

MEDIA ACCESS CONTROL

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12.3.1 FDMA

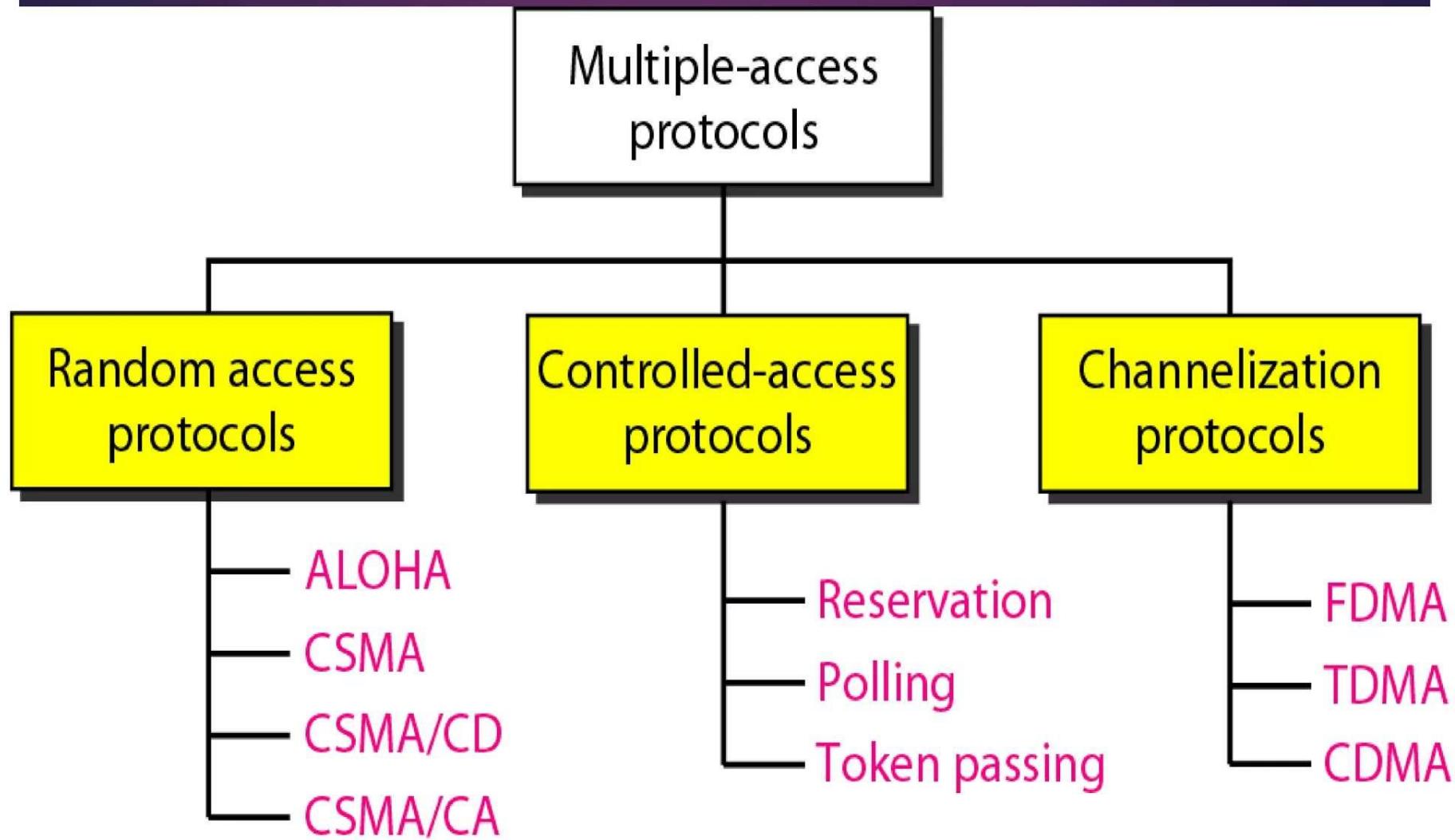
12.3.2 TDMA

12.3.3 CDMA

Introduction

- ▶ The medium access control (MAC) is a **sublayer** of the data link layer.
- ▶ The MAC sublayer emulates a **full-duplex** logical communication channel in a multipoint network.
- ▶ This channel may provide unicast, multicast, or broadcast communication service.
- ▶ The **MAC** sublayer uses **MAC** protocols to ensure that signals sent from different stations across the same channel don't collide. Eg: two people speak
- ▶ A multiple-access protocol to coordinate access to the link (*multipoint* or *broadcast link*).
- ▶ Many protocols have been devised to handle access to a shared link.

Taxonomy of Multiple-access protocols



Random Access



12.1 Random Access

- ▶ Also called **contention-based** access
- ▶ No station is **superior** to another station and No station is assigned to control another.
- ▶ A station that has data to send uses a procedure defined by the protocol to make a **decision on whether or not to send**.
- ▶ Decision depends on the state of the medium (**idle or busy**).
- ▶ Two features of RA:
 - ▶ **No scheduled time for a station to transmit**
 - ▶ **No rules specify which station should send next**
- ▶ Stations compete with one another to access the medium

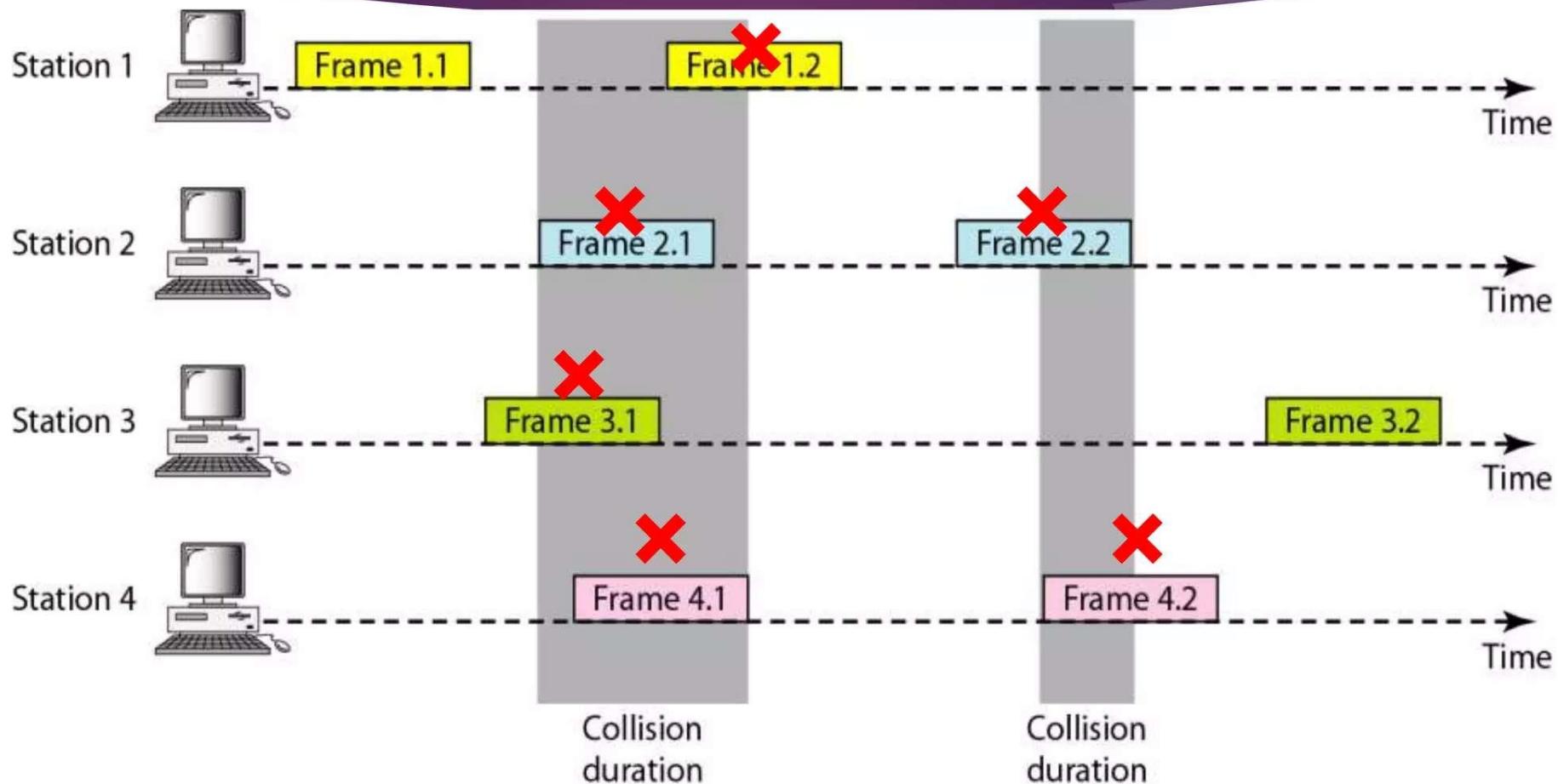
12.1.1 ALOHA

- ▶ Aloha is the type of Random access protocol
- ▶ **ALOHA**, was developed at the University of Hawaii in early 1970.
- ▶ It was designed for a radio (wireless) LAN, but it can be used on any shared medium.
- ▶ It have two types one is **Pure Aloha** and another is **Slotted Aloha**.
- ▶ There is a potential of **collisions**
- ▶ The **medium is shared** between the stations.
- ▶ When a station **sends data**, another station may attempt to do so at the **same time**.
- ▶ The data from the two stations **collide** and become garbled.

12.1.1 Pure ALOHA

- ▶ The original ALOHA protocol is called ***pure ALOHA***.
- ▶ This is a **simple** but elegant protocol.
- ▶ The idea is that each station sends a frame whenever it has a **frame to send** (multiple access).
- ▶ However, since there is only **one channel to share**, there is the **possibility of collision** between frames from different stations.

Frames in Pure ALOHA



12.1.1 Pure ALOHA

Contd...

- ▶ If collision occurs then **retransmission** frames.
- ▶ The pure ALOHA protocol relies on **acknowledgments** from the receiver.
- ▶ If the acknowledgment does not arrive after a **time-out** period, then retransmission take place.
- ▶ If all these stations try to resend their frames after the time-out, the frames will collide again.
- ▶ After time-out, each station waits a random amount of time (**backoff time T_B**) before resending its frame.
- ▶ This help avoid more collisions.

Procedure for pure ALOHA protocol

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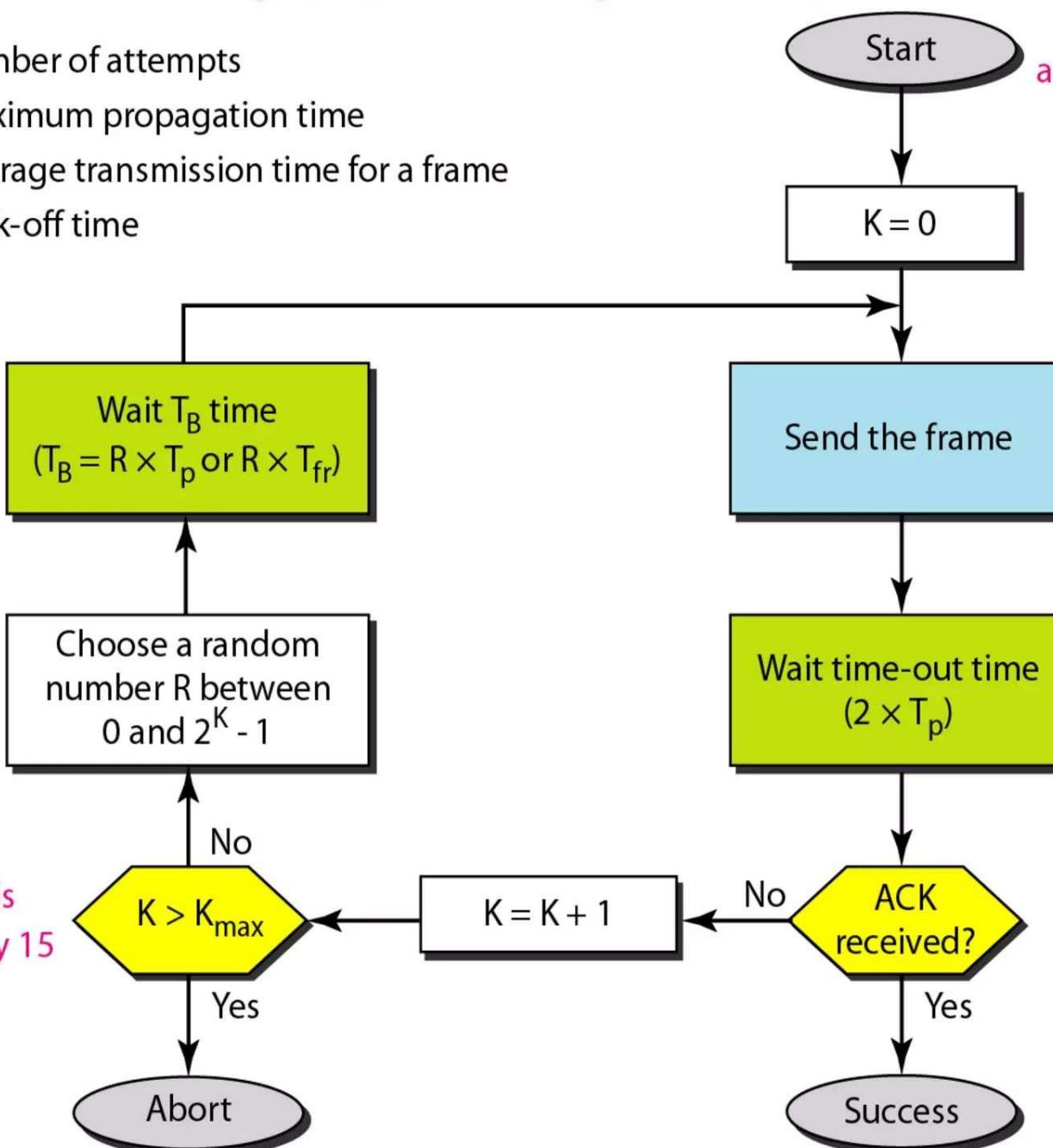
K: Number of attempts

T_p : Maximum propagation time

T_{fr} : Average transmission time for a frame

T_B : Back-off time

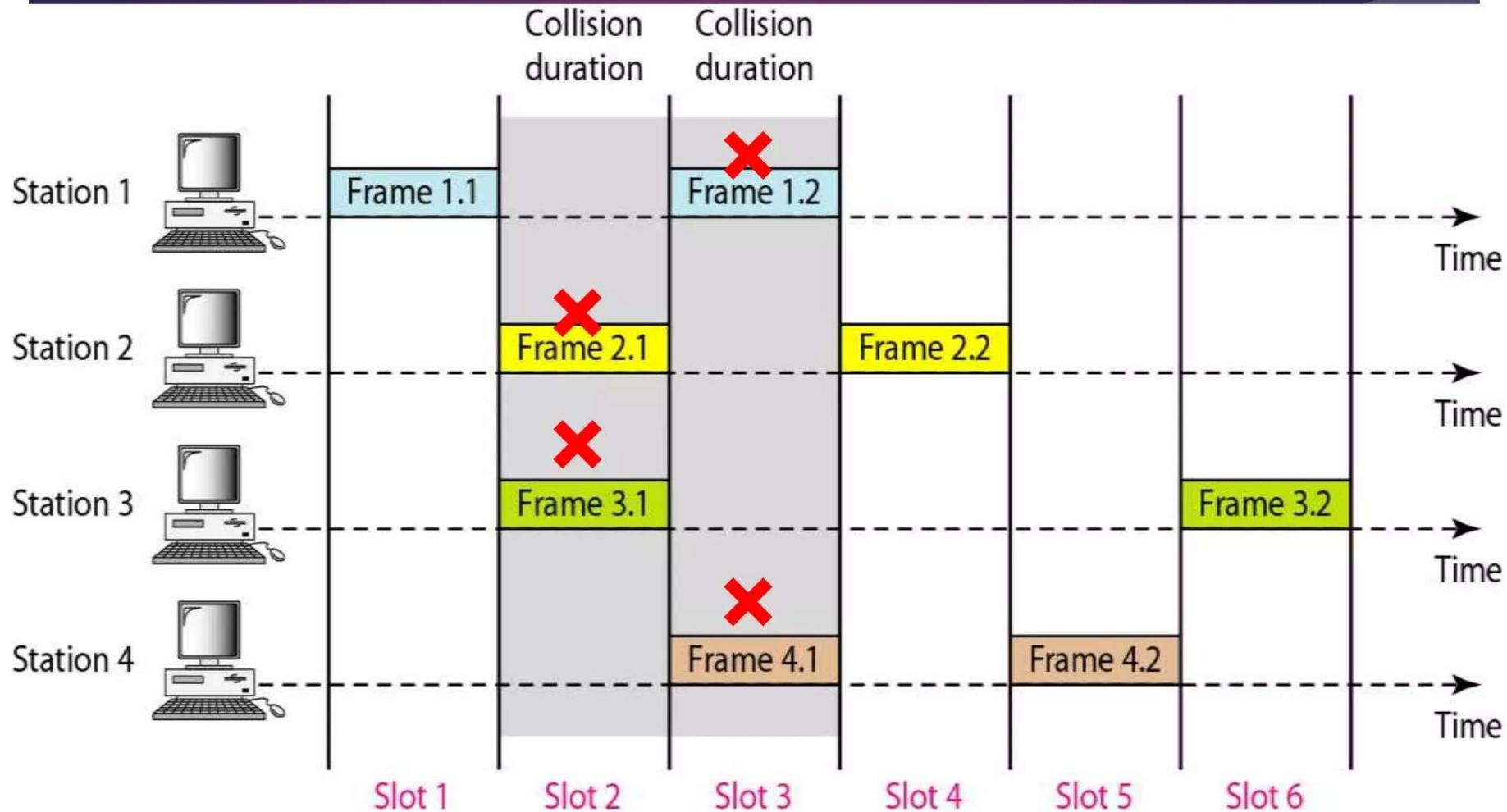
Station has
a frame to send



12.1.1.2 Slotted ALOHA

- ▶ Slotted Aloha divides the time of shared channel into discrete intervals called as **time slots**.
- ▶ Any station can transmit its data in any time slot.
- ▶ The only condition is that station must start its transmission from the beginning of the time slot.
- ▶ If the beginning of the slot is missed, then station has to wait until the beginning of the next time slot.
- ▶ A **collision** may occur if two or more stations try to transmit data at the beginning of the same time slot.
- ▶ Slotted ALOHA was invented to **improve** the efficiency of pure ALOHA.

12.1.1.2 Slotted ALOHA



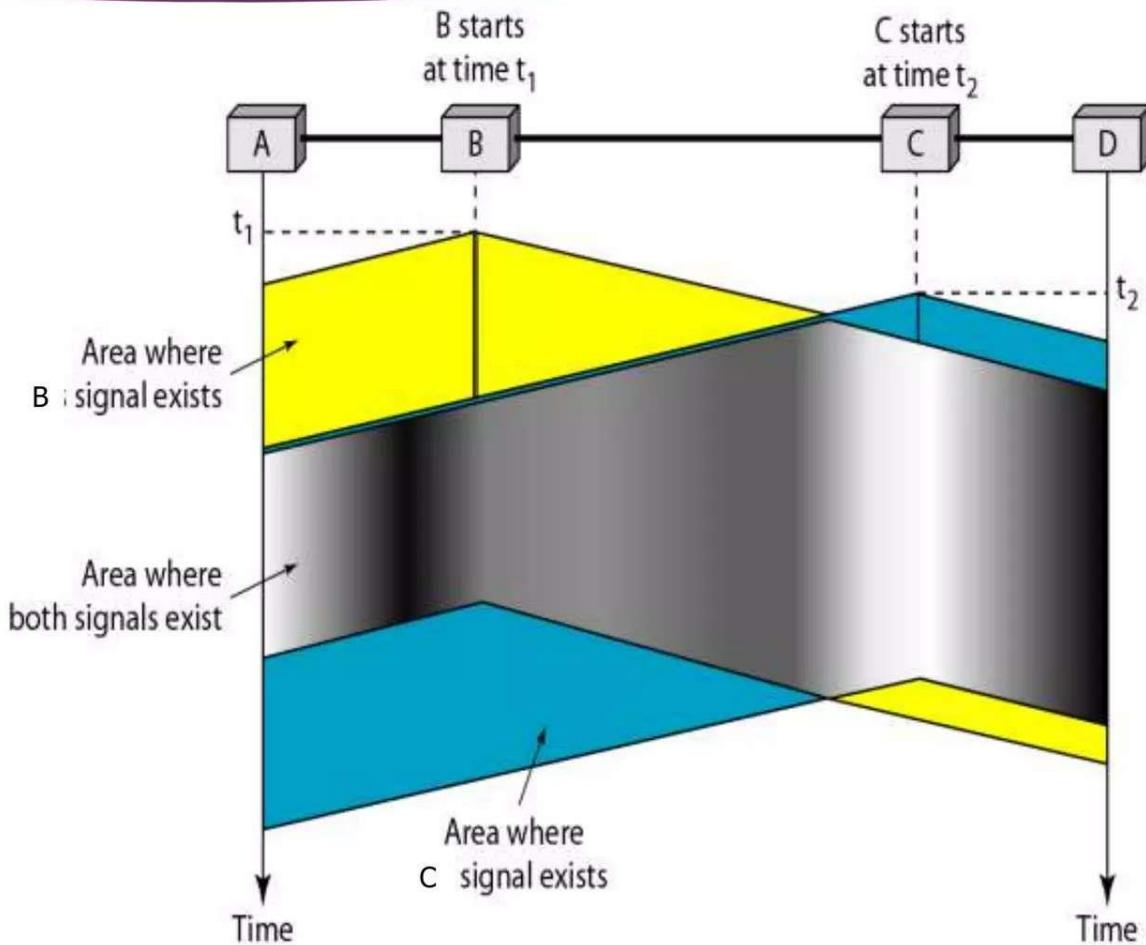
CSMA

12.1.2 CSMA

- ▶ To minimize the chance of collision and to increase the performance
- ▶ Principle of CSMA: “**sense before transmit**” or “**listen before talk**”
- ▶ Carrier busy= **Transmission** is taking place
- ▶ Carrier idle= **No transmission** currently taking place
- ▶ CSMA can **reduce** the possibility of **collision**, but it cannot eliminate it.

12.1.2 Collision in CSMA

- ▶ At time t_1 , station B senses the medium and finds it idle, so it sends a frame.
- ▶ At time t_2 ($t_2 > t_1$), station C senses the medium and finds it idle because, at this time, the first bits from station B have not reached station C.
- ▶ Station C also sends a frame.
- ▶ The two signals collide and both frames are destroyed.

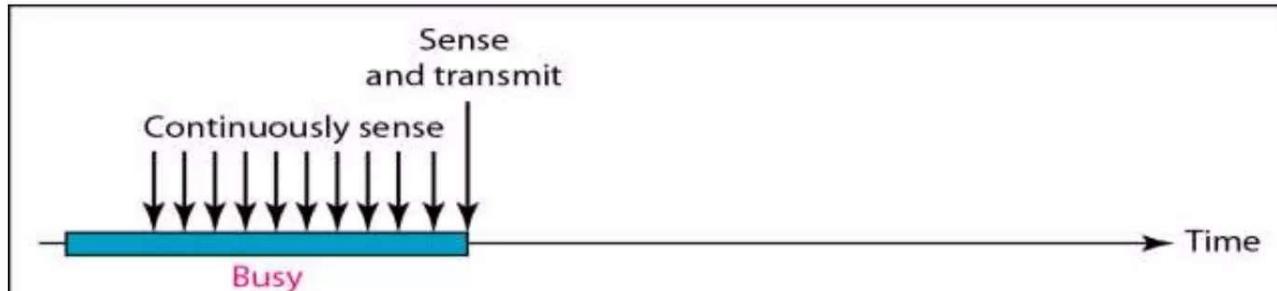


Persistence Methods

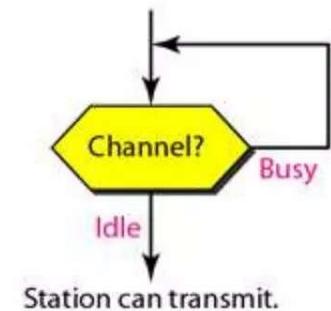
- ▶ What should a station do if the channel is busy?
- ▶ What should a station do if the channel is idle?
- ▶ Three methods have been devised to answer these questions:
 - ▶ **1-persistent method**
 - ▶ **nonpersistent method**
 - ▶ **p -persistent method**

1-Persistent

- ▶ The **1-persistent method** is simple and straightforward.
- ▶ In this method, after the **station finds the line idle**, it sends its frame immediately (**with probability 1**).
- ▶ This method has the **highest chance of collision** because **two or more stations may find the line idle** and send their frames immediately.

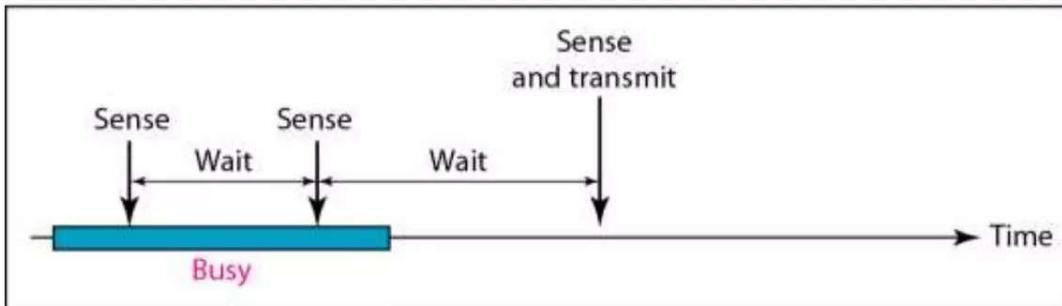


a. 1-persistent

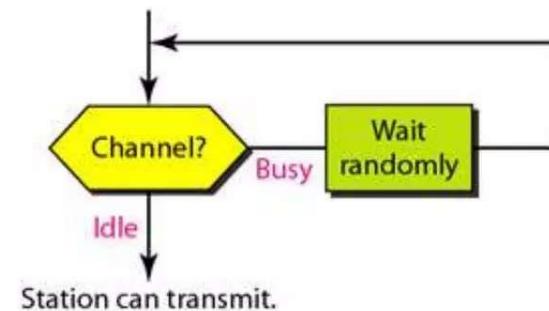


Non-persistent

- ▶ In the *non-persistent method*, a station that has a frame to send senses the line
- ▶ If the line is idle, it sends immediately.
- ▶ If the line is not idle, it waits a **random amount** of time and then senses the line again.
- ▶ The nonpersistent approach reduces the chance of collision

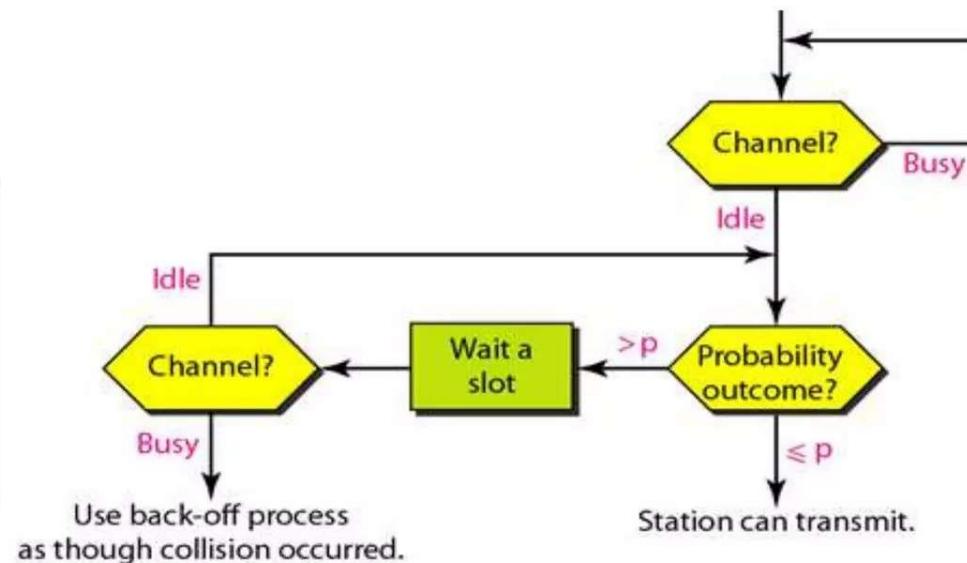
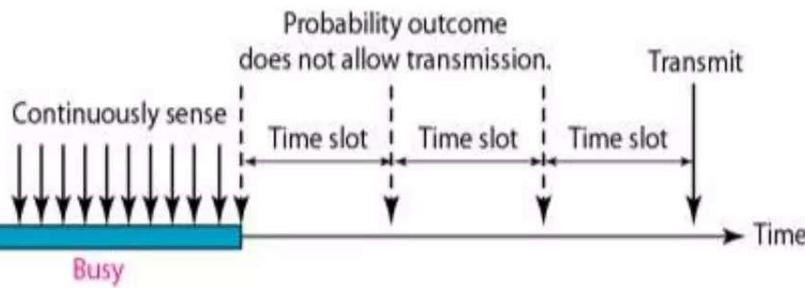


b. Nonpersistent



p-Persistent

- ▶ If the channel has time slots with a slot duration equal to or greater than the maximum propagation time.
- ▶ The p -persistent approach combines the advantages of the other two strategies.
- ▶ It reduces the chance of collision and improves efficiency.

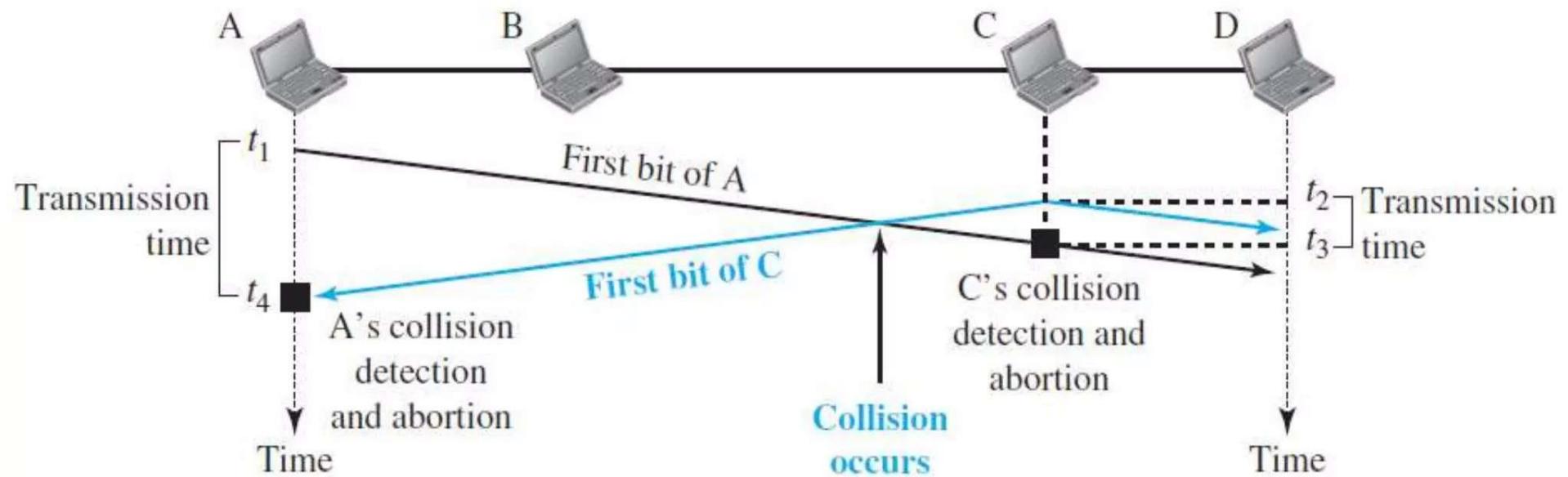


CSMA/CD

12.1.3 CSMA/CD

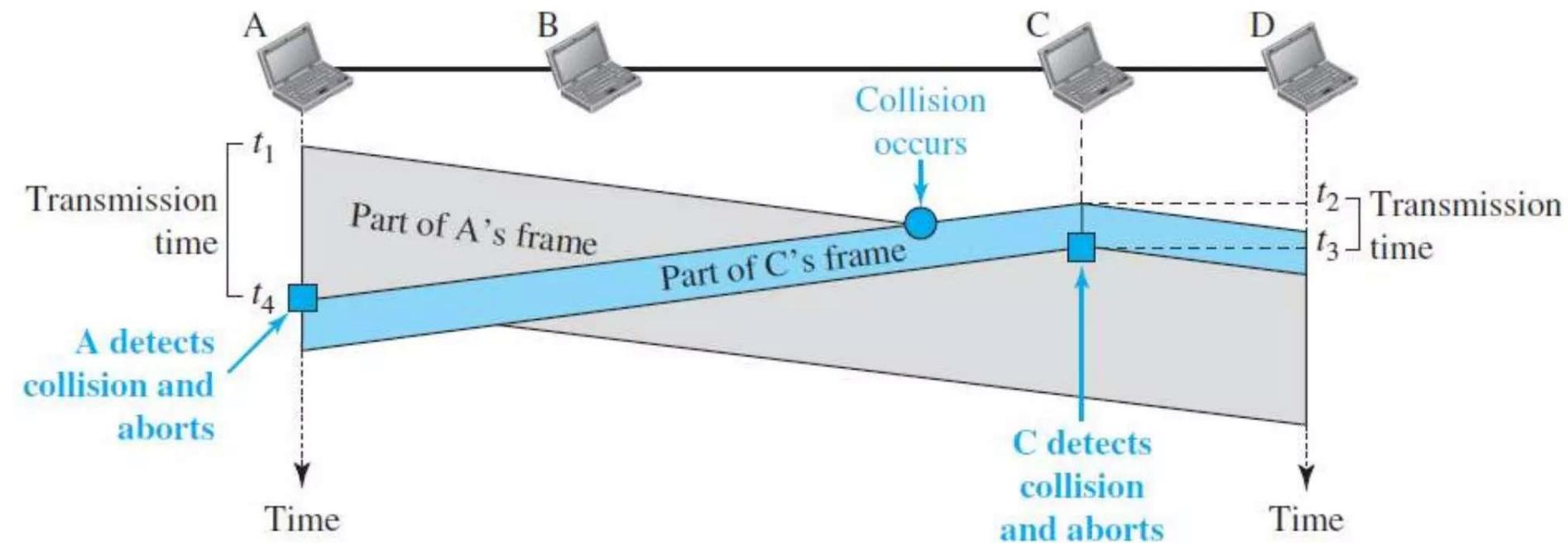
- ▶ Carrier Sense Multiple Access with Collision Detection
- ▶ Station monitors channel while sending a frame
- ▶ If, however, there is a collision, the frame is sent again.
- ▶ Eg. Collision of the first bit in CSMA/CD, stations A and C are involved in the collision.

- ▶ At time t_1 , station A has executed its persistence procedure and starts sending the bits of its frame.
- ▶ At time t_2 , station C has not yet sensed the first bit sent by A.
- ▶ Station C executes its persistence procedure and starts sending the bits in its frame, which propagate both to the left and to the right.
- ▶ The collision occurs sometime after time t_2 .
- ▶ Station C detects a collision at time t_3 when it receives the first bit of A's frame.
- ▶ Station C immediately aborts transmission.
- ▶ Station A detects collision at time t_4 when it receives the first bit of C's frame; it also immediately aborts transmission.
- ▶ Looking at the figure, we see that A transmits for the duration $t_4 - t_1$; C transmits for the duration $t_3 - t_2$.



Collision and abortion in CSMA/CD

Figure 12.12 Collision and abortion in CSMA/CD



CSMA/CD: Flow Diagram

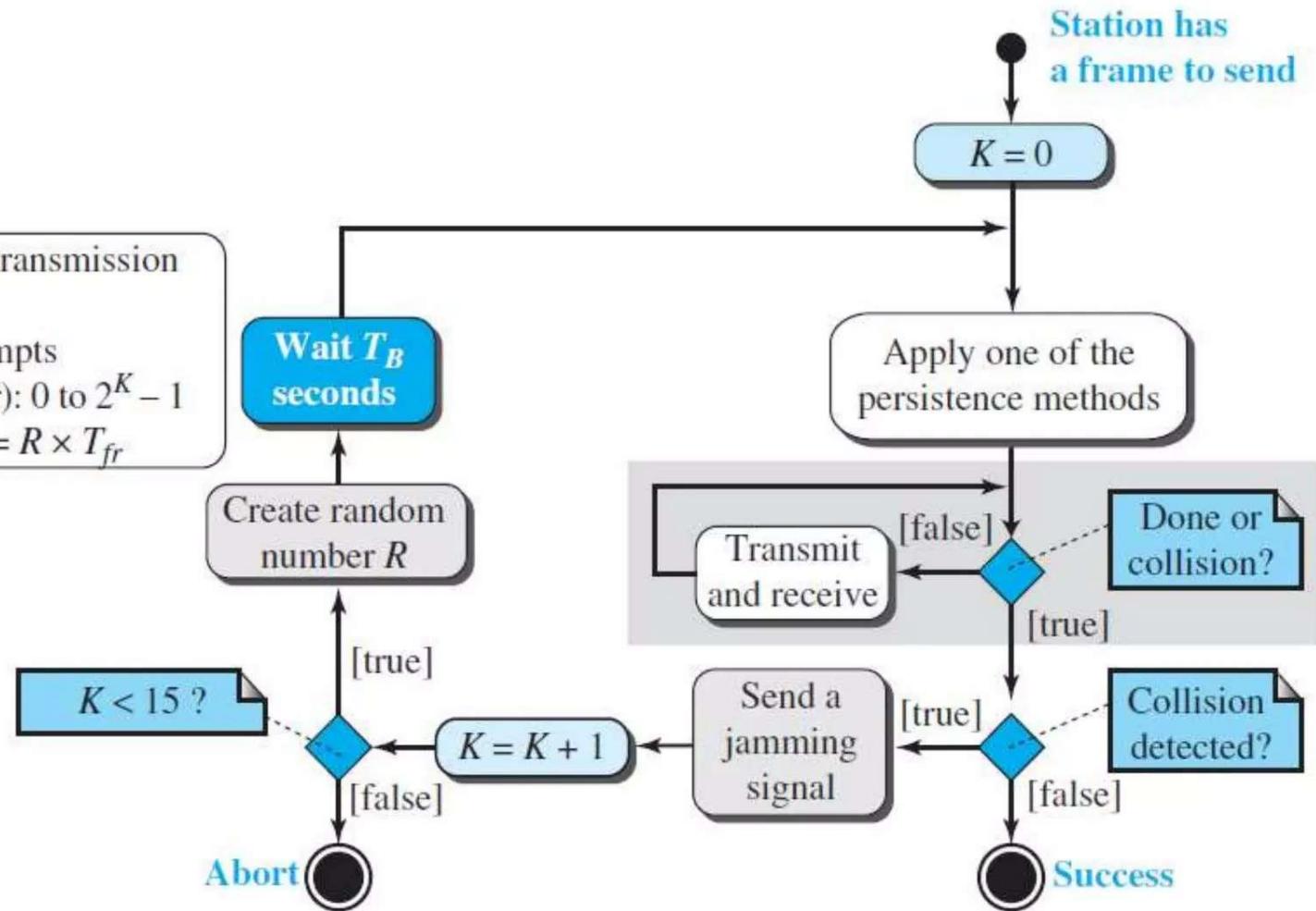
Legend

T_{fr} : Frame average transmission time

K : Number of attempts

R : (random number): 0 to $2^K - 1$

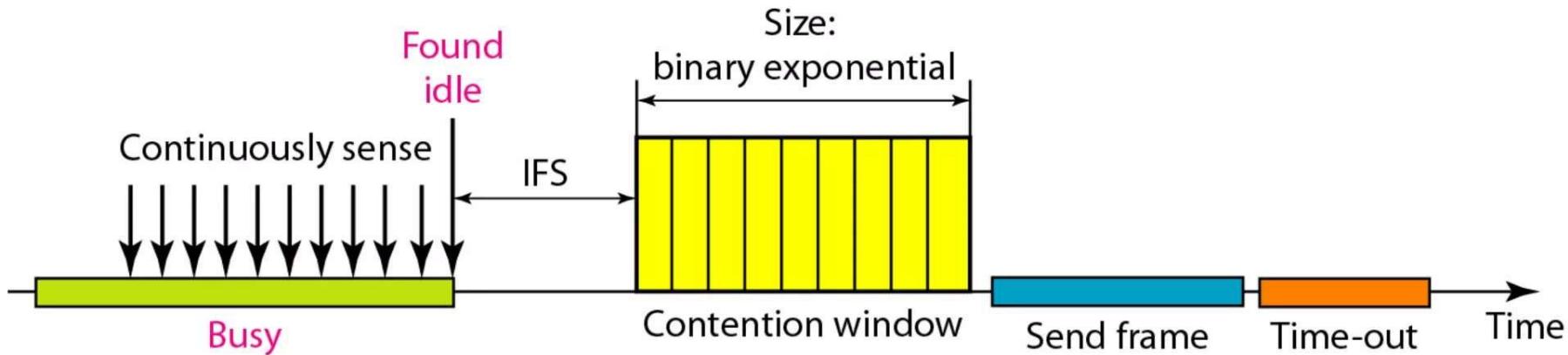
T_B : (Backoff time) = $R \times T_{fr}$



CSMA/CA

12.1.3 CSMA/CA

- ▶ Carrier Sense Multiple Access with Collision Avoidance was invented for **wireless networks**
- ▶ Used in a network where collision cannot be detected
- ▶ Collisions are avoided through the use of CSMA/CA's three strategies:
 - ▶ Interframe space (IFS)
 - ▶ Contention window
 - ▶ Acknowledgments



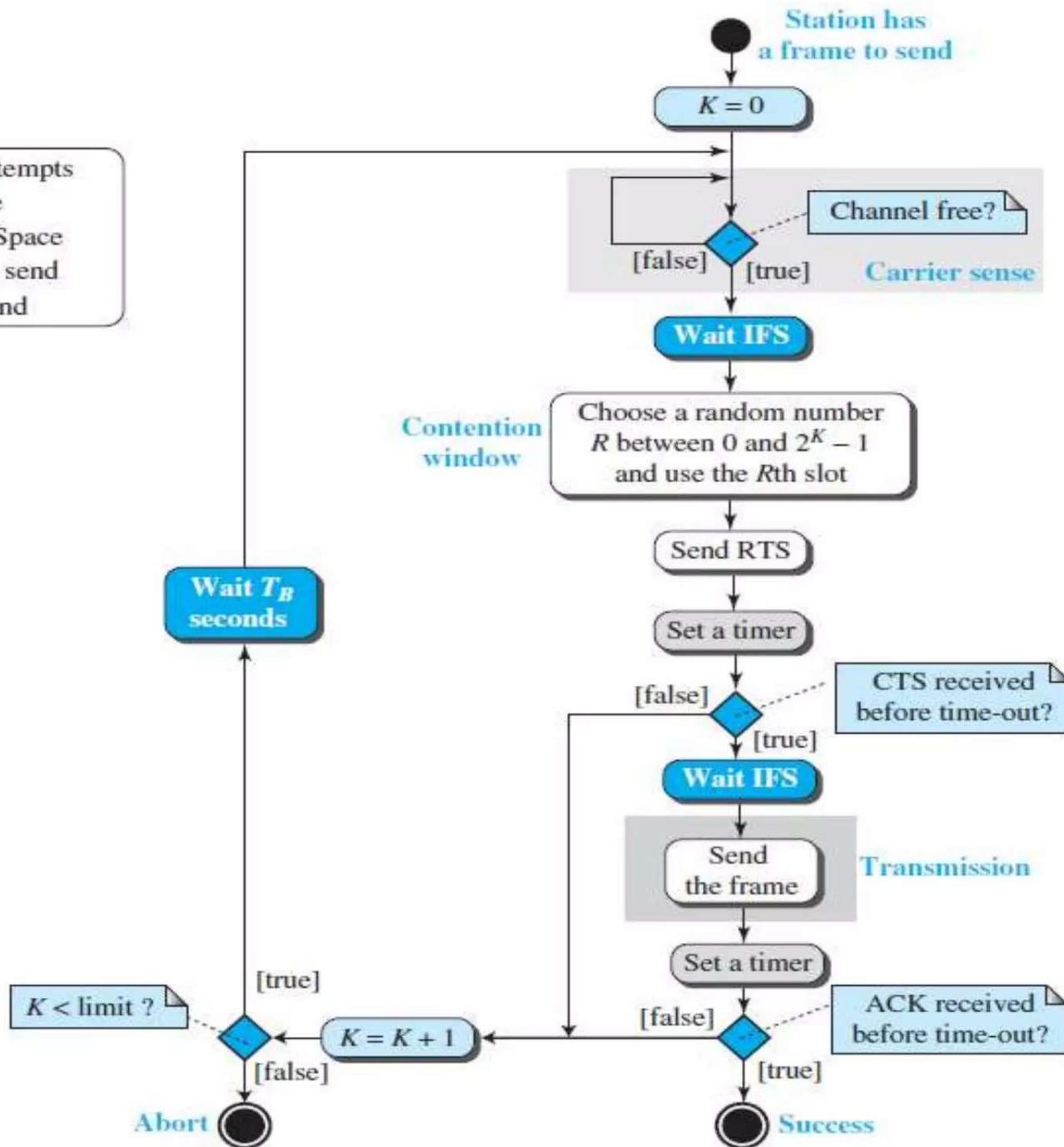
12.1.3 CSMA/CA

Contd...

- ▶ **Interframe space (IFS)**
 - ▶ When an idle channel is found, the station does not send immediately.
 - ▶ It waits for a period of time called the ***interframe space*** or ***IFS***.
- ▶ ***Contention Window***
 - ▶ The **contention window** is an amount of time divided into slots.
 - ▶ if station determine that the channel is free, they wait a random amount of time before they start sending.
 - ▶ This time window doubles with each collision and corresponds to the binary exponential backoff (BEB) that is familiar from CSMA/CD.
- ▶ ***Acknowledgment:***
 - ▶ The positive acknowledgment and the time-out timer can help guarantee that the receiver has received the frame.

Legend

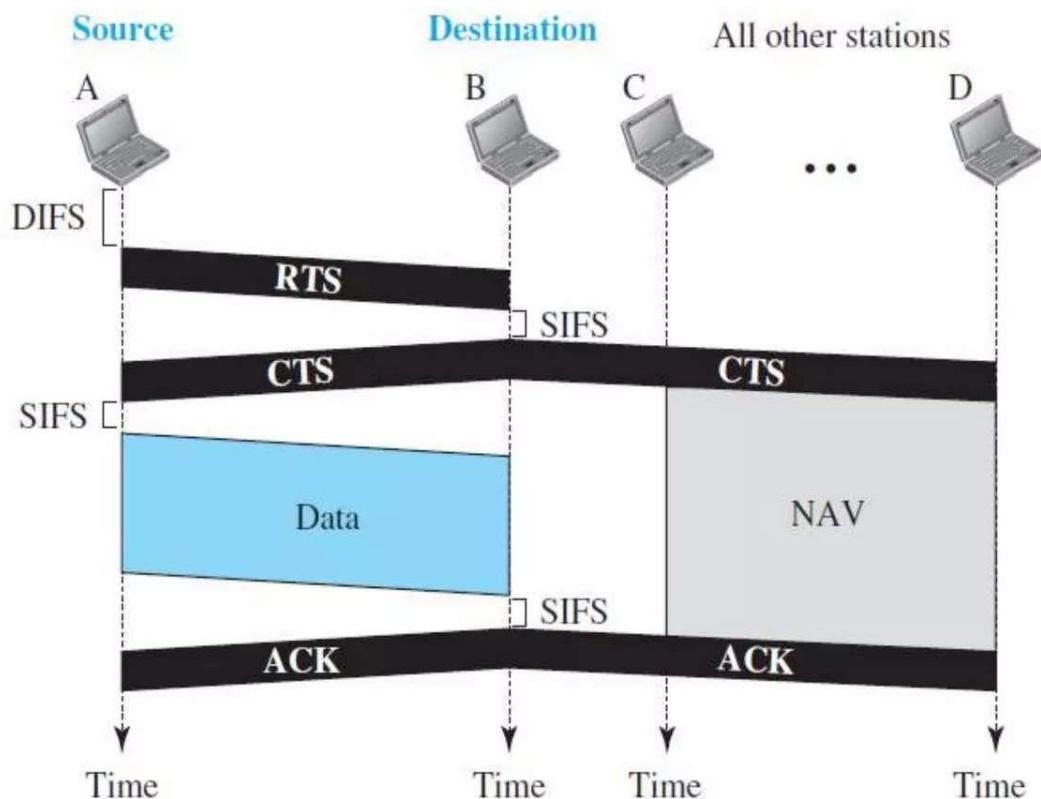
K : Number of attempts
 T_B : Backoff time
IFS: Interframe Space
RTS: Request to send
CTS: Clear to send



CSMA/ CA and NAV

- ▶ **DIFS: DCF interframe space**
- ▶ **RTS: Request to Send**
- ▶ **SIFS: Short interframe space (SIFS)**
- ▶ **NAV: Network Allocation Vector**

CSMA/CA and NAV



Controlled Access

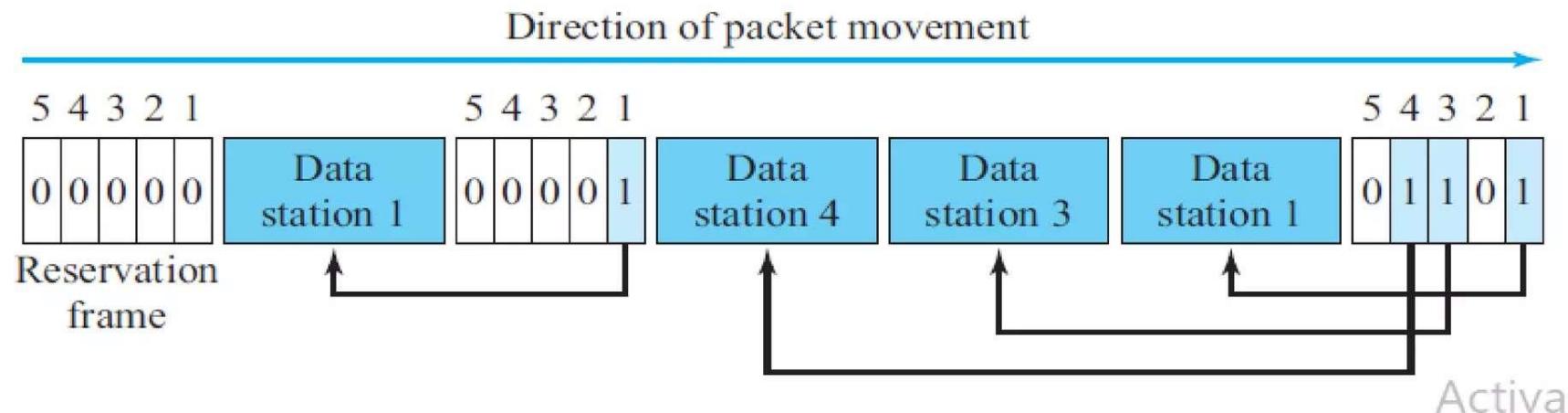


12.2 CONTROLLED ACCESS

- ▶ In **controlled access**, the stations consult one another to find which station has the right to send.
- ▶ A station cannot send unless it has been authorized by other stations.
- ▶ Three common methods:
 - ▶ **Reservation**
 - ▶ **Polling**
 - ▶ **Token passing**

12.2.1 Reservation

- ▶ A station needs to make a **reservation** before sending data.
- ▶ Time is divided into intervals.
- ▶ In each interval, a reservation frame precedes the **data frames** sent in that interval.
- ▶ If there are **N stations** in the system, there are exactly **N reservation minislots** in the reservation frame.



12.2.2 Polling

- ▶ **Polling** works with topologies in which one device is designated as a ***primary station*** and the other devices are ***secondary stations***.
- ▶ **Primary device** is the **initiator** of a session.
- ▶ **All data exchanges must be made through the primary device.**
- ▶ **Primary device controls the link;** the secondary devices follow its **instructions**.

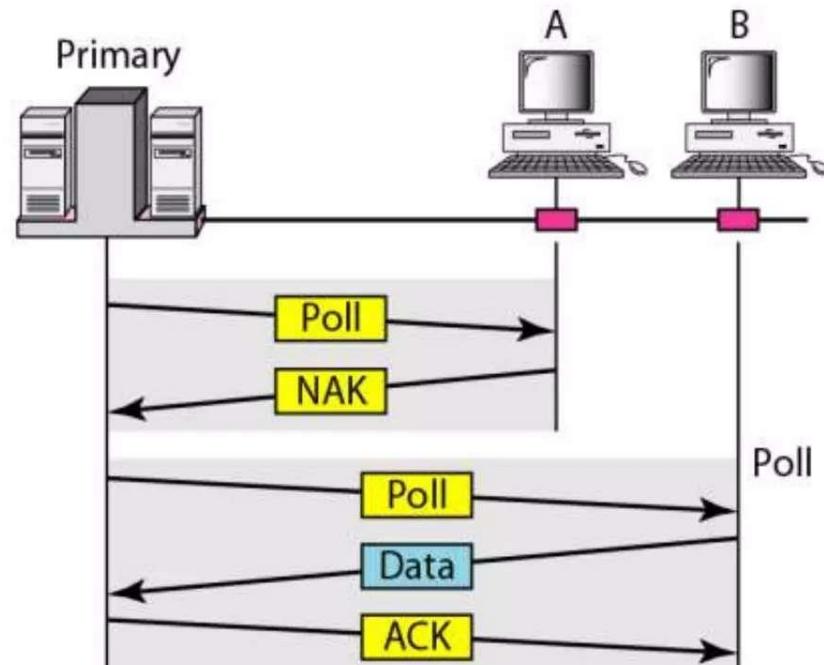
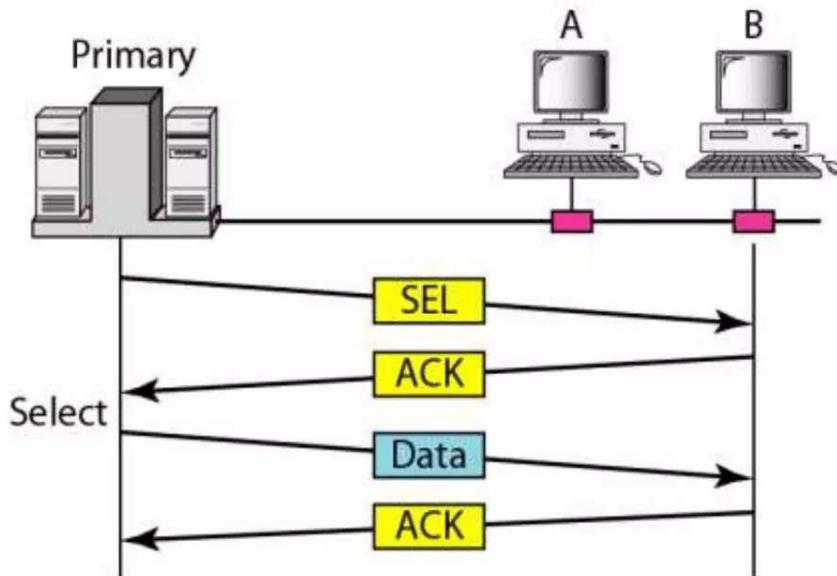
Select and poll functions in polling-access method

▶ Select

- ▶ The **select** function is used whenever the **primary device has something to send**.

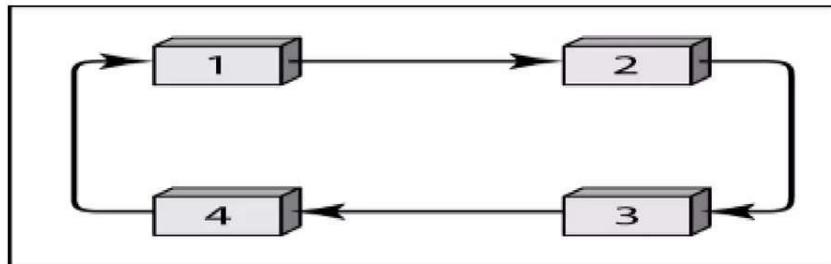
▶ Poll

- ▶ The **poll** function is used by the **primary device to solicit transmissions from the secondary devices**.

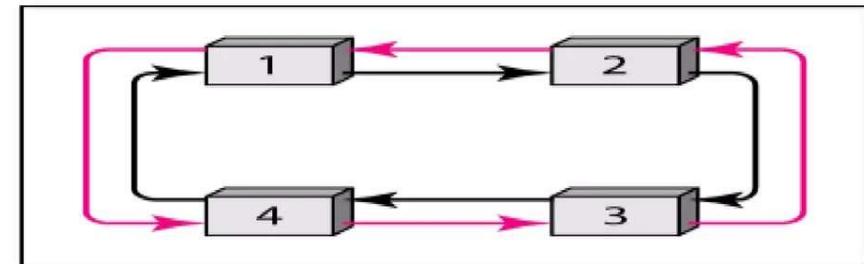


12.2.3 Token Passing

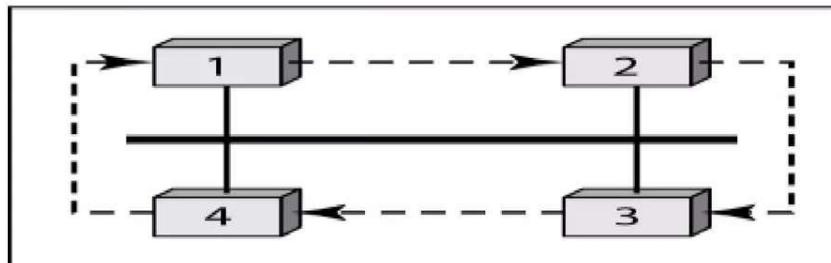
- ▶ The stations in a network are organized in a **logical ring**.
- ▶ For each station, there is a **predecessor** and a **successor**.
- ▶ The **right to this access** has been passed from the **predecessor to the current** station.
- ▶ The right will be passed to the **successor when the current station has no more data to send**.
- ▶ The **RIGHT** passed from by means of special packet called "**TOKEN**".



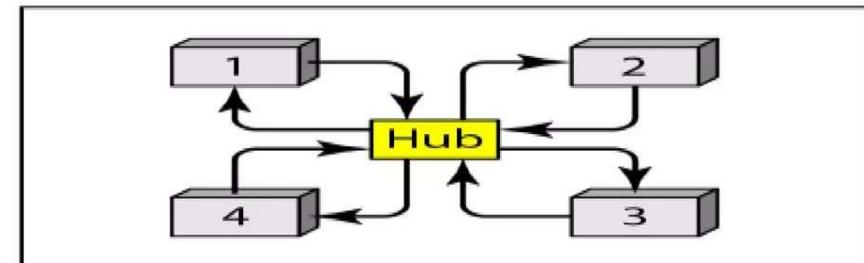
a. Physical ring



b. Dual ring



c. Bus ring



d. Star ring

Channelization

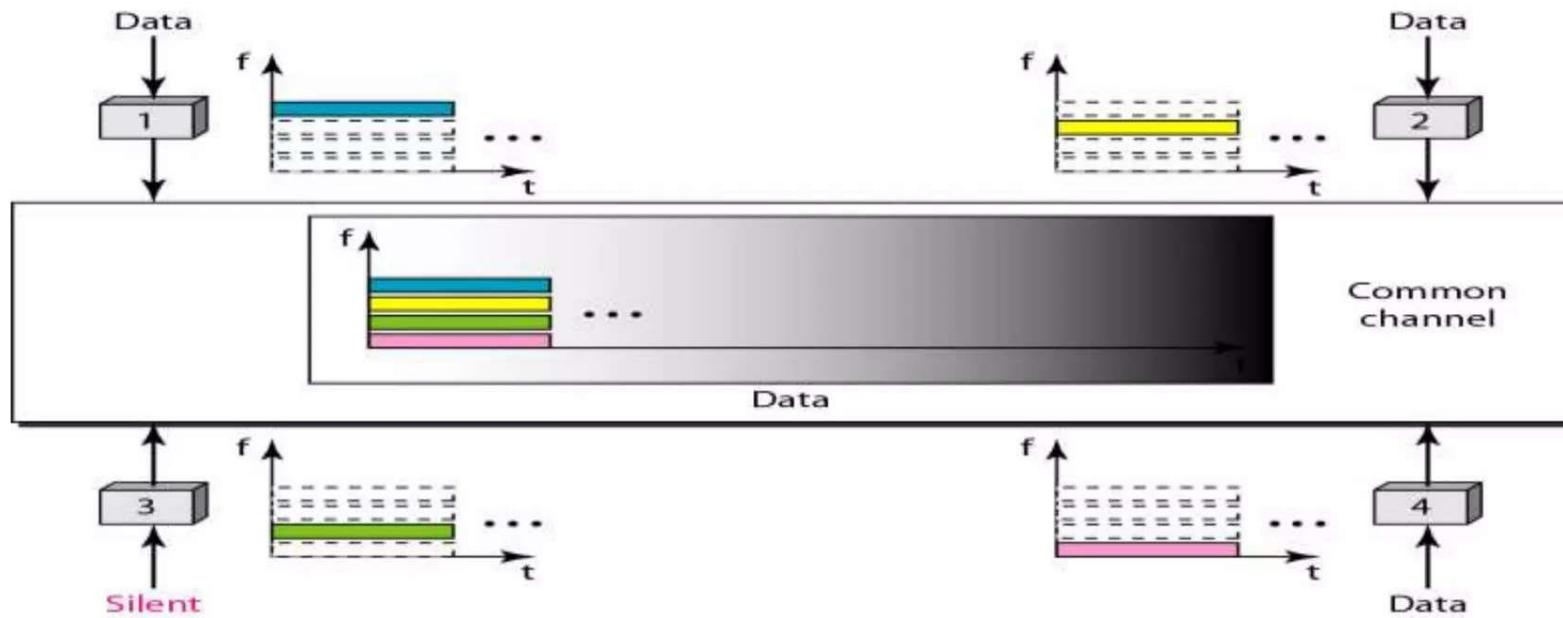


12.3 Channelization

- ▶ **Channelization** is a multiple-access method in which the available bandwidth of a link is shared in **time**, **frequency**, or through **code**, among different stations.
- ▶ Similar to multiplexing
- ▶ Three schemes
 - ▶ **Frequency-Division Multiple Access (FDMA)**
 - ▶ **Time-Division Multiple Access (TDMA)**
 - ▶ **Code-Division Multiple Access (CDMA)**

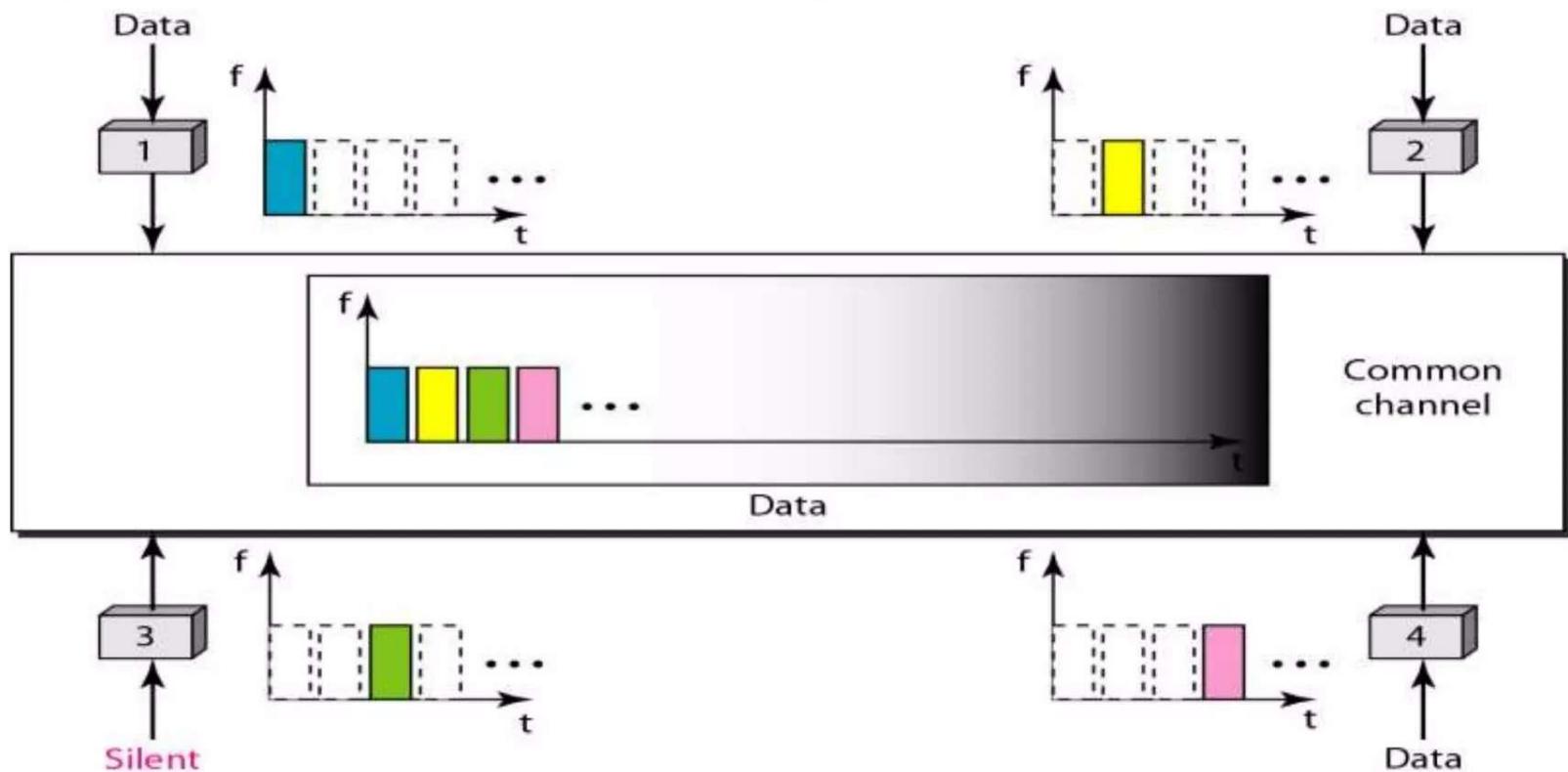
12.3.1 Frequency-Division Multiple Access (FDMA)

- Available bandwidth is divided into frequency bands.
- Each band is reserved for a specific station.
- Each station also uses a bandpass filter to confine the transmitter frequencies.



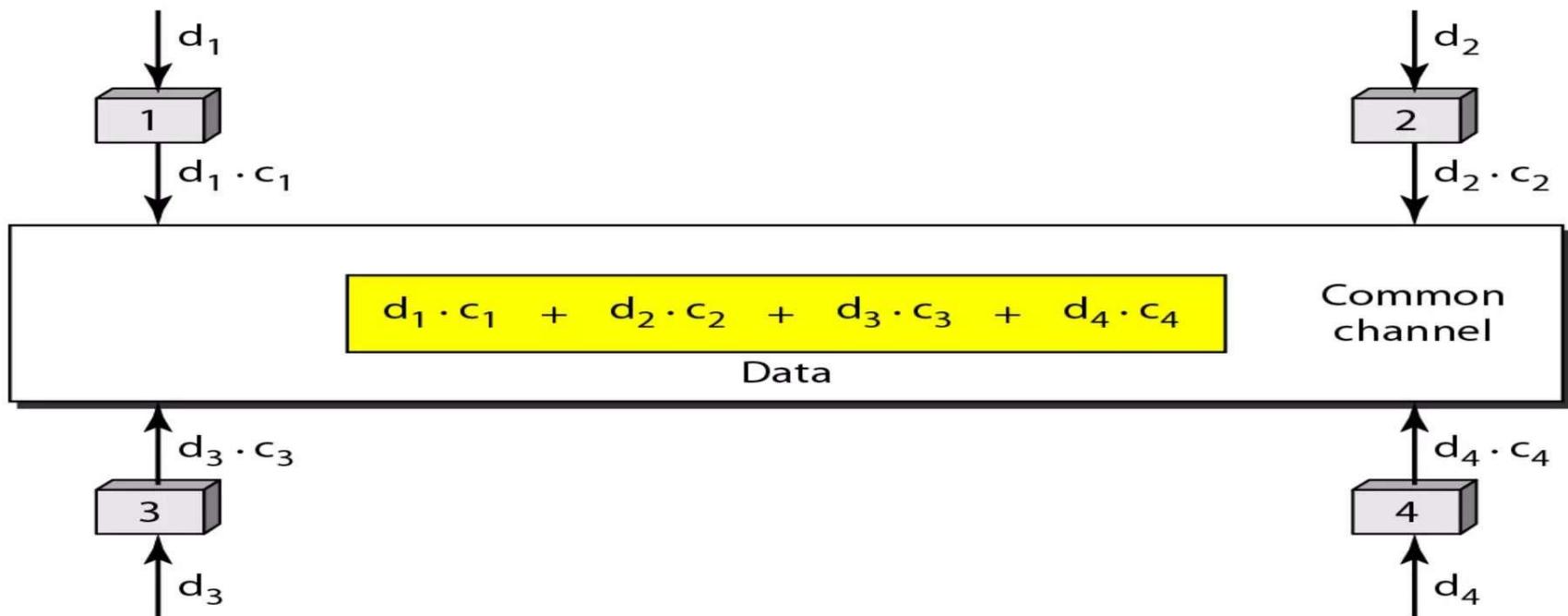
12.3.2 TDMA

- Stations **share the bandwidth** of the channel in time.
- Each station is allocated a **time slot** during which it can send data.



12.3.3 CDMA

- ▶ One channel carries all transmissions at the same time
- ▶ <https://www.youtube.com/watch?v=5pIZGFd-cWc>
- ▶ Each channel is separated by code



CDMA: Chip Sequences

- ▶ Each station is assigned a unique chip sequence

 c_1 $[+1 \ +1 \ +1 \ +1]$ c_2 $[+1 \ -1 \ +1 \ -1]$ c_3 $[+1 \ +1 \ -1 \ -1]$ c_4 $[+1 \ -1 \ -1 \ +1]$

- ▶ Chip sequences are orthogonal vectors
 - ▶ Inner product of any pair must be zero
- ▶ With N stations, sequences must have the following properties:
 - ▶ They are of length N
 - ▶ Their self inner product is always N

CDMA: Bit Representation

Data bit 0 → -1

Data bit 1 → +1

Silence → 0

Transmission in CDMA

