## Deep Q-Learning for Autonomous Driving

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Abstract-What we did

I. INTRODUCTION

ONCE UPON A TIME IN A GALAXY FAR FAR AWAY Task description

II. SETUP

Gazebo + Ros + DQN

III. APPROACH

A. Reward function

Subsection text here.

1) Version 1: Subsubsection text here.

IV. EVALUATION

Time

V. CONCLUSION

The conclusion goes here.

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REFERENCES

[1] author, title.