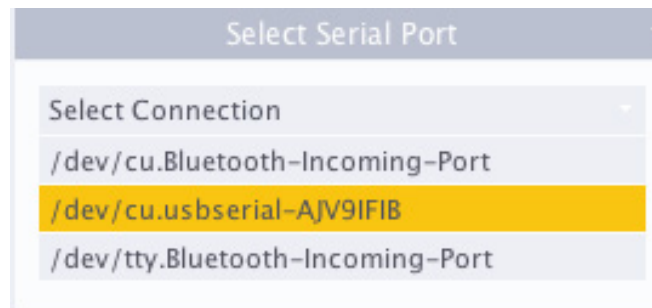


## Quick Start Guide

- 1 Plug the motor box into a power source, and connect the Arduino to your computer via USB.
- 2 Connect your computer to the PS3 controller via bluetooth
- 3 Launch the program
- 4 Select the serial port that's connected to the Arduino. There will be a 5 second delay between when the port is selected, and when it's connected.

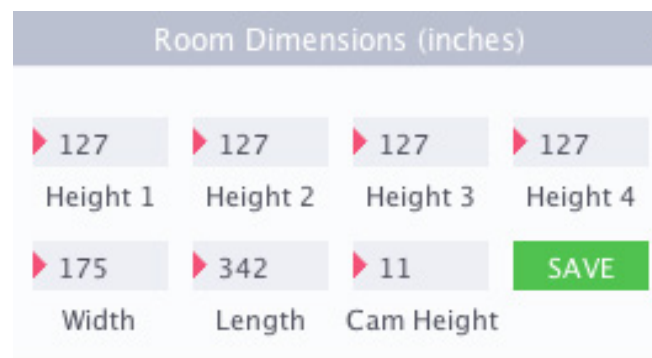


Select Serial Port

Select Connection

- /dev/cu.Bluetooth-Incoming-Port
- /dev/cu.usbserial-AJV9IFIB
- /dev/tty.Bluetooth-Incoming-Port

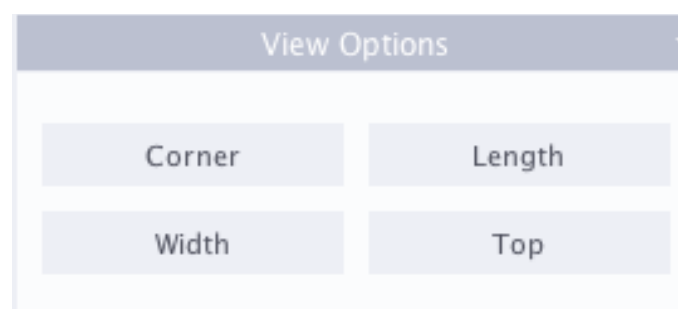
- 5 Set the room dimensions and camera height in inches, then hit 'save' so these values will load the next time the program is launched.



Room Dimensions (inches)

▶ 127	▶ 127	▶ 127	▶ 127
Height 1	Height 2	Height 3	Height 4
▶ 175	▶ 342	▶ 11	SAVE
Width	Length	Cam Height	

- 6 Select width / length / top view and drag the flag point in the visualization to where it is positioned within space.



View Options

Corner	Length
Width	Top