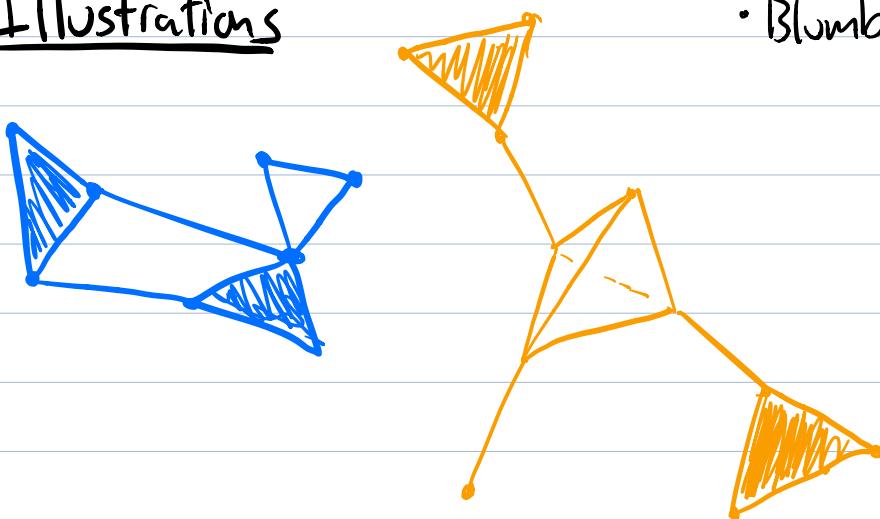


AMAT 584 Lecture 2, 1/24/20

Simplicial Complexes
-Generalizations of graphs

references:
• Edelsbrunner/Harer,
• Munkres, Elements of
• Algebraic Topology
• Blumberg/Rabadian

Illustrations



Simplices are certain simple subsets of \mathbb{R}^n .

A 0-simplex is a point •

A 1-simplex is a line segment ↗

A 2-simplex is a triangle △

A 3-simplex is a solid tetrahedron



To give the precise definition of a simplex, we will need a few preliminary notions.

First, to motivate what follows, let's consider the following simple question:

Question: Given $\vec{x} \neq \vec{y} \in \mathbb{R}^n$, how do we describe the line segment L connecting \vec{x} and \vec{y} as a set?

Answer:

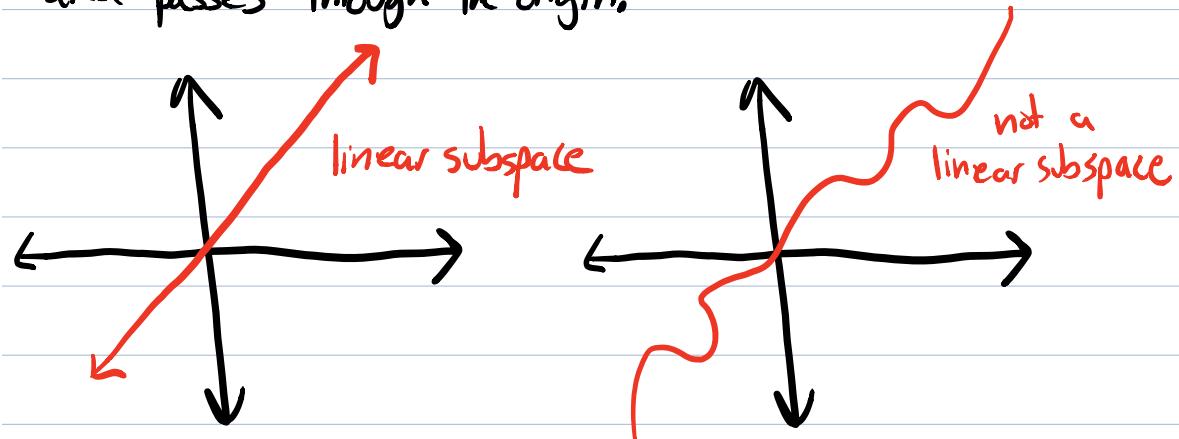
$$L = \left\{ \vec{x} + c(\vec{y} - \vec{x}) \mid c \in [0, 1] \right\}$$

$$= \left\{ c\vec{y} + (1-c)\vec{x} \mid c \in [0, 1] \right\}.$$

$$\vec{x} + \frac{1}{2}(\vec{y} - \vec{x}) = \left\{ c_1 \vec{y} + c_2 \vec{x} \mid c_1 \geq 0, c_1 + c_2 = 1 \right\}$$

A subset $S \subset \mathbb{R}^n$ is called a linear subspace if it is the solution set to a linear equation $A\vec{x} = 0$ (A is a matrix.)

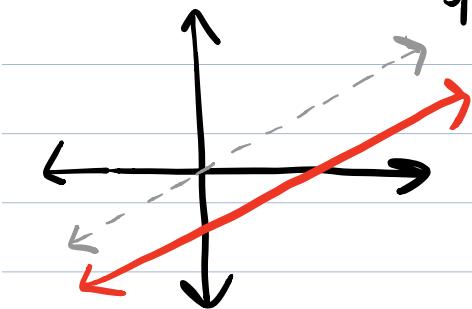
Geometrically, a linear subspace is flat (doesn't curve), and passes through the origin.



An affine subspace of \mathbb{R}^n is the solution set to an equation $A\vec{x} = b$ (A is a matrix, b is a vector).

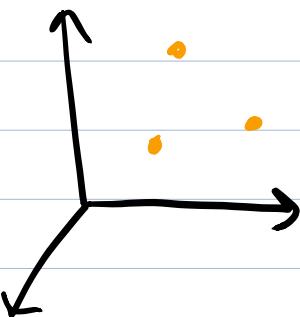
Geometrically, has the same shape as a linear subspace, but needn't pass through the origin.

That is, an affine subspace is a translation of a linear subspace.

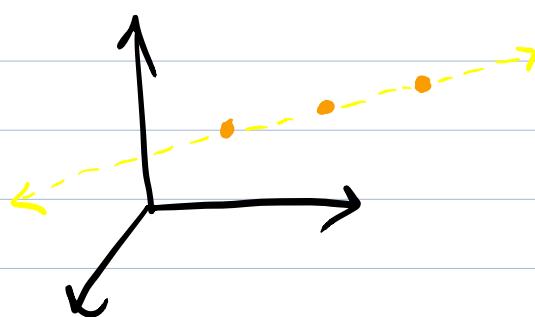


Def: A set X of k points in \mathbb{R}^n is said to be in general position if X does not lie on any $(k-2)$ -dimensional affine subspace.

For example, 3 points in \mathbb{R}^3 are in general position if they don't all lie on a single line

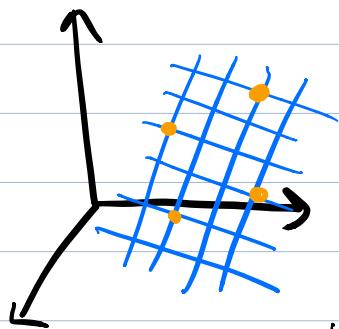


General Position



Not in general position

Four points in \mathbb{R}^3 are in general position if they don't lie on a plane.



Not in general position

Note: If k points in \mathbb{R}^n are in general position, then $n > k-2$.

For $X = \{\vec{x}_1, \dots, \vec{x}_n\} \subset \mathbb{R}^n$, the convex hull of X , is the set

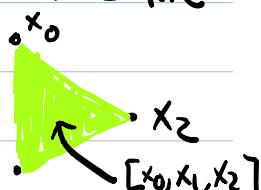
$$\text{Conv}(X) = \left\{ c_1\vec{x}_1 + c_2\vec{x}_2 + c_3\vec{x}_3 + \dots + c_n\vec{x}_n \mid \text{each } c_i \geq 0 \text{ and } \sum_{i=1}^n c_i = 1 \right\}.$$

- The convex hull of a single point is the singleton set containing only that point.
- The convex hull of two points is the line segment connecting them.
- The convex hull of three points in general position is the triangle with these points as vertices.
- The convex hull of four points in general position is a solid tetrahedron with these points as vertices.

Definition: A (k) -simplex is the convex hull of a set of $k+1$ points in general position.

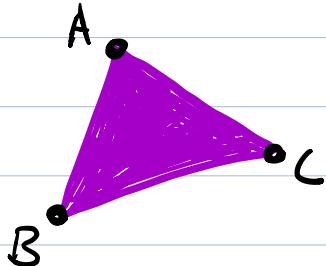
If x_0, \dots, x_k are in general position, we write the associated simplex as $[x_0, \dots, x_k]$.

I'll sometimes call this the simplex spanned by $\{x_0, \dots, x_k\}$



Definition: A face of a simplex $[x_0, \dots, x_k]$ is the simplex spanned by a non-empty subset of $\{x_1, \dots, x_k\}$.

Ex:

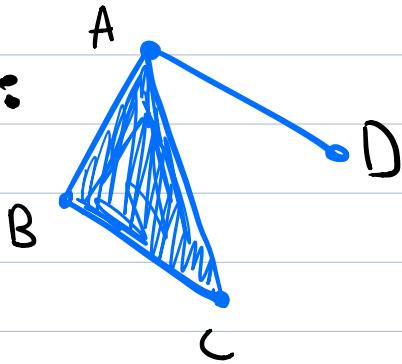


The faces of $[A, B, C]$ are:
 $[A], [B], [C],$
 $[A, B], [B, C], [A, C],$
 $[A, B, C]$.

Definition: A (geometric) simplical complex is a set S of simplices in \mathbb{R}^n (for some fixed n) such that

1. each face of a simplex in S is contained in S
2. the intersection of two simplices in S is a face of each of them (if non empty).

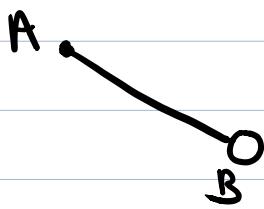
Example:



Let $A, B, C, D \in \mathbb{R}^2$
be as shown

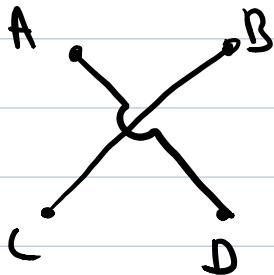
This illustrates the simplicial complex
 $\{[A], [B], [C], [D], [A, B], [A, C], [B, C], [A, D], [A, B, C]\}$.

Example: For $A, B \in \mathbb{R}^2$ as shown,



$\{[A], [AB]\}$ is not a simplicial complex: property 1 is violated.

Example: For $A, B, C, D \in \mathbb{R}^2$ as shown,



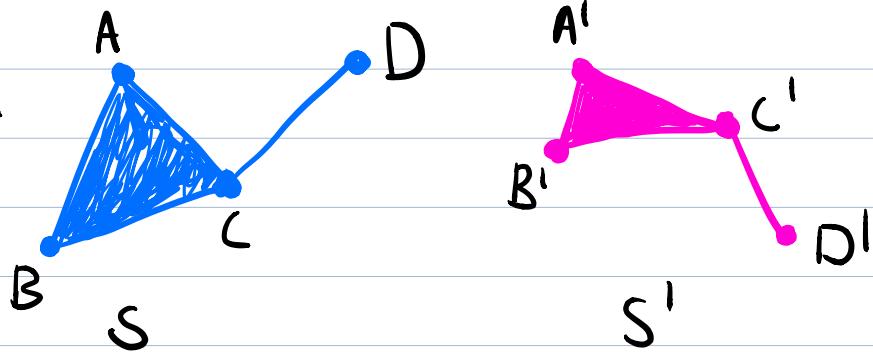
$\{[A], [B], [C], [D], [AD], [BC]\}$ is not a simplicial complex: Property 2. is violated.

Definition: For S a simplicial complex, we call the union of the simplices in S the geometric realization of S , and denote this $|S|$.

Abstract Simplicial Complexes

Motivation: It turns out that up to homeomorphism, $|S|$ doesn't depend on the position of the 0-simplices of S .

Example:



$|S| \cong |S'|$. (Recall that \cong means "is homeomorphic to").

Let's make this precise:

Proposition: Let S and S' be simplicial complexes, and suppose there is a bijection f from the 0-simplices of S to the 0-simplices of S' such that

$$[x_0, \dots, x_k] \in S \text{ iff } [f(x_0), \dots, f(x_k)] \in S'.$$

Then $|S| \cong |S'|$.

Def: an abstract simplicial complex on a set S is a collection X of non-empty finite subsets such that if $\sigma \in X$ and $\emptyset \neq \tau \subset \sigma$, then $\tau \in S$.

The subsets of size $(k+1)$ are called k -simplices of X .

The simplex $\{a_0, \dots, a_k\}$ is written $[a_0, \dots, a_k]$.