

PathAutomaton

```
{outActive1= 0;outActive2= 0;
forw_timer_cur = forw_timer_s;
bck_timer_cur = bck_timer_s;}
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Idle
en: idle_st = 1;

AntegradeConduction
on clk : forw_timer_cur = forw_timer_cur-
on clk : outActive1= 0;
on clk : idle_st = 0;

DoubleSt
on clk : forw_timer_cur = forw_timer_cur- 1;
on clk : bck_timer_cur = bck_timer_cur- 1;

Retro
on clk : bck_timer_cur = bck_timer_cur- 1;
on clk : outActive2= 0;

Conflict
ex: outActive2= 0;
ex: outActive1= 0;

[bck_timer_cur== 0]{bck_timer_cur=bck_timer_def;outActive1= 1;}

[inActive1]

[forw_timer_cur== 0]{forw_timer_cur=forw_timer_def;outActive2= 1;}

UpdateTable

[(NdStEx== 2)&(idle_st)]
{bck_timer_def = 3*bac_param; bck_timer_cur = bck_timer_def;}

[(NdStEx== 3)&(idle_st)]
{bck_timer_def = (bac_param*(1+2*ratioEx*ratioEx*ratioEx*ratioEx));
bck_timer_cur = bck_timer_def;}

[(NdStEn== 1)&(idle_st)]{forw_timer_def = forw_param;forw_timer_cur = forw_timer_def;}

[(NdStEn== 3)&(idle_st)]
{forw_timer_def = (forw_param*(1+2*ratioEn*ratioEn*ratioEn*ratioEn));
forw_timer_cur = forw_timer_def;}

[(NdStEx== 1)&(idle_st)]{bck_timer_def = bac_param; bck_timer_cur = bck_timer_def;}

[(NdStEx== 2)&(idle_st)]{bck_timer_def = 3*bac_param;}

