Insert(2);t.Insert(1);t.Insert(1)
TC6: t.Insert(2); t.Insert(1); t.Insert(2)
TC7: t.Insert(2);t.Insert(2);t.Insert(1)
TC8: t.Insert(2); t.Insert(2); t.Insert(2)
```





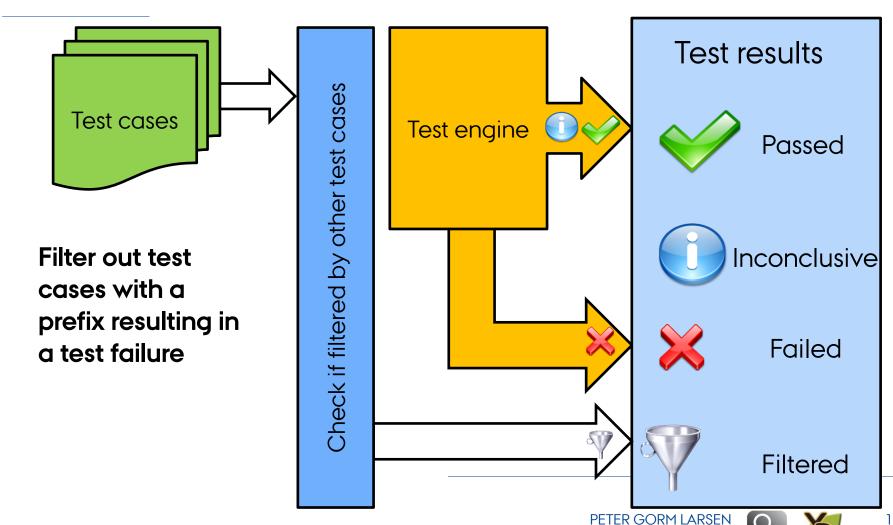
COMBINATORIAL TESTING OVERVIEW







TEST CASE EXECUTION





AN EXAMPLE

```
operations
public insert : int ==> ()
insert(val)== skip
pre val > 1;
```

traces

T1: let x in set $\{1,2\}$ in insert(x);



ANOTHER EXAMPLE

class A values obj : A = new A();

operations public op : nat ==> nat

op $(x) == \mathbf{return} x;$

traces

T2:

let x,y in set {1, ..., 10}
in
(obj.op(x);obj.op(y));

How many test cases will this generate?



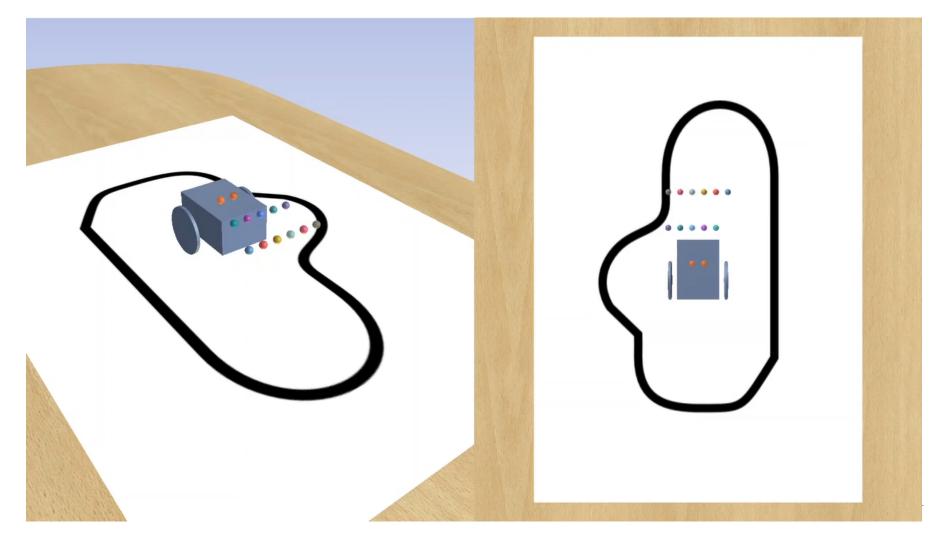


REGULAR EXPRESSIONS IN TRACES

- Let definitions (local naming)
- Let be such that definitions (all selection)
- Repeat traces (fixed or variable number of times)
- Concurrency traces (all interleavings)
- Application expression (calling operations)
- Trace alternatives



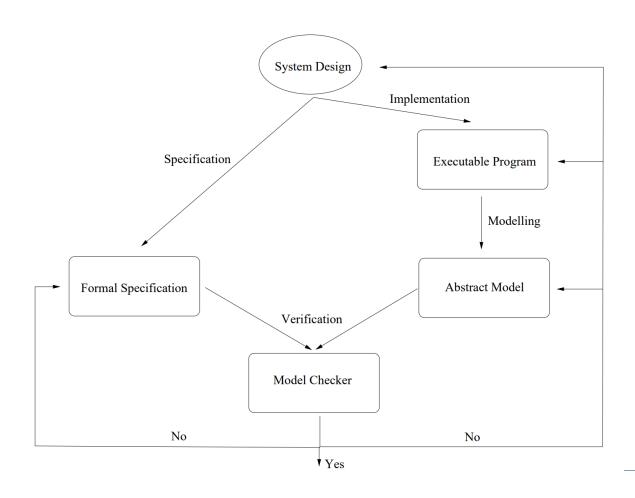
DESIGN SPACE EXPLORATION







MODEL CHECKING (1)





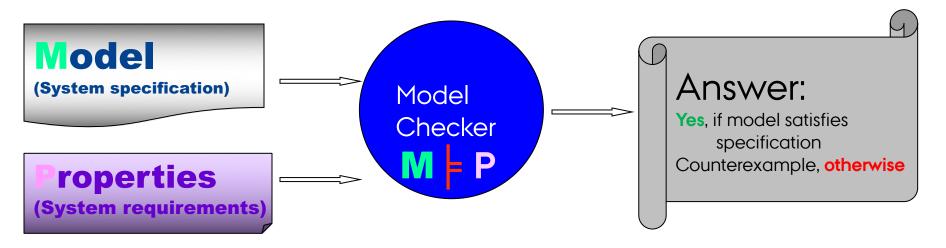


MODEL CHECKING (2)

- > Model checking is applicable for large systems, but with finite state space.
- > Constant and static state space.
- > Normally it uses an exhaustive search of the finite state space of the system.
- > Automatic exploration of the state space.



MODEL CHECKING (3)



- > Model specifies the system behavior in a formal way.
- > Properties:
- > Safety: Invariants, deadlocks, reachability, etc
- > Liveness: faireness, response, infinite traces, etc



SPECIFICATION/MODELING

Description of the behavior of individual processes and potential synchronizations.

Example: 2 concurrent processes M1 and M2 competing for a semaphore S, each process has three states: Noncritical (N), Trying (T), Critical (C). Semaphore available (S_0) or taken (S_1) .



PROPERTIES DESCRIPTION

- > A property describes a requirement that must always be satisfied by the system execution, no matter how the system execution evolves.
- > Properties are usually described using a logic, or a synntax that is compatible with the specification language.

Example: process 1 and process 2 must not be in a critical state at the same time.

$$M1 \parallel M2 \mid A[] \text{ not}(C_1 \land C_2)$$

> Related to VDM syntax, a property can be: all invariants, preconditions and post-conditions must be satisfied.



VERIFICATION (1)

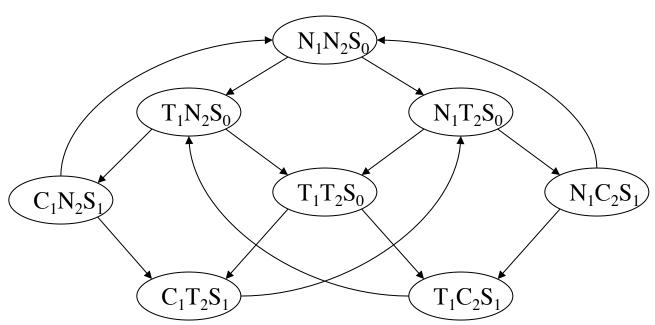
- > To check whether a property is satisfied or not, the model checker calculates first the state space.
- > State space is formed by all potential executions.
- > The verification visits each state in the statespace and checks whether the property is satisfied or not.
- > It terminates with yes/no (counterexample).

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VERIFICATION (2)

Example: state space for M1||M2.



is satisfied.





STATE SPACE EXPLOSION

- The composition of two concurrent processes is modeled by taking the Cartesian product of the corresponding state spaces.
- > In general, state space = $[M_1]^*[M_2]^*..^*[M_n]$.
- > Even a small system (<10 proc) can end up in millions of states due to data/time variables.

Challenging drawback: state space explosion.



SYMBOLIC STATE SPACE

Two main approaches have been proposed to cope with the state explosion problem:

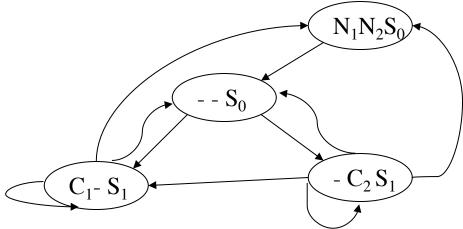
- > Symbolic algorithms.
- > Partial order reduction.

In symbolic model checking, logical formulas may be associated with the set of states that validate the formula. Thus compacting the state space.



SYMBOLIC ALGORITHMS

> Example: formula: inUse(S)=y/n by one of the processes.



> State space can be reduced to n/[p], n: original state space, p:number pf processes.



SUMMARY

- > What have I presented today?
- > Combinatorial testing possibilities
- > Model checking and symbolic algorithms.
- > What do you need to do now?
- > Read chapter 13 for next week
- > Continue working on your mini-projects