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Welcome!

What is SwiftX?

SwiftX is FORTH, Inc.'s interactive cross-compiler, a fast and powerful tool for the development of software for embedded microprocessors and microcontrollers. SwiftX is based on the Forth programming language, which for over 30 years has been the language of choice for engineers developing software for challenging embedded and real-time control systems. SwiftX provides you with the most intimate, interactive relationship possible with your target system, speeding the software development process and helping to ensure thoroughly tested, bug-free code. It also provides a fast, multitasking kernel and libraries to give you a big head start in developing your target application.

This manual describes the basic principles and features of the SwiftX cross-compiler product line. It is accompanied by additional material documenting the specific CPU and platform you have purchased.

Scope of This manual

The purpose of this manual is to help you learn SwiftX and use it effectively. It includes the basic principles of the cross-compiler. SwiftOS multitasking operating system, libraries, development tools, and recommended programming strategies.

This manual does not attempt to teach Forth. If you are learning Forth for the first time, install this system and then turn to the Forth Programmer's Handbook, which accompanies this system.

Audience

This manual is intended for engineers developing software for processors in embedded systems. It assumes general knowledge of embedded system programming, and some familiarity with the Forth programming language (which you can get by following the suggestion above).

How to Proceed

If you are not familiar with Forth, start by reading the first two sections of the Forth Programmer's Handbook. Then experiment with this system by downloading simple definitions to your target and testing them before proceeding. Additional references about the Forth language are provided in Appendix A, "Bibliography."

After you have installed and tested SwiftX on the PC and on the target board sup-

plied with this system, all SwiftX functions will be available to you.

Typographic Conventions

A **BOLDFACE** type is used to distinguish Forth words (including assembler mnemonics) from other words in the text of this document. This same type style is used to display code examples.

Support

The support period included with the original purchase of a SwiftX system is:

- SwiftX Pro -- One year
- SwiftX Lite -- Sixty (60) days

The support period may be renewed in one-year increments. During the support period, you are entitled to unlimited downloads of new releases as well as engineer-level technical support via email. Please send support requests to support@forth.com.

FORTH, Inc. maintains an email list server that enables SwiftX users to share experiences and code and discuss their application-related problems. To subscribe, please send a blank email to swiftx-request@forth.com with the word *subscribe* as the subject. You may cancel your subscription at any time by sending email to the same address with the subject *unsubscribe*. A searchable message archive is located at http://www.forth.com/archive/swiftx.

SECTION 1: GETTING STARTED

This section provides a general overview of SwiftX, including information necessary to help you become familiar with its principal features. Please refer to the platformspecific documentation that comes with your SwiftX system for installation instructions and details about the hardware connections.

1.1 Components of SwiftX

There are two levels of SwiftX:

- **SwiftX Pro** is a full-featured version intended for professional use.
- **SwiftX Lite** is a simplified version intended for hobbyist or personal use.

1.1.1 Common Components

Both **SwiftX Pro** and **SwiftX Lite** versions include the following components:

- Interactive Development Environment (IDE)
- Cross-compiler
- Target assembler
- SwiftOS Multitasker (discussed in Section Section 5:).
- Host support for the SwiftX Cross-Target Link (XTL, discussed in Section 4.9)
- Programming aids including decompiler, disassembler, cross-reference utility, memory dump, and other tools.
- Forth language source files for the SwiftX kernel.
- A demo target board (for most targets), on which you may run the kernel provided with this system in order to test your software and learn about Forth and SwiftX.
- Pre-compiled image of the SwiftX kernel that will run on your target board. This kernel contains a representative set of functions that will support most embedded applications. Using the source files provided with this system, you may regenerate this image, modify it, or compile and test additional software to run on this kernel.

1.1.2 Added Features in SwiftX Pro

In addition to the common components listed above, **SwiftX Pro** includes:

- Project management features (Section 3.1.1), which facilitate setting up and managing the source files for multiple applications.
- An optimizing compiler that produces faster and/or smaller code.
- A code stripper (Sections 2.3.7 and 3.2.2), which removes all un-called words from a completed program, for greater compactness.

- A target-resident interpreter (Section Section 7:) supports full user interaction and limited compiler capabilities via a serial terminal task in a standalone target. This feature is useful for field diagnostics, configuration, and other user interactions. (Not available in all targets.)
- Complete source code for the cross-compiler, host side of Cross-Target Link (XTL), assembler, and decompiler/disassembler.

1.2 Directory Structure

The directory structure for the files provided with SwiftX is shown in Figure 1. This example shows a SwiftX installation with multiple target CPU types to show the hierarchical arrangement.

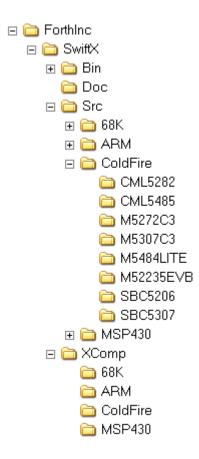


Figure 1. SwiftX directory structure

The default installation directory, Forthline, may contain multiple FORTH, Inc. product directories (e.g, SwiftX, SwiftForth, pfWin32).

The SwiftX directory is a container for the following directories:

• Bin contains the Windows executable program and associated libraries and other

binary files requried by the host SwiftX environment.

- Doc has the reference manuals, license agreement, version history, and other documentation files.
- Src is the target source tree. Source files common to all SwiftX target processor families reside here. The next level down within Src has one subdirectory for each processor family. This example shows four: 68K, ARM, ColdFire, and MSP430.
- XComp contains the source for the host side of the cross compiler. This directory is populated only in the SwiftX Pro version.

1.3 SwiftX System Requirements

In order to use this package, you need the following:

- PC running Windows 95/98, Me, 2000 or NT. At least 32 Mb of RAM is recommended. The package will occupy approximately 13 Mb of disk space.
- A programmer's editor of your choice. Provision is made for linking interactive features of SwiftX with most standard editors.
- A host PC port to connect to the target board; see your product-specific documentation for details.
- Any additional hardware and software required for programming memory devices such as PROMs or EEPROMs, or for in-circuit device programming.

1.4 Installation Instructions

This section describes how to install your SwiftX cross-compiler and connect it to the target board supplied with this system. It also describes basic procedures for downloading and testing a kernel and your programs.

1.4.1 Installing the Host Software

Launch the SwiftX Installer by running SwiftX-<version>.exe on the SwiftX distribution CD-ROM or the one you downloaded. The install procedure may prompt you for additional information or choices.

The default installation directory is \ForthInc\SwiftX. If you prefer another directory or path, you will be given a chance to change it during the installation. However, this manual will use SwiftX\ as the root path.

If you have previously installed SwiftX, you may wish to back up any files have modified before installing a new version on top of the old one.

The installation procedure creates a SwiftX program group on the Windows Start > Programs menu, from which you may launch the main program for your target To complete the installation, launch SwiftX and select other options as described in the sections below.

1.4.2 Linking to a Text Editor

The SwiftX Interactive Development Environment contains a number of programmer aids (discussed in Section 2.4) that are facilitated by a direct link to a text editor. The default editor is Windows Notepad.

You may configure SwiftX to use an editor of your choice by specifying certain command parameters as described in Section 2.3.5.

1.5 Development Procedures

Here we provide a brief overview of some development paths you might pursue. You may wish to:

- Run the development configuration unchanged.
- Change the kernel in some way and debug the new kernel.
- Write and test application routines.
- Run the final debugged system.

Simple guidelines for doing these things are given in the following sections, and will prepare you to interact with your target board by using the software as delivered. Further details about the SwiftX compiler and interactive development aids are given in Sections 2.4 and 4.

1.5.1 Starting a Development Session

Launch SwiftX as described in Section 1.4.1. When SwiftX is running and your target board is connected, you may change any options you wish. When you are ready, you may compile a target image of a SwiftX kernel plus libraries and other routines, depending upon how you have configured your system. There are two options for doing this, both available from SwiftX's project menu (the usual development approach is to use Debug during development, and Build only when you are ready for PROM burning):

- Project > Build compiles the target image in a file on the PC suitable for burning into a PROM.
- Project > Debug compiles the target image, and establishes communication with the Cross-Target Link (XTL) on the target board. If no target is connected, or is not connected properly, this command will fail and will generate the message "No XTL. Try again? (Y/N)". This means the kernel was fully compiled, but the XTL connection was not established; check your connections and select Project > Debug again. If the target system runs from PROM, it will compare the newly compiled image to the image in the target; they must be identical for the XTL to work properly. With some targets, a new image can simply be downloaded.



If these steps are completed, additional debugging facilities are then downloaded to support interactive testing and debugging. When communication has been established successfully, the target will greet you by displaying the system and target IDs. At this point, you may directly execute words on the target, examine its memory or I/O ports, and define additional words which will be downloaded automatically for testing. To try it, type:

26 + .

The numbers you typed will be transmitted to the target, followed by the commands + and . (the command "dot," which types a number). These commands will be executed on the target board, which will add the numbers and display the sum. The sum will be displayed on your screen, because your PC is providing the target's keyboard and display functions.

Whether or not you are connected to a target, you may use LOCATE, DUMP, and many other debugging commands, described in Section 2.4.

1.5.2 Using SwiftX With Other Hardware

If you are using a target system other than the test board supplied with this SwiftX product for your final application, you may need to make some changes to the parameters of your kernel. The configuration procedure described in Section 4.2 will help you to do this.



If your target will execute out of PROM, you will need to burn a PROM. The menu selection Project > Build compiles a target image and writes it in a file suitable for burning to a PROM. See Section 4.8 for the available object file formats.

1.5.3 Running the Demo Application

As shipped, the Debug option is configured to run a demo application based on the Conical Pile Calculator described in Appendix A.2. The source for this program is in the file SwiftX\Src\Conical.f; we recommend that you review it, because it exhibits many features found in SwiftX programming.

The demo program requires that the target be connected and communicating with the host. It may use either the host keyboard and screen via the XTL (the default configuration), or you may connect the target board's serial port to a COM port on your host and set up a separate task in the target to talk to a standard terminal emulator utility in the target, as described in Section 5.5.

To run this program, launch SwiftX as described in Section 1.5.1 and select Project > Debug to bring up the target program. Type **CALCULATE** to start the application; it will issue the prompt:

Enter material, feet, inches: nM nF nI =

followed by a list of materials.

Select a material by typing, for example, 1M. The target will echo, in that example, Loose gravel. Similarly, enter a number of feet and inches. Finally, type = and the target will display the answer.

This demo program is configured to run indefinitely; to exit, press the Esc key.

To explore further, try typing LOCATE DENSITY. This will display the source where this word is defined. If you have linked an editor (as described in Section 1.4.2 and Section 2.3.5) you may press your right mouse button and select Edit This to launch your editor, opening the Coni cal. f file.

You may examine the contents of any of the variables in this program by typing, for example:

DENSITY ?

You may also exercise the individual words in the demo by providing suitable stack arguments (look at the comment following the name of each definition); for example:

1 SELECT

This displays Loose gravel and stores the parameters for that material in **DENSITY**, THETA. and MATTER.

1.5.4 Changing the SwiftX Kernel

When you have successfully compiled the kernel and exercised the Cross-Target Link, you can begin trying changes to the kernel.

The simplest (and safest) changes involve adding new words. You can simply type new definitions at the keyboard, and they will be cross-compiled and downloaded automatically, available for immediate testing. For example, you could type:

```
. " HELLO, WORLD! " CR ;
: Hi
```

This defines a word which, when executed, displays the message between quotation marks, followed by a new-line function (CR). Try it by typing Hi.



You can create a new file—e.g., via the File > Edit menu item or toolbar button or by typing EDIT filename—for your source code, for example, Extras. f. With the board in interactive mode (after doing a Project > Debug), you may compile the words in your new file for interactive testing by using the menu item File > Include or by typing:

INCLUDE EXTRAS

For the typed command, the . **f** extension is assumed.

You may do this repeatedly, until the board runs out of code space. If necessary, you may start over with a new download by repeating Project > Debug, which re-initializes the target.

When the new functions are tested to your satisfaction, you may add them to the kernel by inserting INCLUDE EXTRAS before the last lines of the main load file Kernel. f and before the startup code.

The startup code for a SwiftX system is usually factored into two files, both called **Start. f**, but at different directory levels: one is in the directory **Swi ftx\Src**<CPU>, and one is in the target-specific subdirectory. These must always be the last files to be loaded, with the target-specific one (containing the actual power-up code) last.

Then rebuild and re-install the kernel as described above (using Project > Build), and test. Instructions for installing a new kernel are provided in your platform-specific documentation.



Changes to the Forth primitives (such as those in the file Core.f) should only be made with the greatest of care. The SwiftX kernel and the Cross-Target Link rely on those primitives for their operation. Changes to the model of the underlying Forth system (such as cell size or stack allocation) should only be attempted by an experienced Forth programmer.

Section 2: Introduction to SwiftX

SwiftX is a development system used to create software for microcontrollers and microprocessors in various types of embedded systems.

To debug embedded software, interaction with the target hardware is needed. In a conventional C or assembler programming environment, this usually is achieved by using in-circuit emulators, simulators, and debuggers. These tend to be expensive and complex, and provide only limited interactivity, at best.

SwiftX supports interactive development and testing of software, on even the smallest microcontrollers, without expensive additional hardware and software tools. This is achieved by using a Windows-based host computer to handle a continuous communications link between the PC and an actual target.

This introductory section gives a general view of the design of the SwiftX development environment. We recommend that you read this, even if you are already familiar with the Forth language.

2.1 SwiftX Programming

The SwiftX cross-compiler is based on the Forth language, and its target source code is written in Forth. Therefore, gaining familiarity with the essentials of Forth is strongly recommended before tackling SwiftX programming.

If you are a Forth beginner, read any of the introductory books in "Bibliography" on page 115. Review the demo application ("Conical Pile Calculator") supplied with your system. Find out what software is available by looking through the source code supplied with SwiftX. Finally, don't hesitate to contact the FORTH, Inc. Hotline Support Service with any questions or problems (see page 10). Forth programming courses are available at FORTH. Inc. and can help shorten the learning process. We also offer a full range of consulting and custom programming services to help kickstart your project.

SwiftX is a very powerful and flexible system, supporting software development for virtually any embedded system configuration. Although the internal principles of SwiftX are simple, a necessary side-effect of its power is that it has a large number of commands and capabilities. To get the most benefit, allocate some time to become familiar with this system before you begin your project. This will pay off in vour ability to get results quickly.

2.2 System Organization

The SwiftX system has two basic components: a *host* system (the PC side of the development system) which supports the SwiftX cross-compiler and interactive programming tools, and a target system which executes on the target board and supports interactive debugging with the host.

The host software is based on a 32-bit Forth system running under Windows. This host is designed to support a special cross-compiler for the target processor, along with a cross-assembler and the source code for the target system's kernel and application.

The separation between host and target is manifested in several areas:

- **Memory and address space** There are a number of different address spaces: the host's local memory, which is not directly accessible in the cross-compiler; the various regions of target memory (code space plus initialized and uninitialized data space); and a private region where the host maintains pointers into the target's memory image. When you are programming in SwiftX, you usually are working with target memory space.
- Command set SwiftX compilers are written in Forth. The host provides locally executable versions of many Forth words that are also present in the target. In order to distinguish between the host and target versions of these words, they are maintained in separate, searchable word lists. Commands are provided to select among these word lists. The context in which a word may be accessed (either for execution or for compiling a reference to it) is called its *scope*. The default arrangement is that one accesses the target versions of these words. Scopes are discussed further in Section 4.6.
- Compiler words and directives There actually are two compilers in SwiftX. The most visible compiler is the one used to construct the target program; it contains defining words (such as:, CONSTANT, VARIABLE, etc.), flow-of-control words (such as IF, THEN, BEGIN, DO, LOOP, etc.), words for managing data space (such as, and ALLOT, etc.), and other compiler words. However, an underlying compiler on the host was used to build the cross-compiler. This compiler may be extended in order to provide special compiling or defining capabilities. For this reason, it is accessible via special scope selectors (described in Section 4.6.2), as are the host versions of common Forth commands.

SwiftX contains an assembler which provides direct access to the native instruction set of the CPU. The assembler for your target processor is described in the *Target* Reference Manual specific to your SwiftX system.

SwiftX operates in one of two states: *interpreting* or *compiling*. The programmer may add new words that act in either of these states. New words added for the interpreting state might, for example, support custom target data structures; new words added to the compiling state might support custom conditional or loop structures in target definitions.

SwiftX also supports a third state, called *interacting*. This means that words typed on the command line will be executed on the target. The Cross-Target Link (XTL, described in Section 4.9) connects the host and target systems in this interactive mode. Two programs communicate via this link. The host XTL issues commands to the target and responds to output from the target. The target XTL receives and executes commands from the host, and sends display commands to the host. The XTL allows communication at moderate speed over a serial or parallel line.

The target software may be thought of as having several layers, illustrated in Figure 2. Included with your SwiftX system are the core, drivers (including the XTL protocol on systems using a serial host-target link), SwiftOS multitasking executive (see Section Section 5:), and libraries (supplied in source form). You may select which libraries to add to the system (see Section Section 6:). You may also add custom drivers, other libraries, and application code easily. This makes your SwiftX system very adaptable, in both content and size, to your special requirements.

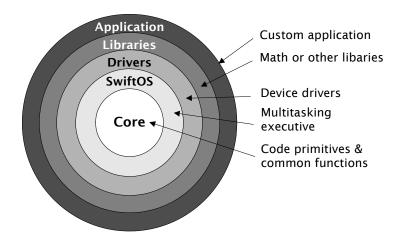


Figure 2. Code layers in a SwiftX system

2.3 IDE Quick Tour

The SwiftX Interactive Development Environment (IDE) presents a user interface that may be managed from a command line or with pull-down menus and toolbar buttons. This section summarizes its principal features.

2.3.1 The Command Window

Your main interface with SwiftX is through the command window, which is displayed when the system boots. In this window, you may type commands, which will be executed by SwiftX or routed to the target for execution, as described in Section 2.5.

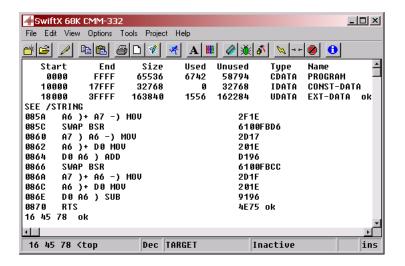


Figure 3. The SwiftX command window

All information displayed in the command window (including commands you type, and system responses or displays) is kept in a large circular buffer while the IDE is running; to see previous parts of the session, you may scroll through this buffer by using the scroll bar or the PageUp and PageDown keys. You may also print or save the entire buffer, or any portion of it you select using the mouse.

The toolbar at the top of the command window provides one-click access to several menu options described in the following sections (see Figure 4).

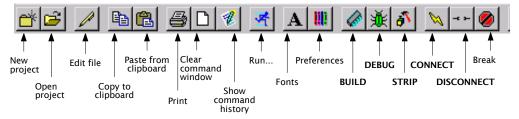


Figure 4. Toolbar items

The status line at the bottom of the command window shows the current number base (the default is decimal), the stack depth with the actual values of the top several items, the current scope (see Section 4.6.2), and other useful information (see Figure 5).



Figure 5. SwiftX command window status line

In addition to the buffer containing the general history of the command window's contents, SwiftX remembers the last several commands you type, storing them in a circular queue. The up-arrow and down-arrow keys allow you to retrieve these command lines from the buffer. You may edit them by using the left-arrow and rightarrow keys and typing; the Insert key toggles between "insert" and "overwrite" mode (indicated at the right end of the status bar). You can execute the entire line (regardless of where on the line your cursor is) by pressing Enter; or leave the line, without executing it, by pressing Esc.

The command-line input processor provides smart command completion. For instance, if you had previously typed INCLUDE FOO, typing INC and pressing the Tab key will complete the phrase INCLUDE FOO for you. Successive presses of the Tab key toggle through entries in the circular command-line buffer.

Lines shorter than three characters are not saved in the recall buffer, as they take more time to get to via the control keys than to retype!

Double-clicking any word in the command window will select it. The right mouse button presents a menu of operations you can apply to a selected word, shown in Figure 6.

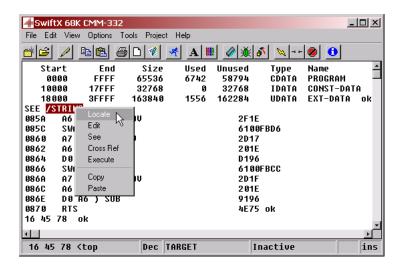


Figure 6. Right mouse button actions on a selected word

- Locate displays the source for any word defined in your current scope by doubleclicking the word. If the source is not present, you will get an error message. For example, double-clicking on a word defined in the metacompiler returns the error alert "Non-existent file" (except on SwiftX Pro systems); attempting to locate the source of a word defined interactively in the command window returns the message "Can't locate keyboard definitions." This feature is discussed further in Section
- Edit launches or switches to your linked editor (see Sections 2.3.5 and 2.4.1) positioned at the source for the word (if it's available).
- *See* disassembles the word, as described in Section 2.4.3.
- *Cross Ref* generates a cross-reference for the word, as described in Section 2.4.2.
- Execute executes the word, just as though you had typed it and pressed Enter. Note that you can only execute Target words if you are currently connected to an

active target, as described in Section 2.5!

- *Copy* copies it to the clipboard.
- Paste pastes whatever is currently in the clipboard at the current cursor position in the command window.

Copy and Paste (below the horizontal line in the menu) differ a bit from the other options. The functions above the line require that you have selected a Forth word that is recognizable in your current scope (or, in the case of Execute, an executable word or number). Copy does not depend on the selected text being a defined Forth word, and Paste will ignore any selected text.

After you have displayed source for a word in the command window, pressing Alt-PageUp and Alt-PageDown will display adjacent portions of that source file.

Table 1: Command window keyboard controls

Key	Action
PageUp PageDown	Scroll through the history of the current session.
ÈÍ	Retrieve commands you have typed.
ÁË	Move cursor on the command line.
Insert	Toggle the insert/overwrite mode of typing.
Enter	Execute the command line the cursor is on.
Ctrl-C Ctrl-V	Copy from, or paste text into, the window. (See Section 2.3.3.)
Double-click on a word	Selects it, making it available for pop-up menu actions LOCATE, EDIT, SEE, WH (cross-reference), or EXECUTE.
Alt-PageUp Alt-PageDown	Scroll through the source file containing the word whose source is currently displayed.
Right-click	Display pop-up menu options: PageUp, PageDown, Edit This (which launches your editor with the cursor positioned at the source line targeted by your previous LOCATE action; see Sections 2.3.5 and 2.4.1); and with shortcuts to previously LOCATE d words. (See Figure 10 on page 32.)

The following sections describe the menu options available from the command window. Where a letter in a menu item is underlined, the Alt key plus that letter is a keyboard equivalent. In each case, we list the menu item, equivalent command (if any), and a description of the item.

2.3.2 File Menu

Item

Table 2: File menu options

The File menu offers the selections described in Table 2.

Command

New Project Include <u>E</u>dit Print Save Command Window Save Keyboard History Session Log Exit

File menu

<u>N</u> ew Project ^a		Open a dialog box to let you construct a new project based on an existing project.
<u>O</u> pen Project [*]		Open an existing project.
Include	INCLUDE <filename></filename>	Interpret a file (load it and any files it loads). Displays a file-selection dialog box; I NCLUDE processes the file <i>filename</i> .
<u>E</u> dit		Launch a linked editor, allowing you to select a source file.
<u>P</u> rint		Print the command window. In the print dialog, you may choose to print the entire con- tents or a selected portion.
Save <u>C</u> om- mand Window		Record the current contents of the command window in a text file.
Save Keyboard <u>H</u> istory		Record all the commands you've typed in this session in a text file

Action

a.SwiftX Pro only

bye

Session <u>L</u>og

Break

Exit

The "New project" and "Open project" items are described in more detail in Section 3.1.1.

Exit SwiftX.

Start recording all actions for

(or target XTL if it's active) to abort; used for error recovery.

this session in a text file. Force the main console task



The Edit menu option opens a file for editing, using your linked editor (see Sections 2.3.5 and 2.4.1).



Both the File > Open Project and File > Edit menu items and their corresponding toolbar buttons bring up a "Browse" dialog box through which you can find your file. Both will reset SwiftX's path to the one for the file you select. However, the command I NCLUDE invoked from the keyboard will not change SwiftX's current-path information.

Save Command Window, Save Keyboard History, and Session Log are discussed further in Section 2.4.6.

2.3.3 Edit Menu



Most editing in SwiftX is done with your associated editor (see Section 1.4.2 and Section 2.4). However, you can copy text—from a file in another window or from elsewhere in the command window—and paste it into the command window, which will have the same effect as typing it. You may also select text for typing, saving, or copying into another window. Edit menu options are summarized in Table 3. (Cut and Delete are not available in the command window, since the purpose of the command window is to maintain a record of your actions during this programming session.)

Table 3: Edit menu options



Item	Keystrok e	Action
<u>C</u> opy	Ctrl-C	Copy selected text to your clipboard.
<u>P</u> aste	Ctrl-V	Paste the current clipboard contents on a new command line and interpret its contents.
<u>S</u> elect All		Select all text in the window.
Clear <u>W</u> indow		Clear the entire command window.



Toolbar buttons are available for Copy and Paste.

Paste

2.3.4 View Menu



The View menu provides alternate views of the command window. Each feature will toggle when you select it. The choices are described in Table 4.

Table 4: View menu options

Item	Action
<u>S</u> tatus line	If checked, displays the status line at the bottom of the screen. See Figure 5 for details.
<u>T</u> oolbar	If checked, displays the toolbar at the top of the screen. Toolbar button options (flat, large, small) may be set using Options > Preferences, described in Section 2.3.5.



Options menu

2.3.5 Options Menu

The Options menu provides ways to customize SwiftX. Its selections are summarized in Table 5.

To use an editor other than Notepad, which is the default when SwiftX is first installed, use Options > Editor and type your editor's path and name into the box or click the browse button to search for it. After providing the pathname, the User Defined radio button should be highlighted.

Table 5: Options menu options

Item	Action
<u>F</u> ont	Select a font for the command window. Only fixed-width (i.e., non-proportional) fonts are listed.
<u>E</u> ditor	Select and set parameters for your editor.
<u>P</u> references	Set text and background colors for normal and highlighted displays, select case sensitivity, and other options
<u>W</u> arnings	Enable/disable various system warnings, and establish how they and error messages will be displayed.
<u>I</u> nclude Monitoring	Sets options for diagnostic features to be performed during file I NCLUDE operations. (See Section 3.1.5 for details.)
Save Options	Save all current settings.

Next you must specify, on the Editor Options line, how SwiftX is to pass line-number and filename parameters to your editor. The specification format is:

line-selection string> %l <file-selection string> %f

When SwiftX calls the editor, it provides the line number at the place in this string that has a **%I** (lower-case L), and provides the filename at the place that has a **%f**. Example parameter strings for some editors are shown in Table 6.

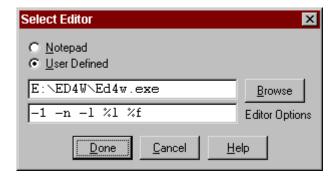


Figure 7. Select Editor dialog box

When your editor's pathname and parameter string are correct, click Done. This

Table 6: Examples of editor parameter sequences

Editor name	Parameter string
CodeWright	"%f" -g%l
Е	-n%l "%f"

Table 6: Examples of editor parameter sequences (continued)

Editor name	Parameter string
ED4W	-1 -n -l %l "%f" (note: the first is minus one, the others are lower-case Ls)
EMACS	+%I "%f"
MultiEdit	%f /L%l"
TextPad	-am -q %f(%l,0)"
TSE	-n%l %f"
UltraEdit	%f/%l"
WinEdit	"%f" /#: %l

information will be saved when you exit SwiftX.



The Options > Preferences dialog (or its equivalent Toolbar button) lets you specify a number of configuration items, shown in Figure 8. The Colors section controls the color scheme of the command window.

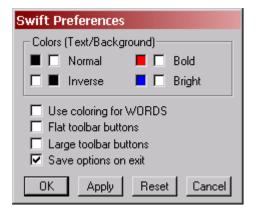


Figure 8. Preferences dialog box

"Use coloring for WORDS" vectors the command **WORDS** (described in Section 2.3.6). If this box is checked, typing **WORDS** in the command window produces a color-coded display in that window. The Words browser window launched from the toolbar or Tools menu is not affected by this.

"Save options on exit" records your selections so they will be in effect when you next launch SwiftForth. (Note: the Reset button will restore all options to the system defaults.)

"Flat" and "Large" toolbar buttons affect the appearance of the toolbar, if it is displayed.

The Options > Warnings dialog provides configuration settings that determine whether, and where, error messages and system warnings will appear.

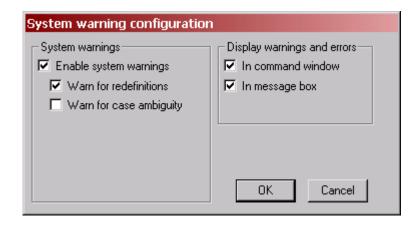


Figure 9. System warning configuration dialog box

Even if warnings are disabled, error messages will always be displayed.

Options > Include monitoring configures diagnostics that can be used when you're **INCLUDE**ing a source file. These are discussed in detail in Section 3.1.5.

References

WORDS command, Section 2.3.6 INCLUDE, Section 3.1.2

2.3.6 Tools Menu

<u>W</u>ords <u>H</u>istory <u>R</u>un Disconnect & Select XTL

This menu provides tools that may be helpful in the development process.

Table 7: Tools menu options

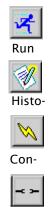


Table 11 Tools mena options		
Item	Command	Action
<u>W</u> ords	WORDS	Display the words available in the current scope.
<u>R</u> un	RUN	Run an auxiliary program (e.g., a PROM programmer).
<u>H</u> istory		Open command history window, and start recording.
Connect	CONNECT TARGET	Start the XTL communicating with the target.
Discon- nect	DI SCONNECT TARGET	Disable the XTL connection.
<u>S</u> elect XTL		Launch a dialog box for configuring a serial XTL connection.

Discon-

The Connect and Disconnect commands let you temporarily change the status of your communication with the target. This is sometimes useful for comparing host and target initialized data spaces, for example.

References XTL communication, Section 2.5, Section 4.9

Action

file.

2.3.7 Project Menu

A project is a link between the SwiftX cross-compiler for the kernel's CPU and a source file set up to build your system. It also incorporates configuration information, such as the port and baud rate used for the XTL. The Project Menu provides features for compiling your project.

SwiftX Pro offers additional project management facilities; these are discussed in Section 3.1.1.

Compile target system and activate XTL for debug-

Compile the target system, leaving its image in a

Recompile the target (as for Build), omitting any

Table 8: Project menu options

Comma

DEBUG

BUILD

STRI P

nd



Debug

Item

Debu g Build

Strip^a







Strip



Section 1.5 discusses the uses of Debug and Build; Debug is the option used most heavily during development.

2.3.8 Help Menu

The Help menus provide on-line documentation for your SwiftX system.

words that are never called.

Table 9: Help menu options

Item	Content	
<u>H</u> andbook	Forth Programmer's Handbook (PDF format).	
<u>R</u> eference Man- ual	This manual (PDF format).	
<u>T</u> arget Manual	Documentation for target MCU and boards (PDF format).	
Go <u>O</u> nline	Connect to the FORTH, Inc. web site.	
<u>A</u> bout	Product release date and related information.	

2.4 Interactive Programming Aids

This section describes the specific features of SwiftX that aid development. These tools typically will be used from the keyboard in the command window.

2.4.1 Interacting With Program Source

The command:

LOCATE <name>

is equivalent to double-clicking on a word in the command window and selecting the "Locate" option from the pop-up menu (discussed in Section 2.3.1). If *name* is defined in the current scope, this will display several lines of the source file from which *name* was compiled, with *name* highlighted. This will work for all code compiled from source files; source is not available for:

- code typed directly into the SwiftX command window
- source code that was pasted into the command window
- words in the SwiftX cross-compiler and assembler (except SwiftX Pro customers. who get all source)
- words in the underlying host implementation

LOCATE may also fail if the source file has been altered after the last time it was compiled, because the host version of each compiled definition contains a pointer to the position in the file that produced it.

For example, the command:

LOCATE /STRING

(or double-clicking on /STRING) opens the correct source file, and displays the source for this word, plus several lines before and after it (the number of lines displayed depends upon the size of your command window).

If you right-click the mouse, you will see a pop-up menu, shown in Figure 10. You can apply any of these menu selections to the most recently LOCATEd word, or to a currently selected word.

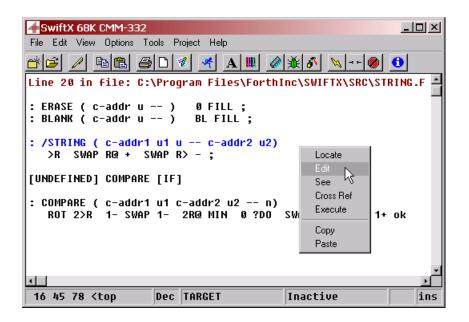


Figure 10. Right-click to revisit or apply other options to LOCATEd words

Near the top of this menu, you will see the option Edit. Selecting that command, or typing EDIT, will launch your linked editor (or switch to it, if it is already open) with the cursor positioned on the source line containing the word you last located. This feature lets you immediately edit the source, if you wish, and examine the rest of the file. (To link to an editor other than the default Notepad, see Section 2.3.5.)

You may also use the EDIT command to open an arbitrary file for editing, by typing **EDIT** wordname or **EDIT** filename. (Also see the File > Edit menu option, discussed in Section 2.3.2.) If **EDIT** sees a string, it will attempt to look it up in the dictionary, in the current scope. If it finds it, it will use the editor to open the source file in which wordname is defined, positioned at the definition. If the text cannot be found in the dictionary, EDIT will attempt to treat it as a filename and open that file in the editor. To avoid confusion, we recommend that you always append the . f extension when you use **EDIT** with a filename.

If the compiler encounters an error and aborts, you may directly view the file and line at which the error occurred by typing **G** (for Go to the error). This is particularly convenient if you have a linked editor (see Section 2.3.5), because you can immediately repair the error and recompile. If you don't have a suitable editor, SwiftX will display the source path and line number in the command window, and you will have to manually switch to your editor to fix the problem.

Glossary

LOCATE < name >

Display the source from which *name* was compiled, with the source path and definition line number, in the SwiftX command window. name must be in the current scope.

L (-)

After a compiler error, display the source line at which the error occurred, along with the source path and line number, in the SwiftX command window.

EDIT <text>

Launch or switch to a linked editor, passing appropriate commands to open and position a source file. The text following **EDIT** is optional. If it is present, **EDIT** will attempt to find it as a defined word and open the file in which it is defined, positioned at its definition. If *text* cannot be found in the dictionary, **EDIT** will attempt to treat it as a filename and open the file. If no text is provided, EDIT will select the source most recently displayed by LOCATE, L, or a double-click.

2.4.2 Cross-references

This tool finds all the places a word is referenced. The syntax is:

WHERE <name>

It displays the first line of the definition of *name*, followed by each line of source code in the currently compiled program that contains *name*.

If the same name has been redefined, WHERE gives the references for each definition separately. The shortcut:

WH <name>

does the same thing. It is also the word that responds to the "Cross ref" option on the right-mouse menu.

This command is not the same as a source search—it is based on the code you have compiled and are debugging. This means you will be spared any instances of name that are in files you aren't using.

Glossary

(-)WH < name >

WHERE < name >

Display a cross-reference showing the definition of *name* and each line of source in which name is used in the currently compiled program. WH and WHERE are synonymous.

2.4.3 Disassembler

The disassembler is used to reconstruct readable source code from compiled **CODE** and: (colon) definitions. This is useful as a cross-check whenever a new definition fails to work as expected.

The single command **SEE** *name* disassembles **CODE** commands and colon definitions defined for the target scope. The results depend somewhat upon the implementation; see your target-specific documentation. Subroutine-threaded systems and systems that compile actual machine code may be unable to reconstruct a high-level definition, and may instead show the assembler code that was generated. In such a case, use **LOCATE** to display the source. **SEE** is one of the options on the right-mouse menu.

An alternative is to disassemble or decompile from a specific address. This is useful for decompiling headless code, such as code preceded only by a LABEL. The command to disassemble a **CODE** definition, given an address *addr*, is:

<addr> DASM

Glossary

SEE <name>

Disassemble or decompile *name*, where *name* must be a target definition. The display format will depend on the CPU and the implementation strategy (see your target-specific documentation).

DASM

(addr -)

Disassemble code beginning at *addr*. The display format is platform dependent.

(addr -)

Displays the name of the definition closest to and preceding addr. Useful for decoding memory dumps.

References

Using **LOCATE** to display source, Section 2.4.1 CODE and LABEL, Section 4.4

2.4.4 Memory Dumps

Sequences from the host image or target may be dumped via these commands. If you are connected with an active XTL, all sections of actual target memory will be displayed; if not, you will see the host image, and uData may not be dumped.

Glossary

DUMP

(addr u —)

Display u bytes of hex characters, starting at addr, in the current section, which may be either code or data. If you are not connected to your target, you can only display code space or initialized data space.

DUMPC

(*addr* u —)

Display u bytes of hex characters, starting at addr, in the current code-space section.

References

CONNECT and **DI SCONNECT**, Section 4.9.1

CODE and **LABEL**, Section 4.4 Memory sections, Section 4.3

2.4.5 Single-Step Debugger

SwiftX's single-step debugger allows you to step through source compiled from a file. A simple example is the sample program **Sstest**. **f**, shown below:

```
TARGET
FDEBUG
: 2X ( n -- n*2)
                     DUP + ;
: 3X ( n -- n*3)
                     DUP 2X + ;
: 4X ( n -- n*4)
                     DUP 2X SWAP 2X + ;
: 5X ( n -- n*5)
                     DUP 3X SWAP 2X + ;
DEBUG<sub>1</sub>
```

The target support for the debugger is normally loaded in **Kernel** . **f**.

When the source has been compiled from the file Sstest. f, type the following to invoke the single-step interface:

4 DEBUG 5X

At each breakpoint between Forth words, the current data stack is displayed along with a prompt to select the next action:

Execute the next word, nesting if it is a call. Nest

Execute the next word, with no nesting. Step

Execute to the end of the current definition without stopping. Return

Finish Finish executing the DEBUG word without stopping.

2.4.6 Managing the Command Window

The command window is implemented internally as a circular buffer: a long session may "wrap" this buffer, so early commands may be lost. Three of the File menu options allow you to record the events of a development session in various ways:

- Save Command Window records a snapshot of the present contents of the command window in a text file. This is useful if, for example, you have just encountered a strange behavior you would like to record for later analysis.
- Save Keyboard History records into a text file only the commands you've typed. Such a file may be edited, if you like, using your text editor. You can replay these commands by including the file. This is useful for developing scripts or for reproducing a bug.
- **Session Log** opens a file and starts recording everything that happens thereafter in the session, until you turn it off by re-selecting this menu item. While it is active, its menu item displays a check mark.

You may display a window containing the keyboard history by selecting Options > History or the Toolbar button. You can edit the contents of this window, using it as Histor a scratch area, and you may copy and paste selections from this window into the command window.

References File menu, Section 2.3.2

2.5 Host-Target Interaction

SwiftX supports interactive development via a debug interface known as the XTL (Cross-Target Link). This provides access to the target through a debug interface such as a serial port, BDM, or JTAG cable. XTL functions include reading and writing memory and registers, as well as controlling execution.

The XTL interface supports the following debug functions:

- Display and modify target memory
- Download code and data to target memory
- Interactively test target words
- Examine the data stack using the . S command

The XTL is discussed in detail in Section 4.9.

Section 3: Programming with SwiftX

3.1 Source-File Management

The primary vehicle for SwiftX program source is text files, which may be edited using a linked editor of your choice as described in Section 2.3.5. This section describes tools for managing text files.

3.1.1 Projects

SwiftX's source files are organized in a hierarchy, with platform-independent files at the top, then a directory for each MCU supported, and within that a directory for each target board supported. You may wish to keep your application files in a separate directory, particularly if you will be developing multiple applications or if your applications are very complex. We call such a directory a "project."

A project directory should have the following components:

- A Windows "shortcut" to the SwiftX IDE executable in the SwiftX\Bin directory (for SwiftX), or a project file (for SwiftX Pro).
- A load file, normally called Kernel . f that loads the files constituting your project, organized as described in Section 3.1.4.
- A configuration file, normally named Config. f. that specifies memory organization and other global configuration parameters for your program, described in Section
- The source files for your project, perhaps in a hierarchy if it is a complex project.

You can find examples of **Kernel**. **f** and **Config. f** in the directory for your target board.

SwiftX Pro contains features that help you manage projects; with SwiftX, the same principles apply, but the procedures are more manual.

3.1.1.1 Project Management with SwiftX

We recommend that you build your project directory by copying into it the files supplied in the directory for your target board. You don't need to copy the entire SwiftX directory. Keep the original target board directory and its files intact, so if you have problems you can use them for comparison!

These files include a shortcut to the SwiftX executable. Do not reset the "Start in" directory in the shortcut's properties! If it stays blank, your project directory will be the default path for finding your application.

You can then customize the files (Kernel . f, Config. f, Start. f, etc.) as needed for your project. If you need to customize any other SwiftX system features, we recommend that you copy those files to your project directory and customize them there.

3.1.1.2 Project Management with SwiftX Pro

SwiftX Pro contains added features to help with setting up and managing projects. These include:

- Maintenance of project information in a special "project file" that has the extension . swx. This includes various settings for each of your projects. (With SwiftX non-Pro, these settings are global.)
- A dialog box to automate creation of a new project (copying files and settings from an existing project).
- A dialog box to open a previously defined project.



To create a new project, launch SwiftX from the target board directory that is most similar to your project's target. Then select File > New Project or the corresponding toolbar button. This will display a dialog box in which you can enter basic information about your project, as shown in Figure 11.

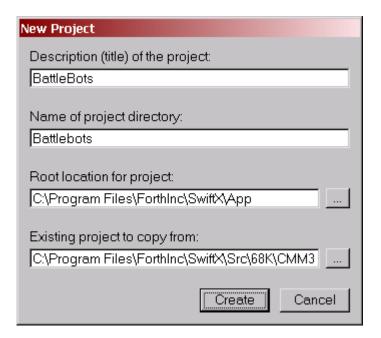


Figure 11. New Project dialog box

The "description" will appear in the title bar when you launch SwiftX from the project icon.

When you click the Create button, the new project will be constructed, necessary files will be copied into the designated directory, the current project will close, and the new one will open.



To open an existing project, select File > Open Project or its corresponding toolbar button. This will open a dialog box showing your present directory and its neighborhood, as shown in Figure 12. Navigate to the project directory of your choice, and click OK. If you select a directory that does not contain a project file, the OK button will be disabled. When you select a directory with a valid project file, your present project will close, and the new one will open.

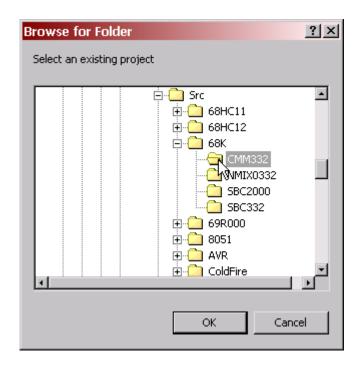


Figure 12. Open project dialog box

The project file itself is a simple text file. You may edit it using any text editor (the default is Notepad).

3.1.2 Interpreting Source Files

You may load source files using the File > Include menu option or by typing:

INCLUDE <filename>

...in the command window. The functional difference between these is that the button and menu options display a browse window in which you can select the file, and they change SwiftX's current path to that of the selected file, whereas the typed command handles a specified file (including relative path information) and doesn't *affect the current path.*

The INCLUDE command causes all of a file to be loaded, as in:

INCLUDE HEXCALC

...where the filename extension . **f** is assumed, if no other extension is given.

The standard DOS/Windows rules for describing paths apply:

- 1. **Absolute path** The name starts with a \ or <dri ve>:\ or \\<name>\. Any of these indicates an absolute path to the file.
- 2. **Relative path to subdirectories** The name does not begin with a \ or . . \ and the file is located in the current directory or in a subdirectory below it.
- 3. **Relative path to parent directories** The name begins with a series of . . \ (two periods and a backslash). Each series raises the location one directory level from the current subdirectory. After you have raised the level sufficiently, you can use the technique in #2 to go down subdirectory levels.

In addition, SwiftX can manage paths relative to the location of the actual executable (normally in the Swi ftX\Bi n directory). Such paths are indicated by the starting symbol %, and the actual root is two levels above wherever the executable is. For example, the shared (platform-independent) core definitions are loaded by the phrase:

INCLUDE %SWIFTX\SRC\CORE

If you have launched SwiftX from a project file or shortcut in your project directory (described in Section 3.1.1), your default path is that directory, so you don't need to preface local files with any path information. So, your local configuration file could be loaded like this:

INCLUDE CONFIG

For examples of this, see the **Kernel** . **f** file in your target board directory.

The CD (Change Directory) command works as it does in a Windows command line, except there must be a space between CD and any following string. The CD command followed by *no* string will display your current path. No spaces are permitted in the pathname, and no other command may appear on the line.

Files can load other files that load still others. It is the programmer's responsibility to develop load sequences that can be maintained well. We recommend that you cluster the INCLUDE commands for a logical section of a program into a single file. rather than scattering INCLUDEs throughout the source: your program will be more manageable if you can look in a small number of files to find the INCLUDE sequences. A good example is the main load file for the SwiftX kernel, Kernel. f (found in your project directory or the directory for your target board).

To see a log of the names and target addresses of all definitions, you may set:

LOGGING ON

This causes any INCLUDE operation to display in the command window a log showing the locations of definitions compiled, which may be printed or saved using the File menu items described in Section 2.3.2.

Glossary

INCLUDE <filename>[<.ext>]

Directs the text interpreter to process *filename*; the extension is required if it is not

. f. Path information is optional; it will search only in the current path, unless you precede *filename* with path information. Leaves **BASE** set to decimal. **INCLUDE** differs from the File > Include menu option and Toolbar button in that it does not offer a browse dialog box and does not change the current path. Preceding the path and filename by % causes the path to be relative to the system root directory (up two levels from the directory from which your . exe file was launched).

LOGGI NG

(— addr)

Returns the address of a switch controlling display of names and target addresses of cross-compiled definitions. To enable the display, use the phrase LOGGING ON. To disable it, use LOGGI NG OFF.

References

File-based disk access, Forth Programmer's Handbook, Section 3.4

3.1.3 Extended Comments

It is common in source files to wish to have commentary extending over several lines. Forth provides for comments beginning with ((left parenthesis) and ending with) (right parenthesis) to extend over several lines. However, the most common use of multi-line comments is to describe a group of words about to follow, and such descriptions frequently need to include parentheses for stack comments or for actual parenthetical remarks.

To accommodate this, SwiftX defines braces as functionally equivalent to parentheses except for taking a terminating brace instead of the right parenthesis. So a multi-line comment can begin with { and end with }, and can contain parenthetical remarks and stack comments. Note that the starting brace, like a left parenthesis, is a Forth word and therefore must be followed by a space. The closing brace is a delimiter, and does not need a space.

For extra visual highlighting of extended comments, SwiftX uses a full line of dashes at the beginning and end of an extended comment:

{ -----Numeric conversion bases Forth allows the user to deal with arbitrary numeric conversion bases for input and output. These are the most common. -----} Glossary { Begin a comment, which may extend over multiple lines, until a terminating right brace } is encountered. // (-)During an INCLUDE operation, treat anything following this word as a comment; i.e., anything that follows \\ in a source file will not be compiled.

3.1.4 File Load Order

The main load file for your system is **Kernel**. **f**. Its contents are organized into groups identified by a comment at the beginning of each:

- Nucleus contains functions that, collectively, represent most of the run-time words in the ANS Forth Core wordset (the compiler and interpreter words are available on the host). Most are required, but the two files called **Double**. **f** (at different directory levels) may be omitted if you do not need 64-bit and mixed 32-bit/64-bit arithmetic. The last file in this group, **Methods**. **f**, is also optional; it supports the ANS Forth word VALUE, which you may or may not use.
- Extensions contains the multitasker and also Tools. f (containing?, . S, and DUMP, which are extremely useful in debugging but are rarely used in applications). The multitasker is quite small, and we recommend keeping it even if you have only one task, because the interaction it provides between interrupts and task-level processing is very convenient.
- **Drivers** supports hardware specific to your SwiftX system. These files are required for the system as shipped, but you may need to modify or replace them if your ultimate target hardware is different from the demo target board.
- **Initialization** contains the startup functions, and must be last.

Near the end of Kernel . f, a file App. f is loaded. This is intended to serve as the main load file for your application. If your program is very small, you may put its code directly in App. f. More commonly, however, you will organize your application in multiple files and use App. f to INCLUDE them.

Files containing new code that is being tested can be loaded interactively using File > Include (described in Section 1.5.4) and the procedures described in Section 3.2.1. When you are confident that it works, you may add it to App. f.

3.1.5 File-related Debugging Aids

You can monitor the progress of an **INCLUDE** operation by using a flexible utility enabled by the command **VERBOSE** and disabled by **SILENT**. The level of monitoring is controlled by the dialog box, shown in Figure 13, which can be invoked by using the Options > Include monitoring menu item. The default behavior is "Display the text of each line."

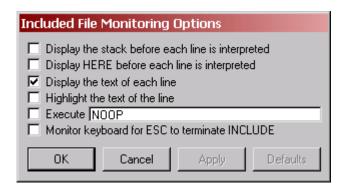


Figure 13. Configuring INCLUDE debugging aids

For example, you might place these commands in a file where there is a problem:

VERBOSE < troublesome code > SI LENT

VERBOSE turns on the monitor; **SILENT** turns off the monitor. While monitoring is active, any INCLUDE also displays the name of the file being processed.

These words are not "immediate," which means they should be used outside definitions unless you specifically intend to define a word that incorporates this behavior.

The default mode for the system is **SI LENT**.

```
Glossary
VERBOSE
            Enables the INCLUDE monitor, with a default behavior of "display the text of each
            line."
SI LENT
                                                                           (-)
            Disables the INCLUDE monitor.
```

3.2 Program Development Strategy

SwiftX ships with a pre-compiled kernel configured to contain representative functions and a simple demo application (described in Section A.2). This section describes the overall procedure for developing and testing your application.

Application development with SwiftX generally follows a pattern of incremental compiling and testing of increasingly complex application functions. If your target allows you to download new code into its memory, this is extremely easy.

The overall process is as follows:

- 1. Write a related set of functions.
- 2. Test them interactively.
- 3. Add them to your **App**. **f** file (see Section 3.1.4).
- 4. Repeat steps 1-3 as necessary until you're finished.
- 5. Move your highest-level functions and start-up code into App. f, ready to run from PROM as a standalone program.

3.2.1 Interactive Development

The interactive development phase should occupy most of your time. It depends on using a modified version of the file **Debug**. **f** supplied with your system, and requires writable code space (preferably RAM, but flash or EEPROM can be used with some inconvenience) for the code under test.

The basic procedure is to replace the demo files (which are loaded in **Debug. f** between the commands SET-DOWNLOAD and DOWNLOAD-ALL) with the files being tested, as described in Section 4.9.1. You may list the files individually or, especially as your application grows more complex, use an INCLUDE file such as the file App. f, as described in Section 3.1.4. Since SwiftX is temporarily disconnected from the target between SET-DOWNLOAD and DOWNLOAD-ALL, however, you cannot do such things as initializing uData or interrupt vectors at this time.

In general, we strongly recommend that you centralize all target initialization functions, because it will be easier to manage them during development and when bringing up your standalone system when you're finished. Depending on the extent of required initialization, you can group such activities in a definition, or as a few definitions in a file. During interactive development, you can do these things when the target is reconnected following the **DOWNLOAD-ALL**.

If your application is large or your RAM code space is limited, you may wish to incrementally test related groups of functions and, after they are tested, add them to the kernel by moving their INCLUDEs to App. f.

3.2.2 Building an Application for ROM

When all your application has been tested interactively, it is time to configure your final application. This generally is done by moving the loading of your application files to the file App. f (which is loaded by the main file Kernel . f). If your application is very complex, you may wish to group major components into their own load files, which are each loaded by App. f.

Two major steps remain before your application is completely finished:

- 1. Remove un-needed code from your kernel.
- 2. Perform all application-related hardware and software initialization functions.

The first may be done in stages. If memory is in short supply even during development, study the list of functions loaded in Kernel . f and discard those you know you won't need (e.g., fraction arithmetic). As your familiarity with SwiftX and your application grows, you may be able to discard more.



When your application is complete and installed in the App. f file loaded by Ker**nel** . **f**, SwiftX Pro users can apply the ultimate weapon: the stripper. This feature Strip (Project > Strip) repeatedly does a Build, noting each time which (if any) words were never called. On the next pass, the compiler will skip those words. When words have been omitted, any additional words *they* called may be freed on the next pass. When two successive compiles give the same target size, the process has completed—your application has everything it needs and nothing more. The source files are not affected. If you wish, you can display the list of stripped words at the end of code stripping operation. To use this feature, type . STRIP BUILD on the command line instead of using the Strip button.

We don't recommend using Strip until your application is essentially complete and tested, as you may strip from your kernel functions you will need later.

If you are a SwiftX (non-Pro) user, you can manually omit from **Kernel**. **f** any files containing features not needed by your application.

Power-up initialization is performed in two files named **Start**. **f**. One of these is in the directory for your MCU, and the other is in the directory for your board. If you have custom hardware, you may have to modify the board-level version.

Basic hardware initialization is performed by the SwiftX kernel in the POWER-UP routine in the board-level **Start**. **f**, and handles these general requirements:

- 1. Low-level hardware initialization—e.g., disables interrupts until interrupt vectors are set, configures memory, etc.
- 2. Forth virtual machine initialization—e.g., sets the data and return stack pointer registers and the multitasker user pointer.
- 3. Sets up interrupt vectors and enables interrupts. If you have specified interrupts in your drivers, they will already have been installed in a table copied to the "live" interrupt vectors by this code; see your MCU-specific manual for details.
- 4. Jumps to the high-level startup routine.

The address of **POWER-UP** is placed in the device's reset vector location.

Most initialization is performed by the high-level startup routine named START, usually found at the end of the board-level **Start**. **f** file. Here's a representative example:

```
| : START ( -- )
    OPERATOR CELL+ STATUS DUP |U| ERASE \ Set up OPERATOR task
    |OPERATOR| CMOVE /IDATA\ Initialize iData
    /CLOCK /SERIAL GO; \ I/O, launch application
```

The default contents of the file App.f (which is intended to be used to load your application) is a single definition for GO, as follows:

```
: GO ( -- )
              DEBUG-LOOP :
```

This simply starts the XTL running. In order to launch your application from power-up (rather than from Debug) you need to replace this with a definition that performs any additional initialization required by the application and that finally calls the highest-level word in the application that makes it all run.

Section 4: Cross-compiler Principles

This section covers the requirements of the cross-compiler used to develop the target program, including methods you may use in source files that will generate target code—such as techniques for mapping memory, controlling the compiler in various ways, and accessing the code and initialized data space images in the host and target.

The cross-compiler uses the same words as a resident Forth system to construct definitions, and to define and manage data objects. The discussion of these words in this section focuses on special issues related to cross-compilation; please refer to the Forth Programmer's Handbook for basic descriptions and examples of usage.

4.1 Cross-compiler Control

This section describes how you can control the SwiftX cross-compiler using typed commands and (more commonly) program source. In most respects, words typed at the command-line in the SwiftX command window are treated identically to program source—anything you do in source may be done interactively.

4.1.1 Input Number Conversions

When the SwiftX text interpreter encounters numbers in the input stream, it converts them to binary. If the system is in compile mode (i.e., between a: and;), it compiles a reference to the number as a literal and, when the word being compiled is executed later, that number will be pushed onto the stack. If the system is interpreting, the number will be pushed onto the host's stack directly.

All number conversions in Forth are controlled by the user variable BASE. The host system's BASE controls all input number conversions on the host; there is also a **BASE** in the target that controls number conversions performed by the target system. The words described in this section are used to control both the host and target versions of BASE. In each case, the requested base will remain in effect until explicitly changed. Punctuation in a number (decimal point, comma, colon, slash, or dash anywhere other than before the leftmost digit) will cause the number to be converted as a double number; see Section 6.1.

In addition, input number conversion may be directed to convert a single number using the base specified by a prefix character from Table 10. Following such a conversion, BASE remains unchanged from its prior value. If the number is to be negative, the minus sign must *follow* the prefix and *precede* the most-significant digit.

Table 10: Number-conversion prefixes

Prefix	Conversion base	Example
%	Binary	%10101010
&	Octal	&177
#	Decimal	#-13579
\$	Hex	\$FE00

References Enhanced number conversion, Section 6.1

4.1.2 Conditional Compilation

[IF], [ELSE], and [THEN] support conditional compilation by allowing the compiler to skip any text found in the unselected branch. These commands can be nested, although you should avoid very complex structures, as they impair the maintainability of the code.

Say, for example, you have defined a flag this way (see **Confi g. f**):

```
O EQU MEM-MAP
                              \ 1 Enables memory diagnostics
```

then in **Kernel** . **f** you might find the statement:

```
MEM-MAP [IF] INCLUDE ..\..\MEMMAP [THEN] \ Report memory use
and later, this one:
```

```
MEM-MAP [IF] . ALLOCATED [THEN]
                                       \ Display data sizes
```

Conditional compilation is also useful when providing a high-level definition that might be used if a code version of a word has not been defined. For example, in **Strings**. **f** we find:

```
[UNDEFINED] -ZEROS [IF]
: -ZEROS ( S: c-addr n -- c-addr n' ) \ Remove trailing Os
    <high-level code>;
[THEN]
```

[UNDEFINED] < word> will return a true flag if word has not been defined. Thus, if a code or optimized version of **-ZEROS** was included in an earlier CPU-specific file (e.g., Core. f), it will not be replaced when this file is compiled later. Note that load order is extremely important!

In contrast, [DEFINED] <word> will return a true flag if word has been defined previously.

References Conditionals, Forth Programmer's Handbook, Section 2.5.3

4.2 Target System Configuration

System configuration occurs in the file

Swiftx\Src\<CPU>\<Target>\Config.f

...which specifies the memory organization of the target system and other options. Platform-specific configuration issues are discussed in your target-specific documentation.

SwiftX divides target memory into two logical regions, as shown in Figure 14: code space (which may or may not be in ROM) and data space (directly accessible RAM). Data space is further divided into *initialized* and *uninitialized* regions. Initialized data space may be pre-set to specific values at compile time; these values will be automatically copied into initialized RAM at power-up in the target. You may further define multiple sub-regions of each type, as discussed in Section 4.3.

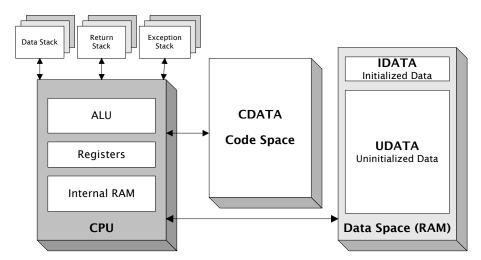


Figure 14. The Forth virtual machine in a SwiftX target

Other options specified in **Confi g**. **f** include:

- Baud rate used for a serial XTL, if the target communicates that way. This is discussed further in Section 4.9.1.
- Flags controlling whether a target-resident interpreter is being used (for SwiftX Pro customers only) and, if so, whether the default is to keep heads on target definitions. The target-resident interpreter option is discussed further in Section Section 7:.

4.3 Memory Allocation

SwiftX provides a very flexible scheme for declaring and managing multiple, possibly discontiguous, memory spaces of different types. Each section of memory must first be declared as described below. Memory can then be allocated using the defining and storage allocation words that follow.

Target memory space can be divided into multiple sections of three types, shown in Table 11. Managing these spaces separately provides an extra measure of flexibility and control, even when the target processor does not distinguish code space from data space.

The words in Table 11 select a *current section type*. The current section type controls data defining words, memory allocation, and memory accesses of various types, both during compilation and during interactive testing

Table 11: Memory section types

Туре	Description
CDATA	Code space; includes all code plus initialization tables. May be in PROM.
I DATA	Initialized data space; contains preset values specified at compile time and instantiated in the target as part of power-up initialization.
UDATA	Uninitialized data space, allocated at compile time. Its contents are unspecified.

At least one *instance* of each section must be defined, with upper and lower address boundaries, before it is used. Address ranges for instances of the same section type may not overlap. The syntax for defining a memory section is:

<low address> <high address> <type> SECTION <name>



There is one exception to this rule: If no iData section is defined, the vectored operators that would normally act on iData will use the current cData section instead, This scheme should only be used when the following conditions are met:

- 1. The CPU does not have separate code and data spaces (i.e. this is not a Harvard Architecture machine).
- 2. No matter what the boot medium (PROM, flash, disk, etc.), the target loads the cData image into RAM for execution.

An instance becomes the *current section* of its type when its name is invoked. The compiler will work with that section as long as it is the current one, maintaining a set of allocation pointers for each section of each type. Only one section of each type is current at any time.

The words used to allocate and access memory (the *vectored words* in the glossaries below) operate on the *current* section of the *current* type. Some words control only cData, and are available any time; their use does not affect the selection of the current section or type. Use of one of the section type selectors CDATA, I DATA, or UDATA sets the section type for the vectored words. If you only have one section of each type, the section *names* are rarely used.

Here is an example from a typical Config.f file with one section of each type:

INTERPRETER HEX 00000000 0001FFFF CDATA SECTION PROG \ Code space 20000400 20001FFF IDATA SECTION CONST-DATA \ Initialized data 20002000 2000FFFF UDATA SECTION EXT-DATA \ Uninitialized data

The current state of all section definitions, including the current section type and the current section of each section type—but not the contents of the sections—is called the section context. It may be saved and restored by SAVE-SECTIONS and RESTORE-SECTIONS.

Glossary **Section Type Selectors**

CDATA

Select cData as the current section type.

I DATA

Select iData as the current section type.

UDATA

Select uData as the current section type.

SECTION < name> $(addr_1 addr_2 -)$

> Define *name* as a section of the current section type, occupying the address range $addr_1$ (low) through $addr_2$ (high).

SAVE-SECTIONS $(-n^*x n)$

Save the entire current section context, consisting of *n* cells.

(n*xn-)**RESTORE-SECTIONS**

Restore the entire section context previously saved by SAVE-SECTIONS.

Vectored Words

ORG (addr -)

> Set the address of the next available location in the current section of the current section type.

(-addr)**HERE**

> Return the address of the next available location in the current section of the current section type.

ALLOT (n-)

> Allocate *n* bytes at the next available location in the current section of the current section type.

ALI GN (-)

> Force the space allocation pointer for the current section of the current section type to be cell-aligned.

ALI GNED (addr - a-addr)

Force *addr* to be cell-aligned.

(b-)C,

Compile *b* at next available location (cData and iData only).

W, (x-)

> Compile a word (the low-order 16-bits of x) at the next available location (cData and iData only). Available on 32-bit targets only.

(x-)

Compile a cell at the next available location (cData and iData only).

cData-specific Words

(-addr)**THERE**

Return the address of the next available location in the current cData section.

(n-)**GAP**

Allocate *n* bytes at the next available location in the current cData section.

C, C

Compile *b* at the next available location in the current cData section.

(x-)W, C

Compile a word (low-order 16-bits of x) at the next available location in the current cData section. Available on 32-bit targets only.

, C (x-)

Compile a cell at the next available location in the current cData section.

Compiling words and literals. Forth Programmer's Handbook, Section 2.9 References

4.4 Defining Words

Most defining words in SwiftX are used to create executable target definitions. Some—such as those created by : (colon) and CODE—are executable functions; others are data objects of various kinds. However, data objects may be thought of as having an executable component (or characteristic behavior), as well as a data component (or value). For example, the behavior of a word defined by CONSTANT is to return its value, whereas a word defined by VARI ABLE returns the address of its data.

One defining word, **EQU**, does not exist in the target. An **EQU** is a constant for use by the cross-compiler, and has neither an executable component nor data space in the target. **EQU** is typically used to name an address, flag, size, etc., that the cross-compiler will use in preparing the target system. When used insdie a target colon definition, an **EQU** will be compiled as a literal. This feature is used to great advantage by the Optimizer in many SwiftX Pro implementations.

Target defining words place their executable components in code space. Datadefining words such as CREATE—and custom defining words based on CREATE—make definitions that reference the section type and instance that are current when CRE-**ATE** is executed.

Because uData is only *allocated* at compile time, there is no compiler access to it. uData is allocated by the defining words themselves; a summary of defining words is given below. At power-up, uData is uninitialized.

Space allocated by a single BUFFER: definition or by a single call to RESERVE or ALLOT is guaranteed to be contiguous.



Important: There is no guarantee that space allocated by successive uses of any series of allocation or defining words will be contiguous. So if you define VARI ABLE X1 followed immediately by VARI ABLE X2 you may not make any assumption about their order (or space between them) in memory. If the target CPU has any memory alignment requirements, the defining and allocation words will force the starting address to that unit of alignment (word, cell, etc.) as needed.

More details on the use of defining words, and how to make custom defining words, may be found in the Forth Programmer's Handbook.

Glossary

EQU <name>

(x-)

Define a one-cell constant in the host only, whose value is x. If an **EQU** is referenced inside a target colon definition, its value will be compiled as a literal. Execution of *name* returns *x*.

CREATE < name>

Define a named reference to the next available location in the current target section. Does not allocate any data space.

CONSTANT < name> (x-)

> Define a one-cell constant whose value is x. Execution of *name* returns x. You cannot change the value of a **CONSTANT**.

2CONSTANT < name> $(x_1 x_2 -)$

> Define a two-cell constant whose values are x_1 x_2 . Execution of *name* returns x_1 x_2 . You cannot change the value of a **2CONSTANT**.

VALUE <name> (x-)

> Define a one-cell, named value in iData, initialized to x. When executed, name will return its value like a **CONSTANT**. To change the value, use:

<new-x> T0 <name>

TO <name> (x-)

Store *x* in *name*'s data space. *name* must have been defined by **VALUE**.

CVARIABLE < name>

Define a one-byte named location in uData. Execution of *name* returns the address of its data space.

WVARIABLE < name>

Define a word-length (16-bit) named location in uData. Execution of *name* returns the address of its data space. Available on 32-bit targets only.

VARIABLE < name> (-)

> Define a one-cell, named location in uData. Execution of *name* returns the address of its data space.

BUFFER: <name> (n-)

> Define a named array of length n bytes in uData. Execution of name returns the address of the start of its data space.

RESERVE (n - addr)

Allocate *n* bytes of uData, starting at *addr*.

References Defining words, Forth Programmer's Handbook, Section 2.7 Custom data objects. Section 4.7

4.5 Memory Access

Words that access code and data space are described in this section. The behavior of these words depends critically on the context in which they are used. When they are used inside target definitions, they behave in a straightforward manner, referencing target data at given addresses as described in the Forth Programmer's Handbook.

However, if you use these words interpretively (e.g., typing them during debugging, outside of definitions in a source file, or in the compile-time part of a defining or compiling word), they have a special cross-compiler behavior that depends on whether you are connected to a running target system using the XTL (see Section 4.9.1).



Unless you are connected to a running target, access using the words described in this section is restricted to cData and iData.

This section specifically describes the cross-compiler (interpreting or compiling) behavior of these words.

4.5.1 Basic Memory Access Commands

The following words are used to access individual bytes, cells, and words. As with the allocation and initialization words in Section 4.3, the primary words are vectored according to the current section type; but some convenient cData-specific equivalents do not affect the selection of the current section type.

(addr - x)

Vectored Words Glossary

(addr - b)C@

Fetch a byte from *addr* in the current section of the current section type.

Fetch a word (16-bits) from addr in the current section of the current section type.

Available on 32-bit targets only.

W@

(addr - x)

Fetch a cell from *addr* in the current section of the current section type.

(*b* addr —) C!

Store a byte at *addr* in the current section of the current section type.

W! (x addr -)

> Store a word (the low-order 16-bits of x) at *addr* in the current section of the current section type. Available on 32-bit targets only.

İ (x addr -)

Store a cell at *addr* in the current section of the current section type.

cData-specific Words

(addr - b)C@C

Fetch a byte from *addr* in the current cData section.

(addr - x)W@C

Fetch a word (16-bits) from *addr* in the current cData section. Available on 32-bit

targets only.

(addr - x)@C

Fetch a cell from *addr* in the current cData section.

C! C (*b* addr —)

Store a byte at *addr* in the current cData section.

W! C (x addr -)

Store a word (low-order 16-bits of *x*) at *addr* in the current cData section. Available

on 32-bit targets only.

(x addr -)!C

Store a cell at *addr* in the current cData section.

References Memory allocation, Section 4.3

4.5.2 String Initialization and Management

The following words are used to initialize and manage strings. All are vectored according to the current section and section type. See Section 4.5 for the restrictions that apply to these words.

Glossary

(c-addr len —) BLANK

Fill area with spaces.

(*c*-addr len −) **ERASE**

Fill area with zeros.

(c-addr len b -)FI LL

Fill area with *len* copies of *b*.

 $(c-addr_1 c-addr_2 len -)$ MOVE

Copy len bytes from c-add r_1 to c-add r_2 .

S" <text>" (— c-addr len)

> Build a string, which must be terminated by ", at HERE and return its address and length.

References String operations, Forth Programmer's Handbook, Section 2.3

4.6 Compiler and Interpreter

This section describes SwiftX tools used to create and test target commands. Forth's compiler and interpreter work together to process source text for this purpose. Strictly speaking, a Forth compiler is only operating between the colon that begins a definition and the semi-colon that ends it. The interpreter is processing the text, finding words and either executing them or delivering them to the compiler for processing. However, the consequence of executing most of the words encountered in source text causes definitions and data objects to be constructed and manipulated in the target image, both inside and outside of colon definitions. an activity that falls within the broad, commonly understood meaning of compilation. It is this broader definition that we will discuss in this section.

4.6.1 Basics of Compilation

A Forth compiler works by interpreting source text—e.g., by executing commands that create data structures, commands that initialize data structures, and commands that begin compilation or that assemble machine instructions. Other commands may control various aspects of the compiler itself.

The glossary below lists examples of defining words used to begin compilation or when creating defining words. Data-space defining words are described in Section 4.4; commands that allocate or fill memory are listed in Section 4.3.

Glossary

CODE <name>

Begin assembling a word that will be executed when referenced. Target CODE words may not be referenced outside a colon definition unless the host is connected to the target with an active XTL.

(-)LABEL <name>

> Begin assembling a word that will return the address of its code when referenced. A **LABEL** may be referenced at any time, inside or outside a definition.

END-CODE (-)

End a code word that was started with **CODE** or **LABEL**.

: <name>

Begin compiling a Forth definition. Target definitions may not be referenced outside a colon definition unless the host is connected to the target with an active XTL.

DOES>

Begin the run-time action of a new defining word written in high-level Forth. Used with **CREATE** (see the *Forth Programmer's Handbook* and Section 4.7).

; CODE (-)

Similar to **DOES>**, but the run-time action is written in assembler code.

End a Forth definition that was started with: (colon).

Defining words, Forth Programmer's Handbook, Section 2.7 References

4.6.2 Compiler Scoping

Many details of this advanced subject are outside the domain of this document; they are covered more thoroughly in the Forth Programmer's Handbook. However, when developing a target application, sometimes it can be helpful to extend the supplied cross-compiler. To do so, it is necessary to understand that a Forth system implements multiple (e.g., host and target) versions of some words and selects among them by managing the way in which its dictionary is searched.

For example, a Forth cross-compiler includes an integral Forth compiler and assembler; they are used to build the target compiler and assembler which, in turn, are used to construct target code. But some words—from simple primitives to higherlevel compiler words like: (colon) and IF—are defined in more than one of these places, and are implemented differently in each to provide specific functionality in each context.

To enable the programmer to access specific versions of compiler and assembler commands, Forth supports a scoping method based on named word lists and on the order in which the dictionary is searched. SwiftX's support for scoping is based on the optional Search-Order Wordset in ANS Forth. These facilities are used to define several compiler directives for managing scope in the cross-compiler.

The scopes defined in SwiftX are listed in Table 12. These words specify the scope to which new words will be added, as well as the words that are available to the compiler. Each of these remains in effect until explicitly changed.

By default, new commands belong to the TARGET scope; i.e., they are compiled onto the target. But after the ASSEMBLER command, new words will be added to the assembler and will be found while assembling machine instructions into the target. Likewise, after the INTERPRETER command, new words are added to the host that will be found when the host is interpreting on behalf of the target; and so on.

If you use any of these scope selectors (or compiler directives) to change the default scope, you must later use TARGET before commands can again be compiled to the target. SwiftX's status line (at the bottom of the command window) indicates the current scope, so you can easily verify, for example, that the current scope is TARGET when you attempt to interactively test a target word.

Table 12: Scope selectors

Command	Type of word to be compiled
ASSEMBLER	Words executed on the host while compiling assembly language definitions for the target. Typically, they provide machine code instructions and addressing modes.
COMPI LER	Words used on the host while compiling target commands. Typically, they aid the target compilation process.
COMPI LER-CODE	Like COMPILER , but places assembler mnemonics at the front of the search order.
HOST	Words that provide support for the cross-compiler and debugging.
I NTERPRETER	Words executed on the host while interpreting on behalf of the target. Typically, they set up data struc- tures, allocate memory, or start compilation.
TARGET	Words compiled onto the target, available to target programs. (The default scope.)
TARGET-SHELL	Like TARGET , but adds definitions that are only available in the target-resident interpreter (not from the debug window).

The compiler directive in force at the time you create a new colon definition is the scope in which the new word will be found. As a trivial example:

```
TARGET ok
: Test1 1 . ; ok
Test1 1 ok
INTERPRETER ok
Test1
Error 0 TEST1 is undefined
```

On rare occasions, while defining a new word, you might need to specify words from scopes other than the one currently in effect. Therefore, the specifiers in Table 13 are provided for use inside colon definitions being built in the host. They add the search orders COMPILER, ASSEMBLER, etc., to the beginning of the current search order, without otherwise changing the search order. These additions normally are for some limited, specific purpose, so the command [PREVI OUS] may be used to remove the most recent addition.

Table 13: Search-order commands for extending the cross-compiler

Command	Search Order	Typical use
[+ASSEMBLER]	ASSEMBLER	Build assembler macros.
[+I NTERPRETER]	I NTERPRETER	Access the INTERPRETER behavior of a defining word.
[+HOST]	HOST	Access the HOST behavior of words defined for HOST and TAR-GET.
[+TARGET]	TARGET	Access TARGET words in an INTERPRETER or HOST definition.
[PREVIOUS]	Remove the most recently added search order.	Restore previous search order after completing the action enabled by one of the words above.

Glossarv

ASSEMBLER

(-)

Select **ASSEMBLER** scope. This provides access to the native instruction set of the target CPU. Selecting this scope lets you customize your assembler, for example, by adding macros.

COMPILER

Select **COMPILER** scope. Words defined in this scope will be available for execution only while compiling target colon definitions; selecting this scope lets you customize your compiler. Examples of COMPILER words include IF, ELSE, THEN, BEGIN, UNTIL, **DO**, **LOOP**, and similar words.

HOST

(-)

Select **HOST** scope. **HOST** words are used on rare occasions to extend the host system to provide specialized compiler capabilities that will be used in scopes other than TARGET, or to execute the host versions of words that have been redefined in other scopes.

INTERPRETER

Select INTERPRETER scope. Add the following definitions to the host environment's interpreter. INTERPRETER words are used to create target data objects. Examples include **CREATE**, **VARI ABLE**, etc.

TARGET

(-)

Select TARGET scope. This is the default compiler state. If you select another scope, you must re-assert **TARGET** before producing any more target definitions.

Target colon definitions are available for interactive execution and testing only when you are connected to a target via an interactive XTL. Target data objects are executable when interpreting, according to the guidelines in Section 4.6.4.

[+ASSEMBLER]

Add ASSEMBLER scope to the current scope inside a colon definition. This gives access to mnemonics, addressing modes, etc., to define assembler macros.

[+INTERPRETER] (-)

Add INTERPRETER scope to the current scope inside a colon definition. This lets you access the compile-time behavior of a defining word.

[+HOST] (-)

Add HOST scope to the current scope inside a colon definition. This lets you access the underlying Forth system's behavior of a word that is defined in both HOST and **TARGET** (e.g., @).

[+TARGET]

Add TARGET scope to the current scope inside a colon definition. This lets you access target words from within an INTERPRETER or HOST definition.

[PREVIOUS] (-)

> Remove the most recently added scope from the search order. This is normally used following the actions enabled by words such as [+ASSEMBLER] above, to return to the previous scope.

References Word lists and search order, Forth Programmer's Handbook, Section 3.6

4.6.3 Effects of Scoping on Colon Definitions

The behavior of words defined in each of these scopes is different for colon definitions than for data objects, and also depends upon the state (compiling or interpreting) in which they are invoked.

The default behavior of colon definitions defined in HOST, INTERPRETER, or TARGET when they are invoked in compiling state is to compile a reference to the word. The default behavior of words defined in COMPILER is to be executed, the usual consequence of which is to modify a colon definition that is being constructed.

The default behavior of colon definitions when they are invoked in interpreting state is to be executed. However, **COMPILER** words may *not* be invoked in interpreting state, and TARGET words may only be invoked when you are connected to a target via an active XTL.

Table 14 shows the accessibility of colon definitions defined in various scopes when they are invoked in interpreting and compiling states.

Table 14: Scopes in which colon definitions are accessible

	Available in these scopes while		
If defined in:	interpreting: compiling:		
ASSEMBLER	ASSEMBLER	ASSEMBLER (used to define macros)	
COMPI LER	Not allowed	TARGET	
HOST	HOST, I NTERPRETER, COMPI LER	HOST, I NTERPRETER, COMPI LER	
INTERPRETER	TARGET	I NTERPRETER	

Table 14: Scopes in which colon definitions are accessible (continued)

	Available in these scopes while	
If defined in:	interpreting:	compiling:
TARGET	Not allowed unless connected	TARGET

Special state-dependent behaviors, if any, of words described in this manual will be described where they differ from the *default behavior* displayed when interpreting (for HOST and INTERPRETER words), compiling (for COMPILER words), or when the target is executing the word (for TARGET words).

4.6.4 Effects of Scoping on Data Object Defining Words

Defining words other than: (colon) are used to build data structures with characteristic behaviors. Many such words are included in SwiftX, and it is possible to construct new ones, if you wish.

Normally, a SwiftX programmer is primarily concerned with building data structures for the target system; therefore, the dominant use of defining words is in the TARGET scope while in interpreting state. You may also build data objects in HOST that may be used in all scopes except TARGET; such objects might, for example, be used to control the compiling process. Data objects fall into three classes:

- *iData objects* in initialized data memory—e.g., words defined by **CREATE**, **VALUE**, etc., including most user-defined words made with CREATE ... DOES>.
- *uData objects* in uninitialized data memory—e.g., words defined by the use of **VARI** -ABLE, BUFFER:, etc.
- Constants—words defined by CONSTANT, 2CONSTANT, and USER.

Unlike target colon definitions, target data objects may be invoked in interpreting state. However, they may not exhibit their defined target behavior, because that is available only in the target (or in interacting state). Constants will always return their value; other words will return the address of their target data space address. iData objects may be given compiled, initial values with , (comma) and C, (ccomma), and you may also use @ and! with them regardless of whether you're connected to a target with an active XTL. However, there is no way to initialize uData objects at compile time, and you may only access their data space when the XTL is connected and active.

4.7 Custom Data Objects

One of the most powerful features of Forth is the ability to construct custom dataobject defining words. The basic principles of custom defining words in Forth are discussed in the Forth Programmer's Handbook.

However, some special issues arise when creating custom data objects in a crosscompiled environment: defining words are executed on the host, to create new definitions that can be executed on the target. Therefore, you must be in the INTER-**PRETER** scope (see Section 4.6.2) when you create a custom defining word, and you must be aware of what data space you are accessing (see Section 4.3) in the new data object.

Consider this example:

```
INTERPRETER
\ PRINTS defines words that display their values.
: PRINTS ( n -- )
      CREATE ,
                                 \ New definition with value n
     DOES> ( -- )
                                 \ Assign run-time behavior
      @ . ;
                                 \ Fetch value and display it
TARGET
1 PRINTS ONE
2 PRINTS TWO
```

ONE and **TWO** are target definitions, *instances* constructed by the defining word PRINTS. Each instance has its own value, but all objects defined by PRINTS share the run-time behavior (@ and .) associated with PRINTS.

You must specify INTERPRETER before you make the new defining word, and then return to TARGET to use this word to add definitions to the target. The INTERPRETER version of DOES> allows you to reference TARGET words in the execution behavior of the word, since that will be executed only on the target.

When **CREATE** (as well as other memory allocation words listed in Section 4.3) is executed to create the new data object, it uses the *current section type*. The default in SwiftX is iData. Defining words that explicitly use uData (VARI ABLE, BUFFER: , etc.) do not affect the current section type. If you wish to force a different section type, you may do so by invoking one of the selector words (CDATA, I DATA, or UDATA) inside the defining portion or before the defining word is used. If you do this, however, you must assume responsibility for re-asserting the default section. You may choose to use **SAVE-SECTIONS** and **RESTORE-SECTIONS** (described in Section 4.3).

You can control where individual instances of **PRI NTS** definitions go, like this:

```
CDATA
1 PRINTS ONE
I DATA
2 PRINTS TWO
```

In this case, the data space for **ONE** is in code space, but the data space for **TWO** is in initialized data space. (Not all processors support data objects in code spaces, so **TWO** is portable and **ONE** is not.)

Alternatively, assuming your processor permits it, you could define PRINTS to explicitly assert cData:

```
: PRINTS ( n -- )
  CDATA\ Select code section.
```

```
CREATE .\ New definition with value n.
IDATA\ Restore default iData section.
DOES> ( -- )\ Target execution behavior.
        . ; \ Fetch value and display it.
```

In this case, both the CREATE and the , (comma) will use cData.

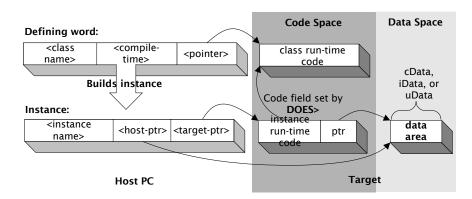


Figure 15. A defining word and an instance, in host and target

Figure 15 shows the action of a defining word. The run-time behavior of all its instances exists at one place in the target cData. The host part of the defining word can compile instances of its class, each of which has a definition in the host, a runtime behavior in the target, and a data space in the target. The host portion of an instance contains two pointers: the *host pointer* is to the data area in target address space, while the target pointer is to the instance's run-time code in the target. The instance's run-time code will call the general run-time code for the class, providing the address of the instance's data area. The data area may be in cData, iData, or uData, but is usually in iData.

The demo program Swi ftX\Src\Coni cal. f (see Section 1.5.3) contains a good example of a custom defining word, MATERIAL, used to define materials. When executed, a word that has been defined by using MATERIAL (an instance of MATERIAL) stores its parameters in the variables used in the demo program.

If you invoke an instance's name interpretively on the host, its behavior depends on whether you're connected to the target with an active XTL. If you're connected, the target pointer will be used to execute the target's run-time behavior. If not, the host pointer will be used to return the address of its data area; if that is in cData or iData, you may read or write that location in the host's target image.

It is possible to define custom host behaviors that emulate target behaviors (assuming, of course, that it's possible and doesn't require access to target-only devices or other features). The technology used to do this is called twins, because it involves making twin dictionary entries in the Interpreter and Target scopes. The two key words are TWIN (which makes a duplicate dictionary entry with one data cell, like a **VARIABLE**) and **2TWIN** (which makes a duplicate entry with two data cells, like a **2VARI ABLE**). These words are already built into pre-existing defining words that return values (e.g., CREATE, VARI ABLE, CONSTANT), but are also available for defining custom host behaviors.

Consider this example:

```
HOST
VARIABLE >FCB
                                    \ Current field, host copy
: (FCB:) ( x -- ) TWIN
                                    \ Host behavior
      DOES> (i -- addr)
                                    \ Assign host behavior
      @ >FCB @ + ;
                                    \ Return offset in >FCB struct
TARGET
VARIABLE >FCB
                                    \ Current field, target copy
I NTERPRETER
: FCB: ( n1 -- n2 )
                                    \ Defining word definition
      DUP (FCB:)
                                    \ Make host twin
      CREATE DUP , CELL+
                                    \ Make target twin
      DOES> @ >FCB @ + ;
                                    \ Target behavi or
TARGET
O FCB: ORG
              FCB: LIM
                          FCB: R#
                                     DROP
```

In this example, FCB: defines fields within a file control block in data space. The host twin word returns the field in the structure whose address is contained in the host variable >FCB. The target word returns the field pointed to by the target variable >FCB. The host twins are useful for defining precompiled structures in iData.

TWIN and 2TWIN should always be used in conjunction with a defining word (CREATE in the above example) that creates target definitions. The built-in TWIN in words like CREATE and CONSTANT is automatically bypassed if you use an explicit TWI N, as in the example.

Glossary

(x-)TWIN < name>

> Make a duplicate dictionary entry for *name* in the current scope, leaving the input stream unchanged (i.e., *name* still visible), and give it the initial value x.

2TWIN < name> $(x_1 x_2 -)$

> Make a duplicate dictionary entry for *name* in the current scope, leaving the input stream unchanged (i.e., *name* still visible), and give it the initial values x_1 and x_2 .

4.8 Saving a Compiled Object Image

SwiftX can generate the object file formats shown in Table 15. Two commands. shown in the glossary below, are available to create object files suitable for PROM programmers and for downloading. In each case, the first letter of the filename extension determines the format that will be used.

Table 15: Object-file format selection

First letter of extension	Format	Example
Н	Intel Hex format	Target.hex
S	S-record format	Target.s19
T	TI txt record format	Target.txt
any other	Binary data	Target.bin

If you have multiple cData or iData sections, each must be saved separately. For example, to save two cData sections named ProgA and ProgB, you might use:

ProgA SAVE-CODE PROGA. HEX ProgB SAVE-CODE PROGB. H

For an example, see the end of \Swiftx\Src\<MCU>\<board>\Build.f for the commands that construct your target image.

You may, if you wish, concatenate several cData or iData sections into a single multi-record image using APPEND-CODE or APPEND-DATA, respectively. For example, to write both sections in the previous example to the same file you could use:

ProgA SAVE-CODE PROG. HEX ProgB APPEND-CODE

Finally, if you are writing cData sections to records which require an absolute address that is different from the logical address for which it is compiled (e.g., code residing in PROM which will execute from a different address), you may specify the absolute address by using ABSOLUTE preceding SAVE-CODE or APPEND-CODE. Note that **ABSOLUTE** applies *only* to the *next* instance of **SAVE-CODE** or **APPEND-CODE**.

See the glossary below for details on these words.

Glossary

(addr —) **ABSOLUTE**

> Used before SAVE-CODE or APPEND-CODE, specifies the absolute address where the record is to begin.

SAVE-CODE < name. ext>

Records the current cData section in the file *name*. ext, where the filename extension *ext* indicates the format to be used, per Table 15.

SAVE-DATA < name. ext>

Records the current iData section in the file *name*. ext, where the filename extension ext indicates the format to be used, per Table 15.

APPEND-CODE

Appends the current cData section to the file initiated by a previous use of SAVE-CODE.

APPEND-DATA (-)

Appends the current iData section to the file initiated by a previous use of SAVE-DATA.

4.9 The Cross-Target Link

The Cross-Target Link, or XTL, is a key feature of SwiftX. It provides an extraordinary level of interactivity and debugging power, facilitating thorough testing of code and interactive testing of the hardware. Major features of the XTL are discussed in this section.

4.9.1 Target/Image Interactions

The cross-compiler can operate while *connected* (i.e., interacting with a terminal using the XTL) or disconnected (not connected, or not using the XTL). Building a program image for later downloading (the Project > Build menu option) may be done in either mode, because the cross-compiler keeps an image in host memory of each iData and cData section that has been defined (described in Section 4.3).

For targets using a serial line for the XTL, the command XTL-BAUD sets the baud rate. This is normally found in the project's **Config.** f file. You can get a copy of the specified baud rate using the command @XTL-BAUD. This is commonly done in conjunction with the target's driver for the port being used for the XTL.

When you are compiling a program image for later downloading, the words in Table 16 access a *host image* of the current section being constructed or maintained. In such circumstances, you may only access cData and iData.

When interacting with actual target memory via the XTL, you may access any type of space, including uData. New definitions (including colon definitions and new data structures) will modify the host image. On systems that support interactive compilation, such changes will also be downloaded to the target, immediately available for interactive testing. See your platform-specific documentation.

The **CONNECT** command establishes an XTL connection. Following this command, memory fetches are made from the remote device, and memory stores go to both the target and the host image. The **DI SCONNECT** command ends the connection; thereafter, memory fetches and stores are to the host image only. Memory commands that are directly affected are shown in Table 16; they are described further in Section 4.5.1.

Table 16: Memory access words affected by target connection

Wor	ds	Descriptions	
Ce C! Byte (character) fetch and store in the current section		Byte (character) fetch and store in the current section	
We W! Word (16-bit) fetch and store in the current section (available only on 32-bit targets)		Word (16-bit) fetch and store in the current section (available only on 32-bit targets)	
@	ļ	Cell fetch and store in the current section	

Table 16: Memory access words affected by target connection (continued)

Word	ls	Descriptions
C@C	CI C	Byte (character) fetch and store to code space
W@C	W! C	Word (16-bit) fetch and store to code space (available only on 32-bit targets)
@C	I C	Cell fetch and store to code space

The XTL is used in one of two modes:

- Fully interactive, in which you can examine target memory and execute target definitions and, also, if you type a colon or code definition it will be immediately downloaded to the target, ready for testing.
- Batch, in which the target is temporarily disconnected and an image of your code is compiled in the host memory for later downloading. This mode is much faster if you're compiling one or more files of source, as opposed to typing single definitions.

These modes are controlled by SET-DOWNLOAD and DOWNLOAD-ALL. You can see how these are used in the file **Debug**. **f**, where you'll find a sequence like:

```
SET-DOWNLOAD
INCLUDE ..\..\CONICAL

√ Conical piles demo

INCLUDE ..\..\DUMB
                           \ Dumb terminal
256 TERMINAL CONSOLE
         CONSOLE ACTIVATE DUMB SCI-TERMINAL
: DFMO
  BEGIN CALCULATE AGAIN;
DOWNLOAD-ALL
```

SET-DOWNLOAD is called before the files are INCLUDEd, the task defined, and the startup word **DEMO** defined. These actions occur in batch mode. When they are complete, DOWNLOAD-ALL downloads the compiled code and reconnects the XTL in full interactive mode. To test your application interactively, all you have to do is replace the demo files and definitions with your application.

To support interactive debugging, the image of the target dictionary and data space in the host must be an exact match for the one in the target. To ensure this, SwiftX places a checksum of a compiled kernel in the kernel image. This will be checked near the beginning of **Debug**. **f**, as follows:

- If SwiftX can install a new kernel without a manual procedure (e.g. it resides in flash or RAM), a check is performed in the word **RELOAD**, which will automatically download a new kernel if there is no match. You can force a new download by executing the command **RELOAD!**. An active XTL is required.
- If a special procedure is required to install a new kernel, the check is performed by the word SYNC-CORE, and you will get an error message if the checksum doesn't match. You must then install a new kernel by the procedure appropriate for your target.

Glossary

XTL-BAUD (n-)

Sets the baud rate for serial XTL communication, on targets using it, to rate n.

@XTL-BAUD

Returns the baud rate for serial XTL communication, on targets using it.

CONNECT

Starts the XTL communicating with the target. **CONNECT** will abort if target communication cannot be established (e.g., it is not connected or not responding). When communication is established, the host can execute words on the target, examine its memory, etc.

DI SCONNECT (-)

> Shuts down the XTL link. When this is done, you may no longer execute target words. You may, however, examine the host image of cData and iData, and perform host functions such as LOCATE, WH, etc.

SET-DOWNLOAD

Disconnects the XTL, saves target code and data space pointers, and enters batch mode. Subsequent compilation affects the host's image of target cData and iData only.

(-)DOWNLOAD-ALL

> Re-connects to the target. Compares the saved code and data space pointers with the current ones, and downloads all new cData and iData. Leaves the target in interactive mode, ready to test the new code.

RELOAD (-)

> Compares the checksum of the most recently compiled kernel with the one in the target, and automatically downloads a new kernel if necessary.

RELOAD! (-)

Downloads a new kernel unconditionally.

SYNC-CORE

Ensures that the host and target images of code space are synchronized by comparing their checksums. If the comparison fails, interactive testing will not be possible until a matching kernel is installed in the target.

4.9.2 XTL Protocol

Figure 16 is an overview of the logical relationship between the host and target using a standard serial XTL. Implementations using a BDM or JTAG may differ; see your platform-specific documentation.

Table 17 lists each command from the host to the target, parameters sent to the target, and parameters received from the target in response to the command.

Table 17: Host-to-target commands

Fn	Description	Parameters to target	Parameters from target
0	Execute target word	n(1), data(n*4)	{cmd(1)}n(1), data(n*4), ack(1)
1	Send back register contents		CPU dependent
2	Fetch byte from data space	addr(4)	data(1), ack(1)
3	Store byte to data space	<i>addr</i> (4), <i>data</i> (1)	ack(1)
4	Fetch half-cell (16-bits) from data space	addr(4)	data(2), ack(1)
5	Store half-cell to data space	<i>addr</i> (4), <i>data</i> (2)	ack(1)
6	Fetch cell from data space	addr(4)	data(4), ack(1)
7	Store cell to data space	<i>addr</i> (4), <i>data</i> (4)	ack(1)
8	Download to data space	n(1), addr(4), data(n)	ack(1)
9	Fetch byte from code space	addr(4)	data(1), ack(1)
10	Store byte to code space	<i>addr</i> (4), <i>data</i> (1)	ack(1)
11	Fetch half-cell from code space	addr(4)	data(2), ack(1)
12	Store half-cell to code space	<i>addr</i> (4), <i>data</i> (2)	ack(1)
13	Fetch cell from code space	addr(4)	data(4), ack(1)
14	Store cell to code space	addr(4), data(4)	ack(1)
15	Download to code space	n(1), addr(4), data(n)	ack(1)

Commands from host to target consist of a single byte, followed by optional parameters; the size of each parameter, in bytes, is noted in parentheses. The target executes the command, returns its optional parameters, and ends with a positive acknowledge (ack) code (see Table 18). Multi-byte parameters are sent most-significant byte first. The half-cell operations (Fn 4, 5, 11, and 12) are available on 32-bit targets only.

All data transmitted, in both directions, are binary 8-bit characters. One exception is the Esc character (1B_H), which has special meaning when transmitted to the target. Esc followed by any other character tells the target to abort the current command in progress and to return an "Announce reset" (255) response. Two Esc characters in a row indicate a single data byte whose value is 1B_H. The Esc character has no special meaning when transmitted from the target to the host.

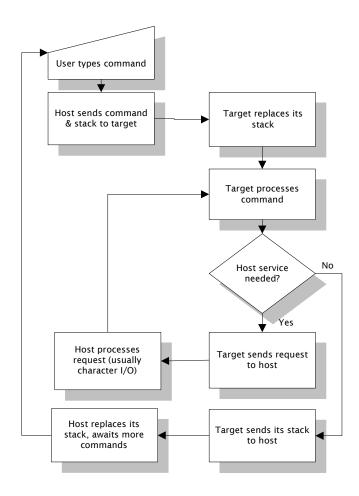


Figure 16. XTL communication

The data indicated in Table 17 for function 0 (execute target word)—for both host and target—is the parameter stack. The stack is passed bottom item first. When sent from the host to the target, the top two stack items are the execution address for the word and the host's BASE. (If the target implements CATCH and THROW exception handling, it executes the word using CATCH.) When returned by the target to the host, the top two stack items are the host's BASE and the function's THROW code (0 indicates successful completion or that CATCH/THROW isn't implemented on the target). Thus, the value n (number of stack items) is always at least two, in both directions. The *cmd* parameter in the "from target" field can be any of the responses listed in Table 18. The host will not begin receiving the target stack until it receives the Ack response, indicating that the target has finished executing its word.

Table 18: Target-to-host responses

Fn	Description	Parameters from target	Parameters to target
255	Announce reset		

Table 18: Target-to-host responses (continued)

Fn	Description	Parameters from target	Parameters to target
254	Ack; command completed successfully		
253	Nak; command aborted ^a		
252	KEY (input key and send it back)		char(1)
251	KEY? (test for keypress, send status back)		flag(1)
250	Display address	addr(4)	
249	ACCEPT (input string, return actual length)	addr(4), length (1)	length(1)
248	AT-XY (cursor position)	row(1), col(1)	
247	Write <i>data</i> to log file	247, length (1), data (length)	
13	CR (new-line function)		
12	PAGE (clear-screen function)		

a. Target issues function 253 on start-up and on restart.

Table 18 lists the possible *cmd* responses from the target; they are only valid while the host awaits the initial response to function 0 (execute target word). These response codes enable the host to provide virtual terminal services to the target. The host will acknowledge any of the terminal output functions by sending an unspecified character to the target, to pace output.

If the program under test never returns control to the host, pressing the "Stop Sign" button on the SwiftX debug window toolbar abort out of the wait loop. This is useful when testing a routine whose behavior is an infinite loop, or when a program behaves unexpectedly. Note that aborting out of the wait loop leaves the target in an indeterminate state. It will be necessary to restart the target and the XTL to regain control from the debug window.

Except for the codes listed in Table 18 and the data logged, all characters sent from the target to the host will be displayed by the host in the command window.

4.9.3 Logging Test Data

The code 247 (supported only on devices with serial XTLs) facilitates writing test data from a target to a file on the host. The applicable commands are X-LOG and X-**CLOSE** use XTL function 247 to send binary log data to the host to be written to a file named Target. Log. Blocks of data are written in records of up to 255 bytes each. The message format is:

<247> <length> <data>

Length is one byte (1-255), followed by that many data bytes.

A special form is used by **X-CLOSE** which sends a length byte of 0 and no data. This tells the host to close the file. Subsequent calls to X-LOG will over-write the existing Target. I og file.

Glossary

X-LOG (*addr* n —)

Sends the data at *addr* of length *n* bytes to the host. The data will be logged in the next record of the file Target. I og (which will be created and/or opened if necessary).

(-)X-CLOSE

Closes the Target. Log file. Subsequent calls to X-LOG will over-write data in this file.

Section 5: The SwiftOS Multitasking Executive

Multitasking allows a computer to appear to be doing many things at once. In particular, the SwiftOS multitasker provides service to multiple programs operating without any fixed timing relationship (i.e., asynchronously). This section explains how tasks are constructed, how they are controlled, and how the processor is shared between them.

SwiftOS supports two types of tasks: background tasks and terminal tasks. These are fundamentally identical, but a terminal task can be thought of as a more elaborate background task tailored to service a serial-type device. You can easily prune unnecessary resources from a terminal task, or add more to either kind of task.

Each task has a private area of uData space containing its data and return stacks and a *user area* for task-specific variables.

A task, in SwiftOS, may be thought of as an entity capable of independently executing Forth definitions. It may be given permanent or temporary job assignments. If it will be given a permanent job assignment, the recommended naming convention is a "job title." For example, a task that will run a hydraulic lift might be named LI FTER.

There are three aspects to task definition and control:

- 1. Task definition takes place at compile time. Tasks are given fixed allocations of memory in which to operate, including stack space and user area.
- 2. **Task initialization** takes place after power-up in the target system. At this time, the task's RAM areas are initialized and it is linked into the running multitasker loop.
- 3. **Task activation** may take place at one or more points in the running application. This involves giving the task words to execute. It may be a temporary assignment (execute this, then stop) or a permanent one (start running an infinite loop).

Although the definition and physical structure of a task is static, its job assignments may change according to the needs of the application.

5.1 Forth Re-entrancy and Multitasking

When more than one task can share a piece of code, that code can be called reentrant. Re-entrancy is valuable, because memory is conserved when tasks share code.

Routines that are not re-entrant are those containing elements that are subject to change while the program runs. Thus, self-modifying code is not re-entrant. Routines with private variables are not re-entrant, but re-entrant routines can have private constants (because a constant's value does not change). Re-entrant routines can always be programmed into ROM.

Forth routines can be made completely re-entrant with very little effort. Most keep their intermediate results on the data stack or the return stack. Programs to handle strings or arrays can be designed to keep their data in the section of RAM allotted to each task. It is possible to define public routines to access variables, and still retain re-entrancy, by providing private versions of these variables to each task; such variables are called user variables.

Since re-entrancy is easily achieved, tasks may share routines in a single program space. This conserves large amounts of memory. In most applications, all system and application routines can be shared (with the minor exception of the I/O instructions on certain processors). Terminal tasks (such as printer spooling) can operate with only a few hundred bytes. The minimum size of a useful task is about 512 bytes, devoted to the task's stacks and user variables. Some applications (PBXs, process control, and some communications systems) naturally use large arrays of small tasks, with each task running a simple shared program.

References User variables, Section 5.2.3

5.2 Principles of Operation

The SwiftOS multitasker is designed to fulfill several objectives:

- 1. Concurrent, asynchronous execution of code.
- 2. Convenient to use
- 3. Fast in execution
- 4. Simple to understand
- 5. Minimal memory requirements
- 6. Independent of hardware configuration (for example, a timer or memory manager is unnecessary)

The SwiftOS multitasker satisfies 2, 3, and 4 above by consisting of only about 13 words. Number 5 is a consequence of Forth's inherently re-entrant structure (see Section 5.1). Numbers 1 and 6 are ensured by the way SwiftOS schedules tasks— SwiftOS services tasks when an executing task stops to await I/O.

Simplicity and good performance are ensured because task-switching only happens at known, programmer-controllable points, and between Forth words. This greatly simplifies the context-switching operation (thus reducing overhead) and the job of writing routines for a multi-user environment.

5.2.1 Task-Scheduling Algorithm

This section provides a detailed discussion of the scheduling algorithm, its associated words, and some useful techniques. Processor-specific details of the SwiftOS implementation are described in a separate document accompanying your SwiftX product.

The SwiftOS multitasker may be said to be I/O driven. A round-robin algorithm (see Figure 17) schedules processor time. Each task has control until it executes the high-level PAUSE or STOP, or the assembler code ending WAIT. Most words performing asynchronous hardware operations (e.g., TYPE, ACCEPT) contain a WAIT or a jump to **PAUSE** so, while a task is waiting for an I/O operation to be completed, other tasks can use the CPU. Since Forth is naturally very fast, tasks tend to spend much of their time awaiting I/O. Tasks that perform extensive computations may be prevented from impacting overall system performance by incorporating PAUSE into a few regularly executed or CPU-intensive words.

The round robin is sometimes called the **PAUSE** loop, the idle loop, or the multitasking loop. Where possible, it is implemented as an endless loop of jump instructions (see Figure 17). Each task has its own jump instruction, which transfers control to the jump instruction of the next task.

When a task is being scheduled to awaken, the task's jump instruction is replaced by an instruction to transfer control to the machine code that awakens the task. This special instruction is usually called **WAKE**, and is usually a trap or subroutine call. The address of the first byte of a task's jump instruction is pushed on the stack by the high-level Forth word **STATUS**, a user variable (see Section 5.2.3) for the current task. In assembly code, the address of the current task's **STATUS** is available in register **U**. The address used by the jump in **STATUS** immediately follows it.

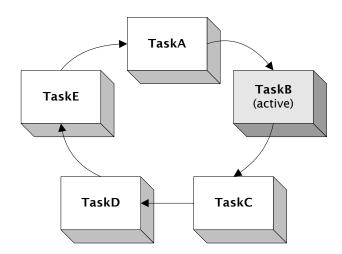


Figure 17. SwiftOS round-robin multitasking loop

The most general case of changing tasks in the round robin occurs when CPU control is relinquished from high-level Forth, with arrangements for the task to awaken and resume execution on its next turn. PAUSE performs this most general case. PAUSE can be embedded in complex calculations which perform no I/O and which might otherwise cause a particular task to control the CPU for undesirably long periods. Consider the following collision-orbit calculation:

- : POSITION X STEP Y STEP;
- : ?COLLI DE 30000 0 DO POSITION HIT PAUSE LOOP;

In this example, the word STEP is assumed to have been defined to perform the calculations for integrating the next step in the target X or Y coordinate. HIT expects the coordinate of the target (computed by POSI TION) on the stack and performs appropriate course corrections. Because these computations are time consuming, and because other functions must be running concurrently, it is desirable to give up the CPU for one turn around the round robin for each step in the integration. Inserting the **PAUSE** in the loop accomplishes this.

The related words STOP and WAIT (see the glossary below) share much of the code for **PAUSE**. These are the steps **PAUSE** performs:

- 1. The WAKE instruction is stored into STATUS, replacing the round-robin jump, so that the task executing PAUSE will awaken on its next turn. On many machines, WAKE is equivalent to a subroutine call to the code for step 5, below.
- 2. The system pointers I and R are saved by being pushed onto the current task's data stack. This portion of the code is the entry point for **STOP** and **WALT**, which by skipping step 1 do not automatically resume execution of the current task on the next turn. (On some implementations, the address interpreter pointer I is not needed; see your platform-specific SwiftX documentation for details.)
- 3. The data stack pointer (S, in assembler) is saved in a reserved location in the user area. At the completion of this step, all non-recoverable unshared task data for the address interpreter has been saved. Tasks only relinquish the CPU between Forth words, so other registers do not have to be saved.
- 4. The CPU jumps to the location whose address follows STATUS (i.e., the next task's STATUS), and proceeds to jump through the circular round-robin loop until a WAKE instruction is encountered. The **WAKE** transfers control to step 5.
- 5. The address of the new task's **STATUS** is stored in **U**. The address of **STATUS** can be obtained from the address left by WAKE.
- 6. Using U to find the task, the data-stack pointer is restored, then I and R are restored from the new task's data stack.
- 7. The **SLEEP** instruction (a jump to the next task) is stored into the current task's **STA**-TUS to make the current task's state "don't awaken."
- 8. Finally, PAUSE is exited and the task will execute its next word, based on the contents of I and R.

The words in the glossary below control task use of the CPU.

Glossary

PAUSE

Suspend the task that calls PAUSE to allow all other tasks one turn in control of the CPU.

STOP

Put the task that calls STOP to sleep until that task is awakened by an interrupt routine or by some other task.

WAIT (-)

An assembler code ending on some systems that is equivalent to **STOP**.

WAKE (-x)

Return x, the machine instruction (usually a trap instruction or subroutine call) that may be stored in a task's **STATUS** to cause the task to be awakened at its next turn in the multitasker round robin. See your platform-specific documentation for implementation details.

SLEEP

(-x)

Return x, the machine instruction (a jump to the task whose address follows the current task's STATUS) that may be stored in a task's STATUS to cause the task to remain inactive (skip its turn in the round robin). See your platform-specific documentation for implementation details.

References Forth re-entrancy and multitasking, Section 5.1 User variables. Section 5.2.3

TYPE, ACCEPT, serial I/O in general, Forth Programmer's Handbook, Section 3.8

5.2.2 Interrupts and Tasks

Interrupt routines are often used to awaken tasks. A common way to perform complex, non-critical interrupt servicing is to have the interrupt routine perform all time-critical operations, and then store **WAKE** into a task's **STATUS**. For example, if a hypothetical data acquisition word **ACQUIRE** solicits data from a serial device, it could send a request to the device and then STOP. Input from the device could be buffered by interrupt code; when the interrupt code sees a carriage return, it would awaken the terminal task associated with the interrupting device. When the round robin gets around to the task, the task resumes execution at the word immediately following STOP, and runs until it executes another STOP or PAUSE, or WAITs for an I/O operation.

Tasks typically perform asynchronous operations such as data reduction and logging. An example of a data reduction loop being run by a dedicated task might be:

: COLLECT BEGIN ACQUIRE DATA REDUCE ARCHIVE STOP AGAIN;

The interrupt routine that services the data source for this example will awaken the task by storing **WAKE** in the task's **STATUS** when data is ready to be accepted.

5.2.3 User Variables

In SwiftOS, tasks can share code for the text interpreter, I/O drivers, etc., but each task will have different data for these facilities. The fact that all users have private copies of variable data for such shared functions enables them to run concurrently without conflicts. For example, number conversion in one task needs to control its BASE value without affecting that of other tasks.

Such private variables are referred to as user variables. User variables are not shared by tasks; each task has its own set, kept in the task's user area.

- Executing the name of a user variable returns the address of that particular variable within the task that executes it.
- Invoking <task-name> @ returns the address of the first user variable in task-

name's user area, which is generally named STATUS.

Some user variables are defined by the system for its use. You may add more in your application, if you need to in order to preserve re-entrancy, to provide private copies of the application-specific data a task might need.

User variables are defined by the defining word **+USER**, which expects on the stack an offset into the user area, plus a size (in bytes) of the new user variable being defined. A copy of the offset will be compiled into the definition of the new word, and the size will be added to it and left on the stack for the next use of +USER. Thus. when specifying a series of user variables, all you have to do is start with an initial offset and then specify the sizes. When you are finished defining **+USER** variables, you may save the current offset to facilitate adding more later. The conventional way to do this is by using **EQU** (which makes a host-only constant and, conveniently, removes the last offset from the stack).

The minimum SwiftOS user area begins something like this (details vary, depending upon your target CPU):

```
0 2 +USER STATUS
CELL +USER FOLLOWER
CELL +USER SSAVE
CELL +USER SO
CELL +USER CATCHER
EQU #USER
```

Here, the task's status area starts at offset 0 relative to the beginning of the user area, and provides two bytes for a jump to the next task. Next, one cell is provided for the address of the next task in the loop, followed by a cell for the "stack-pointer save" location, and then **SO**, etc.

Additional user variables might be assigned as follows:

```
#USER CELL +USER 'EMIT
      CELL +USER 'TYPE
      CELL +USER 'CR
      CELL +USER ' PAGE
      CELL +USER 'ATXY
      CELL +USER 'KEY
      CELL +USER 'KEY?
      CELL +USER 'ACCEPT
      CELL +USER DEVICE
EQU #USER
```

It is good practice to group user variables as much as possible, because they are difficult to keep track of if they are scattered all over your source.

A user variable is defined as an offset into the user area, where a zero offset usually corresponds to **STATUS**. The offset is the number passed on the stack during a sequence of +USER definitions; the current value of the offset is compiled into each user variable definition, and the offset left on the stack is incremented by the number of bytes to be reserved (one cell, in most of the examples above). Eventually, when a task executes a user variable, its offset is added to the register containing the address of the currently executing task's user area. Therefore, all defined user variables are available to all tasks that have a user area large enough to contain them (see Figure 18; also task definition, Section 5.3.1 and Section 5.4.1).

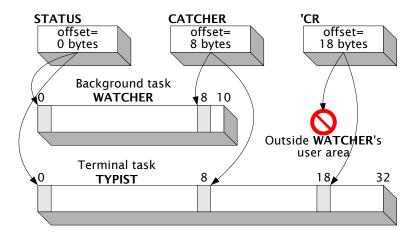


Figure 18. User variables offset into tasks' user areas 1

The system does not test an address returned by invoking a user variable to see if it is within the space allotted to the current task's user variables. It is your responsibility not to let a task reference a user variable outside its own user area!

The *minimum* size for a background task's user area would be about five cells for the example on the previous page, for STATUS through CATCHER. Terminal tasks generally have a larger user area to accommodate I/O, task management, dictionary management (in programmable systems—see Section 7.1.3), text interpretation, and other functions.

A task may need to initialize another task's user variables, or to read or modify them. The word HIS allows a task to access another task's user variables. HIS takes two arguments: the address of the task of interest, and the address of the user variable of interest. For example:

2 CHUCK BASE HIS!

will set the user variable BASE of the terminal task named CHUCK to 2 (binary). In this example, HIS takes the address of the executing task's BASE and subtracts the STA-TUS address of the executing task from it to get the offset, then adds the offset to the **STATUS** address of the desired task, supplied by **CHUCK**.

The user variable definitions provided for **COLLECT** in the sample data logger developed below are examples of application-specific user variables. Note how HIS is used to transfer a value from the stack of the task that starts the definition RECORD to the user variable **#SAMPLES** belonging to the task **SCRIBE**, which will execute the words **COLLECT** and **STOP** following **ACTI VATE**.

This example assumes that A/D will request a sample from an analog-to-digital converter, PAUSE while the conversion takes place, and signal via an interrupt when a

^{1.}Example is for a 16-bit target

sample is ready. The interrupt should read the sample, put it in a temporary place, then set the task to awaken. The rest of A/D will get the value and put it on the stack. This scenario is typical of the relationship between interrupt code and tasklevel code.

```
#USER CELL +USER #SAMPLES
                                    \ Current # of samples
10000 CONSTANT MAX-SAMPLES
                                    \ Maximum # of samples
MAX-SAMPLES CELLS BUFFER: SAMPLES
                                    \ Sample buffer
: COLLECT ( -- )
                                    \ Record #SAMPLES samples
      #SAMPLES @ 0 DO
                                    \ Loop setup
      A/D
                                    \ Read one sample
      SAMPLES I CELLS + !
                                    \ Store in Ith cell
      LOOP ;
                                    \ Repeat
: RECORD ( n -- )
                                    \ User command: n RECORD
      MAX-SAMPLES MIN
                                    \ Clip n to legal value
      SCRIBE #SAMPLES HIS!
                                    \ Pass n to task
      SCRIBE ACTIVATE
                                    \ Start task
      COLLECT STOP;
                                    \ Task collects, stops
```

This version of **RECORD** would be used with the number of samples as its argument; the task address is built in **SCRI BE**. The following phrase would record 500 samples:

500 RECORD

The glossary at the end of this section shows the user variables required by a fully interactive SwiftOS terminal task. Your CPU's implementation may require variables not listed—see your SwiftX implementation's system and user variables defined in Swi ftx\Src\<CPU>\data. f.

Although the order in which they are defined varies, all systems possess these user variables. You can obtain the absolute address of location 0 in a task's user area by typing:

```
<task-name> @
```

All user variables return the address of the value for the task that is executing when they are invoked.

See **Data**. f for the exact organization of user variables in your system. Generally, the most-used user variables are defined first, so tasks needing only some of the user variables can have a minimal-sized user variable area.

The first glossary below lists words used to manage the user variables. It is followed by the user variables in two groups: those required for all tasks, and those used only by terminal tasks.

Glossary

User-variable management

+USER

$$(n_1 n_2 - n_3)$$

Define a user variable at offset n_1 in the user area, and increment the offset by the size n_2 to give a new offset n_3 .

#USER (-n)

Return the number of bytes currently allocated in a user area. This is an appropriate offset for the next user variable when this word is used to start a sequence of **+USER** definitions intended to add to previously defined user variables.

HIS $(addr_1 n - addr_2)$

> Given a task address *addr*₁ and user variable offset *n*, returns the address of the referenced user variable in that task's user area. Usage:

<task-name> <user-vari abl e-name> HIS

User variables required for all tasks

STATUS (-addr)

> Indicates whether the task is ready to become active, by containing a jump to the wake up code or to FOLLOWER.

(-addr)**FOLLOWER**

Address of the next task in the multitasking chain.

SSAVE (— addr)

Stack pointer, saved when the task was last active.

S0 (-addr)

Pointer to the bottom of the data stack and the start of the message buffer (for terminals). The data stack grows toward low memory from addr, and the message buffer, if any, extends toward high memory from this same addr.

CATCHER (-addr)

Pointer to the latest exception frame (0 if none), set by CATCH.

Additional user variables required for terminal tasks

DEVICE (-addr)

Terminal device address or other device information.

BASE (-addr)

> Address of the variable containing the number conversion base (eight for octal, ten for decimal, sixteen for hex).

'EMIT (-addr)

Address of the task's EMIT routine.

'TYPE (-addr)

Address of the task's TYPE routine.

' CR (-addr)

Address of the terminal new-line routine.

' PAGE (-addr)

Address of the terminal screen clear or form-feed routine.

' ATXY (-addr)

Address of a routine to position the terminal's cursor.

(-addr)' CLEAN

Address of the task's "clear to end of line" routine.

C# (-addr)

> Task's current cursor position (column), set to 0 by CR and PAGE, and maintained as appropriate by EMIT, TYPE, and AT-XY.

(-addr)L#

> Task's current cursor position (line), set to 0 by PAGE, and maintained as appropriate by CR and AT-XY.

TOP (-addr)

> Top of task's screen-scrolling area, expressed as a line number, with 0 signifying the top of the screen.

' KEY (-addr)

> Contains the most recent character received since the last ACCEPT or KEY; or 0, if none.

(-addr)'KEY?

Returns *true* if a key is ready to be read by **KEY**.

' ACCEPT (-addr)

Address of the task's **ACCEPT** routine.

(-addr)**SPAN**

Contains the number of characters read by the most recent **ACCEPT**.

#TIB

Contains the actual number of characters available to interpret in the input stream.

References

ACTI VATE. Section 5.3.3

WAIT, Section 5.2

Terminal drivers, Forth Programmer's Handbook, Section 3.8

5.2.4 Sharing Resources

Some system resources must be shared by tasks without giving any single task permanent control of them. Disk units, tape units, printers, non-reentrant routines, and shared data areas are all examples of resources available to any task but limited to use by only one task at a time.

SwiftOS controls access to these resources with two words that resemble Dijkstra's semaphore operations. (Dijkstra, E.W., Comm. ACM, 18, 9, 569.) These words are **GET** and **RELEASE**.

As an example of their use, consider an A/D multiplexor. Various tasks in the system are monitoring certain channels. But it is important that while a conversion is in process, no other task issue a conflicting request. So you might define:

```
VARIABLE MUX
: A/D ( ch# -- n ) \ Read a value from channel ch#
  MUX GET (A/D) MUX RELEASE;
```

In the example above, the word A/D requires private use of the multiplexor while it obtains a value using the lower-level word (A/D). The phrase MUX GET waits in the PAUSE loop (see definition of GET, below) to obtain private access to this resource. The phrase MUX RELEASE releases it, without awakening another task.

In the example above, MUX is an example of a facility variable. A facility variable behaves like a normal **VARI ABLE**. When it contains zero, no task is using the facility it represents. When a facility is in use, its facility variable contains the address of the **STATUS** of the task that owns the facility. The word **GET** waits in the multitasking loop until the facility is free or is owned by the task which is running **GET**. Highlevel code for **GET** would be:

```
: FREE ( a -- a t)
                   @ DUP O= SWAP
  STATUS = OR;
: GET (a -- ) BEGIN PAUSE FREE UNTIL
  STATUS SWAP!;
```

GET checks a facility repeatedly until it is available. **GET** is written in code, and the overhead rarely exceeds two or three machine instructions. Maintaining a queue is almost always slower.

RELEASE checks to see whether a facility is free or is already owned by the task that is executing **RELEASE**. If it is owned by the current task, **RELEASE** stores a zero into the facility variable. If the facility is owned by another task, **RELEASE** does nothing. Using the definition of **FREE** above, a high-level definition of **RELEASE** would be:

```
: RELEASE ( a -- )
                   FREE IF O SWAP! ELSE
  DROP THEN;
```

Note that GET and RELEASE can be used safely by any task at any time, as they don't let any task take a facility from another.

SwiftOS does not have any safeguards against deadlocks, in which two (or more) tasks conflict because each wants a resource the other has. For example:

```
: 1HANG
         MUX GET TAPE GET ...;
: 2HANG
         TAPE GET MUX GET ... :
```

If **1HANG** and **2HANG** are run by different tasks, the tasks could eventually deadlock.



The best way to avoid deadlocks is to get them one at a time, if possible! If you have to get two resources at the same time, it is safest to always request them in the same order. In the multiplexor/tape case, the programmer could use A/D to obtain one or more values stored in a buffer, then move them to tape. In almost all cases, there is a simple way to avoid concurrent **GETs**. However, a poorly written application might have the conflicting requests occur on different nesting levels, hiding the problems until a conflict occurs.

Glossary

GET (addr -)

Obtain control of the facility variable at addr, having first made one circuit of the SwiftOS round robin. If the facility is owned by another task, the task executing GET will wait until the facility is available.

(addr -)**GRAB**

> Obtain control of the facility variable at *addr*. If the facility is owned by another task, the task executing GRAB will wait until the facility is available. GRAB does not PAUSE before attempting to obtain control, so, in order to prevent deadlocks and avoid "resource hogging," it should be used only in circumstances in which it is known that no other task could have the facility.

(addr -)**RELEASE**

> Relinquish the facility variable at *addr*. If the task executing **RELEASE** did not previously own the facility, this operation is a no-op.

5.3 Background Tasks

Background tasks exhibit the general properties of all tasks in SwiftOS. In fact, terminal tasks are *supersets* of background tasks, possessing extended user areas to support the requirements for serial I/O.

Background tasks are suitable for virtually all chores that do *not* require serial I/O. Examples include many kinds of equipment control and data acquisition.

This section describes procedures for defining and managing background tasks.

5.3.1 Defining a Background Task

Background tasks have a data stack, a return stack, and a user area for variables whose values are not shared (the user variables, discussed in Section 5.2.3). Background tasks do not service a terminal or support a compiler.

BACKGROUND creates a *task definition table* in code space that is used, after target power-up, to build a background task's user area and stacks in RAM (see Figure 19). **BACKGROUND** is a defining word that expects the sizes (in bytes) of the user area, data stack, and return stack. BACKGROUND does not link the task into the round robin or make the task run a program; that will be described in the next section.

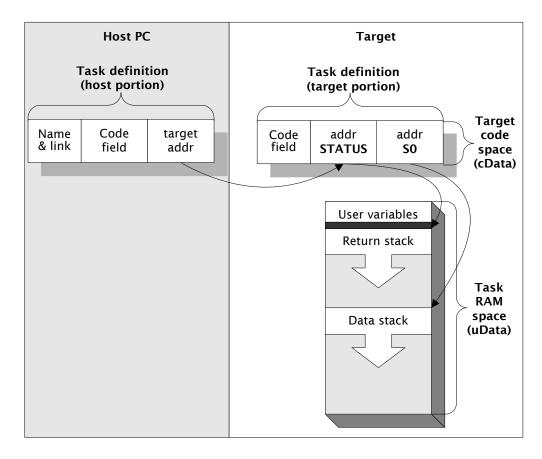


Figure 19. Memory allotted for a background task

An example of **BACKGROUND**'s use is:

32 128 64 BACKGROUND SCRIBE

This defines a task whose name is **SCRIBE**, which has 32 bytes of user area, 128 bytes of data stack, and 64 bytes of return stack. The total target size of **SCRIBE** in this example would be three cells (12 bytes on a 32-bit target, 6 bytes in a 16-bit target) in code space and 224 bytes of RAM. On a target with four bytes per cell, the 64byte return stack allows the program to nest Forth words, loop parameters, etc., to a depth of 16 cells.

The smallest possible user area is the size of the region needed to keep the user variables **STATUS** through **CATCHER**, about five cells (see Section 5.2.3). The extra cells in SCRIBE's user area could be used by SCRIBE's program to keep a sample count, a virtual array address, and a device I/O address for a data-logging application.



There must be sufficient space to store the registers I (or the program counter, in subroutine-threaded implementations) and R on the data stack, in addition to the maximum number of stack items that may be present when the task enters the multitasking loop (e.g., by executing PAUSE).

The run-time behavior of words created by BACKGROUND is to return on the stack the

address of the task's definition table, the first cell of which contains a pointer to the first byte of the task's STATUS. Thus, the location of SCRIBE's STATUS is found by the phrase:

SCRI BE @

Glossary

BACKGROUND < task-name>

(nu ns nr -)

Define the background task task-name—with nu bytes of user area, ns bytes of data stack and *nr* bytes of return stack—and set up its task definition table based on these parameters. Subsequent use of *task-name* returns the address of the table containing the parameters for building the task. The phrase <task-name> ● will return the address of the task's **STATUS** (the start of its user area).

5.3.2 Initializing a Background Task

All SwiftOS kernels contain, at power-up, a terminal task called **OPERATOR**. If no other task exists, OPERATOR's jump address will contain the address of OPERATOR's own **STATUS**. In this way, the round robin first consists of a single jump instruction, which jumps to itself.

After a new background task has been defined, the phrase:

```
<task-name> BUILD
```

is used to initialize *task-name*'s user area and to link it into the round robin. This usually is done as part of the power-up sequence.

In an earlier example, the background task named **SCRI BE** was defined:

32 128 64 BACKGROUND SCRIBE

To initialize the task and link it into the round robin, one would use:

```
SCRIBE BUILD
```

SCRIBE leaves the address of its task definition table on the stack. Then BUILD begins its work:

- 1. **BUILD** uses the address that is on the stack to set up the new task's stack space and user area in RAM.
 - 2. **BUILD** copies the complete jump instruction, including the address of the next task, from the **STATUS** of **OPERATOR** into the **STATUS** of the new task.
 - 3. **BUILD** stores the address of the new task's **STATUS** into **OPERATOR**'s jump address.

(Steps 2 and 3 enable the CPU to jump from **OPERATOR** to the new task, then to the task which formerly followed **OPERATOR** in the round robin.)

4. BUILD gets a copy of the value for the new task's S0—the bottom of its data stack, calculated by BACKGROUND and compiled just after the STATUS address—and stores it into the user variable SO.

At this point, although the task exists and is part of the round robin, it is not yet running a program. The words the task executes may be defined later.

Glossary

BUILD

(addr -)

Initialize a task, given the address of the task's definition table which was constructed by BACKGROUND. The task will be linked in the round-robin after OPERATOR, and before the task previously linked to **OPERATOR**. This must be done at run time in the target before any attempt to **ACTIVATE** the task. Usage:

<task-name> BUILD

OPERATOR

(-addr)

Return the address of the task definition table of the first task defined in any SwiftOS kernel. **OPERATOR** is a **TERMI NAL** task. If no task has been defined, *addr* is **OPERA**-TOR'S OWN STATUS.

References

Defining a background task, Section 5.3.1 Making a background task run a program, Section 5.3.3 Terminal tasks, Section 5.4

5.3.3 Controlling a Background Task

After a task has been defined by BACKGROUND and linked into the round robin by BUILD, the new task is "asleep." This is necessary because the task still has not been given the parameters that will determine what word(s) the task will execute.

The word that makes a task run a program is ACTI VATE, which must be used in a: definition. It expects on the stack the address of a task definition table, placed there by executing a task's name. ACTI VATE clears the task's data and return stacks, then awakens the task such that it will begin executing the word immediately following ACTI VATE. The words following ACTI VATE must end in STOP or in an endless loop.

The example below demonstrates everything needed to run a BACKGROUND task. Assume that a background task was defined and initialized by the following phrases (described in previous sections):

```
32 128 64 BACKGROUND SCRIBE
( power-up initialization)
SCRIBE BUILD
```

In our hypothetical application, the following definition will be used by a task to record data samples onto disk:

```
: RECORD ( addr -- ) ACTIVATE
  BEGIN COLLECT ARCHIVE PAUSE AGAIN;
```

Then **RECORD** could be assigned to a task by the phrase:

SCRI BE RECORD

ACTIVATE uses the address returned by executing a task's name (SCRIBE, in this example) to cause that task to execute the words following ACTI VATE. In the definition of RECORD.

- the words **COLLECT** and **ARCHIVE** perform the data logging;
- PAUSE gives any other tasks in the round robin an opportunity to execute; and
- the BEGIN ... AGAIN phrase fulfills the requirement that code assigned to a task never reach the; in the definition containing **ACTI VATE**.

Note that, in the above example, BUILD is kept separate from RECORD because a task can only be built once, but can be activated many times.

For convenience in the discussion below, a *slave task* is **ACTIVATE**d by another task. A master task uses ACTI VATE to activate the slave task. When the phrase SCRI BE **RECORD** executes, **ACTIVATE** (in the definition of **RECORD**) will do the following:

- 1. Reset the slave task's (**SCRI BE**, in the example) stacks to an empty state. If the slave was previously active, it will forget what it was doing and its data and return stacks will be cleared.
- 2. Store the address of the next word to be executed as the only item on the slave's return stack. In this case, that is the address of COLLECT, since BEGIN only acts at compile time to set up the loop.
- 3. Push the slave's return stack pointer (with one item on it) onto the slave's data stack, and save the data stack pointer in the slave's user area until it begins executing.
- 4. Store a **WAKE** instruction into the slave's **STATUS** cell.

Because the master task's return stack was popped (in step 2, above), when it leaves **ACTIVATE** it will return *not* to the next word in **RECORD**, but to whatever called **RECORD**. In other words, the master task starts executing the word containing ACTI VATE, but goes no further than that; the slave task is the only one that executes the balance of the definition. This relationship is shown in Figure 20.

"Mas	"Master" task executes this part		"Slave" task executes this part
:	RECORD (addr)	ACTIVATE	BEGIN <pre>cess> AGAIN;</pre>

Figure 20. Two tasks are involved in a word containing ACTI VATE



Code following an ACTI VATE must never reach the; because the EXIT or RTS that is compiled by a semicolon would attempt to pop an empty return stack. Therefore, the code following an ACTI VATE must end either in an endless loop (as in the example) or in the word STOP.

Here is another example of a control word, this time using the word **STOP**:

```
: NOD ( -- )
              BEGIN STOP AGAIN;
: HALT ( addr -- ) ACTI VATE NOD ;
```

Because ACTIVATE forcibly resets a task's execution environment, the definition of **HALT** in the example above will forcibly stop the task at *addr* and start it executing an infinite loop in which, should it ever be awakened (e.g., by an interrupt), it will STOP. HALT is occasionally useful to provide a stable, inactive behavior. A HALTed task may be ACTI VATEd in order to perform some other function, when needed.

Note that ACTI VATE does not distinguish whether a task was previously assigned a function that it is performing. In fact, after a task is ACTIVATEd the first time, it will never be without a function to perform, even if that function is **NOD**. Nor is the concept of "busy" relevant; the master task is running, or it couldn't be executing ACTI -**VATE!** So, if you want to avoid interrupting a task until it has finished performing an assigned function, let the task set and clear a flag or variable to indicate when it is busy or free for re-assignment. Facility variables (described in Section 5.2.4) are convenient for this purpose.

Glossary

ACTI VATE

(addr -)

Start the task at *addr* executing part of the definition in which **ACTIVATE** appears, starting with the word following ACTIVATE. ACTIVATE may only be used inside a colon definition. The task executing the balance of the definition must be prevented from ever reaching the end of the definition (e.g., by STOP, NOD, or by being in an infinite loop that describes its desired behavior).

NOD

Infinite loop designed to ensure that a task remains inactive until ACTIVATEd to do something else.

HALT

(addr -)

Cause the task at *addr* to perform **NOD**. Usage:

<task-name> HALT

References BEGIN, in assembler, see target-specific SwiftX documentation Definition of HALT for a terminal task, Section 5.4.3 PAUSE, STOP, and WAIT, Section 5.2

5.4 Terminal Tasks

A terminal task is a background task with additional user variables that enable it to do serial I/O. Optionally, terminal tasks also may be given user variables to support an interpreter.

This section discusses issues peculiar to terminal tasks.

5.4.1 Defining a Terminal Task

The word TERMI NAL allots memory to a terminal task and creates the task definition table for a task that may control a serial port. The return stacks of all terminal tasks in a single system have the same size, and space is allowed for input message buffers and private dictionaries. Because terminal tasks can have a private dictionary, if the target system has an interpreter, they may have user variable space for dictionary management, disk access, editing, and interpretation of text input (from disk or keyboard); see Table 21 on page 109 for related details.

TERMI NAL is used as follows:

<n> TERMINAL <task-name>

where n is size in bytes to be allotted to the task's private dictionary (Section 7.1.2 discusses terminal tasks as they relate to the optional target-resident interpreter). The sizes of individual stacks, user area, and buffers belonging to a terminal task are configuration parameters, specified in Swi ftx\Src\<CPU>\Config. f.

Besides allotting space. TERMINAL may also establish driver routines for the terminal task. The exact method depends on the serial interface hardware; see your hardware-specific SwiftX documentation for details.

A terminal task also has provision for device-specific words for various common functions performed by serial devices. These correspond to certain of the terminal Application Programming Interface (API) functions described in the Forth Programmer's Handbook, Section 3.8, which often require device-specific definition. For example, the control character sequence required for cursor positioning (AT-XY) varies from one terminal to another, and cursor positioning may or may not be supported on a particular printer. SwiftOS provides for these by including execution vectors for these functions in a terminal task's user area. Each function supported in this way has a vector and a standard name for a low-level, device- or task-specific version of its behavior. These are summarized in Table 19.

Table 19: Vectored terminal-specific words

API word	Vector	Device- specific word	Description
EMI T	'EMIT	(EMI T)	Display a character.
TYPE	' TYPE	(TYPE)	Display a string.
CR	' CR	(CR)	Go to next line (carriage-return).
PAGE	' PAGE	(PAGE)	Go to next page (form-feed).
AT-XY	' AT-XY	(AT-XY)	Go to specified column/row.
KEY	' KEY	(KEY)	Await one key-press.
KEY?	' KEY?	(KEY?)	Check whether keypress occurred.
ACCEPT	' ACCEPT	(ACCEPT)	Accept a string.

SO will be copied to the task's user variable area by **CONSTRUCT**. Consult your platform documentation for the procedure for initializing the other vectors for your target system.

As with BACKGROUND, TERMI NAL must be executed at compile time, because TERMI NAL

builds the ROM table used to construct the task in RAM after power-up in the target system.

Glossary

TERMINAL < task-name>

(n-)

Define the terminal task task-name and set up its task definition table for a task whose private dictionary is *n* bytes in size. (A non-zero value for *n* is only appropriate when using the interpreter option; see Section Section 7:.) Subsequent use of *name* returns the address of the task definition table, which contains the parameters for building the task. The phrase <task-name> @ will return the address of the task's **STATUS** (the start of its user area).

References

CONSTRUCT, Section 5.4.2

User variables, Section 5.2.3

Terminal drivers, Forth Programmer's Handbook, Section 3.8

5.4.2 Initializing a Terminal Task

After a terminal task has been defined by the word TERMI NAL, the terminal task must be initialized by the use of the word **CONSTRUCT**, and then be made to run a program by the use of ACTI VATE. CONSTRUCT is used for terminal tasks similarly to how BUILD is used for background tasks.

Terminal task initialization consists of linking the task into the round robin and setting the task's user variables. The only remaining initialization required before a task is running is to set up the task's stacks, which will be performed by ACTIVATE (described in Section 5.3.3).

The word **CONSTRUCT** must be executed after power-up in the target system. It performs four separate functions:

- 1. It links the new terminal task into the round robin (using **BUILD**).
- 2. It copies non-device-dependent initialization from **OPERATOR**'s user variables to the new task's user variables.
- 3. It copies device-dependent data from the task definition table compiled by TERMINAL into the user variable area of the new task. Typical device-dependent data includes **DEVICE** and vectored routines for the terminal-specific functions described in Table
- 4. If the target has an interpreter, it sets the task's interpreter pointers.

After CONSTRUCT has been used, the task may be given a function to perform, as described in Section 5.4.3.

Glossary

CONSTRUCT

(addr -)

Initialize a task, given the *addr* of its task definition table that was constructed by TERMI NAL. The task will be linked in the round-robin after OPERATOR and before the task previously linked to **OPERATOR**. This must be done at run time in the target system, before any attempt to **ACTIVATE** the task. Usage:

<task-name> CONSTRUCT

References Controlling a terminal task, Section 5.4.3 Defining a terminal task, Section 5.4.1 Configuring a terminal task for the interpreter, Section 7.1.2

5.4.3 Controlling a Terminal Task

After a terminal task has been **CONSTRUCT**ed, it may be made to run a program. This is done by ACTIVATE, which controls TERMINAL tasks in the same way it controls **BACKGROUND** tasks.

The usual cautions about using **ACTI VATE** apply:

- ACTI VATE must be in a : definition.
- ACTIVATE takes a task address from the stack, and starts that task executing the words following **ACTIVATE**. The task must never reach the; of the definition containing **ACTI VATE**.
- The task that starts executing ACTIVATE exits from the definition containing ACTI -VATE without executing any of the words following ACTI VATE. That part of the definition is executed by the task that is **ACTIVATE**d. See the reference on **ACTIVATE**, Section 5.3.3, for more information.

References **ACTI VATE**, Section 5.3.3 **EMIT**, Forth Programmer's Handbook PAUSE, STOP, and WAIT, Section 5.3

5.5 A Multitasking Demo

To demonstrate the SwiftOS multitasker at work, you may run the Conical Pile Calculator demo (described in Section A.2) with a separate terminal task. To do this, you will need to:

- 1. Follow directions accompanying your SwiftX product to connect the serial output port on the demo board to a COM port on your computer that is not being used for vour XTL link.
- 2. Launch a terminal emulator (such as Terminal or HyperTerminal) on your PC, and configure it for the COM port connected to your board.
- 3. Check that the following lines are included near the end of **Debug**. **f**:

```
INCLUDE ... \CONI CAL
INCLUDE ... \DUMB
```

```
CONSOLE CONSTRUCT
256 TERMINAL CONSOLE
: DEMO
        CONSOLE ACTIVATE DUMB SCI-TERMINAL CALCULATE;
```

- 4. Launch SwiftX (if it is not already running) and initialize your target by using Project > Debug.
- 5. Run the demo by typing **DEMO** in the SwiftX command window. If you have positioned your terminal emulator window so both it and the SwiftX window are visible, you should see the application's prompt in the terminal emulator window.
- 6. In the terminal emulator window, type any parameters you wish for the demo, as described in Section 1.5.3.

Observe that your target system is responsive to demo program commands in the terminal emulator window, and to normal XTL commands in the SwiftX command window. In fact, you may run the demo from the command window, as well; but you may find that the application is not re-entrant (see the discussions in Section 5.1 and Section 5.2.3), due to its use of variables. If you are feeling ambitious, you might try defining those as user variables, and see if that helps!

5.6 Comparing Background Tasks and Terminal Tasks

Terminal tasks and background tasks are architecturally similar. In fact, a terminal task is technically a superset of a background task. Terminal tasks differ in that they have larger user areas to accommodate user variables related to servicing terminals and other serial devices.

Table 20: Functions applied to background and terminal tasks

	Background tasks	Terminal tasks
Define	<nu> <ns> <nr> BACKGROUND <name></name></nr></ns></nu>	<n> TERMINAL <name></name></n>
Initialize	<name> BUILD</name>	<name> CONSTRUCT</name>
Assign functions	<addr> ACTIVATE (addr returned by name; must be inside a colon definition)</addr>	<addr> ACTIVATE (addr returned by name; must be inside a colon definition)</addr>
Minimum user variables	STATUS through CATCHER	STATUS through DEVI CE

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SECTION 6: TARGET LIBRARIES

A SwiftX system includes libraries for the target system, all supplied in source form. Depending upon the extent of a library, it may be found as an individual file or as a directory. This differs from the method of providing libraries as linkable objects, but it is generally more flexible, and is more consistent with Forth's normal practice of compiling directly from source to executable form without a link phase.

To add a library to your target, just include the relevant files in the main load file, Kernel . f, prior to the line that includes the startup file Start. f.

6.1 Enhanced Number Conversion

Number conversion is often very simple in embedded systems, consisting only of obtaining a key and subtracting the offset to ASCII 0:

```
: DIGIT ( -- n ) KEY [CHAR] 0 - 0 MAX 9 MIN;
```

Such a word could be put inside a loop, starting with a 0 "accumulator" on the stack and, for each digit, multiplying the accumulator by 10 (assuming decimal) before adding the next digit.

For more complex situations, SwiftX provides a more powerful set of number-conversion words. For example, you may need to accept numbers with:

- decimal points (dots or commas, depending on American or European usage)
- colons (used in angles and times)
- slashes (used in dates)
- dashes (used in part numbers, telephone numbers, etc.)

SwiftX's number-conversion words are based on the low-level number-conversion word from ANS Forth, >NUMBER (see the Forth Programmer's Handbook, section 1.1.6).

The word NUMBER? takes the address and length of a string, and attempts to convert it until the length expires (in which case it is finished) or it encounters a character that is neither a digit (0 to BASE-1) nor valid punctuation.

NUMBER? interprets any number containing one or more valid embedded punctuation characters as a double-precision integer. Single-precision numbers are recognized by their *lack* of punctuation. Conversions operate on character strings of the following format:

```
[ - ]dddd[ punctuation ]dddd ... delimiter
```

where *dddd* is one or more valid digits in the task's current base (or *radix*). All numeric strings must end with a blank or expiration of the length. If another character is encountered (i.e., a character which is neither a digit in that base nor punctuation), conversion will end. There must be no spaces within the number, since a space is a delimiter. If a leading minus sign is present, it must immediately precede the leftmost digit or punctuation character.

Any of the following punctuation characters may appear in a number:

All punctuation characters are functionally equivalent, causing the digits that follow to be counted. This count may be used later by certain conversion words. The punctuation character itself performs no function other than to set a flag indicating its presence, and does not affect the resulting converted number.

Multiple punctuation characters may be contained in a single number; the following two character strings would convert to the same number:

```
1234, 56
1, 23, 456
```

NUMBER? will return one of three possible results:

- If number conversion failed (i.e., a character was encountered that was neither a digit nor a punctuation character), it returns the single value zero.
- If the number is single-precision (i.e., not punctuated), it returns a 1 on top of the stack, with the converted value beneath.
- If the number is double-precision (i.e., contained at least one valid punctuation character), it returns a 2 on top of the stack, with the converted value beneath.

The variable **DPL** is used to track punctuation during the conversion process. **DPL** is initialized to a large negative value, and is incremented every time a digit is processed. Whenever a punctuation character is detected, it is set to zero. Thus, the value of DPL immediately following a number conversion indicates potentially useful information:

- If it is negative, the number was not punctuated and is single-precision.
- Zero or a positive non-zero value indicates the presence of a double-precision number, and equals the number of digits to the right of the rightmost punctuation character.

This information may be used to scale a number with a variable number of decimal places. Since DPL doesn't care (or know) what punctuation character was used, it works equally well with American decimal points and European commas to start the fractional part of a number.

The word **NUMBER** is the high-level, input number-conversion routine used by SwiftX, both in the host's interpreter that processes source text and in the target kernels. It performs number conversions explicitly from ASCII to binary, using the value in **BASE** to determine which radix should be used. This word is a superset of **NUMBER?**.

NUMBER will attempt to convert the string to binary and, if successful, will leave the result on the stack. Its rules for behavior in the conversion are similar to the rules for **NUMBER?** except it always returns *just the value* (single or double). It is most useful in situations in which you know (because of information relating to the application) whether you will be expecting punctuated numbers. If the conversion fails due

to illegal characters, a THROW will occur.

If NUMBER's result is single-precision (DPL remains negative), the high-order part of the working number (normally zero) is saved in the variable NH, and may be recovered to force the number to double precision. This can be useful when dealing with naturally unpunctuated numbers whose values may exceed 65536 on a 16-bit system—for example, United States zip codes (e.g., 90266).

Glossary

>NUMBER

$$(ud_1 c-addr_1 u_1 - ud_2 c-addr_2 u_2)$$

Convert the characters in the string at c-add r_1 , whose length is u_1 , into digits, using the radix in **BASE**. The first digit is added to ud_1 . Subsequent digits are added to ud_1 after multiplying ud_1 by the number in BASE. Conversion continues until a non-convertible character (including any algebraic sign) is encountered or the string is entirely converted; the result is ud_2 . c-add r_2 is the location of the first unconverted character or, if the entire string was converted, of the first character beyond the string. u_2 is the number of unconverted characters in the string. "to-number"

NUMBER?

$$(c-addr u - 0 | n 1 | d 2)$$

Attempt to convert the characters in the string at *c-addr*, whose length is *u*, into digits, using the radix in BASE, until the length expires. If valid punctuation is encountered (, , + - / :), returns d and 2; if there is no punctuation, returns n and 1; if conversion fails due to a character that is neither a digit nor punctuation, returns 0 (false).

NUMBER

$$(c-addr u - n \mid d)$$

Attempt to convert the characters in the string at *c-addr*, whose length is *u*, into digits, using the radix in BASE, until the length expires. If valid punctuation is encountered (, , + - / :), returns d; if there is no punctuation, returns n; if conversion fails due to a character that is neither a digit nor punctuation, a THROW will occur.

DPL

$$(-addr)$$

Return the address of a variable containing the punctuation state of the number most recently converted by NUMBER? or NUMBER. If the value is negative, the number was not punctuated. If it is non-negative, it represents the number of digits to the right of the rightmost punctuation character.

NH

$$(-addr)$$

Return the address of a variable containing the high-order part of the number most recently converted by NUMBER? or NUMBER.

References

Numeric input, Forth Programmer's Handbook, Section 1.1.6 Number conversions in SwiftX, Section 4.1.1

6.2 Timing Functions

The words in this section support a hardware time-of-day clock and calendar. On targets without a built-in clock, you may enter a date and time, and SwiftX will maintain it using an internal clock or programmable timer, if one is available. See

your hardware-specific documentation for details. The accuracy with which this can be done depends, of course, upon the resolution of the available clock hardware.

The functions described in this section require the extended number-conversion facilities described in Section 6.1.

6.2.1 Date and Time of Day Functions

SwiftX supports a calendar using the mm/dd/yyyy format. Some of the words described below are intended primarily for internal use, whereas others provide convenient ways to enter and display date and time-of-day information.

SwiftX stores time information internally as an unsigned, double number representing seconds since midnight. There are 86,400 seconds in a day, so a double number is required for portability across 16- and 32-bit implementations.

Dates are represented internally as the number of days since January 1, 1900, also known as the *modified Julian date* (MJD). This is a simple, compact representation that avoids the "Year 2000 problem," because you can easily do arithmetic on the integer value, while using the words described in this section for input and output in various formats.

The range of dates that can be converted accurately by this algorithm is from March 1 1900 through February 28, 2100. Both of these are not leap years and are not handled by this algorithm, which is good only for leap years that are divisible by four with no remainder.

A date presented in the form mm/dd/yyyy is converted to a double-precision integer on the stack by the standard input number-conversion routines. A leading zero is not required on the month number, but is required on day numbers less than 10. Years must be entered with all four digits. A double-precision number entered in this form may be presented to the word M/D/Y, which will convert it to an MJD. For example:

8/03/1940 M/D/Y

will present the double-precision integer 80340 to M/D/Y, which will convert it to the MID for August 3, 1940. This takes advantage of the enhanced SwiftX number-conversion facility that automatically processes punctuated numbers as double-precision (see Section 6.1).

Normally, M/D/Y is included in the application user interface command that accepts the date. For example:

: HIRED (-- n)\ Gets date of hire CR . " Enter date of hire: "\ User prompt PAD 10 ACCEPT\ Await input to PAD PAD 10 NUMBER\ Text to number M/D/Y\ Number to MJD DATE-HIRED!;\ Store date

On most target platforms, you can set the system date by typing:

<mm/dd/yyyy> NOW

To obtain the day of the week from an MJD, simply take the number modulo 7; a value of zero is Sunday. For example:

8/03/1940 M/D/Y 7 MOD .

gives 6 (Saturday).

The alternative input form D/M/Y is also available (see "Date functions" on page 100).

Output formatting is done by (DATE), which takes an MJD as an unsigned number and returns the address and length of a string that represents this date as mm/dd/ yyyy. The word . DATE will take an MJD and display it in that format.

Glossary

Low-level time and date functions

@NOW

(-udn)

Return the system time as an unsigned, double number ud representing seconds since midnight, and the system date as n days since 01/01/1900. Used (for example) by TIME&DATE (see the Forth Programmer's Handbook).

! NOW

(udu -)

Take the same parameters as those returned by @NOW and set the system time and date.

! TI ME&DATE

$$(u_1 u_2 u_3 u_4 u_5 u_6 -)$$

Convert stack arguments u_1 seconds (0–59), u_2 minutes (0-59), u_3 hours (0–23), u_4 day (1-31), u_5 month (1-12), u_6 year (1900-2079) to internal form and store them as the system date and time.

Time functions

@TIME

(-ud)

Return the system time as an unsigned, double number representing seconds since midnight.

(TIME)

(ud — c-addr u)

Format the time ud as a string with the format hh:mm:ss, returning the address and length of the string.

. TI ME

(ud -)

Display the time *ud* in the format applied by **(TIME)** above.

TI ME

(-)

Display the current system time.

HOURS

(ud -)

Set the current system time to the value represented by ud, which was entered as hh:mm:ss.

Date functions

 $(u_1 u_2 u_3 - u_4)$

Convert day u_1 , month u_2 , and year u_3 into MJD u_4 .

 $\mathsf{M/D/Y}$ (ud-u)

Accept an unsigned, double-number date which was entered as *mm/dd/yyyy*, and convert it to MID.

(-u)

Return the current system date as an MJD.

(DATE) $(u_1 - c - addr u_2)$

Format the MJD u_1 as a string with the format mm/dd/yyyy, returning the address and length of the string.

. DATE (u-)

Display the MJD u in the format applied by **(DATE)** above.

(-)

Display the current system date.

NOW (ud-)

Set the current system date to the value represented by the unsigned, double number which was entered as mm/dd/yyyy.

References

Enhanced number conversion, Section 6.1

6.2.2 Interval Timing

SwiftX includes facilities to time events, for specifying when something will be done, and for measuring how long something takes. These words are described in the glossary below.

The word MS causes a task to suspend its operations for a specified number of milliseconds, during which time other tasks can run. For example, if an application word SAMPLE records a sample, and you want it to record a specified number of samples, one every 100 ms., you could write a loop like this:

Because **MS** is dependent upon the target system's clock, the accuracy of the measured interval depends upon the resolution of that clock. As a general statement, the error on an interval will be approximately the number of milliseconds in one clock tick. If you need to respond more promptly to an external event, the best way is to associate an interrupt directly with the event.

The words **COUNTER** and **TIMER** can be used together to measure the elapsed time between two events. For example, if you wanted to measure the overhead caused by

other tasks in the system, you could do it this way:

```
: MEASURE ( -- )
                                    \ Measure the measurement overhead
  COUNTER
                                    \ Initial value
   100000 0 DO
                                    \ Total time for 100,000 trials
                                    \ One loop around the multitasker
      PAUSE
  L00P
  TIMER;
                                    \ Display results
```

Following a run of MEASURE, you can divide the time by 100,000 to get the time for an average **PAUSE**. For maximum accuracy, you can run an empty loop (without **PAUSE**) and measure the measurement overhead itself.

A formula you can use in Forth for computing the time of a single execution is:

```
< t > 100 < n > */ .
```

where t is the time given by a word such as **MEASURE**, above, and n is the number of iterations. This yields the number of 1/100ths of a millisecond per iteration (the extra 100 is used to obtain greater precision).

The maximum clock error per iteration (in 1/100ths of a millisecond) may be calculated by:

```
1000 100 T/SEC */ <n> / .
```

where T/SEC is the number of clock interrupts per second (usually defined as an EQU in the INTERPRETER scope on the host, and used to compile the timing definitions discussed here), and *n* is the number of iterations, as above.

Glossary

MS (n-)

> **PAUSE** the current task for *n* milliseconds. The accuracy of this interval is always about one clock tick.

(-u)COUNTER

Return the low-order cell of the millisecond timer.

TI MER

Repeat COUNTER, then subtract the two values and display the interval between the two in milliseconds.

(u - flag)**EXPIRED**

> Return true if the current millisecond timer reading has passed u. For example, the following word will execute the hypothetical word **TEST** for *u* milliseconds:

```
: TRY ( u -- )
                                    \ Run TEST repeatedly for u ms.
  COUNTER + BEGIN
                                    \ Add interval to curr. value.
                                    \ Perform TEST ...
  DUP EXPIRED UNTIL
                                    \ ...until timer expires
  DROP ;
```

References Time and timing functions. Forth Programmer's Handbook. Section 3.7

Interrupt (exception) handlers, see your hardware-specific SwiftX documentation

6.2.3 Benchmarks

The file \Swi ftx\Src\Bench. f contains a small suite of benchmarks, useful for comparing various targets. It is also a good example of how to time functions using the tools described in Section 6.2.2. You may wish to apply similar techniques for measuring time-critical application functions.

Load the benchmarks with this command line:

INCLUDE %SWIFTX\SRC\BENCH

You may then run the benchmarks by typing BENCH. The output displayed is a list of words and the time each takes to execute on the target.



Timing is only as accurate as the granularity of the target's millisecond counter.

The first of these benchmarks measures the DO ... LOOP overhead associated with the measurement process. The last, PAUSE, measures the time it takes for the multitasking loop. The other tests in **BENCH** measure arithmetic function timings.

6.3 Arithmetic Library

SwiftX provides a variety of arithmetic operators for use in applications. They are designed to work efficiently on small microcomputer systems, trading extreme precision for size and speed. We recommend that you study the requirements of an application carefully; the provided routines have nearly always been found adequate when the limited precision of the associated I/O is properly taken into account. Most analog I/O has a precision of 12 bits or less; rarely does it exceed 16 bits. Numeric I/O, in real-time applications typical of SwiftX projects, rarely needs to be entered or displayed with any more precision than this.

6.3.1 Double-Precision Arithmetic

The standard double-precision operations (64 bit, in this case) defined in the Forth Programmer's Handbook have all been included in SwiftX as separate files, so they can be included or excluded, depending on the application. High-level words may be found in SwiftX\Src\Double.f, while code primitives may be found in SwiftX\ Src\<cpu>\Doubl e. f.

References Arithmetic and logical operators, Forth Programmer's Handbook

6.3.2 Fixed-Point Fractions

Fixed-point fractions are very simple and are widely applicable. In most cases, math

using them executes much faster than math using floating-point numbers—hence their inherent desirability. As a basic starting point, this SwiftX includes 14-bit fractions. These are convenient, because they have sufficient headroom in 16 bits to exactly describe unity and, in fact, can almost reach two (handy for vector magnitudes, etc.); and they have sufficient precision for most applications.

For those who are unfamiliar with fractional arithmetic, a brief overview follows.

Fractional arithmetic involves scaling and an implied decimal point. Instead of scaling by multiples of ten, as we do with decimal numbers (digits 0-9), we scale by multiples of two, as you would expect with binary numbers (digits 0 and 1). The implied decimal point is actually a binary point. We need to establish some sort of convenient scale to represent the positive integer 1. For 14-bit fractions, we define:

16384 CONSTANT +1

As a 16-bit binary number, 16384 looks like this:

0100000000000000

The one bit is scaled up in binary, along with the binary point, with 14 bits to its right to represent the fraction. A number scaled in this way has a precision of one part in 16384. If the number is used to represent a fraction of a circle (see below), the angular resolution is about 0.022 degrees.

Addition and subtraction of fractional numbers is done with the usual + and - operators, but some way of multiplying and dividing is needed. The words *. and /. perform this work. To assure ourselves that these operators really work, we can divide 1 by 1, and get 1 (16384).

In order to display the results of fractional arithmetic operations in a meaningful form, the word . F is included. It displays a fraction as a real number with four decimal places.

Readers who wish to learn more about fractional arithmetic should read the book Starting Forth, which offers an excellent discussion of rational numbers and fractional arithmetic.

Glo	ossary
-----	--------

(-n)+1

> implied binary point just after the second-most-significant bit.

(nf-n)

Multiply two numbers, one of which is a fraction, to return a whole number.

 $(n_1 n_2 - f)$ ٧.

Divide n_1 by n_2 and return a fractional result. The divisor must be positive.

(f-). F

Display a fraction with four decimal places.

References Fixed-point fractions, Starting Forth

6.3.3 Angles

Angles are hard to work with in conventional programming environments, for two major reasons: they usually are expressed in radians, and they are realized as floating-point numbers. This can be costly in both code and time, because many practical applications (such as encoders) work in revolutions, not radians; representation in radians wastes a fractional bit, and the arithmetic to convert back to revolutions adds time and computational noise.

The SwiftX approach is to represent angles in terms of revolutions; specifically, as fixed-point fractions of a revolution. For the usual 14-bit fractions, 360 degrees is represented internally as 16384, 45 degrees as 2048, and so forth; the least-significant bit is equal to approximately 0.022 degrees. In addition to gaining substantial convenience, the other benefits of representing angles in this way are legion; among them are extreme simplification of range reductions, maintenance of maximum precision and accuracy regardless of the manipulation involved, scale-independent error functions, and much faster execution. Thus, overall execution speed can be significantly improved in end-user applications or library functions that use large numbers of angular functions (e.g., Fast Fourier Transform). In those rare formulae (such as Kepler's equation) where the angle must be in radians, it's usually worthwhile to scale into radians, as necessary, but to keep most of the work in revolutions.

References

Fixed-point fractions, Section 6.3.2

6.3.4 Transcendentals

The most often needed transcendental routines are square root, trigonometric, and log/exponential, usually in that order. With the exception of square root, we usually employ Chebyshev polynomial approximations and consider Hart, et al., to be the definitive reference work. In the interest of providing reasonable standards, most of our routines apply the highest-precision polynomial that fits within the precision of the data type. The nice thing about using Hart for a source is that you can easily adjust the precision of the algorithm to match the required accuracy of the calculation, often with a substantial reduction of execution time. (Remember that few analog input or output devices exceed 12 or 16 bits of precision.)

References

Hart, John F. et al., Computer Approximations, Krieger Publishing Co., Inc., P.O. Box 9542, Melbourne, FL 32902-9542, (305) 724-9542.

6.3.4.1 Square Root

The basic square root algorithm has many uses and, with suitable prescaling, may be used for any fixed-point data when a root accurate to 15 bits is sufficient.

6.3.4.2 Trigonometric Functions

A full set of 14-bit fractional trigonometric functions, along with some support words, is supplied, as well as a test file that loads all the required arithmetic and which contains some useful examples.

As discussed in Section 6.3.3, angles are expressed as fractions of a circle, scaled by 16384. That is, a value of 8192 is equivalent to 180 degrees. The output fractional value is scaled to 16384 in the same way. For example, the SIN of 2048 (45 degrees) returns 11585 (0.707).

All trig functions that can go to infinity represent their potentially infinite values as ratios. Only in rational form are such values manipulable and meaningful; more to the point, the most common uses of these functions involve direction cosines for rotations. By using this representation, we affirm the purposes of the functions and maintain the utility of their results. Reduction of a ratio to a fraction, where needed, is done by /.

Glossary	
SIN	Sine $(n-f)$
cos	Cosine $(n-f)$
TAN	$\left(n - f_1 f_2 \right)$ Tangent
СОТ	$(n-f_1f_2)$ Cotangent
CSC	Cosecant $(n-f_1 f_2)$
SEC	Secant $(n-f_1 f_2)$
ASI N	(f-n) Arc-sine
ACOS	(f-n) Arc-cosine
ATAN	$\left(n_1 n_2 - n_3 \right)$ Arc-tangent of the ratio n_1/n_2 , giving n_3 .
DEG	(n-f) Converts an angle in degrees into a fraction representing part of a circle. For example, 45 degrees is $1/8$ of a circle. If you type:

45 DEG . you should get 2048.

- $(\it f-\it n\,)$ Converts a fractional angle into an integer with two implied decimal places. **REV**
- (f_1-f_2) Converts an angle from a fraction in the range 0–360 degrees to the range -180 +180 degrees. <. 5

SECTION 7: INTERPRETER/COMPILER OPTION

SwiftX Pro includes an optional target-resident interpreter and high-level Forth compiler to provide Forth services via a serial line to a terminal or terminal emulator from the target. This facility supports:

- Field service debugging without a full SwiftX host system
- Simple command-line user interfaces
- Ability to change configuration parameters easily

This facility is far less powerful than the full SwiftX development environment. It supports programming only to the extent of adding simple high-level Forth definitions; no target-resident assembler is provided. For complex programming or debugging chores, the SwiftX host remains the environment of choice.



The target-resident interpreter and compiler option is only available on targets with sufficient resources (RAM, writable code space) to support it.

7.1 Configuring SwiftX for the Interpreter Option

To include the target-resident interpreter in your target, you must edit the **Config. f** file in your project directory such that the flag TARGET-INTERP is true:

-1 EQU TARGET-INTERP

There are some additional configuration issues, however. In order for your target program to use the interpreter option:

- Some or all of your target definitions must have heads in order to be found from the terminal. This is described in Section 7.1.1 below.
- The terminal task communicating with your serial port must be configured for additional user variables and sufficient memory for a private dictionary. This is described in Section 7.1.2 below.

7.1.1 Configuring the Target Dictionary

SwiftX normally compiles only executable code in its target program space, making an extremely compact system. In order to use the interpreter option, however, at least some definitions must have heads in order to make them accessible. There are two ways to configure your SwiftX cross-compiler for this, depending upon your needs:

- 1. Put heads on all words, but retaining the ability to specify certain words to be without heads.
- 2. Omit heads except for the selected words you wish to make available.

Option 1 is appropriate if you wish most words in your target to be available for

debugging or added programs, and if you have sufficient memory. Option 2 is available if you need to keep your program small, or wish to make only certain words available for user interface purposes.

Managing these options involves two words to set defaults, and two to over-ride the current default for a single definition:

- +HEADS configures the cross-compiler to put heads on all words; | (vertical bar, pronounced "bar") causes the next target definition to be compiled without a head.
- -HEADS configures the cross-compiler to compile definitions without heads; ~ (tilde) causes the next target definition to be compiled with a head.

Both the defaults and the overrides affect all SwiftX defining words operating in the TARGET scope, constructed with: (colon), CODE, CREATE, VARIABLE, etc. It will not affect EQU definitions, because they compile target literals rather than actual definitions.

You may change your default at any time. Thus, you may have certain files compiled with the **+HEADS** setting and others with the **-HEADS** setting.

An override symbol must precede the defining word you wish it to affect. (Since these are words themselves, they must be delimited by spaces.) For example, if you are compiling with the -HEADS default set and wish to put a head on a word that displays a user menu, you might use:

~ : MENU ...

Similarly, if you are compiling with the +HEADS default and wish to specify no head on a word containing a password, you might use:

3728493 | CONSTANT PASS

or

| 3728493 CONSTANT PASS

Remember, only words compiled with heads may be accessed from the target's interpreter, either by users or by added definitions. All words remain available in the cross-compiler's TARGET scope.

Glossary	
+HEADS	$(-) \\$ Set the cross-compiler to put heads on all subsequent target definitions.
-HEADS	$(-) \\$ Set the cross-compiler to omit heads on all subsequent target definitions.
~	$(-) \\$ Cause the next target definition to have a head, regardless of the current default.
I	$(-) \\$ Cause the next target definition to have no head, regardless of the current default.

References TARGET scope, Section 4.6.2 Defining words in SwiftX, Section 4.4

7.1.2 Configuring a Terminal Task for the Interpreter

The interpreter and compiler are accessed through a terminal task attached to the serial port through which interactivity will take place. All terminal tasks have the ability to support serial-type I/O and, potentially, an interpreter and a private dictionary. (Basic principles of defining and managing terminal tasks are described in Section 5.4.)

A terminal task is defined using the form:

<n> TERMI NAL <name>

where n is the size of its private dictionary. The dictionary size may be zero for tasks with no private dictionary (such tasks may still use the interpreter, but may not compile anything). The total amount of space used by the task is the sum of nplus all the parameters listed in Table 21. The default sizes for these parameters on your system may be found in \Src\<CPU>\Confi g. f.

Table 21: Parameters governing the space allocation for a terminal task

Name	Description	Typical size (bytes)
U	Maximum size of user area	256
S	Maximum size of data stack	256
R	Maximum size of return stack	256
NUM	Space reserved for output number conversions	66
PAD	Space reserved for PAD (scratch string storage)	84
TIB	Terminal input buffer (TIB)	80

The task space will be allocated out of uData when the target program is compiled. The target-resident compiler doesn't have different memory sections.

The locations of the user area, return stack, and data stack are permanent, as is the location of the start of the private dictionary (H0). However, PAD "floats" above the current top of the dictionary (the location returned by HERE), at a distance given by | NUM|. Therefore, if you put data at PAD and then extend your dictionary (by adding definitions), PAD will have moved and that data will no longer be accessible.

A map of the various spaces in a terminal task area is shown in Figure 21. The arrows show the direction of growth of the various resources. Since various of these resources are configured to grow towards each other, they effectively share a larger pool of space than is allocated for each individually. For example, if the return stack is small (as it tends to be), a string longer than 80 bytes may be accepted into the terminal input buffer. This greatly improves the overall use of space and system reliability. However, if you know your application will regularly require more space for any particular resource, you should adjust the default allocations.

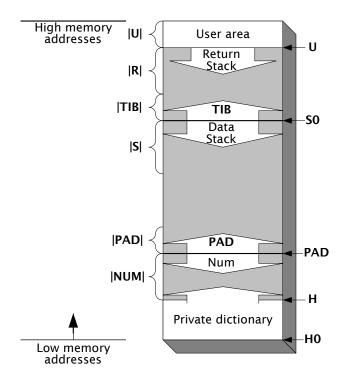


Figure 21. Terminal task use of memory

The terminal task that is to run the interpreter should be initialized as part of the start-up code in your target program. You will need to CONSTRUCT this task, as described in Section 5.4.2. You must then connect it to its serial port, as described in your CPU-specific documentation. Finally, if you wish its behavior to be that of a normal Forth system (accepting and interpreting user input), you must assign this behavior to it by using a definition such as:

```
: LISTEN ( -- )
                  <task-name> ACTIVATE QUIT ;
```

References

ACTI VATE, Section 5.4.3 QUIT, Section 7.2 Terminal tasks, Section 5.4

7.1.3 Additional User Variables

A number of user variables are added to the SwiftX target in order to support the interpreter. These are described in the following glossary, along with some related words.

Glossary

BASE (-addr)

Contains the current radix used for input and output number conversions.

Н (-addr)

Contains the address of the next available location in the user dictionary.

HERE

Returns the address of the next available location in the user dictionary (equivalent

to the **H** @ sequence).

HO (-addr)

Contains the address of the start of the user dictionary.

(-addr)**LAST**

Contains the address of the start of the most recent definition.

STATE (-addr)

Contains zero if the task is in interpret mode, non-zero if it's compiling (i.e., inside

a colon definition).

TI B (-addr)

Returns the address of the start of the terminal input buffer.

>IN

Returns the offset from the start of the TIB indicating the next bytes to be inter-

preted.

References #TIB. Section 5.2.3

7.2 Using the Interpreter

The target-resident interpreter works as described in the Forth Programmer's Handbook, Sections 1.1.5 and 2.6. It is case-sensitive, so you should give careful thought to the use of case in your word names.

A number of the low-level components of the interpreter are available, and may be useful on occasion. These are summarized in the glossary below.

INTERPRET uses WORD to parse the current input stream in a loop, and uses FIND to search the dictionary for it. It will compile or execute each word, depending on whether it is inside a colon definition, as indicated by a non-zero value in **STATE**. (A flowchart of this process is provided in the Forth Programmer's Handbook, Figure 5.) This continues until the input stream is exhausted.

This input stream is normally received by **ACCEPT** into the terminal input buffer. Its parameters (address and length) are returned by **SOURCE**. The high-level word that does this, including setting parameters as necessary, is **QUERY**.

Glossary

QUERY (-n)

Accepts a line of text into TIB and leaves its actual length in #TIB.

SOURCE (-c-addr n)

Returns the address and length of the input buffer.

INTERPRET

Attempts to execute, or convert to a number, each word found in the current input buffer. Throws -4 if the stack underflowed as a result of executing a word.

PARSE (char - c-addr n)

Parses the current input stream (whose parameters are given by **SOURCE**) looking for the first occurrence of *char*, or the end of the input stream if it is not found. Returns the address and length of the found string. The length is zero if the string cannot be parsed.

WORD (char - c-addr)

> Parses the input stream (using PARSE) looking for the delimiter *char*. Returns the address of a resulting counted string (length in its first byte).

FIND $(c-addr - c-addr 0 \mid xt 1 \mid xt - 1)$

> Searches the dictionary for the counted string at *c-addr*. If a match is found, returns its xt and 1 if the word is IMMEDIATE (bit 7 is set), or its xt and -1 if the word is not **IMMEDIATE**. Returns *c-addr* and *false* if the word is not found.

References Dictionary searches, Forth Programmer's Handbook, Section 2.6.3 I MMEDI ATE words, Forth Programmer's Handbook, Section 2.10

7.3 Using the Compiler

The target-resident compiler is intended only for relatively simple programming. such as simple definitions used for troubleshooting or for adding minor program features. It is optimized for small size and portability, rather than for power and speed. The principle programming support for SwiftX remains the host cross-compiler and XTL.

As a result, the following features are *not* supported:

- Assembler
- Word lists, or scopes
- Ability to add new data types or compiler directives
- Local storage for program source
- Other advanced programming features

Source may be transmitted to the target using a terminal emulator to send a text file. The target can interpret such source a line at a time. It will acknowledge each line as a line typed by a user, by replying "ok" followed by a CR. Therefore, you can pace transmission by configuring your terminal emulator to wait for a CR before

sending each line.

The target-resident compiler can handle references to all words that were crosscompiled with heads, as described in Section 7.1.1. You may type WORDS to see a list of available words.

All compiling actions that increase the size of the dictionary will check the remaining space, and will abort if there is not enough for the sum of the stack size, PAD, and the number-conversion buffer.

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APPENDIX A: PROGRAMMING EXAMPLES

This section presents some simple application examples to illustrate the process of writing and testing SwiftX programs. Since this book is designed to be independent of the particular board or processor you're using, these examples will necessarily omit detailed memory mapping and hardware considerations; refer to your platform-specific documentation for those. However, these examples will illustrate some important principles:

- Factor your definitions into very short, preferably re-usable, components.
- Give your definitions brief but meaningful names to improve your code readability.
- Design "top-down."
- Test "bottom-up" using the intrinsic interactivity of Forth.

A.1 THE WASHING MACHINE

This is a simple example that illustrates some basic principles of application organization and design. We will also describe how you would actually go about developing and testing this simple program.

There are two basic aspects to this program: the control of the I/O (consisting of six digital switches that control various components of the washing machine plus the standard system timer), and the logic of the washing machine's behavior. These follow directly from the basic design.

This example represents a minimal kind of embedded system. It can run on a stripped kernel only a few hundred bytes in size, although it would run equally well (just take more space) on a full kernel as shipped with SwiftX.

The complete source for this example is given in Section A.1.3

A.1.1 Top-down Program Design

The process of developing a program in SwiftX is consistent with the recommended practices of top-down design and bottom-up coding and testing. However, Forth adds two elements: extreme modularity and interactivity. You don't write page after page of code and then try to figure out why it doesn't work; instead, you write a few very brief definitions and then exercise them interactively, one by one.

Suppose we are designing a washing machine. The overall, highest-level definition might be:

: WASHER WASH SPIN RINSE SPIN;

The colon indicates that a new word is being defined; following it is the name of that new word, WASHER. The remainder are the previously defined words that comprise this definition. Finally, the definition is terminated by a semi-colon.

Typically, we design the highest-level routines first. This approach leads to conceptually correct solutions with a minimum of effort. In Forth, words must be compiled before they can be referenced. Thus, a listing begins with the most primitive definitions and ends with the highest-level words. If the higher-level words are entered first, lower-level routines are added above them in the file.

The code in this example (given in Section A.1.3) is nearly self-documenting; the few comments show the parameters being passed to certain words and identify groups of words. Forth allows as many comments as desired, with no penalty in object code size or performance.

When reading,

```
: WASHER
         WASH SPIN RINSE SPIN;
```

it is obvious what RINSE does. To determine how it does it, you read:

```
: RINSE
         FILL AGITATE DRAIN;
```

When you wonder how FILL works, you find:

```
FAUCET ON TILL-FULL
: FILL
                                FAUCET OFF;
```

Reading further, one finds that **FAUCET** is simply a constant which returns the bit mask for the port that controls the I/O, while **ON** is a simple word that turns on the selected bit.

Even from this simple example, it may be clear that Forth is not so much a language, as a tool for building application-oriented command sets. The definition of WASHER is based not on low-level Forth words, but on washing-machine words like SPIN and RINSE. By "factoring" the program into tiny components like this, you make your program not only more readable, but also easier to test. And the components are much more likely to be reusable: here, we use words like FILL-TUB, AGITATE, and **DRAIN** several times, and the **ON** and **OFF** commands frequently.

Because Forth is extensible, Forth programmers write collections of words that apply to the problem at hand. The power of Forth, which is simple and universal to begin with, grows rapidly as words are defined in terms of previously defined words. Each successive, newer word becomes more powerful and more specific. The final program becomes as readable as you wish to make it.

When developing this program, you would follow your top-down logic, as described above. But when the time comes to test it using SwiftX's XTL, you see the real convenience of Forth's interactivity.

A.1.2 Hardware Control

This example assumes six digital switches, which are represented as individual bits in an 8-bit control register. For simplicity, we assume this control register is memory mapped to a port address that we'll show here as 01. Where such a port would be in actual address space depends, of course, upon your CPU and other engineering and design decisions beyond the scope of this manual. Timing is done using the standard SwiftX word MS (see Section 6.2.2), which is defined in terms of your system clock; see your platform-specific documentation for details.

From a software perspective, a memory-mapped port is simplest, because you can read and write it using high-level fetch and store operators.

If your hardware is available, your first step would be to see if it works. Even without writing a formal driver or application code, you can read and write the hardware registers by typing phrases such as:

HEX 01 C@ .

This would read the port and display its value in hex, so you can see the individual bits. You could do things to the hardware that would cause the bit values to change (e.g., press a button or throw a switch) and see if the bit on the port does change appropriately. You could write to the port, for example, by typing:

1 01 C!

and see if the motor turns on. In this way, you can verify that your hardware is connected and functioning before you even write a line of code.

Program access to the I/O is provided by naming the port, and then defining various bit masks that can be used to isolate individual switches on the port:

\ Port assignments 01 CONSTANT PORT

```
\ bit-mask
                     bi t-mask
            name
                                 name
 1 CONSTANT MOTOR
                     8 CONSTANT FAUCET
 2 CONSTANT CLUTCH 16 CONSTANT DETERGENT
  4 CONSTANT PUMP
                     32 CONSTANT LEVEL
```

If the hardware is unavailable, you might temporarily re-define **PORT** as a variable, so you can read and write it, and thus test the rest of the logic.

These definitions would be put at the beginning of your source file. Naming the port and device bits in this way provides *information hiding*, which means, in this case, that if the port or bit assignments change, all you have to do is modify these definitions, and the rest of your code will run unchanged.

You can load your source file by using the command INCLUDE <fil ename>, whereupon all its definitions are available for testing. You can further exercise your I/O by typing phrases such as:

```
MOTOR ON or MOTOR OFF
```

to see what happens. Then you can exercise your low-level words, such as:

DETERGENT ADD

and so on, until your highest-level words are tested.

As you work, you can use any of the additional programmer aids provided by

SwiftX. You can also easily change your code and re-load it. But your main ally is the intrinsically interactive nature of Forth itself.

A.1.3 Code for the Washing Machine

```
( Washing Machine Application )
\ Port assignments
01 CONSTANT PORT
\ bit-mask name
                     bit-mask
                                 name
 1 CONSTANT MOTOR
                     8 CONSTANT FAUCET
  2 CONSTANT CLUTCH 16 CONSTANT DETERGENT
 4 CONSTANT PUMP
                     32 CONSTANT LEVEL
\ Device control
: ON ( mask -- ) PORT C@ OR PORT C! ;
: OFF ( mask -- ) INVERT PORT C@ AND PORT C! ;
\ Timing functions
: SECONDS ( n -- ) 0 ?DO 1000 MS LOOP ;
: MINUTES ( n -- ) 60 * SECONDS ;
: TILL-FULL ( -- ) \ Wait till level switch is on
  BEGIN PORT C@ LEVEL AND UNTIL;
\ Washing machine functions
: ADD ( mask -- ) DUP ON 10 SECONDS OFF ;
: DRAIN ( -- ) PUMP ON 3 MINUTES ;
: AGITATE ( -- ) MOTOR ON 10 MINUTES MOTOR OFF ;
: SPIN ( -- ) CLUTCH ON MOTOR ON 5 MINUTES
  MOTOR OFF CLUTCH OFF PUMP OFF;
: FILL-TUB ( -- ) FAUCET ON TILL-FULL FAUCET OFF ;
\ Wash cycles
: WASH ( -- ) FILL-TUB DETERGENT ADD AGITATE DRAIN ;
: RINSE ( -- ) FILL-TUB AGITATE DRAIN ;
\ Top-level control
: WASHER ( -- ) WASH SPIN RINSE SPIN ;
```

A.2 THE CONICAL PILE CALCULATOR

SwiftX includes an example of a complete (though small) application based on an example in the popular Forth tutorial book *Starting Forth* by Leo Brodie. The following description is adapted from the 2nd edition, p. 302 ff.

The SwiftX source for this program is in the file SwiftX\Src\Coni cal. f. Instructions for running this demo application using the Cross-Target Link may be found in Section 1.5.3. Instructions for running it on a separate serial port using a second multiprogrammed task are given in Section 5.5.

A.2.1 Algorithm Description

This example is a math problem that many people would assume could be solved only by using floating point. It will illustrate how to handle a fairly complicated equation with fixed-point arithmetic, and will demonstrate that for all the advantages of using fixed-point, range and precision need not suffer.

In this example, we will compute the weight of a cone-shaped pile of material, knowing the height of the pile, the angle of the slope of the pile, and the density of the material.

To make the example more "concrete," let's weigh several huge piles of sand, gravel, and cement. The slope of each pile, called the *angle of repose*, depends on the type of material. For example, sand piles more steeply than gravel.

(In reality, these values vary widely, depending on many factors; we have chosen approximate angles and densities for purposes of illustration.)

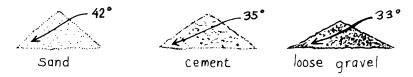


Figure 22. Angles of repose

Here is the formula for computing the weight of a conical pile h feet tall with an angle of repose of Θ degrees, where D is the density of the material in pounds per cubic foot:1

$$W = \frac{\pi h^3 D}{3 \tan^2(\Theta)}$$

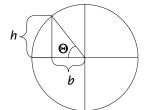
This will be the formula we must express in Forth.

Let's design our application so that we can enter parameters to specify the material, then the height of the pile, using single letters to identify the parameter. This will be easy to support with a terminal emulator or the XTL, and in a real device, the single letters could easily map to special function keys. So, we might enter 1M to select the first material, **10F** to specify 10 feet, and **6I** for six inches. You can enter these selections repeatedly, and then enter = to perform the calculations and get a result.

1. **Derivation:** The volume *V* of a cone is given by:

 $V = 1/3(\pi b^2 h)$

where b is the radius of the base and h is the height. We can compute the base by knowing the angle or, more specifically, the tangent of the angle. The tangent of an angle is simply the ratio of the segment marked h to the segment marked b in the drawing. If we call this angle Θ ("theta"), then:



 $\tan \Theta = h/b$

Thus, we can compute the radius of the base with:

 $b = h/\tan \Theta$

When we substitute this into the expression for V and then multiply the result by the density D in pounds per cubic foot, we get the foregoing formula. Let's assume that for any one type of material, the density and angle of repose never vary. We can store both of these values, for each type of material, into a table. Since we ultimately need each angle's tangent, rather than the number of degrees, we will store the tangent. For instance, the angle of repose for a pile of cement is 35°, for which the tangent is .700. We will store this as the integer 700.

Bear in mind that our goal is not just to get an answer; we are programming a computer or device to get the answer for us in the fastest, most efficient, and most accurate way possible. To write equations using fixed-point arithmetic requires an extra amount of thought. But the effort pays off in two ways:

- 1. Vastly improved run-time speed, which can be very important when there are millions of steps involved in a single calculation, or when we must perform thousands of calculations every minute. Also,
 - 2. Program size, which would be critical if, for instance, we wanted to put this application in a hand-held device specifically designed as a pile-measuring calculator. Forth is often used in this type of instrument, for this very reason.



Figure 23. Conical pile calculator

Let's approach our problem by first considering scale. The height of our piles ranges from 5 to 50 feet. By working out our equation for a pile of cement 50 feet high, we find that the weight will be nearly 35,000,000 pounds.

However, because our piles will not be shaped as perfect cones, and because our values are averages, we cannot expect better than four or five decimal places of accuracy. If we scale our result to tons, we get about 17,500. This value will comfortably fit within the range of a 16-bit number. For this reason, let's write this application entirely with single-length arithmetic operators.

Applications that require greater accuracy can be written using double-length arithmetic. But we intend to show the accuracy that Forth can achieve even with 16-bit math.

By running another test with a pile 40 feet high, we find that a difference of onetenth of a foot in height can make a difference of 85 tons in weight! So we decide to scale our input to tenths of a foot, not just whole feet.

We'd like the user to be able to enter:

15F 2I =

^{1.} For Math Experts: In fact, since our height will be expressed in three digits, we can't expect greater than three-digit precision. For purposes of our example, however, we'll keep better than four-digit precision.

where the function keys F and I will cause the execution of words FOOT and INCH, respectively, to convert the feet and inches into tenths of an inch, and = will execute the word PILE to do the calculation. Here's how we might define FOOT and INCH: 1

```
\ Convert n1 feet to n2 tenths of an inch.
: F00T ( n1 -- n2 )
                      10 * :
\ Convert n2 inches to tenths and add n1.
                        100 12 */ 5 + 10 / +;
: INCH ( n1 n2 -- n3 )
```

(The use of INCH is optional.) Thus, 23 FOOT will put the number 230 on the stack; 15 **FOOT 4 INCH** will put 153 on the stack, and so on. We could as easily have designed input to be in tenths of an inch, with a decimal point, like this:

15.2

In such a case, the number-conversion routine would convert the input as a doublelength value. Since we are only doing single-precision arithmetic, PILE could simply begin with **DROP**, to eliminate the high-order part.

In writing the definition of PILE, we must try to maintain the maximum number of places of precision without overflowing 15 bits. According to the formula on page 119, the first thing we must do is cube the argument. But let's remember that we will have an argument that may be as high as 50 feet, which will be 500 as a scaled integer. Even to square 500 produces 250,000, which exceeds the capacity of a single-precision number on a 16-bit system.

We might reason that, sooner or later in this calculation, we're going to have to divide by 2000 to yield an answer in tons. Thus, the phrase:

```
DUP DUP 2000 */
```

will square the argument and convert it to tons at the same time, taking advantage of */'s double-length intermediate result. Using 500 as our test argument, the above phrase will yield 125.

However, our pile may be as small as 5 feet, which when squared is only 25. To divide by 2000 would produce a zero in integer arithmetic, which suggests that we are scaling down too much.

To retain maximum accuracy, we should scale down no more than necessary. 250,000 can be safely accommodated by dividing by 10. Thus we will begin our definition of PILE with the phrase:

```
DUP DUP 10 */
```

The integer result at this stage will be scaled to one place to the right of the decimal point (25000 for 2500.0).

Now we must cube the argument. Once again, straight multiplication will produce a double-length result, so we must use */ to scale down. We find that by using 1000 as our division, we can stay just within single-length range. Our result at this stage

^{1.} In fact, the definitions in the file that ships with SwiftX are slightly more complicated, in order to provide error checking and some user feedback.

will be scaled to one place to the left of the decimal point (12500 for 125000), and is still accurate to five digits.

According to our formula, we must multiply our argument by π . We know that we can do this in Forth with the phrase:

```
355 113 */
```

But we must also divide our argument by 3; we can do both at once with the phrase:

```
355 339 */
```

which causes no problems with scaling.

Next, we must divide our argument by the tangent squared, which we can do by dividing the argument by the tangent twice. Because our tangent is scaled to 3 decimal places, to divide by the tangent we multiply by 1000 and divide by the table value. Thus, we will use the phrase:

```
1000 THETA @ */
```

Since we must perform this twice, let's make it a definition, called /TAN (for "divide by the tangent") and use the word /TAN twice in our definition of PILE. Our result at this point will still be scaled to one place to the left of the decimal (26711 for 267110, using our maximum test values).

All that remains is to multiply by the density of the material, of which the highest is 131 pounds per cubic foot. To avoid overflowing, let's try scaling down by two decimal places with the phrase:

```
DENSITY @ 100 */
```

By testing, we find that the result at this point for a 50-foot pile of cement will be 34,991, which just exceeds the 15-bit limit. Now is a good time to take the 2000 (pounds per ton) into account. Instead of:

```
DENSITY @ 100 */
```

we can say:

```
DENSITY @ 200 */
```

and our answer will now be scaled to whole tons.

By using double-precision arithmetic on a 16-bit system, or by using a 32-bit system and scaling differently, we are able to compute the weight of the pile to the nearest whole pound. The range of 32-bit arithmetic compares with that of most floatingpoint arithmetic, but is much slower on processors that lack floating-point hardware or firmware.

The following is a comparison of the results obtained using a 10-decimal-digit calculator, 16-bit Forth and 32-bit Forth. The test assumes a 50-foot pile of cement, using the table values.

Table 22: Comparison of results using 16-bit and 32-bit arithmetic

	In Pounds	In Tons
Calculator	34,995,634	17,497,817
Forth, 16-bit	n/a	17,495
Forth, 32-bit	34,995,634	17,497,817

A.2.2 Material Selection

This application supports six different materials: cement, loose gravel, packed gravel, dry sand, wet sand, and clay. Each material has a characteristic density and theta, and a string to identify it for the user. This is an excellent example of an occasion where Forth's ability to define special data types comes in handy. The defining word MATERIAL (see the file SwiftX\Src\Coni cal . f) can be used to define each material:

\	Densi ty	Theta	
	131	700	MATERIAL CEMENT"Cement"
	93	649	MATERIAL LOOSE-GRAVEL"Loose
grav	/el "		
-	100	700	MATERIAL PACKED-GRAVEL"Packed
grav	/el "		
_	90	754	MATERIAL DRY-SAND"Dry sand"
	118	900	MATERIAL WET-SAND"Wet sand"
	120	727	MATERIAL CLAY"Clay"

Each of the words defined by MATERIAL (CEMENT, etc.) will, when executed, store its density and theta in the variables **DENSITY** and **THETA** used for the calculation, and will put the address of the descriptive string in the variable **MATTER**.

Next, a table is constructed listing the *execution tokens* of these materials:

```
\ List of xt's of material words.
CREATE TABLE ' CEMENT , ' LOOSE-GRAVEL , ' PACKED-GRAVEL .
  ' DRY-SAND , ' WET-SAND , ' CLAY ,
```

A numeric parameter in the range 0-5 can be used to index into this table, and then **EXECUTE** the selected *xt*. This is done by the word **SELECT**:

```
\ Select material n, execute its xt in TABLE above.
: SELECT ( n)
              DUP 6 < IF
    CELLS TABLE + @EXECUTE . SUBSTANCE
    ELSE . ERROR THEN ;
```

SELECT is even used by . **DI RECTI ONS** to display the menu.

The highest level of the program is a loop called **CALCULATE**. It processes the input. When feet and inches are entered, that value is accumulated in the variable ACCM, which is then given as a parameter to PILE.

^{1.} See the Forth Programmer's Handbook, Section 2.7, and this manual, Section 4.7.

CALCULATE begins by clearing ACCM, displaying directions, and setting the default material to CEMENT. It then enters an infinite loop in which it solicits user input and then acts on it. Pressing 'M' selects the material, 'F' and 'I' set feet and inches, '=' performs the actual calculation, and the Escape key exits the loop.

```
: CALCULATE ( -- )
  O ACCM! . DIRECTIONS CEMENT
  BEGIN #INPUT CASE
     [CHAR] M OF SELECT ENDOF
     [CHAR] F OF FOOT ACCM! ENDOF
     [CHAR] I OF ACCM @ SWAP INCH ACCM!
     NIP [CHAR] = OF ACCM @ PILE O ACCM ! ENDOF
     $1B (Esc) OF EXIT ENDOF
ENDCASE AGAIN;
```

We recommend that you read the full source for this application in the file SwiftX\ Src\Conical.f, as it provides a good example of how a program may be constructed.

References

Execution tokens, Forth Programmer's Handbook, Section 2.5.6

A.2.3 Testing the Calculator

As with the Washing Machine example (Section A.1), we develop and test the program incrementally.

First, we would test the computational words by storing various values in the variables **DENSITY**, **THETA**, and **ACCM**, and by executing **PILE** with various heights. Remember that if you're connected to your target, you can fetch and store its variables from the keyboard, by typing phrases such as:

```
131 DENSITY! or DENSITY@. (which would return 131.)
```

Next, we would construct the list of materials, and test the defining word MATERIAL by, for example, typing 1 SELECT and then examining the values in the variables to verify that the correct values were stored and that the behavior assigned to the new words by MATERIAL is what you intended.

You can look at the user directions by typing . DI RECTIONS. You can adjust the message, spacing, etc., as much as you like until you get a pleasing display.

Finally, when you are confident that the low-level components of your program are working, you may type **CALCULATE**. If one of its components fails to work, you can exercise it individually from the keyboard. For example, if you seem to be getting the wrong material, you might type:

```
1 SELECT MATTER COUNT TYPE
```

and see if you get the string Loose gravel. Or, if you're getting wrong answers, you might try:

```
1 SELECT 10 FOOT PILE
```

and compare the result you get with results from a pocket calculator. Check the

values stores in **DENSITY** and **THETA** to be sure they were set properly. If they aren't, your problem may be with SELECT; if they are, check your computational definitions again by executing their components.

This style of informal, interactive testing usually gets results much more quickly than steppers, breakpoints, etc.

SwiftX Reference Manual

APPENDIX B: FORTH WORDS INDEX

This section provides an alphabetical index to the Forth words that appear in the glossaries in this book. Each word is shown with its stack arguments and with a page number where you may find more information. If you're viewing the PDF version of this document, you can click on the Forth word name to go to its glossary definition.

B.1 STACK ARGUMENTS

The stack-argument notation is described in Table 23. Where several arguments are of the same type, and clarity demands that they be distinguished, numeric subscripts are used.

Table 23: Stack argument notation

Notation	Description
a-addr	A cell-wide byte address that is cell-aligned (i.e., the address is evenly divisible by the cell size in bytes).
c-addr	A cell-wide byte address that is character-aligned (because a character is always one byte on current systems, this amounts to an arbitrary byte address).
addr	A cell-wide byte address.
b	A byte, stored as the least-significant 8 bits of a stack entry. The remaining bits of the stack entry are zero in results or are ignored in arguments.
С	An ASCII character, stored as a byte (see above) with the parity bit reset to zero.
d	A double-precision, signed, 2's complement integer, stored as two stack entries (least-significant cell underneath the most-significant cell). On 16-bit machines, the range is from -2**31 through +2**31-1. On 32-bit machines, the range is from -2**63 through +2**63-1.
flag	A single-precision Boolean truth flag (zero means <i>false</i> , non-zero means <i>true</i>).
i*x, j*x, etc.	Zero or more cells of unspecified data type.
n	A signed, single-precision, 2's complement number. On 16-bit machines, the range is from $-2**15$ through $+2**15-1$. On 32-bit machines, the range is from $-2**31$ through $+2**31-1$. (Note that Forth arithmetic rarely checks for integer overflow.) If a stack comment is shown as n , u is also implied unless specifically stated otherwise (e.g., $+$ may be used to add either signed or unsigned numbers). If there is more than one input argument, signed and unsigned types may not be mixed.

Table 23: Stack argument notation

Notation	Description
+n	A single-precision, unsigned number with the same positive range as n above. An input stack argument shown as $+n$ must not be negative.
и	A single-precision, unsigned number with a range from 0 to 2**16-1 on 16-bit machines, or 0 through 2**32-1 on 32-bit machines.
ud	A double-precision, unsigned integer with a range from 0 to 2**32 on 16-bit machines, or 0 through 2**64-1 on 32-bit machines.
X	A cell (single stack item), otherwise unspecified
xt	Execution token. This is a value that identifies the execution behavior of a definition. When this value is passed to EXECUTE , the definition's execution behavior is performed.

INDEX TO FORTH WORDS

Table 24: Index to Forth words

Word	Stack	Page
,	(x-)	65
+1	(-n)	131
1	(x addr —)	69
IC	(x addr —)	69
! NOW	(ud u —)	125
! TI ME&DATE	$(u_1 u_2 u_3 u_4 u_5 u_6 -)$	125
#TI B	(— addr)	103
#USER	(-n)	101
(DATE)	$(u_1 - c$ -addr $u_2)$	126
(TIME)	(ud — c-addr u)	125
*.	(nf-n)	131
, C	(x-)	66
. '	(addr —)	40
. DATE	(u-)	126
. F	(f-)	131
. TI ME	(ud —)	125
1.	$(n_1 n_2 - f)$	131
: <name></name>	(-)	71
;	(-)	71
; CODE	(-)	71
@	(addr - x)	69
@C	(addr - x)	69

Table 24: Index to Forth words (continued)

Word	Stack	Page
@DATE	(— u)	126
@NOW	(— ud n)	125
@TI ME	(— ud)	125
@XTL-BAUD	(-n)	85
[+ASSEMBLER]	(-)	75
[+HOST]	(-)	75
[+I NTERPRETER]	(-)	75
[+TARGET]	(-)	75
[PREVI OUS]	(-)	75
\\	(-)	51
{	(-)	51
1	(-)	137
~	(-)	137
+HEADS	(-)	137
+USER	(n1 n2 - n3)	101
<. 5	(f_1-f_2)	134
>I N	(-n)	140
>NUMBER	$(ud_1 c-addr_1 u_1 - ud_2 c-addr_2 u_2)$	122
2CONSTANT <name></name>	$(x_1 x_2 -)$	67
2TWIN <name></name>	$(x_1 x_2 -)$	81
ABSOLUTE	(addr —)	82
' ACCEPT	(— addr)	103
ACOS	(f-n)	133
ACTI VATE	(addr —)	112
ALI GN	(-)	65
ALI GNED	(addr — a-addr)	65
ALLOT	(n-)	65
APPEND-CODE	(-)	82
APPEND-DATA	(-)	83
ASIN	(f-n)	133
ASSEMBLER	(-)	74
ATAN	$(n_1 n_2 - n_3)$	133
' ATXY	(— addr)	103
BACKGROUND <task-name></task-name>	(nu ns nr —)	108
BASE	(— addr)	102
BASE	(— addr)	140
BLANK	(c-addr len —)	70
BUFFER: <name></name>	(n -)	67

Table 24: Index to Forth words (continued)

Word	Stack	Page
BUI LD	(addr —)	109
CI	(b addr —)	69
C! C	(b addr —)	69
C#	(— addr)	103
C,	(b-)	65
C, C	(b-)	65
C@	(addr — b)	68
C@C	(addr — b)	69
CATCHER	(— addr)	102
CDATA	(-)	64
' CLEAN	(— addr)	103
CODE <name></name>	(-)	71
COMPI LER	(-)	74
CONNECT	(-)	85
CONSTANT <name></name>	(x —)	67
CONSTRUCT	(addr —)	116
cos	(n-f)	133
СОТ	$(n-f_1f_2)$	133
COUNTER	(— u)	128
' CR	(— addr)	102
CREATE <name></name>	(-)	67
CSC	$(n-f_1f_2)$	133
CVARI ABLE <name></name>	(-)	67
D/M/Y	$(u_1 u_2 u_3 - u_4)$	126
DASM	(addr —)	40
DATE	(-)	126
DEG	(n-f)	134
DEVI CE	(— addr)	102
DI SCONNECT	(-)	85
DOES>	(-)	71
DOWNLOAD-ALL	(-)	86
DPL	(— addr)	122
DUMP	(addr u —)	40
DUMPC	(addr u —)	40
EDIT <text></text>	(-)	38
' EMI T	(— addr)	102
END-CODE	(-)	71
EQU <name></name>	(x -)	67

Table 24: Index to Forth words (continued)

Word	Stack	Page
ERASE	(c-addr len —)	70
EXPI RED	(u — flag)	128
FILL	(c-addr len b —)	70
FIND	(c-addr — c-addr 0 xt 1 xt -1)	142
FOLLOWER	(— addr)	102
GAP	(n-)	65
GET	(addr —)	105
GRAB	(addr —)	106
н	(— addr)	140
НО	(— addr)	140
HALT	(addr —)	112
-HEADS	(-)	137
HERE	(— addr)	65
HERE	(— addr)	140
HIS	$(addr_1 n - addr_2)$	101
HOST	(-)	74
HOURS	(ud —)	125
I DATA	(-)	64
INCLUDE <filename>[<.ext>]</filename>	(-)	50
INTERPRET	(-)	141
INTERPRETER	(-)	74
' KEY	(— addr)	103
' KEY?	(— addr)	103
L	(-)	38
L#	(— addr)	103
LABEL <name></name>	(-)	71
LAST	(— addr)	140
LOCATE <name></name>	(-)	38
LOGGI NG	(— addr)	50
M/D/Y	(ud — u)	126
MOVE	$(c$ -add r_1 c -add r_2 $len -)$	70
MS	(n-)	128
NH	(— addr)	122
NOD	(-)	112
NOW	(ud —)	126
NUMBER	(c-addru-n/d)	122
NUMBER?	$(c$ -addr $u - 0 \mid n \mid 1 \mid d \mid 2)$	122
OPERATOR	(— addr)	109

Table 24: Index to Forth words (continued)

Word	Stack	Page
ORG	(addr —)	65
' PAGE	(— addr)	102
PARSE	(char — c-addr n)	141
PAUSE	(-)	96
QUERY	(-n)	141
RELEASE	(addr —)	106
RELOAD	(-)	86
RELOAD!	(-)	86
RESERVE	(n — addr)	68
RESTORE-SECTI ONS	$(n^*x n -)$	64
REV	(f-n)	134
S" <text>"</text>	(— c-addr len)	70
S0	(— addr)	102
SAVE-CODE <name. ext=""></name.>	(-)	82
SAVE-DATA <name. ext=""></name.>	(-)	82
SAVE-SECTI ONS	$(-n^*x n)$	64
SEC	$(n-f_1 f_2)$	133
SECTION <name></name>	(addr1 addr2 —)	64
SEE <name></name>	(-)	39
SET-DOWNLOAD	(-)	85
SILENT	(-)	53
SIN	(n-f)	133
SLEEP	(-x)	96
SOURCE	(— c-addr n)	141
SPAN	(— addr)	103
SSAVE	(— addr)	102
STATE	(— addr)	140
STATUS	(— addr)	102
STOP	(-)	96
SYNC-CORE	(-)	86
TAN	$(n-f_1f_2)$	133
TARGET	(-)	75
TERMINAL <task-name></task-name>	(n-)	114
THERE	(— addr)	65
TIB	(— addr)	140
TIME	(-)	125
TIMER	(u -)	128
TO <name></name>	(x-)	67

Table 24: Index to Forth words (continued)

Word	Stack	Page
ТОР	(— addr)	103
TWIN <name></name>	(x-)	81
' TYPE	(— addr)	102
UDATA	(-)	64
VALUE <name></name>	(x-)	67
VARIABLE <name></name>	(-)	67
VERBOSE	(-)	53
W!	(x addr —)	69
W! C	(x addr —)	69
W,	(x-)	65
W, C	(x-)	66
W@	(addr - x)	68
W@C	(addr - x)	69
WAIT	(-)	96
WAKE	(-x)	96
WH <name></name>	(-)	39
WHERE <name></name>	(-)	39
WORD	(char — c-addr)	141
WVARI ABLE <name></name>	(-)	67
X-CLOSE	(-)	90
X-LOG	(addr n —)	90
XTL-BAUD	(n-)	85

APPENDIX C: P&E USB MULTILINK BDM INSTALLATION

This installation procedure applies only to the P&E USB MultiLink BDM. The parallel port (LPT) connected BDM does not require any additional driver installation and is ready to use.

C.1 Driver component Installation

All necessary driver components for the P&E USB Multilink (USB-ML) BDM modules are installed by the SwiftX installer.



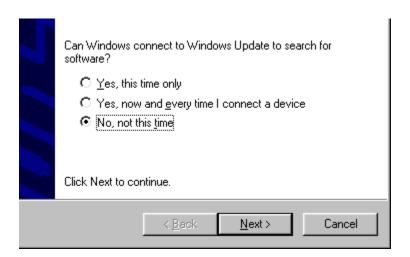
Be sure to install SwiftX before connecting a USB-ML BDM module. Any P&E branded driver CD-ROM that came with the BDM module is not needed.

C.2 HARDWARE INSTALLATION

After SwiftX has been installed, connect the USB-ML to a USB port on your computer. This should launch the Found New Hardware Wizard.

The steps in the Wizard sequence are as follows:

1. Do not connect to Windows Update to search for software.



2. Install the software automatically (not from a specific location).



3. Finish.

Each new USB-ML that you connect to the system (uniquely identified to the system by its serial number) will follow this same procedure.

INDEX

Also see Forth Words Index starting on page 127.

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