

# Sundial Generator: basic concept

Michele Marro

July 2019

## 1 Introduction

Sun position in cartesian coordinates in the reference system  $(\mathbf{S}, \mathbf{E}, \mathbf{Z})$  is  $\mathbf{s} = (s_S, s_E, s_Z)$  are [Spr07]:

$$\begin{aligned}\mathbf{s} = & -(\sin \delta \cos \phi - \cos \delta \sin \phi \cos \omega)\mathbf{S} \\ & - \cos \delta \sin \omega \mathbf{E} \\ & + (\cos \delta \cos \phi \cos \omega + \sin \delta \sin \phi)\mathbf{Z}\end{aligned}\tag{1}$$

where  $\delta$  is the declination angle of the sun,  $\phi$  is the latitude of the considered location and  $\omega$  is the local time express as:

$$\omega = 15^\circ(\text{hour} - 12)\tag{2}$$

In the same reference system, we can define the normal of the wall  $\mathbf{n}$ , where  $\mathbf{n} = (n_S, n_E, n_Z)$ , via angle  $\alpha$  and angle  $\beta$  as depicted in figure below. In particular, angle  $\alpha$  is the angle between  $\mathbf{n}$  and  $\mathbf{Z}$  (i.e.,  $\alpha = \arccos \mathbf{n} \cdot \mathbf{Z}$ ), while angle  $\beta$  is the angle between  $\mathbf{S}$  and the projections of  $\mathbf{n}$  onto the plane specified by the two vectors  $\mathbf{S}$  and  $\mathbf{E}$ , that can be defined as  $\mathbf{n}_{SE}$ .

Now we can express  $\mathbf{s}$  in the reference system of the wall. To do so, we can apply two rotations. The first rotation is around the  $\mathbf{Z}$  to align  $\mathbf{S}$  with  $\mathbf{n}_{SE}$ . The second rotation is around  $\mathbf{E}$  in order to align  $\mathbf{Z}$  with  $\mathbf{n}$ .

Rotation around  $\mathbf{Z}$  is:

$$R_Z(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}\tag{3}$$

Rotation around  $\mathbf{E}$  is:

$$R_E(\theta) = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}\tag{4}$$

The vector  $\mathbf{s}$  in the basis of the reference system of the wall is renamed as  $\mathbf{s}'$  and will be:

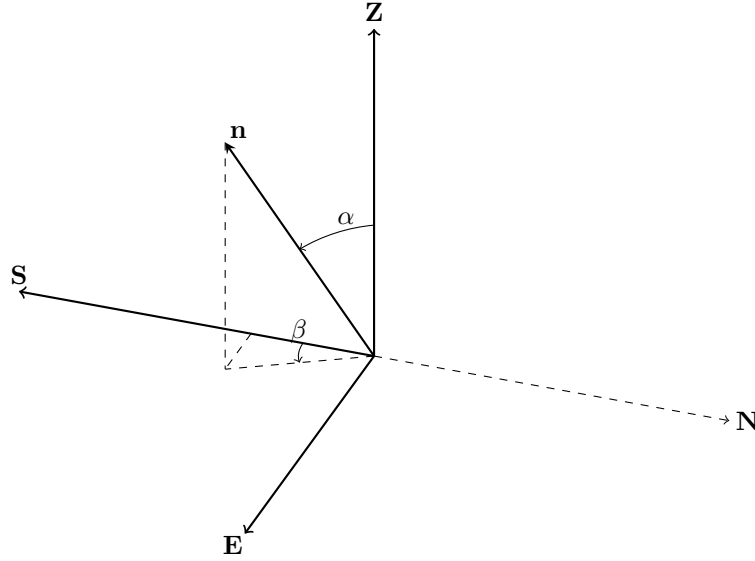
$$\mathbf{s}' = R_E^{-1}(\alpha)[R_Z^{-1}(\beta)\mathbf{s}^T] \quad (5)$$

Explicitly:

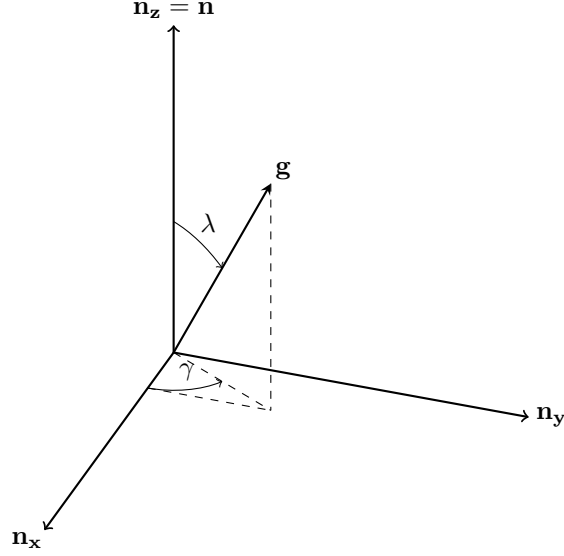
$$\begin{aligned} \mathbf{s}' = & \left[ -((\sin \delta \cos \phi - \sin \phi \cos \delta \cos \omega) \cos \beta + \sin \beta \sin \omega \cos \delta) \cos \alpha \right. \\ & \left. -(\sin \delta \sin \phi + \cos \delta \cos \omega \cos \phi) \sin \alpha \right] \mathbf{n}_x \\ & + \left[ (\sin \delta \cos \phi - \sin \phi \cos \delta \cos \omega) \sin \beta - \sin \omega \cos \beta \cos \delta \right] \mathbf{n}_y \\ & + \left[ -((\sin \delta \cos \phi - \sin \phi \cos \delta \cos \omega) \cos \beta + \sin \beta \sin \omega \cos \delta) \sin \alpha \right. \\ & \left. +(\sin \delta \sin \phi + \cos \delta \cos \omega \cos \phi) \cos \alpha \right] \mathbf{n}_z \end{aligned} \quad (6)$$

We can rewrite this equation using the notation of  $\mathbf{s}$  as simply:

$$\begin{aligned} \mathbf{s}' = & \left[ -(s_S \cos \beta + s_E \sin \beta) \cos \alpha \right. \\ & \left. -s_Z \sin \alpha \right] \mathbf{n}_x \\ & + \left[ s_S \sin \beta - s_E \cos \beta \right] \mathbf{n}_y \\ & + \left[ -(s_S \cos \beta + s_E \sin \beta) \sin \alpha \right. \\ & \left. +s_Z \cos \alpha \right] \mathbf{n}_z \end{aligned} \quad (7)$$



Now that we have  $\mathbf{s}'$  we can define the gnomon vector  $\mathbf{g}$  angles as depicted in figure below. In details, the angle  $\lambda$  is the angle between the wall normal  $\mathbf{n}$ , or  $\mathbf{n}_z$  and the gnomon  $\mathbf{g}$ , while  $\gamma$  is the angle between  $\mathbf{n}_x$  and the projection of the gnomon onto the plane  $\mathbf{n}_x \mathbf{n}_y$ .



Now we can express the vector  $\mathbf{s}$  in parametric form passing from the extreme point of  $\mathbf{g} = h(g_x, g_y, g_z) = (\sin \lambda \cos \gamma, \sin \lambda \sin \gamma, \cos \lambda)$ , where  $h$  is the gnomon length. The intersection of  $\mathbf{s}$ , when  $\mathbf{s} \cdot \mathbf{g} > 0$  is actually the shadow of the gnomon projected onto the plane.

## References

- [Spr07] Alistair B. Sproul. Derivation of the solar geometric relationships using vector analysis. *Renewable Energy 2007-jun vol. 32 iss. 7*, 32, jun 2007.