

Today: Linear maps

Definition: Let V, W be vector spaces over a field k . $f: V \rightarrow W$ is said to be linear if:

$$f(\vec{v} + \vec{w}) = f(\vec{v}) + f(\vec{w}) \quad \forall \vec{v}, \vec{w} \in V$$

$$f(c\vec{v}) = cf(\vec{v}) \quad \forall \vec{v} \in V, c \in F.$$

We call such f a linear map or linear transformation.

Example: any $m \times n$ matrix A with coefficients in a field F defines a linear map $T^A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ given by

$$T^A(\vec{x}) = A\vec{x}.$$

matrix-vector multiplication

For instance, if

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix},$$

then $T^A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is given by

$$T^A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 + 2x_2 + 3x_3 \\ 4x_1 + 5x_2 + 6x_3 \\ 7x_1 + 8x_2 + 9x_3 \end{pmatrix}$$

The linearity of T^A follows from basic properties of matrix-vector multiplication.

Subspaces associated to a linear map $f: V \rightarrow W$:

$$\text{im}(f) = \{\vec{w} \in W \mid \vec{w} = f(\vec{v}) \text{ for some } \vec{v} \in V\}.$$

$$\ker(f) = \{\vec{v} \in V \mid f(\vec{v}) = 0\}.$$

called the kernel of f .

Proof that $\text{im}(f)$ is a subspace:

- If $\vec{w}, \vec{w}' \in \text{im}(f)$, then $\vec{w} = f(\vec{v})$ and $\vec{w}' = f(\vec{v}')$ for some $\vec{v}, \vec{v}' \in V$. By linearity $f(\vec{v} + \vec{v}') = f(\vec{v}) + f(\vec{v}') = \vec{w} + \vec{w}'$, so $\vec{w} + \vec{w}' \in \text{im}(f)$.
- If $c \in K$, then $f(c\vec{v}) = c f(\vec{v}) = c\vec{w}$, so $c\vec{w} \in \text{im}(f)$. ■

The proof that $\ker(f)$ is a subspace is quite similar. I leave it as an exercise.

Definitions For $f: V \rightarrow W$ a linear map:

1. We call $\dim(\text{im } f)$ the rank of f .
2. We call $\dim(\ker f)$ the nullity of f .

Rank-Nullity Theorem: For $f: V \rightarrow W$ a linear map between finite-dimensional vector spaces,

$$\dim(V) = \text{rank}(f) + \text{nullity}(f).$$

How does one compute $\text{rank}(f)$ or $\text{nullity}(f)$ in practice?
 We will address this below.

Representing Linear Maps with Matrices

Recall from last lecture: For V a finite dimensional vector space over F with basis $B = \{b_1, \dots, b_m\}$ and $\vec{v} \in V$, we can write

$$\vec{v} = c_1 b_1 + \dots + c_m b_m \text{ for unique } c_1, \dots, c_m \in F.$$

We call this the representation of \vec{v} in the basis B .

$$\text{We let } [\vec{v}]_B = \begin{pmatrix} c_1 \\ \vdots \\ c_m \end{pmatrix} \in F^m$$

Let $f: V \rightarrow W$ be a linear map of finite dimensional vector spaces.

Given bases $B = \{b_1, \dots, b_n\}$ and $B' = \{b'_1, \dots, b'_m\}$

for V and W respectively, we can represent f via the

$m \times n$ matrix
 #rows #columns

$$[f]_{B';B} = ([f(b_1)]_{B'}, [f(b_2)]_{B'}, \dots, [f(b_n)]_{B'})$$

↑ ↑ ↑
 1st column 2nd column nth column

In words, the j^{th} column of $[f]_{B', B}$ is the representation of $f(b_j)$ in the basis B' .

The idea behind this is that by linearity, to know the value of f on an arbitrary $\vec{v} \in V$, it's enough to know the value of $f(b)$ for each $b \in B$.

Indeed, if $\vec{v} = c_1 b_1 + \dots + c_n b_n$, then by linearity $f(\vec{v}) = f(c_1 b_1 + \dots + c_n b_n) = c_1 f(b_1) + \dots + c_n f(b_n)$.

Fact: If S is the set of columns of $[f]_{B', B}$, then

$$\text{Rank}(f) = \dim(\text{Span}(S)).$$

This can be computed by putting $[f]_{B', B}$ into row echelon form using Gaussian Elimination: The number of pivot rows in the reduced matrix is the rank of f .

Example: Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be given by

$$f\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ x-y \end{pmatrix}, \text{ ie } f = T^A, \text{ where } A = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}.$$

$$\text{Let } B = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}, \quad B' = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$$

$$\begin{array}{cc} \parallel & \parallel \\ b_1 & b_2 \end{array} \qquad \qquad \begin{array}{cc} \parallel & \parallel \\ b'_1 & b'_2 \end{array}$$

$$f\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 1\begin{pmatrix} 1 \\ 1 \end{pmatrix} + 0\begin{pmatrix} -1 \\ 1 \end{pmatrix}, \text{ so } [f(b_1)]_{B^1} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$f\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 0\begin{pmatrix} 1 \\ 1 \end{pmatrix} + 1\begin{pmatrix} -1 \\ 1 \end{pmatrix}, \text{ so } [f(b_2)]_{B^1} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

$$[F]_{B,B^1} = ([f(b_1)]_{B^1} \mid [f(b_2)]_{B^1}) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ is already in reduced echelon form. It has two pivots, so $\text{rank}(f) = 2$.

By the rank-nullity thm, $\text{nullity}(f) = 2 - 2 = 0$.