PR2_sheet1

May 6, 2021

1 Exercise 1 - Eigenvalues, Eigenvectors, and Prototypes

```
In [1]: import numpy as np
    import numpy.linalg as la
    import matplotlib.pyplot as plt

from sklearn.preprocessing import normalize

import timeit
    import functools

from scipy.spatial.distance import cdist
    import numpy.random as rnd
    import imageio as imageio
```

1.1 Task 1.1

```
In [3]: ### load the data as a float-vector
    matX = np.load('faceMatrix.npy').astype('float')
    ### interpret the float-vector as a mxn matrix and print these dimensions
    m, n = matX.shape
    print(m,n)

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In [4]: ### re-interpret column 15 of this huge matrix 'matX' (lenght 361=19x19),
    ### as a 19x19 matrix
    vecX = matX[:,14].reshape(19,19)
    def plot_matrix(M):
        plt.imshow(vecX, cmap='gray')
        plt.xticks([]) ### dont plot the x/y coordinates 1..18 (instead use [])
        plt.yticks([])
        plt.show

    plot_matrix(vecX)
```



1. Normalize the matrix



```
In [7]: ### Normalize data to zero mean
    method2_normX = matX - np.mean(matX, axis=1).reshape(m,1)
```

show_mat_blue(method2_normX)
matX = method2_normX



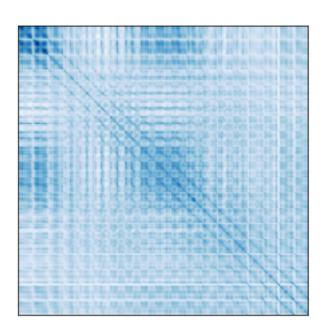
In [8]: np.array_equal(method1_normX, method2_normX)

Out[8]: False

2. Compute XX^T

There are different methods for matrix multiplication. For example: - matC_1 = np.matmul(matX, matX.transpose()) - matC_2 = np.dot(matX, matX.T) - matC_3 = matX.dot(matX.T)

But as suggested in the lecture, use the @ operator:



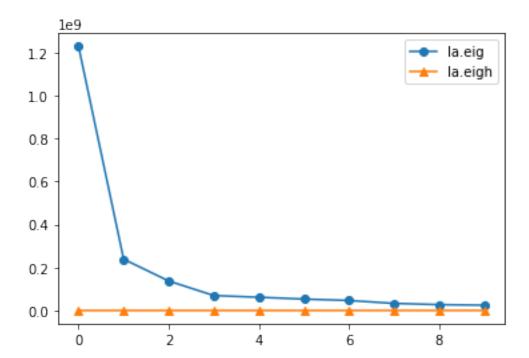
3. Compute $C = U\Lambda U^T$ - la.eig

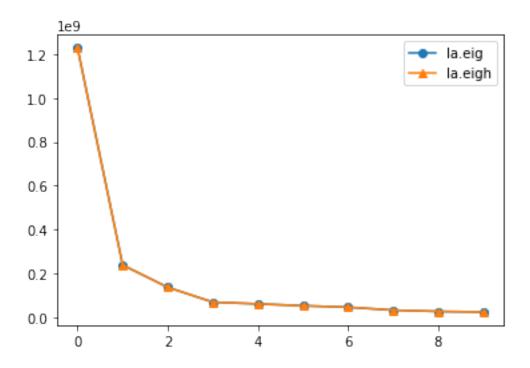
In [10]: eigenval_eig, eigenvec_eig = la.eig(matC)

4. Compute $C = U\Lambda U^T$ - la.eigh

In [11]: eigenval_eigh, eigenvec_eigh = la.eigh(matC)

5. Compare la.eig and la.eigh



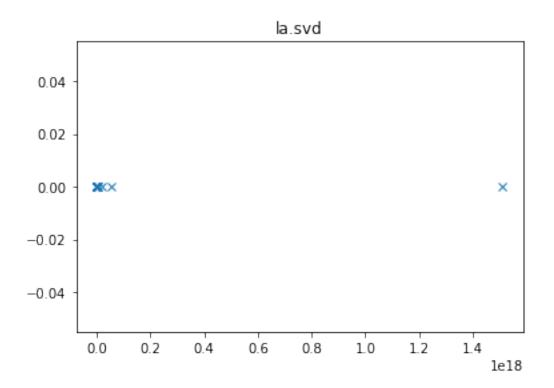


- la.eig does not give any guarantees on the order of the eigenvalues it returns
 - From documentation: "Compute the eigenvalues and right eigenvectors of a square array."
- la.eigh
 - From documentation: "Return the eigenvalues and eigenvectors of *a complex Hermitian* (conjugate symmetric) or a real symmetric matrix"
 - returns eigenvalues in ascending order
- both methods return normalized eigenvectors

6. Compute $X = U\Sigma V^T$ - la.svd

7. Square Eigenvalues

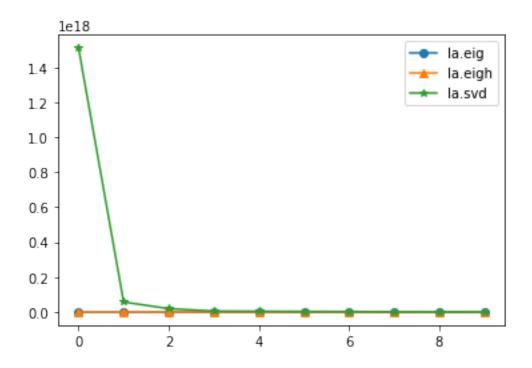
```
In [15]: fig, ax = plt.subplots()
    # ax.matshow(eigenval_svd.reshape(19,19), cmap=plt.cm.Blues)
    # plt.xticks([]), plt.yticks([])
    plt.title('la.svd')
    plt.plot(eigenval_svd, np.zeros_like(eigenval_svd), 'x')
    plt.show()
```



8. Plot spectra

```
In [16]: ### plot the eigenvalues
    plt.plot(eigenval_eig[:10], marker='o', label='la.eig')
    plt.plot(eigenval_eigh[:10], marker='^', label='la.eigh')
    plt.plot(eigenval_svd[:10], marker='*', label='la.svd')
    plt.legend()
    plt.show()

### Note the scale of the y-axis: 1e18 = 10**18
    ### Above it was: 1e9 = 10**9
```



1.2 Task 1.2

```
In [17]: ### Define functions for time measurements
    ### For fairness: include the necessary computation of C

def PCA_eig(X):
        C = X @ X.T
        1, U = la.eig(C)

def PCA_eigh(X):
        C = X @ X.T
        1, U = la.eigh(C)

def SVD(X):
        U, s, Vt = la.svd(X)

In [18]: matX = np.load('Exercise1/Data/faceMatrix.npy').astype('float')
        m, n = matX.shape
        matX = matX - np.mean(matX, axis=1).reshape(m,1)
```

FileNotFoundError

Traceback (most recent call last)

```
<ipython-input-18-32451c31b09d> in <module>
    ----> 1 matX = np.load('Exercise1/Data/faceMatrix.npy').astype('float')
          2 m, n = matX.shape
          3 matX = matX - np.mean(matX, axis=1).reshape(m,1)
        ~/anaconda3/lib/python3.7/site-packages/numpy/lib/npyio.py in load(file, mmap_mode, al
                        own_fid = False
        414
        415
                    else:
    --> 416
                        fid = stack.enter_context(open(os_fspath(file), "rb"))
                        own_fid = True
        417
        418
       FileNotFoundError: [Errno 2] No such file or directory: 'Exercise1/Data/faceMatrix.npy
In [19]: # according to: https://www.researchgate.net/publication/329449786_NumPy_SciPy_Recipe
         ts = timeit.Timer(functools.partial(PCA_eig, matX)).repeat(3, 100)
         print (min(ts) / 100)
         ts = timeit.Timer(functools.partial(PCA_eigh, matX)).repeat(3, 100)
         print (min(ts) / 100)
         ts = timeit.Timer(functools.partial(SVD, matX)).repeat(3, 100)
         print (min(ts) / 100)
0.07110150369000622
0.015912863520206884
```

The timeit-number (here '100') is the number of executions of the main statement. = Return time it takes to execute the fct 100 times [sec, float] The repeat-number (here '3') is the number of timeit-executions. From python.org (https://docs.python.org/3/library/timeit.html): Do not calculate mean and std.dev. Use the lowest value = lower bound for how fast your machine can run the given code snippet Higher values are typically not caused by variability in Python's speed, but by other processes interfering with your timing accuracy.

Here are runtimes (in seconds) measured on an Intel i5 (2.9 GHz) (outside a notebook)

la.eig: 0.03231685656995978
la.eigh: 0.00624352695012930
la.svd: 0.14175234847993123

0.9599347343301633

Conclusion: la.eigh is by far the fastest!

1.3 Task 1.3

Run the QR algorithm and print diagonal of resulting matrix C

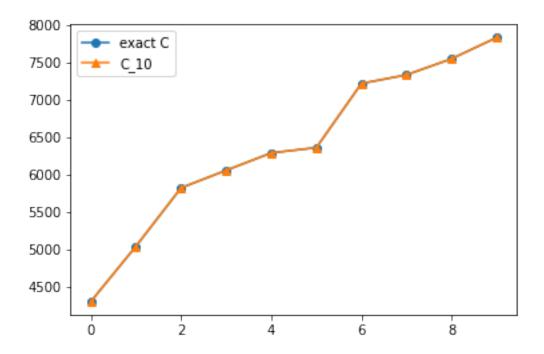
```
In [23]: matX = np.load('faceMatrix.npy').astype('float')
    m, n = matX.shape
    matX = matX - np.mean(matX, axis=1).reshape(m,1)

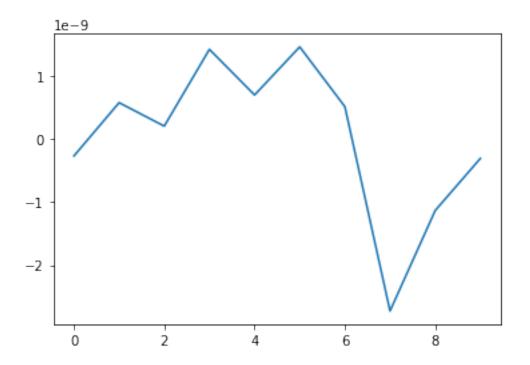
In [24]: matC = qrAlgorithm(matX)
    # print (np.diag(matC))

In [25]: C = matX @ matX.T
    eigenvals, U = la.eigh(C)
    eigenvals_10, U_10 = la.eigh(matC)

    difference = eigenvals - eigenvals_10

    plt.plot(eigenvals[:10], marker='o', label='exact C')
    plt.plot(eigenvals_10[:10], marker='o', label='C_10')
    plt.legend()
    plt.show()
    plt.plot(difference[:10])
    plt.show()
```





```
In [26]: ### Compating the diagonal entries
    plt.plot(np.diag(C)[:100], marker='o', label='exact C')
    plt.plot(np.diag(matC)[:100], marker='^', label='C_10')
```