

Time Series Management

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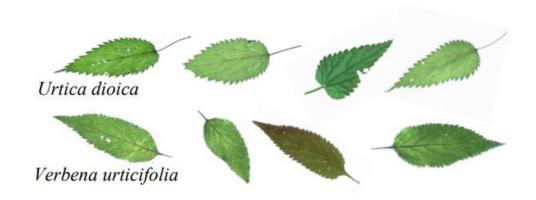
Q2 Q3

Syllabus

- Time series classification
- Shapelet Discovery primitive

Time series classification – an example

• If we aim to design a classifier to differentiate between the time series of two plant species, what features should we focus on? Given that the **intra-class variability** in color and size **significantly exceeds** the **inter-class differences**, a viable strategy consists into analyzing the shapes of the leaves.

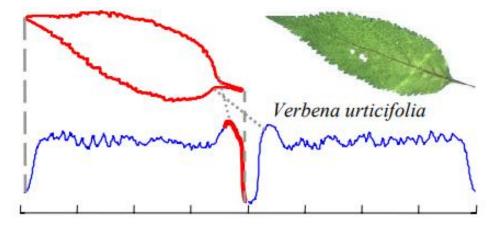


Time series classification – general intuition

 However, the global shape differences are quite subtle. Moreover, leaves often exhibit distortions or "occlusions" caused by insect damage, which can confound any global shape-based measurements.

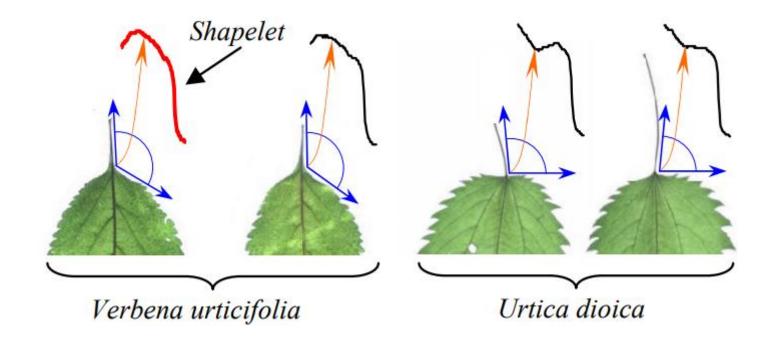
• To address this, we propose an alternative approach: converting each leaf into a one-dimensional representation, as demonstrated in the

figure below.



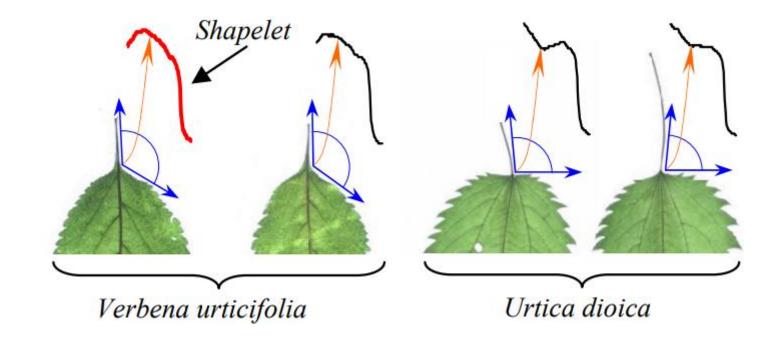
Time series Shapelet

• Instead of comparing all the shapes, we can focus on analyzing a small, highly distinctive subsection of the shapes from the two classes.



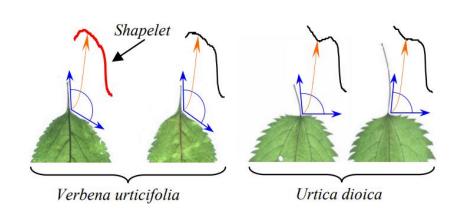
Time series Shapelet

• We call such discriminative subsequence: Time series Shapelet.



Time series Shapelet

• Shapelets were first proposed as time-series segments that maximally predict the target variable. All possible segments were considered as potential candidates. In contrast, the **minimum distances** of a candidate to all training series were used as a predictor feature for ranking the *information gain* accuracy of that candidate on the target variable.



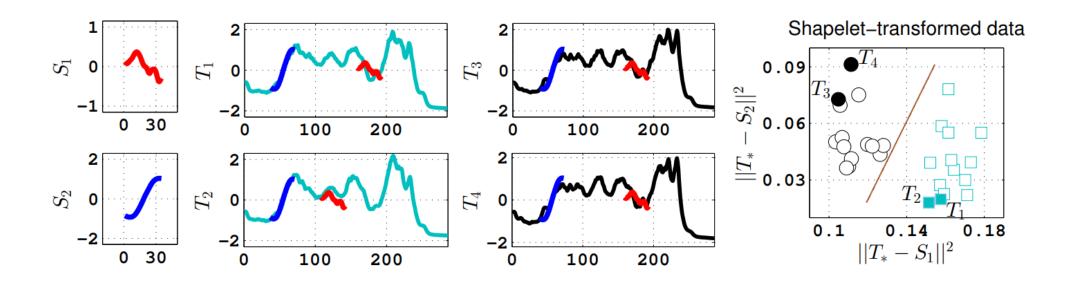
Learning Time series shapelet

1) We can consider a mathematical formulation of the shapelet learning task as an optimization of a classification objective function.

2) Shapelets can be learnt such as their distances to the original series can linearly separate the time series instances by their targets.

Learning Time series shapelet

- Two learned shapelets S1, S2.
- Series' distances to shapelets can optimally project the series into a
- 2-dimensional space, called the shapelet-transformed representation



Notation

• *Time Series Dataset*: A time-series dataset composed of I training instances, with each series contains Q-many ordered values, is denoted as $T^{I\times Q}$, while the series target is a nominal variable $Y\in\{1,\ldots,C\}^I$ having C categories.

• **Shapelets**: A shapelet of length L is simply an ordered sequence of values from a data structure perspective. Nevertheless, shapelets semantically represent intelligence on how to discriminate the target variable of a series dataset. The K-most informative shapelets are denoted as $S \in \mathbb{R}^{K \times L}$.

Notation

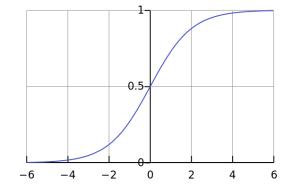
• Shapalet Transformation: Minimum distances to shapelets can be characterized as a transformation of the time-series data $T \in \mathbb{R}^{I \times Q}$ into a new representation $M \in \mathbb{R}^{I \times K}$. Such a transformation reduces the dimensionality of the original time-series, because typically K < Q

• General purpose classifiers (e.g.: SVMs, Bayesian Network, . . .) show high prediction accuracy over the new representation *M*.

Logistic regression model

• We consider a *logistic regression* classification model. It provides an option to interpret predicted binary targets as probabilistic confidences. Nonetheless, it can ensure extending to the multi-class case.

• Logistic Sigmoid Function: $\sigma(Y) = (1 + e^{-Y})^{-1}$.



• It is used for the prediction of target variables via a logistic regression loss.

Learning model

• The minimum distances M become the new predictors in the transformed shapelets space, a *linear learning model* can predict approximate target values $\hat{Y} \in \mathbb{R}^{I \times K}$ via the predictors M and linear weights $W \in \mathbb{R}^{K}$ (plus bias $W_0 \in \mathbb{R}$).

$$\widehat{Y}_i = W_0 + \sum_{k=1}^K M_{i,k} W_k, \forall i \in \{1, \dots, I\}$$

Loss Function

• The logistic regression operates by minimizing the *logistic loss*, between true targets Y and estimated ones \widehat{Y} .

$$\mathcal{L}(Y,\widehat{Y}) = -Y \ln \left(\sigma(\widehat{Y})\right) - (1 - Y) \ln \left(1 - \sigma(\widehat{Y})\right)$$

Regularized Objective Function

- The logistic loss function together with regularization terms represent the regularized objective function.
- The idea is to jointly learn the optimal shapelets
 S and the optimal linear hyper-plane W that minimize the classification objective F.

$$\underset{S,W}{\operatorname{argmin}} \mathcal{F}(S, W) = \underset{S,W}{\operatorname{argmin}} \sum_{i=1}^{I} \mathcal{L}(Y_i, \hat{Y}_i) + \lambda_W ||W||^2$$

Differentiable Soft-Minimum Function

• In order to compute the derivative of the objective function, all the involved functions of the model need to be differentiable.

• We denote the distance between the j-th segment of series i and the k-th shapelet as $D_{i,k,j}$.

$$D_{i,k,j} := \frac{1}{L} \sum_{l=1}^{L} (T_{i,j+l-1} - S_{k,l})^2$$

Differentiable Soft-Minimum Function

- A differentiable approximation of the minimum function is the popular *Soft Minimum*.
- A parameter α controls the *precision* of the function and the soft minimum approaches the true minimum for $\alpha \rightarrow -\infty$.

$$M_{i,k} \approx \widehat{M}_{i,k} = \frac{\sum_{j=1}^{J} D_{i,k,j} e^{\alpha D_{i,k,j}}}{\sum_{j'}^{J} e^{\alpha D_{i,k,j}}}$$

Per-instance objective

• The decomposed objective function \mathcal{F}_i corresponds to a division of the objective function \mathcal{F} into per-instance losses for each time series.

$$\mathcal{F}_i = \mathcal{L}(Y_i, \hat{Y}_i) + \frac{\lambda_w}{I} \sum_{k=1}^K W_k^2$$

Optimization algorithm - Gradient descent

Algorithm 1 Learning Time-Series Shapelets

```
Require: T \in \mathbb{R}^{I \times Q}, Number of Shapelets K, Length of a
      shapelet L, Regularization \lambda_W, Learning Rate \eta, Number of
      iterations: maxIter
Ensure: Shapelets S \in \mathbb{R}^{K \times L}, Classification weights W \in \mathbb{R}^K,
      Bias W_0 \in \mathbb{R}
 1: for iteration=\mathbb{N}_1^{\text{maxIter}} do
         for i = 1, ..., I do
             for k = 1, \ldots, K do
      W_k \leftarrow W_k - \eta \frac{\partial \mathcal{F}_i}{\partial W_i}
 5: for L = 1, ..., L do
6: S_{k,l} \leftarrow S_{k,l} - \eta \frac{\partial \mathcal{F}_i}{\partial S_{k,l}}
      end for
             end for
          W_0 \leftarrow W_0 - \eta \frac{\partial \mathcal{F}_i}{\partial W_0}
          end for
11: end for
12: return S, W, W_0
```

References

 Ye, Keogh, Time Series Shapelets: A New Primitive for Data Mining, KDD 2009 https://dl.acm.org/doi/10.1145/1557019.1557122

 Josif Grabocka et al. Learning time-series shapelets Published in Knowledge Discovery and Data 2014, https://www.semanticscholar.org/paper/Learning-time-series-shapelets-Grabocka-Schilling/5900721a7ff9e91782dd4dc33956b09d3adb67f5