

AMAT 584 Lecture 24, 3/27/20

Today: Chain Complexes, continued  
Quotient Vector Spaces

To start, let's review the definition of a chain complex:

For  $X$  a finite simplicial complex, the chain complex of  $X$  is the sequence of vector spaces and linear maps

$$\dots \xrightarrow{\delta_4} C_3(X) \xrightarrow{\delta_3} C_2(X) \xrightarrow{\delta_2} C_1(X) \xrightarrow{\delta_1} C_0(X) \xrightarrow{\delta_0} 0$$

Where  $C_j(X) = P(X^j)$ , for  $X^j$  the set of  $j$ -simplices of  $X$ ,  
power set, regarded as vector space over  $F_2$ .

$$\delta: X^j \rightarrow C_{j-1}(X), \quad \delta([x_0, \dots, x_j]) = \sum_{k=0}^j [x_0, \dots, \cancel{x_k}, \dots, x_j]$$

$$\delta_j(\sigma_1 + \dots + \sigma_k) = \delta(\sigma_1) + \delta(\sigma_2) + \dots + \delta(\sigma_n).$$

Recall:  $X^j$  is (identified with) a basis for  $C_j(X)$ , called the standard basis.

$$\Rightarrow \dim(C_j(X)) = |X^j|.$$

Since each  $C_j(X)$  is finite dimensional, if we order  $C_j(X)$  and  $C_{j+1}(X)$ , then we can represent  $\delta_j$  via a matrix with coefficients in  $F_2$ .

Example: Consider

$$X = \begin{array}{c} 3 \\ \diagdown \quad \diagup \\ 1 \quad 2 \end{array}$$

Consider the following orderings of  $X^0$  and  $X^1$

$$X^0: [1], [2], [3]$$

$$X^1: [2, 3], [1, 3], [1, 2]$$

$\delta_2$  is represented by the  $3 \times 1$  matrix:

$$\begin{matrix} [1, 2, 3] \\ [2, 3] \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ [1, 3] \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \\ [1, 2] \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \end{matrix}$$

I've labeled the rows and columns of the matrices by the corresponding basis elements

$\delta_1$  is represented by the  $3 \times 3$  matrix:

$$\begin{matrix} [2, 3] \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \\ [1] \\ [2] \\ [3] \end{matrix}$$

$$\text{Note that } \delta_1 \circ \delta_2 = \begin{pmatrix} 0+1+1 \\ 1+0+1 \\ 1+1+0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

More generally, we have the following

Proposition:  $\forall j \geq 0$ ,

$$\delta_j \circ \delta_{j+1} : C_{j+1}(X) \rightarrow C_j(X) = 0,$$

i.e., is the constant map to  $\vec{0}$ .

Example: For  $X$  as above,

$$\delta_1 \circ \delta_2 ([1, 2, 3]) = \delta_1 (\delta([1, 2, 3]))$$

$$= \delta_1 ([2, 3] + [1, 3] + [1, 2])$$

$$= \delta([2, 3]) + \delta([1, 3]) + \delta([1, 2])$$

$$= [2] + [3] + [1] + [3] + [1] + [2] *$$

$$- ([1] + [1]) + ([2] + [2]) + ([3] + [3])$$

$$= \vec{0} + \vec{0} + \vec{0} = \vec{0}.$$

Note that  $\delta_1 \circ \delta_2 ([1, 2, 3])$  is  $\vec{0}$  because the  $\vec{0}$  simplices in the sum \* cancel in pairs.

The proof of the proposition amounts to the observation that this phenomena generalizes to any simplex in any simplicial complex.

## Cycles and Boundaries

For  $j \geq 0$ ,

$\ker(\delta_j) \subset C_j(X)$  is called the cycle subspace, and is denoted  $Z_j(X)$ . Elements of  $Z_j(X)$  are called  $j$ -cycles.

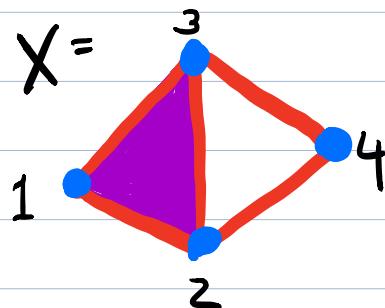
$\text{im}(\delta_{j+1}) \subset C_j(X)$  is called the image subspace, and is denoted  $B_j(X)$ . Elements of  $B_j(X)$  are called  $j$ -boundaries.

Proposition:  $B_j(X) \subset Z_j(X)$ .

Proof: If  $z \in B_j(X) = \text{im}(\delta_{j+1})$  then  $z = \delta_{j+1}(y)$  for some  $y \in C_{j+1}(X)$ . Then  $\delta_j(z) = \delta_j(\delta_{j+1}(y)) = \bar{0}$ , so  $z \in \ker(\delta_j) = Z_j(X)$ . □

As the names "cycles" and "boundaries" suggest, these objects have a nice geometric interpretation:

Example: Let  $X =$



$Z_0(X) = C_0(X)$ , since  $\delta_0 = 0$ .

It can be checked that

$$Z_1(X) = \{\vec{0}, [1, 2] + [1, 3] + [2, 3], [2, 3] + [3, 4] + [2, 4], [1, 2] + [2, 4] + [3, 4] + [1, 3]\}$$

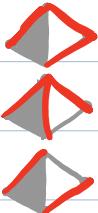


For example,

$$\begin{aligned} \delta_1([1, 2] + [2, 4] + [3, 4] + [1, 3]) &= \\ &[1] + [2] + [2] + [4] + [3] + [4] + [1] + [3] \\ &= ([1] + [1]) + ([2] + [2]) + ([3] + [3]) + ([4] + [4]) \\ &= \vec{0}. \end{aligned}$$

Examples of 1-chains which are not 1-cycles include:

$$\begin{aligned} [1, 3] + [3, 4] + [2, 4] \\ [1, 3] + [3, 4] + [2, 3] \\ [1, 3] + [2, 4] \end{aligned}$$



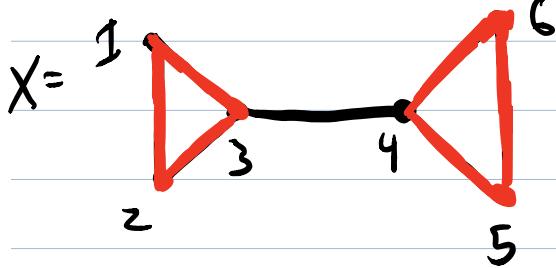
It is easy to see that  $B_1(X) = \{\vec{0}, [1, 2] + [1, 3] + [2, 3]\}$ .

Indeed,  $C_2(X) = \{\vec{0}, [1, 2, 3]\}$ .

$$\delta_2(\vec{0}) = \vec{0} \text{ and } \delta_2([1, 2, 3]) = \underbrace{[1, 2] + [1, 3] + [2, 3]}.$$

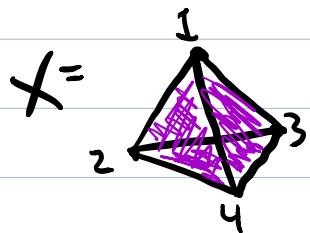
For  $j \geq 2$ ,  $Z_j(X) = B_j(X) = \{\vec{0}\}$ . boundary of a triangle!

Example: Cycles needn't form a connected subgraph:



$$[1,2] + [2,3] + [1,3] + [4,5] + [5,6] + [4,6] \in B_1(X).$$

Example: Consider the 3-simplex



$$[1,2,3] + [2,3,4] + [1,2,4] + [1,3,4] \in Z_2(X)$$

Sum of all the 2-simplices,  
i.e. hollow tetrahedron.