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Linear Systems and Matrix Equations – Bartels Stewart Algorithm.

We want to compute the solution X of the Lyapunov equation

$$AX + XA^T = W, \quad A \in \mathbb{R}^{n \times n}, \quad W = W^T \in \mathbb{R}^{n \times n}.$$
 (1)

Algorithmus 1 Bartels-Stewart (complex)

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Input: A, W \in \mathbb{C}^{n \times n}, W = W^H

Output: X = X^H solving (1)

1: Compute T = Q^H A Q with QR-algorithm

2: if diag (T) \cap \text{diag}(-T) \neq \emptyset then

3: STOP (no unique solution)

4: end if

5: \begin{bmatrix} W_1 & W_2 \\ W_2^H & W_3 \end{bmatrix} \leftarrow Q^H W Q

6: k = n - 1

7: while k > 1 do

8: Solve X_3 = \frac{\tilde{W}_3}{T_3 + \overline{T}_3} with T_3 = T_{kk}

9: Solve

T_1 X_2 + X_2 \overline{T}_3^H = W_1

with T_1 = T(1:k, 1:k), W_1 = W_1 - T_2 X_2^H - X_2 T_2^H

10: k = k - 1

11: end while
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12: Solve $T_1X_1 + X_1T_1^H = W_2 - T_2X_2^H - X_2T_2^H$ in $\mathbb{C}^{1\times 1}$ 13: Back transformation $X \leftarrow QXQ^H$

The Bartels-Stewart algorithm requires approximately $32n^3$ elementary operations, consisting of $\approx 25n^3$ for the QR algorithm, and $\approx 3n^3$ for each of the steps 5 and 13. The whole backward substitution (**while**-loop) requires only n^3 flops. The QR Algorithmus as well as the backward substitution can be implemented numerically backwards stable, and, moreover, only unitary similarity transformations are used. Hence, the Bartels-Stewart algorithm can be considered as numerically backwards stable. The Bartels-Stewart algorithm for solving Lyapunov and Sylvester equations is, e.g., in the MATLAB Control Toolbox routine lyap implemented.

Literatur

- [1] R. Bartels and G. Stewart, Solution of the Matrix Equation AX + XB = C: Algorithm 432, Comm. ACM, 15 (1972), pp. 820–826.
- [2] D. Sorensen and Y. Zhou, P. Benner, P. Kürschner, and J. Saak, *Direct methods for matrix Sylvester and Lyapunov equations*, J. Appl. Math, 2003 (2003), pp. 277–303.