

Admin Throttle

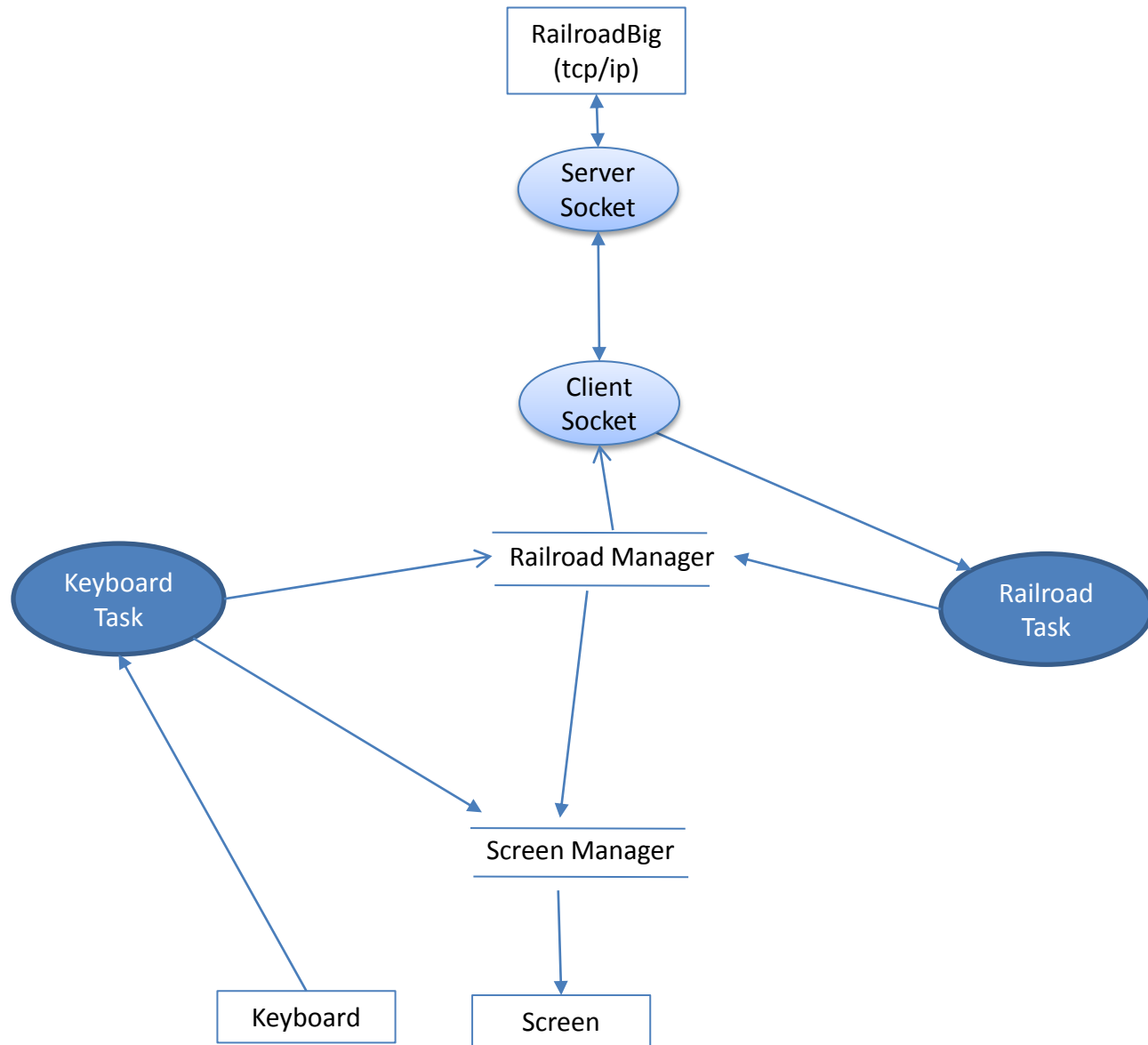
Design

Admin Throttle

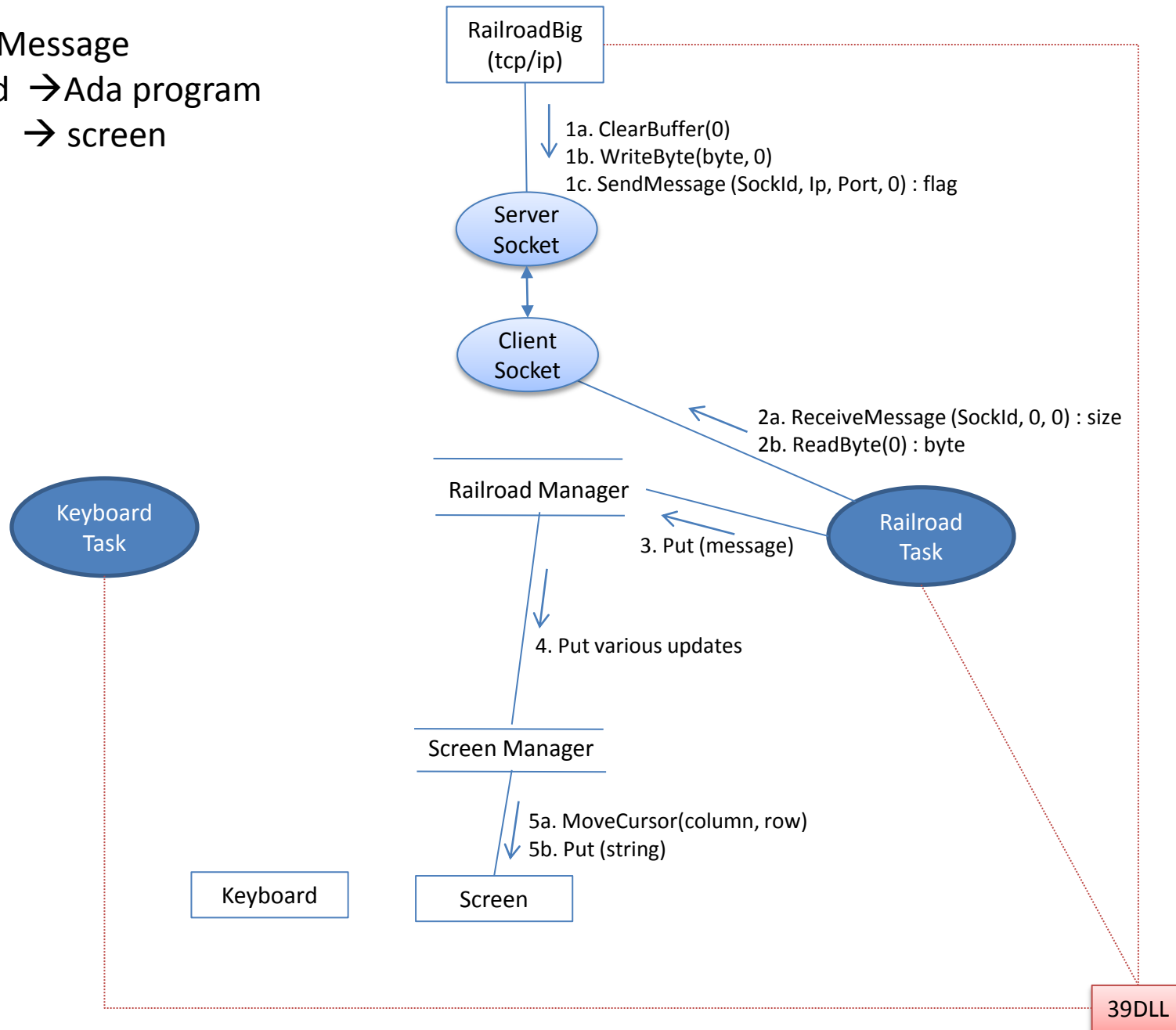
```

                                1          2          3          4          5          6          7 . . . to          100
1234567890123456789012345678901234567890123456789012345678901234567890123456789. . .

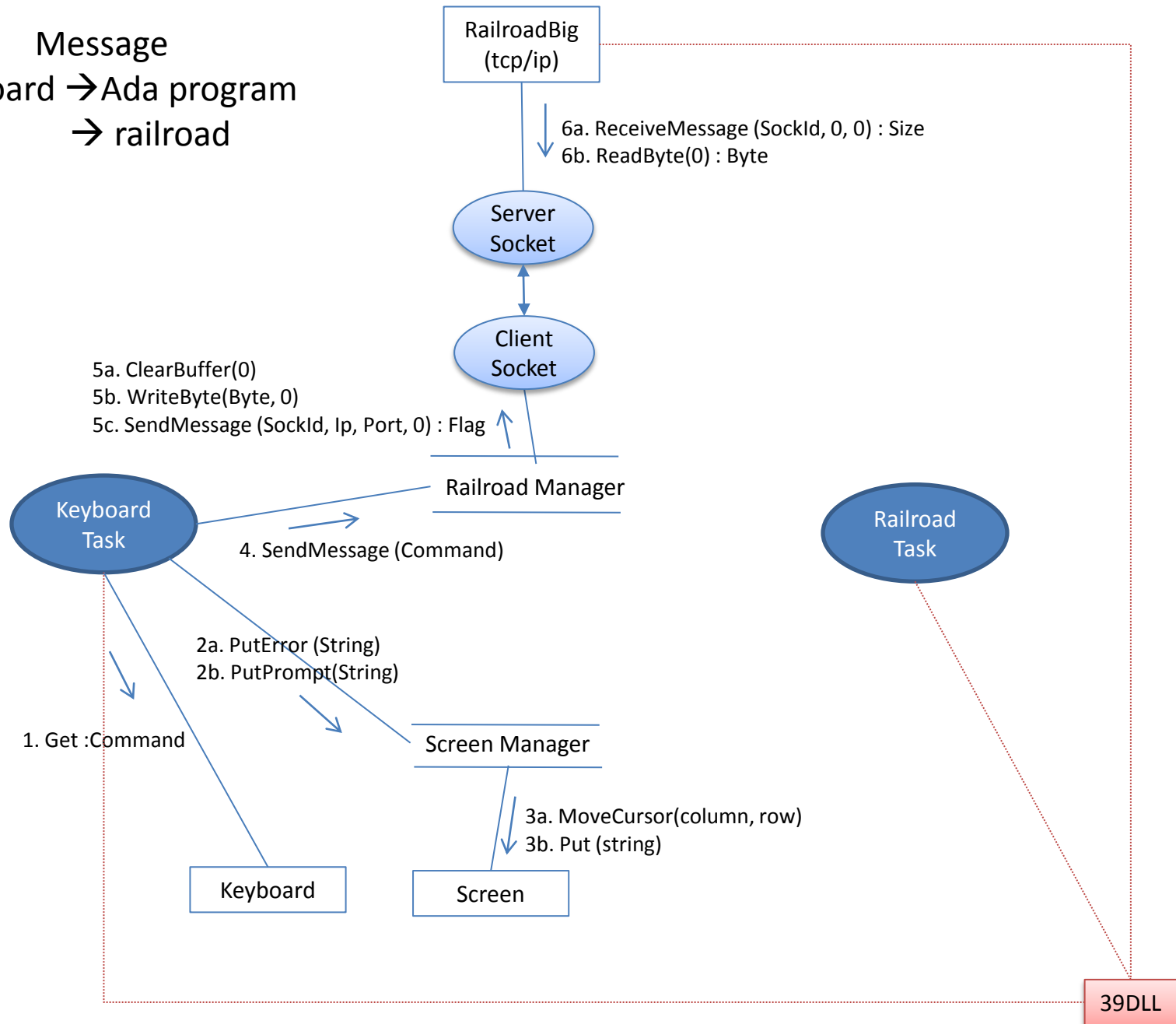
01  Train PhyAdr/Slot VirAdr/Slot State Speed Dir Light Bell Horn Mute Location
02  -----
03   1      3333 / 3      13 / 10   W    60    F   on   off  off  off  13   14   26
04   2      2222 / 2      14 / 11  BH    0    R   on   on   on   on  103  104  77
05   -
06   -
07
08  Last msg received: set speed train 2 to 50
09                        bytes in decimal / bytes in hex
10  Switches                      Commands
11    0 1 2 3 4 5 6 7 8 9          Xf  read XML          Za  s#...s# initialize loco
12    0  T T T T T T C C T          SEa select loco      STa steal loco
13    1 C c T C T C C T C t
14    2 T T C C C C C
15                                Cs close                Ts throw
16                                Vt n -- set velocity of t to n
17                                Ft forward                Rt reverse          Q  quit
18                                Bt bell                  Ht horn              .  halt all
19                                Lt light                  Mt mute
20                                P+ power on              P- power off
21                                a = physical loco address s = switch          s# = sensor#
22                                t = train                  f = file name          n  = 0..127
23  Error messages displayed here
>
```



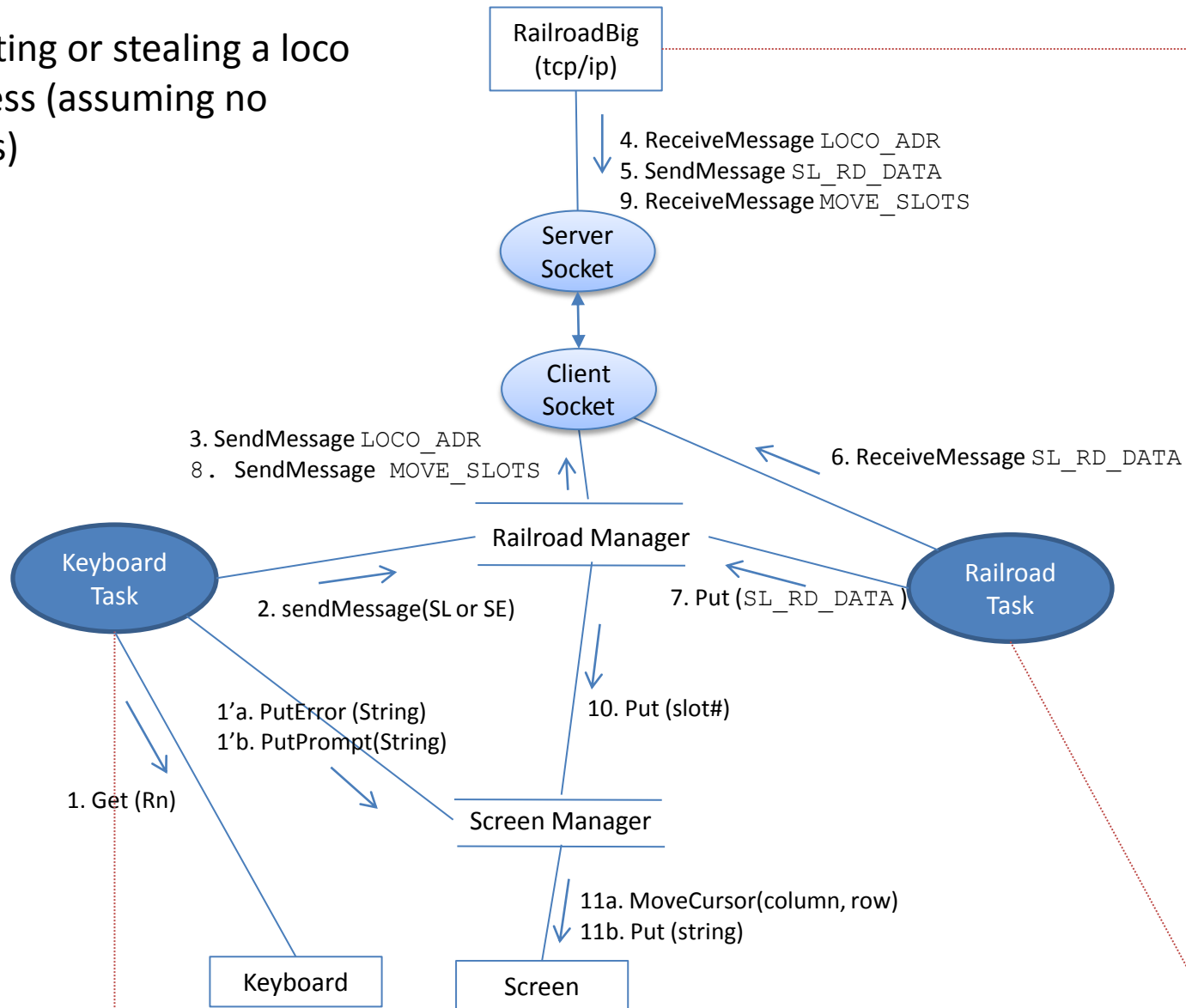
Message
railroad → Ada program
→ screen



Message
keyboard → Ada program
→ railroad



Selecting or stealing a loco
address (assuming no
errors)



Globals.ads

+ kNumTrains	:= 4
+ kNumSwitches	:= 26
+ kMaxLenMsg	:= 14
+ kMaxLenError	:= 80
+ kGreen	:= "green"
+ kWhite	:= "white"
+ kRed	:= "red"
+ kYellow	:= "yellow"
+ kNoColor	:= " "
+ kDeltaSpeed	:= 10
+ ColorType	string(1..6)
+ LocoAddressType	(0..4444)
+ SlotType	(0..120)
+ DirectionType	(Forward, Backward)
+ SpeedType	(0..127)
+ OnOffType	(On, Off)
+ TrainType	record of isConnected, phyadr, physlot, viradr, virslot, state, direction, speed, light, horn, bell, mute, sensors(a list of natural)
+ TrainArrayType	(1..kNumTrains) of TrainType
+ SwitchType	(Closed, Thrown, Moving, Unknown)
+ SwitchArrayType	(1..kNumSwitches) of SwitchType
+ ByteArrayType	array (Integer RANGE <>) of unsigned_8
+ MessageType	bytes(1..kMaxLenMsg), InUse
+ CmdType	(ReadXML, InitializeLoco, SelectLoco, StealLoco, Close, Throw, Forward, Backward, Increase, Decrease, Halt, Horn, Bell, Mute, Light, Power, MoveSlots, Unknown, Quit)
+ CommandType	record of cmd, natural

Globals.ads

```
+   ConnectSocket      C.Double;
+   IpStrAda           String := "127.0.0.1";
+   IpStrC             Chars_Ptr := New_String(IpStrAda);
+   CEmptyString       Chars_Ptr := New_String("");
+   ServerPort         c.double := c.double(14804);
+   Buffer0             C.Double := C.Double(0.0);
+   BlockingMode       C.double := c.double(0);
+   NonblockingMode    C.double := c.double(1);
+   CValue             C.Double;
+   CZero              C.double := c.double(0);
```


Packages

Api39dll

- +f dllInit
- +f TcpConnect
- +f ClearBuffer
- +f WriteByte
- +f SendMessage
- +f ReceiveMessage
- +f ReadByte

ScreenManager

- +p Initialize
- +p PutTrains(Trains)
- +p PutMessage(Stgring)
- +p PutSwitches(Switches)
- +p PutError(String)
- +p PutPrompt(String)
- +o objScreenManager**

RailroadTask

- +e Start

+o obj RailroadTask

KeyboardTask

- +e Start

+o objKeyboardTask

Screen

- +d ScreenDepth
- +d ScreenWidth
- +p Beep
- +p ClearScreen
- +p MoveCursor

RailroadManager

- d Trains
- d Switches
- d Last message received
- +p Initialize
- +p Put(Message)
- +f GetMessage(Command, Success):Message
- +o objRailroadManager**

AdminThrottle

It all starts here
Connect to server
Start tasks
Initialize managers

At startup

- ☐ Trains initialized to
 - slot number for a train is 0 until registered
 - direction forward, speed 0
 - light, horn, bell, mute all off
- ☐ Message sent to throw all switches
- ☐ Last message received is blank

-- Constants for direction, lights, horn, bell, mute, turnout action

```
kForward      := 16#00#;
kBackward     := 16#20#; -- 0010 0000
kLightsOn     := 16#10#; -- 0001 0000
kLightsOff    := 16#00#;
kHornOn       := 16#02#; -- 0000 0010
kHornOff      := 16#00#;
kBellOn       := 16#01#; -- 0000 0001
kBellOff      := 16#00#;
kMuteOn       := 16#08#; -- 0000 1000
kMuteOff      := 16#00#;
```

-- Constants for switches

```
kCloseIt      := 16#20#; -- 0010 0000
kIsClosed     := 16#10#; -- 0001 0000
kThrown       := 16#00#; -- 0000 0000
```

-- Opcodes

```
OPC_GPON      := 16#83#; -- power on
OPC_GPOFF     := 16#82#; -- power off
OPC_INPUT_REP := 16#B2#; -- report sensor fired
OPC_SW_REP    := 16#B1#; -- report turnout now open/thrown

OPC_LOCO_SPD  := 16#A0#; -- set speed
OPC_LOCO_DIRF := 16#A1#; -- set direction, horn, bell, lights
OPC_LOCO_SND  := 16#A2#; -- set mute and unmute sound
OPC_SW_REQ    := 16#B0#; -- move a turnout

OPC_LOCO_ADR  := 16#BF#; -- request for slot data
OPC_SL_RD_DATA := 16#E7#; -- slot data response
OPC_LONG_ACK  := 16#B4#; -- insufficient slots
OPC_MOVE_SLOTS := 16#BA#; -- register slot
```

All the above are declared as "constant unsigned_8"

Messages Sent

OPC_SW_REQ – move switch

<0xB0><SW1><SW2><CHK>
byte1 := switch number (0..127)
byte2 := switch direction

OPC_LOCO_SPD – set speed

<0x A0 ><SLOT#><SPEED><CHK>
byte1 := slot;
byte2 := speed

OPC_LOCO_DIRF – set direction, lights, horn, bell

<0xA1><SLOT#><DIR_STATE><CHK>
byte1 := slot;
byte2 := 16#00# or Direction or Light or Horn or Bell;

OPC_LOCO_SND – set mute

<0xA2><SLOT#><SOUND><CHK>
byte1 := slot;
byte2 := 16#00# | Mute;

OPC_LOCO_ADR – request information about a loco address

<0xBF><adrhigh><adrlow><chk>
byte2 := 16#FF# and (LocoAddress mod 128);
byte1 := 16#FF# and ((LocoAddress - byte2) / 128);

OPC_MOVE_SLOTS – register a slot

<0xBA><slot#><slot#><chk>
byte1 := slot;
byte2 := slot;

checksum := 16#FF# xor opCode xor byte1 xor byte2;
clearbuffer();
writebyte(opCode);
writebyte(byte1);
writebyte(byte2);
writebyte(checksum);
sendmessage(socketToSimulator);

Messages Received

All the output messages, which are displayed on the screen, but otherwise ignored.

OPC_INPUT_REP – report sensor fired

```
<0xB2><SN1><SN2><CHK>  
  SN1  <0,A6,A5,A4,A3,A2,A1,A0>  
  SN2  <0,X,I,L,A10,A9,A8,A7>  
        I = 1 => add 1000 to the address  
        L = 1 => sensor high else low
```

OPC_SW_REP – report turnout now open/thrown

```
<0xB1><SW1><SW2><CHK>  
  SW1  <0,A6,A5,A4,A3,A2,A1,A0>  
  SW2  <0,1,I,L,A10,A9,A8,A7>  
        I = 1 => turnout closed else thrown
```

OPC_SL_RD_DATA – report loco address information

```
<0xE7><0E><slot#><status><adrlow><spd><dirf><trk><ss2><adrhigh><snd><id1><id2><chk>  
  0      1      2      3      4      5      6      7      8      9      10     11     12     13  
  slot#   the number of the slot  
  status  address already registered in the indicated slot (D5D4 == 11) or  
           the slot is available for registering the address (D5D4 == other)  
           (The simulator makes no attempt to get the other bits correct and  
           sets them all to 0's.)  
  address that was sent  
  other   information that we choose to ignore so we set it to 0x00;
```

OPC_LONG_ACK – report that there aren't enough slots

```
<0xB4><lopc><ack1><chk>  
  lopc    0x00, indicating insufficient slots  
  other   information that we choose to ignore so the simulator sets it to 0x00;
```