

## Final Project One Page Report

### Current Strategy

In the current code, the focus is on the implementation of General Matrix-Matrix Multiplication (GEMM) on GPU and parallelization of the code by MPI so the code can run on several nodes.

In the first version of GEMM, a naïve approach using 1D blocks was implemented. If the GEMM operation is expressed as  $D = \alpha * A * B + \beta * C$ , then each thread of the 1D blocks is responsible for the computation of one element in matrix D. It is found that the speed of this 1D block approach for computing GEMM is much slower than that by using CPU with the Armadillo library. This is because in multiplying A by B, we have to access elements along rows of A and columns of B. However, since matrices are in column-major order, the reads in A is not coalesced and each row/column of B is large so there is no good reuse of cache. Therefore, to better reuse data loaded into cache, an improved approach of using 2D blocks is implemented. In the 2D block approach, each thread is still responsible for one thread but the speed of GEMM increases a lot because of the reuse of data loaded into cache in each block.

For the MPI implementation, the input X is first scattered to each node evenly before the iteration. At the end of each iteration,  $\Delta W$  and  $\Delta b$  computed from different nodes are summed up by using `MPI_Allreduce()`. Then, each node updates the network parameters by using the reduced  $\Delta W$  and  $\Delta b$ .

### Intended Optimizations

A better GEMM should be implemented instead of using the naïve 2D block approach because that approach uses global memory that resides in device memory which is slower than shared memory in accessing data. Shared memory has to be used with 2D blocks. Each block compute a sub-matrix of the output matrix. A loop is used to loop over blocks of matrices A and B. In each loop, sub-blocks of matrices A and B are loaded into shared memory and then each thread in the block loop along the sub-blocks of A and B to compute one element of D.

To further optimize the code, the data sent over the PCI express bus should be minimized. So far, only GEMM part of `feedforward()` and `backprop()` is changed to the GPU version and data such as matrices X and W is sent to GPU repeatedly between successive GEMM processes. This kind of communication should be minimized by implementing the `feedforward()` and `backprop()` on GPU entirely so data on GPU can be reused for GEMM and other operations like sigmoid and softmax.