

# Zephyr: Timers & Atomic Operations Lab

BME554L - Spring 2026 - Palmeri

Dr. Mark Palmeri, M.D., Ph.D.

2026-02-15

## Table of contents

Refactor your GPIO Lab Code . . . . .	1
Git Version Control . . . . .	2
Test the Accuracy of your Timing . . . . .	2
Methods . . . . .	2
Logging Statements . . . . .	3
Oscilloscope Measurements . . . . .	4
Discussion . . . . .	5
How to Ask for Help . . . . .	5
What to Submit . . . . .	6

## Refactor your GPIO Lab Code

You will be refactoring your code from the GPIO lab to now use timers and atomic operations. Do all of the refactoring below on a new branch called `timers` branched from `main` and your last annotated tag for the previous assignment.

- Eliminate any conditional logic (`if/else` statements) to test for elapsed time to toggle/set LED output states and refactor using timers.
- Refactor all button press boolean variables that are modified in ISRs to use atomic operations.
- Implement finer resolution for timing than what `k_uptime_get()` can provide (ms) by using `k_uptime_ticks()` ([documentation](#)) and `k_ticks_to_ns_near64()` ([documentation](#)).
- Make sure that when you put your device to sleep, that your code saves the partial period of the time that has elapsed for the action LEDs, so that when the device wakes up, the action LEDs will toggle at the correct time relative to when they were put to

sleep. You can use `k_timer_remaining_get()` ([documentation](#)) to get the remaining time until the next timer expiration.

- You do not have to use work queues if your timer handler functions run quickly and do not block. However, if your handler functions are more complex, you should use work queues to submit the work to the system work queue.

## Git Version Control

- Use best practices for version control (branching, commit messages, etc.).
- Do all development on a dedicated branch that is merged into `main` once it is functional.
- Commits should be very specific to the changes/additions you are making to your code. This will help you and others understand what you did and why you did it.
- On a given development branch, try to implement one small piece of functionality at a time, commit it, and then move on to the next piece of functionality.

### ! Important

You do not want one, monolithic git commit right before you submit your project.

### 💡 Tip

For this lab, you should capture changes related to your different refactoring efforts in separate commits.

## Test the Accuracy of your Timing

For the measurements below, record and analyze your data in the technical report captured in a Jupyter notebook called `testing/timer_testing.ipynb`. You can use the Jupyter notebook included in the lab repository (`testing/technical_report.ipynb`), which includes some example code, as a starting point, but be sure to rename the notebook in the `testing/` directory.

Your technical report should include:

### Methods

A brief Methods section describing what you did (e.g., how you captured the timing via logging or how you measured timing on the oscilloscope).

## Logging Statements

- Use logging statements to test the accuracy of your heartbeat and action LED timing for the (a) default, (b) fastest and (c) slowest blink rate of your action LEDs.

### Note

Note that logging statements, by default, are low priority and non-blocking (asynchronous).

- Given the latency of when a log message may be printed relative to the event you are trying to get the timing of, you should save the execution time of the timing handler to be log printed later.
- Save your logging output data to a CSV file to be read into your Jupyter notebook.

### Note

There is no elegant way to directly save your data to a CSV file directly from the Terminal in VS Code.

Two possible approaches:

1. You can save the entire Terminal output to a file and parse it in your Jupyter notebook, or
2. You can cut-and-paste the relevant values from the Terminal output to a CSV file.

An example Terminal output might look like:

```
[00:01:00.009,429] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.109,436] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.209,442] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.254,333] <inf> timers_lab: heart toggle period (ns): 500000000
[00:01:00.309,448] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.409,454] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.509,460] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.609,466] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.709,472] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.754,333] <inf> timers_lab: heart toggle period (ns): 500000000
[00:01:00.809,478] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:00.909,484] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:01.009,490] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:01.109,497] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:01.209,503] <inf> timers_lab: action toggle period (ns): 100006104
[00:01:01.254,333] <inf> timers_lab: heart toggle period (ns): 500000000
```

You could then leverage the following snippet in your Jupyter notebook to parse out the relevant data:

```
log_5Hz = pd.read_csv('log_5Hz.txt', sep=" ", header=None, usecols=[0,3,7],
                      names=['timestamp','type','toggle duration (ns)'])
log_5Hz['frequency (Hz)'] = (1e9/(2*log_5Hz['toggle duration (ns)']))
print('Table with action LEDs nominally set to 5 Hz:')
with pd.option_context('display.max_rows', None,
                       'display.max_columns', None):
    print(log_5Hz)
```

If you run out of terminal output buffer, you can increase the buffer size in VS Code settings under **Terminal > Integrated: Scrollback**.

- Estimate the 95% confidence interval (2x standard deviation for normally-distributed data) for your timing relative to the nominal specification.

#### Tip

When measuring your timing accuracy with a confidence interval, you need to make repeated measurements. If your measured timing periods are identical, your standard deviation of 0 and a confidence interval of 0. But that apparent “identical” replicate measurement is a function of the finite resolution of your measurement system. In this case, you can use the resolution of your timing measurement as the upper bound of an estimated confidence interval.

For example, if your timing resolution is 1 ms, and you measure a period of 500 ms repeatedly, you can say that your 95% confidence interval is  $< 1$  ms (i.e.,  $500 \pm 0.5$  ms).

## Oscilloscope Measurements

- Repeat your timing accuracy analysis you performed with logging statements using an oscilloscope directly measuring the GPIO pin signals (using the **Measure** functionality for **Period** and **Frequency** metrics).
  - You can measurement the highest and lowest frequencies of your action LEDs (you don’t have to measure each discrete frequency).
  - You do not need to take multiple measurements to estimate a confidence interval with the oscilloscope, since the resolution of the oscilloscope will be the limiting factor for your reported confidence interval estimation (see tip above).

### 💡 Tip

Be sure to have at least 5 cycles of your action LED toggling to get a good estimate of the period and frequency with the oscilloscope's measurement tools.

- Demonstrate that your LEDs are perfectly out of phase with each other (i.e., when one is on, the other is off). You can do this with an oscilloscope measurement or with a cellphone picture of the oscilloscope screen showing both traces for the two action LEDs overlaid on top of each other.

### 💡 Tip

Remember that all of the GPIO pins are accessible as female header sockets on the development kit; you do not need to try to directly connect to the pads of the LEDs and buttons!

- Quantify a 95% confidence interval for your timing relative to the nominal specification using these oscilloscope measurements. (See the tip above for how to estimate a confidence interval when you have finite measurement resolution.)

## Discussion

Discuss how well the measurements match their nominal values, and if significant deviation has occurred, discuss why this may have happened and how it could be improved moving forward.

## How to Ask for Help

1. If you have a general / non-coding question, you should ask your TAs / Dr. Palmeri on Ed to allow any of them to respond in a timely manner.
2. Push your code to your GitLab repository, ideally with your active development on a non-main branch.
3. Create an [Issue](#) in your repository.
  - Add as much detail as possible as to your problem, and add links to specific lines / section of code when possible.
  - Assign the label “Bug” or “Question”, as appropriate.
  - Be sure to specify what branch you are working on.
  - Assign the Issue to one of the TAs.
  - If your TA cannot solve your Issue, they can escalate the Issue to Dr. Palmeri.

4. You will get a response to your Issue, and maybe a new branch of code will be pushed to help you with some example syntax that you can use `git diff` to visualize.

## What to Submit

- Make sure that your complete `timing_analysis.ipynb` notebook is in your `timers` branch in a directory called `testing/`, which also includes all raw CSV logging data.
- Make sure that your Jupyter notebook reads in data from relative paths for the repository, **not** absolute paths on your local machine.
- Push your `timers` branch to GitLab.
- Create a new Merge Request to merge `timers` into your forked repository's `main` branch.

### Warning

Do not create a Merge Request in to the parent repository that you forked from!

- Merge your `timers` branch into your `main` branch.
- Create an annotated tag for that merge commit called `v1.1.0`.
- Create a new Issue assigned to Dr. Palmeri to request a code review for `v1.1.0`.

### Note

If you fix any bugs after creating the original annotated tag, increment up the patch number with a new annotated tag version number, and update the Issue to reflect which annotated tag should be reviewed.