CS 7545: Machine Learning Theory

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Lecture 2: Convex Analysis

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Disclaimer: These notes have not been subjected to the usual scrutiny reserved for formal publications.

2.1 Vector analysis

Definition 2.1 Let $f: \mathbb{R}^n \to \mathbb{R}$ be a differentiable function and $\vec{x} \in \mathbb{R}^n$. The gradient of f at \vec{x} is

$$\nabla f(\vec{x}) = \left(\frac{\partial f}{\partial x_1}(\vec{x}) \quad \dots \quad \frac{\partial f}{\partial x_n}(\vec{x})\right).$$

Remark 2.2 The gradient is correctly represented as a row vector but during analysis and proofs, we may represent it as a column vector to make it clear that the products are matrix vector products.

Definition 2.3 Let $f: \mathbb{R}^n \to \mathbb{R}$ be a twice differentiable function and $\vec{x} \in \mathbb{R}^n$. The **Hessian of** f at \vec{x} is

$$\nabla^2 f(\vec{x}) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} (\vec{x}) & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_n} (\vec{x}) \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} (\vec{x}) & \dots & \frac{\partial^2 f}{\partial x_n^2} (\vec{x}) \end{pmatrix}.$$

Fact 2.4 Let $f: \mathbb{R}^n \to \mathbb{R}$ be a twice differentiable function and $\vec{x} \in \mathbb{R}^n$. Then $\nabla^2 f(\vec{x})$ is a symmetric matrix, because for all $i, j \in [1, n]$, it holds¹

$$\frac{\partial^2 f}{\partial x_i \partial x_j}(\vec{x}) = \frac{\partial^2 f}{\partial x_j \partial x_i}(\vec{x}).$$

2.2 Convexity

Definition 2.5 Let $\mathcal{U} \subseteq \mathbb{R}^n$. The set \mathcal{U} is a **convex** set if

$$\forall \vec{x}, \vec{y} \in \mathcal{U}, \forall t \in [0, 1]: \quad t\vec{x} + (1 - t)\vec{y} \in \mathcal{U},$$

i.e., any line segment connecting two points in \mathcal{U} is in \mathcal{U} .

Definition 2.6 Let $\mathcal{U} \subseteq \mathbb{R}^n$ be a convex set and $f: \mathcal{U} \to \mathbb{R}$. f is **convex** if

$$\forall \vec{x}, \vec{y} \in \mathcal{U}, \forall t \in [0, 1]: f((1 - t)\vec{x} + t\vec{y}) < (1 - t)f(\vec{x}) + tf(\vec{y}),$$

i.e., any line segment connecting two points on the graph of f is above the graph of f.

Claim 2.7 Let $\mathcal{U} \subseteq \mathbb{R}^n$ be a convex set and $f: \mathcal{U} \to \mathbb{R}$ be a differentiable function. Then f is convex if and only if

$$\forall \vec{x}, \vec{y} \in \mathcal{U}: \quad f(\vec{x}) > f(\vec{y}) + \langle \nabla f(\vec{y}), \vec{x} - \vec{y} \rangle,$$

i.e., f is always above its tangents.

¹See Schwarz' theorem.

Proof: Exercise 1.

Notation 2.8 Let $M \in \mathbb{R}^{n \times n}$ be a square matrix. We denote M is positive semi-definite by $M \succeq 0$ and M is positive definite by $M \succ 0$. We denote $M \preceq 0$ if $-M \succeq 0$ and $M \prec 0$ if $-M \succ 0$.

Claim 2.9 Let $\mathcal{U} \subseteq \mathbb{R}^n$ be a convex set and $f: \mathcal{U} \to \mathbb{R}$ be a twice differentiable function. Then f is convex if and only if

$$\forall \vec{x} \in \mathcal{U}, \nabla^2 f(\vec{x}) \succeq 0.$$

Remark 2.10 In order to check if a twice differentiable function $f: \mathbb{R}^n \to \mathbb{R}$ is convex or not at a point $\vec{x} \in \mathbb{R}^n$, it is sometimes easier to check Claim 2.9 than Claim 2.7, because it only requires studying one object: the Hessian matrix $\nabla^2 f(\vec{x})$ (although computing its eigenvalues may be costly).

Definition 2.11 Let $\|\cdot\|$ be a norm on \mathbb{R}^n , $f:\mathbb{R}^n\to\mathbb{R}$, and $c\geq 0$. f is c-Lipschitz with respect to $\|\cdot\|$ if

$$\forall \vec{x}, \vec{y} \in \mathbb{R}^n : |f(\vec{x}) - f(\vec{y})| \le c ||\vec{x} - \vec{y}||.$$
 (2.1)

A Lipschitz function grows at most and at least linearly.

Claim 2.12 A differentiable function $f: \mathbb{R}^n \to \mathbb{R}$ is c-Lipschitz with respect to $\|\cdot\|$ if and only if

$$\forall \vec{x} \in \mathbb{R}^n : \|\nabla f(\vec{x})\|_* \le c$$

where $\|\cdot\|_*$ is the dual norm associated with $\|\cdot\|_*$.

Proof: \implies Suppose that f is c-Lipschitz with respect to $\|\cdot\|$ and let $\vec{x}, \vec{u} \in \mathbb{R}^n$. The quantity $\langle \nabla f(\vec{x}), \vec{u} \rangle$ is the directional derivative of f at \vec{x} in the direction of \vec{u} . We have

$$\begin{split} \langle \nabla f(\vec{x}), \vec{u} \rangle &= \lim_{\substack{h \to 0 \\ h > 0}} \frac{f(\vec{x} + h\vec{u}) - f(\vec{x})}{h} \\ &\leq \lim_{\substack{h \to 0 \\ h > 0}} \frac{c\|\vec{x} + h\vec{u} - \vec{x}\|}{h} \quad \text{by Equation (2.1)} \\ &= c \lim_{\substack{h \to 0 \\ h > 0}} \frac{h\|\vec{u}\|}{h} = c\|\vec{u}\| \end{split}$$

thus

$$\|\nabla f(\vec{x})\|_* = \sup_{\|u\| \le 1} \langle \nabla f(\vec{x}), \vec{u} \rangle \le \sup_{\|u\| \le 1} c\|\vec{u}\| = c.$$

Therefore,

$$\forall \vec{x} \in \mathbb{R}^n : \|\nabla f(\vec{x})\|_* \le c.$$

 \sqsubseteq Let $\|\cdot\|$ be a norm on \mathbb{R}^n and $c \geq 0$, and suppose that $\|\nabla f(\vec{x})\|_* \leq c$ for all $\vec{x} \in \mathbb{R}^n$. By the mean value theorem, there exists $t \in [0,1]$ such that

$$f(\vec{x}) = f(\vec{y}) + \langle \nabla f(\vec{z}), \vec{x} - \vec{y} \rangle,$$

where $z = (1 - t)\vec{x} + t\vec{y}$. By Hölder's inequality, we conclude that

$$\begin{aligned} |f(\vec{x}) - f(\vec{y})| &= |\langle \nabla f(\vec{z}), \vec{x} - \vec{y} \rangle| \\ &\leq ||\nabla f(\vec{z})||_* ||\vec{x} - \vec{y}|| \\ &\leq c||\vec{x} - \vec{y}||. \end{aligned}$$

Therefore, f is c-Lipschitz with respect to $\|\cdot\|$.

Theorem 2.13 (Jensen's inequality) Let $\mathcal{U} \subseteq \mathbb{R}^n$ be a convex set, $f: \mathcal{U} \to \mathbb{R}$ be a convex function, and X be a random variable on \mathcal{U} . Then

$$f(\mathbb{E}[X]) \le \mathbb{E}[f(X)].$$

Properties 2.14

- 1. f convex, g convex $\Rightarrow f + g$ convex.
- 2. $\alpha \geq 0$, f convex $\Rightarrow \alpha f$ convex.
- 3. f convex, g convex $\Rightarrow h := \max\{f, g\}$ convex.
- 4. $g(\vec{x}, \vec{y})$ jointly convex in $\vec{x}, \vec{y} \Rightarrow f(\vec{x}) \coloneqq \inf_{\vec{y}} g(\vec{x}, \vec{y})$ is convex.

Definition 2.15 Let $\mathcal{U} \subseteq \mathbb{R}^n$ be a convex set and $f: \mathcal{U} \to \mathbb{R}$. f is **concave** if -f is convex.

Example 2.16 log is a concave function.

Theorem 2.17 (Young's inequality) Let p, q > 1 be such that $\frac{1}{p} + \frac{1}{q} = 1$. Then

$$\forall a, b > 0: \quad ab \le \frac{a^p}{p} + \frac{b^q}{q}.$$

Proof: Let a, b > 0. By Jensen's inequality applied to the convex function $-\log$,

$$\log(ab) = \log(a) + \log(b)$$

$$= \frac{p}{p}\log(a) + \frac{q}{q}\log(b)$$

$$= \frac{1}{p}\log(a^p) + \frac{1}{q}\log(b^q)$$

$$\leq \log\left(\frac{1}{p}a^p + \frac{1}{q}b^q\right).$$

Therefore, by applying the monotonically increasing function exp to both sides, we obtain

$$ab \le \frac{a^p}{p} + \frac{b^q}{q}.$$

Definition 2.18 Let $f: dom(f) \to \mathbb{R}$ be a differentiable function and $\alpha > 0$. f is α -strongly convex if

$$\forall \vec{x}, \vec{y} \in \text{dom}(f): \quad f(\vec{x}) \ge f(\vec{y}) + \langle \nabla f(\vec{y}), \vec{x} - \vec{y} \rangle + \frac{\alpha}{2} ||\vec{x} - \vec{y}||^2.$$

A strongly convex function grows at least quadratically.

Claim 2.19 Let $f : dom(f) \to \mathbb{R}$ be a twice differentiable function. Then f is α -strongly convex if and only if

$$\forall \vec{x} \in \text{dom}(f) : \nabla^2 f(\vec{x}) - \alpha I \succeq 0.$$

Definition 2.20 Let $f: dom(f) \to \mathbb{R}$ be a differentiable function and $\alpha > 0$. f is α -smooth if

$$\forall \vec{x}, \vec{y} \in \mathrm{dom}(f): \quad f(\vec{x}) \leq f(\vec{y}) + \langle \nabla f(\vec{y}), \vec{x} - \vec{y} \rangle + \frac{\alpha}{2} \|\vec{x} - \vec{y}\|^2.$$

A smooth function grows at most quadratically.

Claim 2.21 Let $f: dom(f) \to \mathbb{R}$ be a twice differentiable function. Then f is α -smooth if and only if

$$\forall \vec{x} \in \text{dom}(f) : \nabla^2 f(\vec{x}) - \alpha I \leq 0.$$

Example 2.22 Let $M \in \mathbb{R}^{n \times n}$ be a symmetric positive definite matrix and $f(\vec{x}) = \frac{1}{2}\vec{x}^{\top}M\vec{x}$. Denote λ_{\min} and λ_{\max} the smallest and largest eigenvalues of M respectively. Then f is λ_{\min} -strongly convex and λ_{\max} -smooth. Note that $\nabla f(\vec{x}) = \vec{x}^{\top}M$ (see Remark 2.2) and $\nabla^2 f(\vec{x}) = M$ for all $\vec{x} \in \mathbb{R}^n$.

2.3 Bregman divergence

Definition 2.23 Let $f: \mathcal{U} \to \mathbb{R}$ be a convex differentiable function and $\vec{x}, \vec{y} \in \mathcal{U}$. The **Bregman divergence** of f from \vec{x} to \vec{y} is

$$D_f(\vec{x}, \vec{y}) := f(\vec{x}) - f(\vec{y}) - \langle \nabla f(\vec{y}), \vec{x} - \vec{y} \rangle.$$

It measures the distance at \vec{x} between the graph of f and its tangent at \vec{y} , i.e. the distance between $f(\vec{x})$ and $f(\vec{y}) + \langle \nabla f(\vec{y}), \vec{x} - \vec{y} \rangle$.

Example 2.24

1. Let $f(\vec{x}) = \frac{1}{2} ||\vec{x}||_2^2$. Then

$$\forall \vec{x}, \vec{y} \in \mathbb{R}^n : D_f(\vec{x}, \vec{y}) = \frac{1}{2} ||\vec{x} - \vec{y}||_2^2.$$

Note that this is the only situation where the Bregman divergence is quadratic (see Fact 2.25).

2. Let $\Delta^n = \{\vec{p} \in \mathbb{R}^n \mid \sum_{i=1}^n p_i = 1, p_i \geq 0\}$ denote the unit simplex in dimension n and $f(\vec{p}) = \sum_{i=1}^n p_i \log p_i$ denote the entropy function, with the convention $0 \log 0 = 0$. Then

$$\forall \vec{p}, \vec{q} \in \Delta^n : \quad D_f(\vec{p}, \vec{q}) = \sum_{i=1}^n p_i \log \frac{p_i}{q_i} =: \mathrm{KL}(\vec{p} \parallel \vec{q}),$$

where KL is the Kullback-Leibler divergence.

Fact 2.25 Let $f: dom(f) \subseteq \mathbb{R}^n \to \mathbb{R}$ be a convex differentiable function. Then

$$(\forall \vec{x}, \vec{y} \in \text{dom}(f) : D_f(\vec{x}, \vec{y}) = D_f(\vec{y}, \vec{x})) \Leftrightarrow (f \text{ is quadratic}).$$