

Non-convex matrix sensing: Breaking the quadratic rank barrier in the sample complexity

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Abstract

For the problem of reconstructing a low-rank matrix from a few linear measurements, two classes of algorithms have been widely studied in the literature: convex approaches based on nuclear norm minimization, and non-convex approaches that use factorized gradient descent. Under certain statistical model assumptions, it is known that nuclear norm minimization recovers the ground truth as soon as the number of samples scales linearly with the number of degrees of freedom of the ground-truth. In contrast, while non-convex approaches are computationally less expensive, existing recovery guarantees assume that the number of samples scales at least quadratically with the rank r of the ground-truth matrix.

In this paper, we close this gap by showing that the non-convex approaches can be as efficient as nuclear norm minimization in terms of sample complexity. Namely, we consider the problem of reconstructing a positive semidefinite matrix $\mathbf{X}_\star \in \mathbb{R}^{d \times d}$ from a few Gaussian measurements of the form

$$\mathbf{y}_i = \frac{1}{\sqrt{m}} \text{trace}(\mathbf{A}_i \mathbf{X}_\star) \quad \text{for } i = 1, 2, \dots, m.$$

We show that factorized gradient descent with spectral initialization converges to the ground truth with a linear rate as soon as the number of samples scales with $\Omega(rd\kappa^2)$, where d is the dimension, and κ is the condition number of the ground truth matrix. This improves the previous rank-dependence in the sample complexity of non-convex matrix factorization from quadratic to linear. Our proof relies on a probabilistic decoupling argument, where we show that the gradient descent iterates are only weakly dependent on the individual entries of the measurement matrices. We expect that our proof technique will be of independent interest to other non-convex problems.¹

Keywords: non-convex optimization, matrix sensing, sample complexity, virtual sequences

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