

# AMAT 584 Lecture 26 4/1/2020

## Today: Quotient Spaces and Homology

Quotient Spaces are the last main linear algebra ingredient we need to define homology.

Given a vector space  $V$  over a field  $F$  and a subspace  $W \subset V$ , we define the quotient space  $V/W$  to be a vector space over  $F$ .

Very roughly speaking  $V/W$  is obtained from  $V$  by setting elements of  $W$  to 0.

If  $V$  is finite dimensional, then

$$\dim(V/W) = \dim(V) - \dim(W).$$

Before defining quotient spaces, we describe the application to homology.

Recall: For a finite simplicial complex  $X$ , the chain complex of  $X$  is:

$$\dots \xrightarrow{\delta_3} C_2(X) \xrightarrow{\delta_2} C_1(X) \xrightarrow{\delta_1} C_0(X) \xrightarrow{\delta_0} 0$$

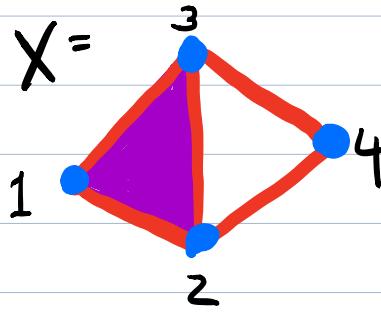
For  $j \geq 0$ ,  $Z_j(X) = \ker(\delta_j)$ ,  $B_j(X) = \text{im}(\delta_{j+1})$ . Prop:  $B_j(X) \subset Z_j(X)$ .

Definition: For  $j \geq 0$ , the  $j^{\text{th}}$  homology vector space of  $X$  denoted  $H_j(X)$ , is the quotient space  $Z_j(X)/B_j(X)$ .

Intuitively,  $\dim_{\mathbb{Z}}(H_j(X)) = \# j\text{-dimensional holes of } X$ .

$$\dim(Z_j(X)) - \dim(B_j(X)).$$

Example:



We saw earlier that  $\{[1,2] + [2,3] + [1,3], [2,3] + [3,4] + [3,4]\}$  is a basis for  $Z_1(X)$ , so  $\dim(Z_1(X)) = 2$ .

We also saw that  $\{b_1\}$  is a basis for  $B_1(X)$ , so  $\dim(B_1(X)) = 1$ .

Hence,  $\dim(H_1(X)) = 2 - 1 = 1$ , reflecting that  $X$  has a single 1-D hole.

Let us write  $Z_1(X)$  as  $Z$  and  $B_1(X)$  as  $B$ .

## Definition of Quotient Spaces

As above, let  $V$  be any vector space and  $W \subset V$  be a subspace.

We will illustrate the definitions with the example  
 $V = \mathbb{Z}$ ,  $W = B$ .

First, we define  $V/W$  as a set:

Recall that for  $V$  an abstract vector space and  $v, v' \in V$ ,  $v - v'$  is shorthand for  $v + (-v')$ .

Note: When  $F = F_2$ ,  $w + w = \vec{0}$ , so  $-w = w$ , and  $v - w = v + w$ !  
Define an equivalence relation  $\sim$  on  $V$  by  
 $v \sim v'$  if and only if  $v - v' \in W$ .

Let's check that this is really an equivalence relation:

Reflexivity:  $\forall v \in V, v - v = \vec{0} \in W \checkmark$

Symmetry:  
 $v \sim w \Rightarrow v - w \in W \Rightarrow -(v - w) \in W$   
 $\Rightarrow w - v \in W$ .

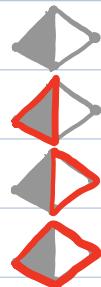
Transitivity:  $v \sim w$  and  $w \sim x \Rightarrow v - w \in W$  and  $w - x \in W$ .  
Therefore  $(v - w) + (w - x) = v - x \in W$ , so  $v \sim x$ .

As a set, we define  $V/W$  to be  $V/\sim$ , the set of equivalence classes of  $\sim$ .

In the case where  $V = Z_j(X)$ ,  $W = B_j(X)$  for some  $X$  and  $j \geq 0$ , two cycles are equivalent if their difference is a boundary.

Example Let's determine  $Z/B$  as a set.

$$Z = \left\{ \begin{array}{l} \vec{0}, \\ b_1 = [1, 2] + [1, 3] + [2, 3], \\ b_2 = [2, 3] + [3, 4] + [2, 4], \\ b_3 = [1, 2] + [2, 4] + [3, 4] + [1, 3]. \end{array} \right\}$$



$$B = \{\vec{0}, b_1\}.$$

$$b_1 - \vec{0} = b_1 \in B, \text{ so } b_1 \sim \vec{0}.$$

Interpretation: The cycle  $b_1$  doesn't count as a hole, because it's a boundary.

$$\begin{aligned} b_2 - b_3 &= b_2 + b_3 = [2, 3] + [3, 4] + [2, 4] + \\ &\quad [1, 2] + [2, 4] + [3, 4] + [1, 3] \\ &= [1, 2] + [2, 3] + [1, 3] = b_1 \in W, \end{aligned}$$

So  $b_2 \sim b_3$ .

Interpretation:  $b_2$  and  $b_3$  represent the same hole, because geometrically,  $[2, 3]$  can be continuously deformed in  $X$  to  $[1, 2] \cup [1, 3]$ .

$b_1 \neq b_2$  because  $b_1 - b_2 = b_1 + b_2 = b_3 \notin B$ .

Thus as a set  $Z/B = Z/\sim = \{\{\vec{0}, b_1\}, \{b_2, b_3\}\}$ .

Recall: For any set  $S$ ,  $\sim$  an equivalence relation on  $S$ , and  $x \in S$ ,  $[x]$  denotes the equivalence class containing  $x$ .

Example:  $[b_2] = [b_3] = \{b_2, b_3\}$

$[\vec{0}] = [b_1] = \{\vec{0}, b_1\} = B$ .

Equivalence classes are disjoint, so if  $x, y \in S$ , either  $[x] = [y]$  or  $[x] \cap [y] = \emptyset$ .

Now, we define the vector space structure on  $V/W$ .  
We need to define addition and scalar multiplication.

We define  $[v] + [w] = [v+w]$   $\forall v, w \in V$   
 $c[v] = [cv]$   $\forall v \in V, c \in F$ .

Then  $\vec{0} \in V/W$  is  $[\vec{0}] = W$ .

We need to check that  $+$  and  $\cdot$  do not depend  
on the choice of representative for the equivalence  
classes; otherwise, they are not well defined.

check that + is well defined:

Suppose  $\begin{bmatrix} v \\ w \end{bmatrix} = \begin{bmatrix} v' \\ w' \end{bmatrix}$ . Then

Then  $\begin{bmatrix} v \\ w \end{bmatrix} + \begin{bmatrix} v \\ w \end{bmatrix} = \begin{bmatrix} v+w \\ v+w \end{bmatrix}$  and  $\begin{bmatrix} v' \\ w' \end{bmatrix} + \begin{bmatrix} v' \\ w' \end{bmatrix} = \begin{bmatrix} v'+w' \\ v'+w' \end{bmatrix}$ .

$$(v+w) - (v'+w') = \underbrace{v-v'}_{\text{in } W} + \underbrace{w-w'}_{\text{in } W} \in W$$

$$\text{so } v+w \sim v'+w' \Rightarrow \begin{bmatrix} v+w \\ v+w \end{bmatrix} = \begin{bmatrix} v'+w' \\ v'+w' \end{bmatrix}.$$

This shows that addition is well defined in  $V/W$ .  
The check that scalar multiplication is well defined is similar.

One can check that with these definitions  $V/W$  is indeed an abstract vector space over  $F$ .