

AMAT 583, Lec 20, 11/7/19

Today: Single linkage clustering
- graphs
- dendrograms

Review (generalities about clustering)

The input X to a clustering method is a finite subset of \mathbb{R}^n , or more generally, a finite metric space.

The output is one of the following:

- 1) A (sub)partition of X
- 2) A hierarchical (sub)partition of X .

Methods that output a hierarchical (sub)partition are called hierarchical clustering methods.

Recall: A partition of X is a set P of non-empty subsets X such that each element of X is contained in exactly one element of P .

A subpartition P of X is a partition of a subset of X
 \Rightarrow each element of X is contained in at most one element of P .

A hierarchical (sub)partition of X is a collection $\{P_\alpha\}_{\alpha \in [0, \infty)}$ of (sub)partitions of X such that if $\alpha \leq \beta$ and $A \in P_\alpha$, then $A \subset B$ for some $B \in P_\beta$. (I phrased this slightly differently, but equivalently, in the last lecture).

Note: Sometimes for simplicity, we'll consider hierarchical subpartitions indexed by $\mathbb{N} = \{0, 1, 2, \dots\}$ rather than $[0, \infty)$.

Today, we'll focus on a simple and very natural clustering technique called single linkage.

Single linkage is closely connected to topology and has good mathematic properties. But it has some bad properties that make it useful only in special settings.

Input: Any finite metric space (X, d)

Output: A hierarchical partition of X .

To explain single linkage, we will need to define graphs.

Graphs

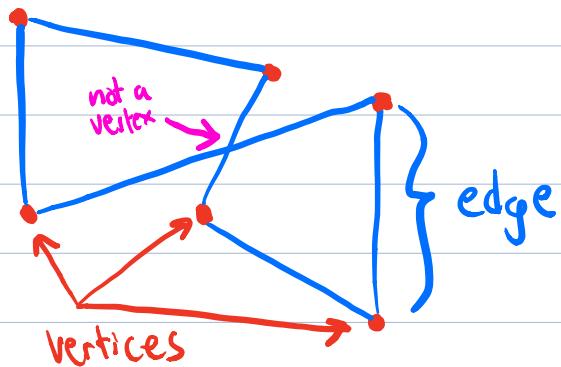
- very important constructions in computer science, mathematics, and statistics

- Note: These graphs are not the same as the graphs of functions you've seen since high school.

We distinguish between directed and undirected graphs.

Intuitively, an undirected graph is a collection of points (vertices) with edges connecting them.

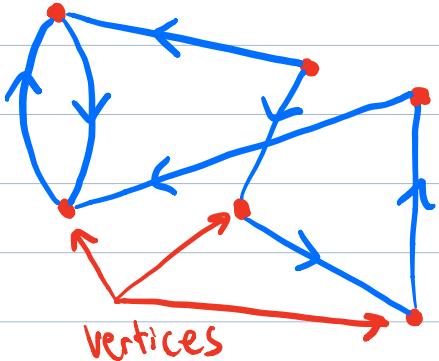
We can draw this in the plane like so



However, formally, we don't usually assume that the vertices live in \mathbb{R}^2 .

A directed graph is a similar kind of object, but the

edges are each assumed to have a direction from one vertex to another.



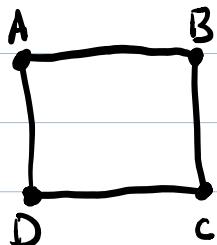
For now, we will be concerned only with undirected graphs, so we define only these formally.

Definition: An undirected graph is a pair (V, E) where

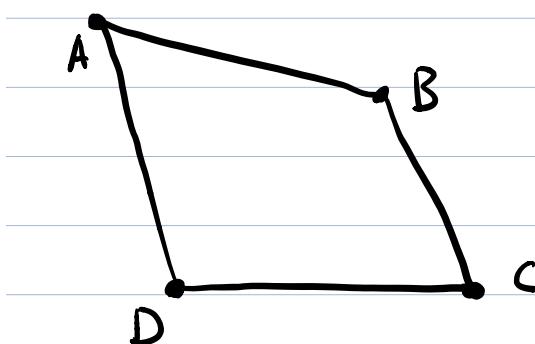
- V is any set (called the vertex set)
- E is a set of two element subsets of V (called the edge set). We will abuse notation slightly and write the two element set $\{A, B\}$ as $[A, B]$.

Example: $V = \{A, B, C, D\}$, $E = \{[A, B], [B, C], [C, D], [D, A]\}$.

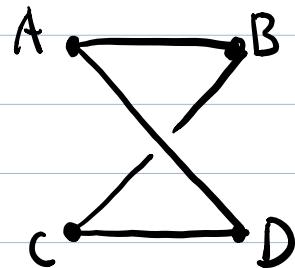
We can draw this as follows:



or like this:



or even like this:



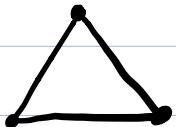
(There's no prescribed rule for where to place the vertices in the plane, though some choices are clearly more awkward than others,

Example: A complete graph is one with an edge between every possible pair of vertices.

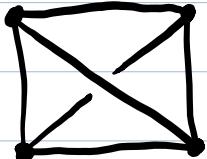
Complete graph on 2 vertices:



Complete graph on 3 vertices:



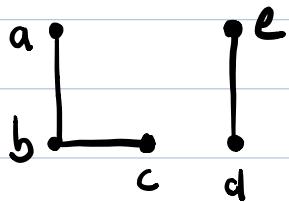
Complete graph on 4 vertices:



Example: A graph can have multiple "components."

$$V = \{a, b, c, d, e\}$$

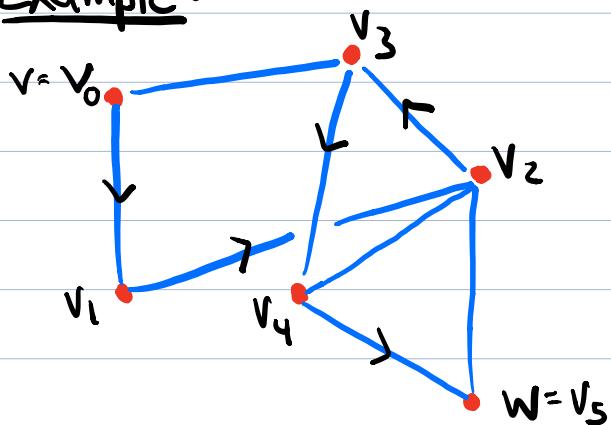
$$E = \{[a, b], [b, c], [d, e]\}$$



Connected components of (undirected) graphs

For $G = (V, E)$ an undirected graph and $v, w \in V$,
a path from v to w is a sequence of $n \geq 1$ vertices
 $v = v_1, v_2, \dots, v_n = w$ such that for $1 \leq i \leq n-1$,
 $[v_i, v_{i+1}] \in E$.

Example:



Note: If $n=1$, then $v=v_1=v_n=v_w$ and the 1-element sequence v is a path from v to itself.

Define a relation \sim on V by taking $v \sim w$ iff \exists a path from v to w .

Proposition: \sim is an equivalence relation.

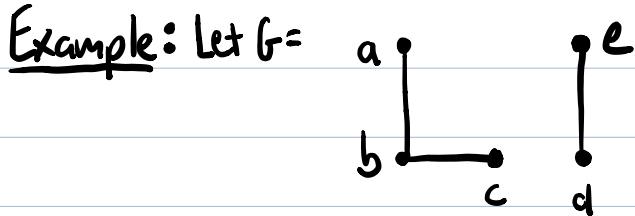
Proof is an easy exercise

A subgraph of a graph $G=(V,E)$ is a graph $G'=(V',E')$ with $V' \subset V$, $E' \subset E$.

Def: A connected component of G is a subgraph $G'=(V',E')$ such that

1) V' is an equivalence class of \sim

2) $E' = \{(v,w) \in E \mid v, w \in V'\}$. That is, every edge between vertices in V' is included in E' .



The connected components of G are

$$G^1 = (\{a, b, c\}, \{\{a, b\}, \{b, c\}\})$$

$$G^2 = (\{d, e\}, \{\{d, e\}\}).$$

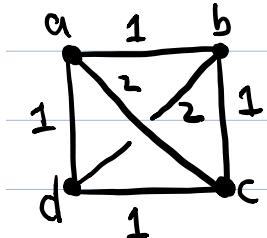
Let (X, d) be a finite metric space.

For simplicity, assume the metric is integer-valued.

For $z \in \mathbb{N} = \{0, 1, 2, 3, \dots\}$, let $N_z(X)$ be the graph with:

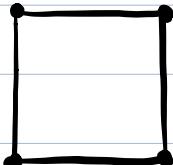
- Vertex set X
- An edge $[x, y]$ included iff $d(x, y) \leq z$.

Example: $X = \{a, b, c, d\}$, with the metric given as follows

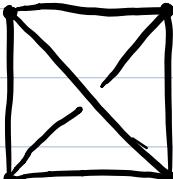


Then $N_0(X) = \begin{array}{cc} a & b \\ \bullet & \bullet \\ c & d \end{array}$ [no edges]

$N_1(X) =$



$N_2(X) =$



Note That if $y \leq z$, $N_y(X) \subset N_z(X)$.

We define the single linkage clustering of $X \{P_z\}_{z \in \mathbb{N}}$ by taking

$$P_z = \left\{ X' \subset X \mid X' \text{ is the vertex set of a connected component of } N_z(X) \right\}$$