Parallel Quick Sort in OpenCL

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Abstract. We have implemented a parallel version of the Quick Sort algorithm using OpenCL to be executed on GPUs. Experiments show, that a significant speedup compared to the sequential CPU version is only possible for very large inputs. A combination with a GPU algorithm that performs better for smaller inputs is advisable to maximize speedup.

1 Algorithm

Since the sequential Quick Sort algorithm is inherently recursive in nature, we used a similar approach for our GPU version. In every recursive call a pivot is selected and the GPU swaps elements such that smaller elements than the pivot are to its left in the array and larger elements are to its right. This is done by computing two prefix sums - one for the lower elements, one for the upper elements. An element adds 1 to the respective prefix sum, if it is lower/higher than the pivot, otherwise 0. As a result the number in the prefix sum array at the position of an element is its target index in the output array. Afterwards we only have to fill the gap between lower and upper numbers with pivots.

Pseudocode for this is shown in Algorithm 1. It is written in SIMD-style such that the function is called on a new thread for every item in the input. The parameter i is the index of the current item. The parameters of f set and count describe the bounds of the current recursion; they start at 0 and input-length respectively.

2 Implementation Details

There is no proper way to write templates for OpenCL kernels. Therefore, our algorithm only supports 32-bit integers. Support for floating point numbers and 64-bit integers could be trivially achieved by copying the existing kernels and changing the relevant data types. On top of that, many GPUs only support 64-bit integers by software emulation.

3 Experimental Results

We benchmarked our algorithm on a machine with an i5-4670, 8GB of RAM and an AMD Radeon R290. We used std::uniform_int_distribution to generate a random array of numbers.

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Algorithm 1 SIMD-pseudocode for the parallel quick sort algorithm on GPUs.
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\mathbf{function} \ \mathrm{QuickSort}(input, output, of \overline{fset}, count, i)
   pivot \leftarrow Choose pivot
   lps \leftarrow Left prefix sum array
   rps \leftarrow \text{Right prefix sum array}
   if input[offset + i] < pivot then
       lps[i] \leftarrow 1
   else if input[offset + i] > pivot then
       rps[i] \leftarrow 1
   end if
   PrefixSum(lps)
   PrefixSum(rps)
   countLeft \leftarrow lps[last]
   countRight \leftarrow rps[last]
   countPivots \leftarrow count - countLeft - countRight
   if input[offset + i] < pivot then
       output[offset + lps[i]] \leftarrow input[offset + i]
   else if input[offset + i] > pivot then
       output[offset + countLeft + countPivots + rps[i]] \leftarrow input[offset + i]
   end if
   if i < numberPivots then
       output[offset + countLeft + i] \leftarrow pivot
   end if
   input \leftarrow output
   QuickSort(input, output, offset, countLeft, i)
   QuickSort(input, output, offset + countLeft + countPivot, countRight, i)
end function
```

Table 1 compares the runtime of std::sort and our implementation for different input sizes. Our implementation has a large amount of overhead, especially for small input sizes. However, it scales better than std::sort for larger input sizes because more and more elements in each step are equal to the pivot and are discarded in further recursion steps.

Table 2 shows the impact of different amounts of unique numbers for a constant input size of 2^{20} . With more unique numbers, less and less elements will be equal to the pivot element in each step. This increases the size of the remaining blocks and therefore the number of necessary recursion steps for our algorithm. The last column shows the runtime of our algorithm if the recursion is stopped if the block size is smaller than 1024.

We did not achieve a speedup with respect to std::sort for any input size. As shown in Table 2, a large percentage of the total runtime is spent in recursion steps with block sizes smaller than 1024 elements. For these small blocks, the overhead for the kernel invocations and copy operations on the OpenCL buffers becomes too large. Since OpenCL kernels are invoked from a command queue and only one kernel is executed at a time, the number of active GPU threads becomes smaller and smaller for each recursion step. This problem could be solved by implementing a second sorting algorithm for small block sizes that uses a single workgroup to sort a small block and sorts multiple small blocks at a time, such as bitonic sort.

| n | CPU | GPU |
|----------|------|-------|
| 2^{20} | 73 | 10151 |
| 2^{21} | 140 | 10183 |
| 2^{22} | 284 | 11050 |
| 2^{23} | 548 | 11134 |
| 2^{24} | 1091 | 11093 |
| 2^{25} | 2133 | 11809 |
| 2^{26} | 4263 | 12909 |
| 2^{27} | 8620 | 13764 |

Table 1. Runtime in milliseconds of the QuickSort algorithm with 2¹⁴ different numbers.

| # number | s CPU | GPU | rec. aborted |
|----------|-------|-------|--------------|
| 2^{14} | 74 | 10934 | 393 |
| 2^{18} | 82 | 37087 | 393 |
| 2^{20} | 84 | 76149 | 373 |

Table 2. Runtime in milliseconds for $n = 2^{20}$ and different amounts of unique numbers. The last column shows the runtime if the recursion is aborted when the block size is smaller than 1024 to show the impact of the last recursion steps.