

# Khalifa University of Science, Technology and Research Electronic Engineering Department

### **ELCE333Microprocessor Systems laboratory**

# **Laboratory Experiment 5**

# SERIAL COMMUNICATION INTERFACE

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**Date Experiment Performed**: 25/2/2015 **Date Lab Report Submitted**: 4/3/2015

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**Spring 2015** 

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# **Summary**

This report illustrates the concept of using the programming with C languages and use of the asynchronous serial communication interface in HCS12 microcontroller.

In this experiment contains different tasks. Some of them is about is Transmitting Characters and String. Others are is about ASCII Data and Serial I/O and Dip Switches Calculator. This report contains the results and the conclusion from the lab

#### 1. Introduction

A serial communication interface (SCI) is an interface designed to transfer data only in asynchronous mode that utilizes the EIA 232 standard. Our microcontroller has two asynchronous serial Communications interfaces which are SCI0 an SCI1 and an extra synchronous serial peripheral interface, SPI. The extra chip allows the microcontroller to communicate with deceive that implements RS-232 standard. Port S of HCS12 is connected to two signal pins for each SCI channel.

- -SCI0 shares the use of Port S pins PS0 (RxD0) and PS1 (TxD0)
- -SCI1 shares the use of Port S pins PS2 (RxD1) and PS3 (TxD1)

There are 10 registers for status, control and data transfers. For examples:

- **SCnDRL**: is Data Register Low in which the character is transmitted or received.
- SCnCR2: is Control Register 2, TE& RE enable transmitting & receiving data
- **SCnCR1**: is Control Register 1 has advanced features as well as parity, bit length, and stop bits setting.
- **SCnBDH** & **SCnBDL** is SCIn Baud Rate Control which are double registers for setting the baud rate.
- **SCnSR1:is** SCIn Status Register 1 **TDRE** responsible for stating that data has been transmitted or **RDRF** responsible for stating that data has been received respectively.

\*The setup for asynchronous serial port is the following:

- 1. Set baud rate with **SBR12-0** bits of **SCnBDH** and **SCnBDL**. Specfic values are calculated based on the equation  $SBR = f_E \div 16 \div$  baud rate where fE is the processor clock speed.
- 2. Enable transmitter and receiver (**TE** and **RE** bits of **SCnCR2**)
- 3. Select 8-bit or 9-bit mode (**M** bit of **SCnCR1**)
- 4. If using parity, enable parity (**PE** bit of **SCnCR1**) and choose odd or even (**PT** bit of **SCnCR1**)
- 5. If using interrupts enable **TIE** or **RIE** interrupt in **SCnCR2**

C library functions can be used to start then access the Serial Interface. The SCI1 library functions are presented in table 1 and are written in a header file (sci1.h) which is included in the main program by the aid of this command: #include "sci1.h"

**Table 1: SCI interface library functions** 

| Function                                  | Input Parameters                | Description                          |
|---|---------------------------------|--------------------------------------|
| void SCI1_Init(unsigned short             | Baud Rate                       | Initialize Serial port SCI1 with     |
| baudRate);                                | Ex (BAUD_9600)                  | baud rate in bits/sec                |
| char SCI1_InStatus(void);                 | -                               | Checks if new input is ready         |
| char SCI1_OutStatus(void);                |                                 | Checks if output data buffer is      |
|   | -                               | empty                                |
| ahan GCII Tu Chan(anid).                  | oid);                           | Reads 2 nibbles character from       |
| char SCI1_InChar(void);                   |                                 | SCI1                                 |
| SCI1_InString(char *, unsigned short);    |                                 | Reads in a String until a carriage   |
|   | 1) Empty string ""              | return is inputted                   |
|   | 2) String Length                | or until max length of the string is |
|   |                                 | reached                              |
| unsigned short SCI1_InUDec(void);         |                                 | Reads ASCII input in unsigned        |
|   | -                               | decimal format                       |
| void SCI1_OutChar(char);                  | Char: 'A'                       | Writes 2 nibbles character to SCI1   |
| void SCI1_OutString(char *pt);            | String "Hi"                     | Writes a string of characters        |
|   |                                 | character to SCI1                    |
| void SCI1_OutUDec(unsigned short); Int: 1 | Writes ASCII output in unsigned |                                      |
|   | Int: 1                          | decimal format                       |
|   | -                               |                                      |

#### 1.1 Aim

To introduce the students to the programming and the use of the asynchronous serial communication interface in HCS12 microcontroller.

#### 1.2 Objectives

On completion of this experiment the student should be able to:

- 1- Understand serial I/O and its parameters
- 2- Write an HCS12 program to send and receive data from and to a PC.
- 3- To compile, download and debug/test a C program using CodeWarrior C compiler and Dragon12 Plus Trainer board.

#### 2. Design and results

#### **Task 1: Transmit Characters**

In the first task of this lab we explored HCS12DG256 on board asynchronous serial communication SCI1 in which we were given the following code to run it and debug it:

```
#include <hidef.h>
#include "derivative.h"

#include "sci1.h"

void main(void)

{

SCI1_Init(BAUD_9600);

for(;;)

{

SCI1_OutChar ('*');// transmits * to SCI1

SCI1_OutChar (0x0A);// new line

SCI1_OutChar (0x0D);// carriage return

} /* loop forever */
}// end of main
```

The difference in this code than previous lab is that the header file of SCI1 was added to enable usage of functions related to serial port SCI1. Also, in the main body, the serial port SCI1 was initialized with a baud rate of 9600 bps. In addition to that, in the loop, the function "void SCI1 OutChar(char)" is used to display a character output to Tera Term display.

As we can notice in figure 1that the character '\*' was printed in each line separately (because of new line and carriage return) and continuously (because of the forever running loop).

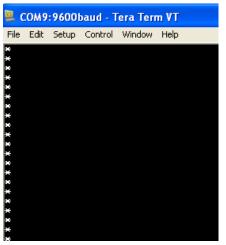


Figure 1: Transmit char '\*' to serial port

#### **Task 2: Transmit String**

In this task, we were asked to modify the given code in task 1 but declare a string output. Instead of the stars we want to output "I love microcontroller" endlessly. The modified code is shown below:

```
#include <hidef.h> /* common defines and macros */
#include "derivative.h" /* derivative-specific definitions */
#include "sci1.h"
void main(void)
{SCI1_Init(BAUD_9600);
for(;;)
{
    SCI1_OutString ("I love microcontroller");// transmits string to
    SCI1
    SCI1_OutChar (0x0A);// new line
    SCI1_OutChar (0x0D);// carriage return
} /* loop forever */
/* please make sure that you never leave main */}
```

The difference in this code is that we print a string using the function "void SCII\_OutString()" to display a string output to Tera Term display. As we can notice in figure 2 the string was printed in each line separately (because of new line and carriage return) and continuously (because of the forever running loop).

The figure below shows the output after running the program:

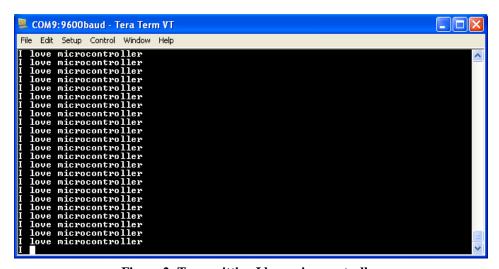


Figure 2: Transmitting I love microcontroller

#### Task 3: ASCII Data and Serial I/O

In the third task, we are asked to write a code that allows the user to enter a character and displays the ASCII equivalent on the screen in the following format "The ASCII code for A is 65" but however when the ESC button is pressed the program should display "Bye" and it should stop. The written code is shown below:

```
#include <hidef.h>
#include "derivative.h"
#include "sci1.h"
void main(void)
{char y;
SCI1_Init(BAUD_9600);
for(;;)
 \{ if (y == 0x1B) \}
 SCI1 OutString ("Bye");// transmits * to SCI1
 SCI1 OutChar (0x0A);// new line
 SCI1 OutChar (0x0D);// carriage return
 break;
} //end of IF
else {
  SCI1_OutString ("The ASCII code for ");// transmits * to SCI1
  y= SCI1 InChar();
  SCI1 OutChar(y);
  SCI1 OutString (" is ");// transmits * to SCI1
  SCI1 OutUDec(y);
  SCI1 OutChar (0x0A);// new line
  SCI1 OutChar (0x0D);// carriage return
}//end of else
```

In this code, we had to define two cases; the first case is when the user enters a valid letter. The second is for when the user presses ESC. We defined if (y == 0x1B) which represents ESC in ASCII code, the code will output "Bye" on a new line and terminate. However, for when the user enters a character, the code outputs "The ASCII code for" and the entered character. Then, the code uses the function  $SCII\_OutUDec(y)$ ; to display the ASCII equivalent of the entered character. When a valid character is entered, the program will loop motivating the user to enter another value.

```
COM9:9600baud - Tera Term VT

File Edit Setup Control Window Help

The ASCII code for a is 97

The ASCII code for A is 65

The ASCII code for A is 65

The ASCII code for S 27

Bye
```

Figure 3: HyperTerminal Screen display of task 3

#### **Task 4: DIP switches calculator**

In this task we were asked to write a C# code for calculator using the first 4 DIP switches from the right for the first number and the other left 4 DIP switches for the second number whereas the operation is entered by user using the serial terminal.

In order to write such code, we had first to define all variables that are needed (i.e. variables for operands (int), operations (char) and operation functions (int & float). Then we assigned 4-LSB of PTH (that controls the DIP switches) to be used for the num1 and the 4-MSB of PTH to be used for num2. In the serial terminal, the decimal equivalent representation of binary num1 and num2 in PTH is displayed followed by message that pulls the user to enter an operation (+, -, \*, /) to be performed. The code include an IF condition statement that compares the user entered operation and do the relevant arithmetic operation and result displaying using the function "void SCI1\_OutUDec(unsigned short)". The addition and the multiplication operations are performed ordinarily without any special cases; however, the subtraction operation contains a case of a negative result when the second operand is larger than the first one. Therefore, before performing the subtraction num1 and num2 are checked such that if num2 > num1 then sub= num2 - num1 with adding a negative sign to the number, else perform an ordinary subtraction operation (i.e. sub= num1-num2). The other special case we dealt with in this task is the case of non-integer division result and to overcome this problem "div" variable was defined as float and the following function was used to represent the division result : "SCI1\_OutFloat(div, num1, num2)".

```
No.1= 3 , No.2= 2
enter an operation (+,-,*,/)

No.1= 3 , No.2= 2
enter an operation (+,-,*,/)

3 + 2 = 5

No.1= 3 , No.2= 2
enter an operation (+,-,*,/)

3 - 2 = 1

No.1= 3 , No.2= 2
enter an operation (+,-,*,/)

3 * 2 = 6

No.1= 3 , No.2= 2
enter an operation (+,-,*,/)

3 / 2 = 1.66
```

Figure 4: DIP switch calculator results

```
No.1= 1 , No.2= 3
enter an operation (+,-,*,/)
1 - 3 = -2
```

Figure 5: Case of negative results

The following is the code for this task:

```
#include <hidef.h>
#include "derivative.h"
#include "sci1.h"
void main()
int num1, num2;
int sum, sub, mul, subn;
float div;
char op;
SCI1 Init(BAUD 9600);
for(;;)
{ // 4-LSB of DIP switches assigned to No.1
  num1= PTH PTH0*1+PTH PTH1*2+
PTH_PTH2*4 + PTH_PTH3*8;
  // 4-MSB of DIP switches assigned to No.1
  num2= PTH PTH4*1+PTH PTH5*2+
PTH PTH6*4 + PTH PTH7*8;
  op= SCI1 InChar();
  SCI1 OutString ("No.1=");
  SCI1 OutUDec(num1);
  SCI1_OutString (", No.2=");
  SCI1_OutUDec(num2);
  SCI1_OutChar (0x0A);// new line
  SCI1_OutChar (0x0D);// carriage return
  SCI1_OutString ("enter an operation (+,-,*,/)");
  SCI1 OutChar (0x0A);// new line
  SCI1 OutChar (0x0D);// carriage return
if (op == '+')
{
 sum= num1+num2;
 SCI1 OutUDec(num1);
 SCI1 OutString (" + ");
 SCI1 OutUDec(num2);
 SCI1_OutString (" = ");
 // display decimal value of sum on serial terminal
 SCI1 OutUDec(sum);
 SCI1 OutChar (0x0A);// new line
 SCI1 OutChar (0x0D);// carriage return
 SCI1 OutChar (0x0A);// new line
  SCI1 OutChar (0x0D);// carriage return
sub= num1-num2;
 SCI1 OutUDec(num1);
 SCI1_OutString (" - ");
```

```
SCI1_OutUDec(num2);
 SCI1 OutString (" = ");
 // To handle negative results (i.e. num2 > num1)
 if (num2>num1)
  subn=num2-num1;
  SCI1 OutChar ('-');
  SCI1_OutUDec(subn);
 } else {
// when subtraction result is positive (i.e. num1>num2)
  SCI1 OutUDec(sub);
 }//end of else
 SCI1_OutChar (0x0A);// new line
 SCI1 OutChar (0x0D);// carriage return
if (op == '*')
  mul= num1* num2;
 SCI1 OutUDec(num1);
 SCI1_OutString (" * ");
 SCI1_OutUDec(num2);
 SCI1_OutString (" = ");
 SCI1 OutUDec(mul);
 SCI1_OutChar (0x0A);// new line
 SCI1 OutChar (0x0D);// carriage return
if (op == '/')
 div= num1/num2;
 SCI1 OutUDec(num1);
 SCI1 OutString (" / ");
 SCI1 OutUDec(num2);
 SCI1_OutString (" = ");
 /* as the division result can sometimes be float
 we use the following function */
 SCI1 OutFloat(div, num1,num2);
 SCI1 OutChar (0x0A);// new line
 SCI1 OutChar (0x0D);// carriage return
  SCI1 OutChar (0x0A);// new line
  SCI1 OutChar (0x0D);// carriage return
  break;
}//end of loop
}// end of main
```

#### 3. Assigned question

# 1) Write an HCS12 program in C to receive bytes serial and put them on PORTB. Set the baud rate at 19200, 8-bit data.

The first step in this code is initializing the 4- LSB LEDs for displaying the output by assigning the outputs and inputs to corresponding ports. Then, in the loop section, we wrote functions for reading the character input from the serial ports. In case of reading numbers from 10 to 15 we converted it corresponding letter representation (i.e. A to F) to and then display its binary code in PORTB.

```
#include <hidef.h>
#include "derivative.h"
#include "SCI1.h"
void main(void) {
char x;
int n;
SCI1 Init(BAUD 9600);
  // initilizing LEDs for displaying the results
  DDRB = 0x0F;
// becuase we will only represent 4 bits [0,F]
  DDRJ = 0xFF;
  DDRP= 0x0F;
  DDRT = 0xFF;
  PTJ = 0x00;
  PTP = 0x0F;
  PORTB =0;
for(;;) {
  n=0;
  SCI1 OutString ("Enter a Character: ");
  x= SCI1 InChar ();
  if ((x=='a') | (x=='A')) n=10;
  if (( x=='b') || (x=='B')) n=11;
  if ((x=='c') | | (x=='C')) n=12;
  if ((x=='d') | (x=='D')) n=13;
  if ((x=='e') | | (x=='E')) n=14;
  if ((x=='f') | | (x=='F')) n=15;
```



Figure 7: Assignment Question 1 results

```
if (n!=0)
{
    SCI1_OutUDec(n);
    PORTB = n;
}
else
{
    SCI1_OutChar(x);
    PORTB = x;
}

SCI1_OutChar (0x0A);// new line
    SCI1_OutChar (0x0D);// retutn carriage
} //end of loop
}//end of main
```

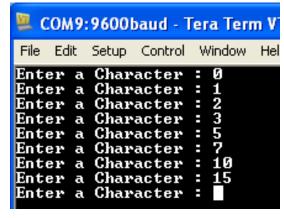


Figure 6: Assignment Question: TeraTerm results

2) Write a program to prompt the user to enter a sentence and then count the number of characters excluding spaces as well as the number of spaces in the entered sentence. Then display the numbers on the serial terminal. Run the program and provide snap shot of your serial terminal.

In this task we define an array that takes each character and stored. Then a while loop that checks for the Null character, if not detected so checks for the number for spaces and characters. Then we display the number of the character-1 to remove the effect of the Enter key. Then the variables are cleared to read new sentence.

```
#include <hidef.h>
#include "derivative.h"
#include "SCI1.h"
void main(void) {
 int n=0;
        int charsp=0;
        int Charnum2=0;
        int less=0;
        char Array[30];
        SCI1_Init(BAUD_9600);
for(;;)
        SCI1 OutString ("Please Enter a
sentence: ");
 SCI1 InString(Array, 30);
 SCI1_OutString( Array+1);
while (Array [n]! = 0x00)
 if(Array[n] == 0x20)
 charsp++;
 else
        Charnum2++;
  n++;
 less= Charnum2-1;
SCI1_OutString (" has ");
SCI1_OutUDec(less);
SCI1_OutString ("characters & ");
SCI1_OutUDec(charsp);
SCI1_OutString (" Spaces");
 n=0;
 charsp=0;
 Charnum2=0;
 less=0;
SCI1 OutChar (0x0A);
SCI1_OutChar (0x0A);
SCI1_OutChar (0x0D);
}
```

```
COM9:9600baud - Tera Term VT

File Edit Setup Control Window Help

Please Enter a sentence: I Love ELCE has 9characters & 2 Spaces

Please Enter a sentence: Dragon 12 has 8characters & 1 Spaces

Please Enter a sentence: lab6 has 4characters & 0 Spaces

Please Enter a sentence:
```

Figure 8: Results for assigned question

#### 3. Conclusion

The aim of this lab session was to introduce students by the use of asynchronous serial communication interface in HCS12 and how to program it. Task one, requires to transmit the character \* to SCI1 using the command "SCI1\_OutChar(char)" and observes the output obtained in HyperTerminal or Tera Term display. In the second task, modifies the first task to display a string, where each string must be displayed in a new line. In the third task, it was required to designed a program. The program allows the user to enter a character which will be converted to its ASCII value than display it. This is done using the instruction "SCI1\_OutUDec(y)". If the user pressed "Esc" instead of the character the string "Bye" should be displayed in a new line and the transmission session. The fourth task asked us to write a C language program that reads two numbers from the Dip switches then do a specific operation such as (+, -, /, \*), to display the whole operation and the result on serial terminal. In order to display the results if we have fraction such as the division operation it is required need to use the command "SCI1\_OutFloat ( results, num1,num2)" to display the full result. Also, the program should be able to give the right result in the subtraction operation in the case the first number is less than the second number. To do so, an if statement will be defined.