# STAT 653 - Notes Introduction to Mathematical Statistics

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## Contents

1	Statistical Model	1
<b>2</b>	The Likelihood Function	3
3	Identifiability of Statistical Models	4
4	Sufficient Statistic	7
5	Fisher-Neyman Factorization Theorem	8
6	Exchangable Random Variables	10
7	Minimal Sufficient Statistic	12
8	Ancillary Statistic	13
9	Scale and Location Family	14
10	Point Estimation	15
11	Maximum Likelihood	<b>15</b>

# 1 Statistical Model

**Example.** A coin is tossed n times. The data available is  $X = (X_1, X_2, \dots, X_n)$ , where  $X_i \in \{0, 1\}$ . The assumptions are:

- 1. outcomes are independent.
- 2.  $P(X_i = 1) = \theta \in \Theta$  where  $\theta$  is an unknown parameter and  $\Theta$  is the parameter space. In this case  $\Theta = [0, 1]$ .

We need to estimate  $\theta$  based on the data  $X = (X_1, X_2, \dots, X_n)$ , where  $X_i$  are random variables before the experiment is conducted.

So we need to find an estimator  $T(X_1, X_2, \dots, X_n)$  of  $\theta \in \Theta$ .

#### Possible Estimators

1. 
$$T_1 := T_1(X_1, X_2, \dots, X_n) = \overline{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

**Remark.** (a)  $\mathbb{E}(T_1) = \mathbb{E}(\overline{X}_n) = \mathbb{E}(X_1) = \theta$  for all  $\theta \in \Theta$  then  $T_1$  is unbiased estimator of  $\theta$ .

(b) 
$$\lim_{n\to\infty} P(|\overline{X}_n - \theta| > \epsilon) = 0$$
 for all  $\epsilon > 0$ .

**Definition.** In general, if  $\lim_{n\to\infty} P(|T(X_1,\ldots,X_n)-\theta|\epsilon)=0$  for all  $\epsilon>0$  and for all  $\theta\in\Theta$ , then we call  $T(X_1,\ldots,X_n)$  consistent.

2.  $T_2(X_1, \ldots, X_n) := X_1$ , where  $X_1 \in \{0, 1\}$ . Then  $\mathbb{E}(T_2) = \mathbb{E}(X_1) = \theta$  for all  $\theta \in \Theta$ .

 $T_2$  is unbiased but is not <u>consistent</u>.

3.

$$T_3 := T_3(X_1, \dots, X_n)$$

$$= \sqrt{\frac{1}{\lfloor \frac{n}{2} \rfloor} \sum_{i=1}^{\lfloor \frac{n}{2} \rfloor} X_{2i} X_{2i-1}}$$

 $T_3$  is biased because

$$\mathbb{E}(T_3) \le \sqrt{\frac{1}{\lfloor \frac{n}{2} \rfloor} \sum_{i=1}^{\lfloor \frac{n}{2} \rfloor} X_{2i} X_{2i-1}}$$
$$= \theta \quad \forall \theta \in \Theta$$

**Example.** Suppose  $X_1, X_2, ..., X_n$  are independent and have uniform $[0, \theta]$ , where  $theta \in \Theta = \mathbb{R}_+$ . So  $\Theta = \{\theta : \theta > 0\}$ .

#### Possible Estimators

1. 
$$T_1(X_1,\ldots,X_n)=2\overline{X}_n$$

2. 
$$T_2(X_1, \ldots, X_n) = X_{(n)} \pmod{n}$$

3.  $T_3(X_1,\ldots,X_n)=c_nX_{(n)}$ 

Correct the max by a constant so it is unbiased.

**Example.** We want to receive a shipment of oranges and suspect that part of them rot off. To check the shipment we draw a random sample without replacement of size n from the shipment (population) of size N.

Let  $\theta$  be the proportion of bad oranges in the population. So  $\Theta = \{\frac{0}{N}, \frac{1}{N}, \dots, \frac{N}{N}\}.$ 

Let

$$X_i = \begin{cases} 0 & \text{if good} \\ 1 & \text{if bad} \end{cases}$$

for i = 1, 2, ..., n and let  $X = (X_1, X_2, ..., X_n)$ .

Let  $T_1(X) = \sum_{i=1}^n X_i$ . Then  $T_1$  has a hypergeometric distribution. So

$$P_{\theta}(X_1 = k) = \frac{\left(\frac{N\theta}{k}\right)\left(\frac{N-N\theta}{n-k}\right)}{\left(\frac{N}{n}\right)}$$

for  $k \in {\max(0, n - (N - N\theta), \dots, \min(n, N\theta))}$ 

# 2 The Likelihood Function

$$X \sim P_{\theta}, \quad \theta \in \Theta$$

We have 2 cases for now (discrete and continuous):

- (R1)  $P_{\theta}$  is defined by a joint pdf  $f_X(x;\theta)$  for all  $\theta \in \Theta$ .
- (R2)  $P_{\theta}$  is defined by a joint pmf  $P(X = x; \theta)$  for all  $\theta \in \Theta$ .

**Definition.** Let  $P_{\theta}$ ,  $\theta \in \Theta$  be a model satisfying (R1) or (R2). Then the function

$$L(x;\theta) = \begin{cases} f_X(x;\theta) & \text{if (R1)} \\ P(X=x;\theta) & \text{if (R2)} \end{cases}.$$

**Example.** Not (R1) and not (R2).

Let

$$X \sim N(\theta, 1)$$
  $\theta \in \Theta = \mathbb{R}$ .

We observe  $Y = \max(0, X)$ ,

$$Y = \begin{cases} 0 & \text{if } X \le 0 \\ X & \text{if } X > 0 \end{cases} = XI(X > 0)$$

where  $I(\cdot)$  is the indicator function.

$$F_{\theta}(t) = P(Y \leq t)$$
 for all  $t \in \mathbb{R}$ .

**Example.** Back to oranges example where  $X = (X_1, X_2, ..., X_n)$  is the data and  $\Theta = \{\frac{0}{N}, \frac{1}{N}, ..., \frac{N}{N}\}$ . Let  $T(X) = \sum_{i=1}^{n} X_i$ . Then

$$L(x;\theta) = P_{\theta}(X_1 = x_1, X_2 = x_2, \dots, X_n = x_n)$$

$$= P_{\theta} \left( X_1 = x_1, X_2 = x_2, \dots, X_n = x_n, T(X) = \sum_{i=1}^n x_i \right)$$

$$= P_{\theta} \left( T(X) = \sum_{i=1}^n x_i \right) P\left( X_1 = x_1, \dots, X_n = x_n \middle| T(X) = \sum_{i=1}^n x_i \right).$$

Now define  $K_n = \sum_{i=1}^n x_i$ . For example, if n = 5 and we observed (1, 0, 0, 1, 1) then

$$K = \sum_{i=1}^{5} x_i = 3.$$

Since there are 10 possibilities for which entries are 1 versus 0,  $\binom{5}{3} = 10$ . Because all possible combinations of 1 and 0 are possible we can use symmetry to calculate the probability of any particular sequence of 1 and 0 as  $1/\binom{5}{3}$ . We use this reasoning below to derive the expression on the right.

Then

$$L(x;\theta) = \frac{\binom{N\theta}{K_n} \binom{N-N\theta}{n-K_n}}{\binom{N}{n}} \times \frac{1}{\binom{n}{K_n}}.$$

# 3 Identifiability of Statistical Models

**Definition.** Let  $X \sim P_{\theta}$ ,  $\theta \in \Theta$ . A model  $P_{\theta}$ ,  $\theta \in \Theta$  is <u>identifiable</u> if for any pair  $(\theta, \theta')$  such that  $\theta \neq \theta'$  and  $\theta, \theta' \in \Theta$ , then  $P_{\theta} \neq P_{\theta'}$ .

**Remark.** This means that there is an event A, such that  $P_{\theta}(A) \neq P_{\theta'}$  where  $\theta \neq \theta'$ .

- R(1) For  $\theta \neq \theta'$ ,  $f(x;\theta) \neq f(x;\theta')$  for any neighborhood of x (an open ball B(x,r) centered at x).
  - By open ball we mean  $B(x,r)=\{y:|x-y|<\epsilon\}$  where  $|v|=(\sum_{i=1}^n v_i^2)^{1/2}$  (euclidean norm).
- R(2) Discrete support, for some x  $P_{\theta}(X = x) \neq P_{\theta'}(X = x)$  where  $\theta \neq \theta'$ .

**Example.** Suppose we observe  $X_1, X_2, ..., X_n$  where  $X_i = \theta \cdot Z_i \sim N(0, \theta^2)$  and  $Z_i \sim N(0, 1)$  and  $\theta \in \Theta = \mathbb{R} \setminus \{0\}$ .

If  $\theta_1 = 1 \neq -1 = \theta_2$ , then

$$L(x_1, x_2, \dots, x_n; \theta = 1) = L(x_1, x_2, \dots, x_n; \theta = -1)$$

for any  $x = (x_1, ..., x_n)$ .

**Result.** The model  $\{P_{\theta}, \theta \in \Theta\}$  is identifiable if there exists a statistic T(X)  $(X \sim P_{\theta}, \theta \in \Theta)$  where expectation is a one-to-one function of  $\theta \in \Theta$ , i.e., such that

$$\forall (\theta, \theta'), \quad \theta \neq \theta' \implies \mathbb{E}_{\theta}(T(X)) \neq \mathbb{E}_{\theta'}(T(X))$$
 (1)

*Proof.* We use proof by contradiction. Suppose that (1) holds, but there exists  $\theta \neq \theta'$  such that  $P_{\theta} = P_{\theta'}$ . If so, then  $\mathbb{E}_{\theta}(T(X)) = \mathbb{E}_{\theta'}(T(X))$ , which contradicts (1).

In the previous example,  $\theta = 1$ ,  $\theta' = -1$ .

**Example.** Let  $X_1, X_2, \ldots, X_n \stackrel{\text{iid}}{\sim} \text{Bernoulli}(\theta)$  where  $\theta \in \Theta = [0, 1]$ . We will show that  $\theta$  is identifiable using the definition and also the above result.

Let  $\theta$  and  $\theta'$  be arbitrary and suppose  $\theta \neq \theta'$  and  $\theta', \theta \in \Theta$ . Also suppose  $X = (1, 1, \ldots, 1)$ . Then

$$P_{\theta}(X_1, X_2, \dots, X_n) = \theta^n$$
  
$$P_{\theta'}(X_1 = 1, \dots, X_n) = (\theta')^n.$$

Since  $\theta \in [0, 1]$  then  $\theta^n \neq (\theta')^n$  and the model is identifiable.

Now take a statistic  $T(X_1,\ldots,X_n)=X_1$  (or we could take  $T(X_1,\ldots,X_n)=\sum_{i=1}^n X_i$  or  $T(X_1,\ldots,X_n)=\sum_{i=1}^n \overline{X}_i$ ).

For any  $(\theta, \theta') \in \Theta$ , if  $\theta \neq \theta'$  then  $\mathbb{E}_{\theta}(\overline{X}_n) = \theta \neq \theta' = \mathbb{E}_{\theta'}(\overline{X}_n)$ . Then by the above result the model is identifiable.

#### Example.

$$X_1, \dots, X_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$$

Part 1) Let  $\theta = (\mu, \sigma^2) \in \Theta = \mathbb{R} \times \mathbb{R}^2$ . Then

$$L(x_1, \dots, x_n; \theta) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{\frac{-(x_1 - \mu)^2}{2\sigma^2}} I(\mu \in \mathbb{R}) I(\sigma^2 > 0).$$

It is difficult in this case to use the definition to show identifiability in this case, but we can use the previous result.

We are given  $X = (X_1, X_2, \dots, X_N)$ . Let

$$T(X) = \left(\sum_{i=1}^{n} X_i, \sum_{i=1}^{n} X_i^2\right)$$

Then

$$\mathbb{E}_{\theta}(T) = (n\mu, n(\sigma^2 + \mu^2)),$$
  

$$\mathbb{E}_{\theta'}(T) = (n\mu', n(\sigma^{2'} + (\mu')^2))$$

Thus, if  $(\theta, \theta^2) \in \Theta$  then

$$\forall \theta \neq \theta' \implies \mathbb{E}_{\theta}(T(X)) \neq \mathbb{E}_{\theta'}(T(X)).$$

If  $\theta \neq \theta'$  then  $\mu \neq \mu'$  or  $\sigma^2 \neq \sigma^{2'}$  or  $\mu \neq \mu'$  and  $\sigma^2 \neq \sigma^{2'}$ . In all three cases then  $\mathbb{E}_{\ell}(T(X)) \neq \mathbb{E}_{\theta'}(T(X))$ .

Part 2) Suppose we observe only  $Y_1, \ldots, Y_n$  where

$$Y_i = \begin{cases} +1 & \text{if } X_i \ge 0\\ -1 & \text{if } X_i < 0. \end{cases}$$

Since  $Y_i = g(X_i)$  and the  $X_i$ 's are independent, then the  $Y_i$ 's are also independent. Then the likelihood function is

$$L(y_i, \dots, y_n; \theta) = \prod_{i=1}^n P(Y_i = y_i; \theta)$$
  
=  $\prod_{i=1}^n [I(y_i = 1)P(X_i \ge 0) + I(y_i = -1)P(X_i < 0)].$ 

Now note that

$$P(X_i \ge 0) = 1 - P(X_i < 0) = 1 - \Phi\left(-\frac{\mu}{\sigma}\right) = \Phi\left(\frac{\mu}{\sigma}\right)$$
$$P(X_i < 0) = \Phi\left(-\frac{\mu}{\sigma}\right)$$

so that only the ratio  $\mu/\sigma$  matters for the likelihood.

Now let  $\theta = (3,9) \neq (4,16) = \theta'$ . For  $\theta$  we have  $\mu/\sigma = 3/3 = 1$  and for  $\theta'$  we have  $\mu/\sigma = 4/4 = 1$ . Thus we have

$$\theta = (3,9) \neq (4,16) = \theta' \implies L(y;\theta) = L(y;\theta')$$

and so the model is not identifiable. For any  $y = (y_1, \ldots, y_n)$  we have  $L(y; \theta) = L(y; \theta')$  and thus the model is not identifiable.

**Remark.** Above we used the fact that for a general normal random variable  $N(\mu, \sigma^2)$ ,  $F(x) = \Phi((x - \mu)/\sigma)$ .

### 4 Sufficient Statistic

**Definition.** Let  $X \sim P_{\theta}$ ,  $\theta \in \Theta$  and we observe data  $X = (X_1, \dots, X_n)$ . A statistic T(X) is **sufficient** for the model  $\{P_{\theta}, \theta \in \Theta\}$  if the conditional distribution of  $X \mid T(X)$  does not depend on  $\theta$ .

**Remark.** Consider the following 2 stage procedure. Assume T(X) is a sufficient statistic for the model  $\{P_{\theta}, \theta \in \Theta\}$ .

- (1) Suppose we observed data from  $X \sim P_{\theta}$ ,  $\theta \in \Theta$ . Now calculate T(X), keep it and discard X.
- (2) Generate X' from conditional distribution  $X \mid T(X)$ .

For any  $\theta \in \Theta$  calculate marginal distribution of new X'. Then

$$P_{\theta}(X' = x) = \sum_{t} P_{\theta}(X' = x \mid T(X) = t) P_{\theta}(T(X) = t)$$
$$= \sum_{t} P_{\theta}(X = x \mid T(X) = t) P_{\theta}(T(X) = t)$$
$$= P_{\theta}(X = x)$$

for any X.

**Example.** Let  $X = (X_1, X_2, \dots, X_n) \stackrel{iid}{\sim} \text{Bernoulli}(\theta)$  where  $\theta \in \Theta = (0, 1)$ . Let  $T(X) = \sum_{i=1}^n X_i \stackrel{iid}{\sim} \text{Binomial}(n, \theta)$ .

Then

$$P_{\theta}(X_1 = x_1, X_2 = x_2, \dots, X_n = x_n \mid T(X) = t) = \begin{cases} 0 & \text{if } t \neq \sum_{i=1}^n x_i \\ * & \text{if } t = \sum_{i=1}^n x_i \end{cases}$$

where

$$* = \frac{\theta^t (1 - \theta)^{n-t}}{\binom{n}{t} \theta^t (1 - \theta)^{n-t}} = \frac{1}{\binom{n}{t}}$$

which does not depend on  $\theta$ .

Thus the  $X \mid T(X)$  has a discrete uniform distribution,

$$(X_1, \dots, X_n) \mid T(X) = t \sim \text{uniform} \left\{ x_1, \dots, x_n : x_i \in \{0, 1\} \text{ and } \sum_{i=1}^n x_i = t \right\}$$

**Remark.** In the above example  $\sum_{i=1}^{n-1} X_i$  is not a sufficient statistic. To see this note that

$$\mathbb{E}\left(X \mid \sum_{i=1}^{n-1} X_i = t\right) = \theta$$

which implies that the conditional distribution depends on  $\theta$ .

#### Example.

$$X_1, X_2, \dots, X_n \stackrel{\text{iid}}{\sim} N(\theta, 1) \qquad \theta \in \Theta = \mathbb{R}$$

Let 
$$T(X) = \sum_{i=1}^{n} X_i = \overline{X}_n$$
. Then

$$\begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} \mid \overline{X}_n = t \sim N \begin{pmatrix} t \\ t \\ \vdots \\ t \end{pmatrix}, \begin{bmatrix} 1 - \frac{1}{n}, & -\frac{1}{n}, & \dots, & -\frac{1}{n} \\ -\frac{1}{n}, & 1 - \frac{1}{n}, & \dots, & -\frac{1}{n} \\ \vdots \\ -\frac{1}{n}, & \dots, & -\frac{1}{n}, & 1 - \frac{1}{n} \end{bmatrix}$$

where the multivariate normal distribution on the right does not depend on  $\theta$ . Thus  $\overline{X}_n$  is sufficient for this model.

# 5 Fisher-Neyman Factorization Theorem

Consider the model  $X \sim P_{\theta}$ ,  $\theta \in \Theta$ . Then T(X) is sufficient statistic for  $P_{\theta}$  if and only if there exists functions  $g(\theta, t)$  and h(x) (with appropriate domains) such that

$$L(x;\theta) = g(\theta,T(x))h(x) \qquad \forall x; \forall \theta \in \Theta$$

Proof. (I) Sufficient condition

Assume holds and we must show that T(X) is sufficient. We do only the discrete case.

$$P_{\theta}(X = x \mid T(X) = t) = \begin{cases} 0 & \text{if } T(x) \neq t \\ * & \text{if } T(x) = t \end{cases}$$

where \* is

$$* = \frac{P_{\theta}(X = x)}{P_{\theta}(T(x) = t)} = \frac{P_{\theta}(X = x)}{\sum\limits_{y:T(y) = t} P_{\theta}(X = y)}$$
$$= \frac{g(\theta, T(x) = t)h(x)}{\sum\limits_{y:T(y) = t} g(\theta, T(x) = t)h(y)}$$
$$= \frac{h(x)}{\sum\limits_{y:T(y) = t} h(y)}.$$

Since the final expression above does not depend on  $\theta$ , which implies that T(X) is a sufficient statistic for the given model.

#### (II) Necessary Condition

Now assume that T(X) is a sufficient statistic for the given model. Then

$$P_{\theta}(X = x) = P_{\theta}(X = x, T(x) = T(x))$$
  
=  $P(X = x \mid T(x) = t_x)P_{\theta}(T(x) = t_x)$   
=  $h(x)g(\theta, t_x)$ .

**Example.** Let  $X_1, X_2, \ldots, X_n \stackrel{\text{iid}}{\sim} \text{Bernoulli}(\theta)$  where  $X_i \in \{0, 1\}$ . Then the likelihood is

$$L(x;\theta) = P_{\theta}(X_1 = x_1, \dots, X_n = x_n)$$

$$= \theta^{\sum_{i=1}^{n} x_i} (1 - \theta)^{n - \sum_{i=1}^{n} x_i} \prod_{i=1}^{n} I(x_i \in \{0, 1\})$$

$$= g\left(\theta, T(x) = \sum_{i=1}^{n} x_i\right) h(x).$$

Thus,  $T(X) = \sum_{i=1}^{n} X_i$  is sufficient for this model.

**Example.** Let  $X_1, X_2, \ldots, X_n \stackrel{\text{iid}}{\sim} N(\theta, 1)$ . Then the likelihood is

$$L(x;\theta) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi}} e^{-\frac{(x_i - \theta)^2}{2}} \prod_{i=1}^{n} I(-\infty < x_i < \infty)$$

$$= e^{\theta(\sum_{i=1}^{n} x_i) - \frac{n\theta^2}{2}} \left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{1}{2} \sum_{i=1}^{n} x_i^2} \prod_{i=1}^{n} I(-\infty < x_i < \infty)$$

$$= \left[ e^{\theta n \overline{X}_n - \frac{n\theta^2}{2}} \right] \left[ \left(\frac{1}{\sqrt{2\pi}}\right)^n e^{-\frac{1}{2} \sum_{i=1}^{n} x_i^2} \prod_{i=1}^{n} I(-\infty < x_i < \infty) \right]$$

$$= g(\theta, \overline{X}_n) h(x)$$

Thus,  $\overline{X}_n$  is a sufficient statistic for this model.

#### Example.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim N \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \right), \quad -1 < \rho < 1, \quad -\infty < x_1, x_2, < \infty$$

Suppose we have on observation  $x = (x_1, x_2)$ . Then the likelihood is

$$L(x; \rho) = \frac{1}{2\pi\sqrt{1-\rho}} e^{-\frac{x_1^2 + x_2^2 - 2\rho x_1 x_2}{2(1-\rho^2)}} I(-\infty < x_1, x_2 < \infty)$$
$$= g(\rho; T(x) = (x_1^2 + x_2^2, x_1 x_2))h(x)$$

where h(x) = 1. Now suppose we have n observations

$$x = \left( \begin{bmatrix} x_{11} \\ x_{21} \end{bmatrix}, \begin{bmatrix} x_{12} \\ x_{22} \end{bmatrix}, \dots, \begin{bmatrix} x_{1n} \\ x_{2n} \end{bmatrix} \right)$$

where each vector in x is independent of all others. Then the sufficient statistic T(X) is

$$T(x) = \left(\sum_{j=1}^{n} (x_{1j}^2 + x_{2j}^2), \sum_{j=1}^{n} x_{1j} x_{2j}\right).$$

# 6 Exchangable Random Variables

**Definition.** The random variables  $X_1, X_2, \ldots, X_n$  are **exchangable** random variables if

$$(X_1,\ldots,X_n) \sim (X_{\pi(1)},\ldots,X_{\pi(n)})$$

for any permutation  $\pi(1), \ldots, \pi(n)$  of integers  $1, 2, \ldots, n$ .

**Remark.** If  $X_1, \ldots, X_n$  are identically and independently distributed  $\implies X_1, \ldots, X_n$  are exchangable. However,  $X_1, \ldots, X_n$  are exchangable  $\implies X_1, \ldots, X_n$  are identically and independently distributed.

Example.

$$P(X_1 = x_1, X_2 = x_2) = P(X_2 = x_2, X_1 = x_1)$$

Example.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim N \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \right), \quad -1 < \rho < 1, \quad -\infty < x_1, x_2, < \infty$$

Suppose we have on observation  $x = (x_1, x_2)$ .

Then  $f_{x_1,x_2}(x_1,x_2;\rho) = f_{x_1,x_2}(x_2,x_1;\rho)$  so that  $(X_1,X_2) \sim (X_2,X_1)$ .

**Result.** If  $(X_1, \ldots, X_n) \sim P_{\theta}, \ \theta \in \Theta$  are exchangable random variables then

$$T(X) = (X_{(1)}, \dots, X_{(n)})$$

is a sufficient statistic for  $P_{\theta}$ ,  $\theta \in \Theta$  where T(X) is the vector of order statistics.

*Proof.* Let  $(X_1, \ldots, X_n) \sim P_{\theta}, \theta \in \Theta$  are exchangable random variables. Let  $y_1 \leq y_2 \leq \ldots \leq y_n$  be the observed order statistics. Then

$$P_{\theta}(X_1 = x_1, X_2, = x_2, \dots, X_n = x_n \mid X_{(1)} = y_1, \dots, X_{(n)} = y_n)$$

$$= \begin{cases} * & \text{if } \{x_1, \dots, x_n\} = \{y_1, \dots, y_n\} \\ 0 & \text{if } \{x_1, \dots, x_n\} \neq \{y_1, \dots, y_n\} \end{cases}$$

where

$$* = \frac{P_{\theta}(X_{1} = x_{1}, X_{2} = x_{2}, \dots, X_{n} = x_{n})}{P_{\theta}(X_{(1)} = y_{1}, \dots, X_{(n)} = y_{n})}$$

$$= \frac{P_{\theta}(X_{1} = x_{1}, X_{2} = x_{2}, \dots, X_{n} = x_{n})}{\sum_{\substack{\text{all possible permutations}}} P_{\theta}(X_{1} = y_{\pi(1)}, \dots, X_{n} = y_{\pi(n)})}$$

$$= \frac{P_{\theta}(X_{1} = x_{1}, X_{2} = x_{2}, \dots, X_{n} = x_{n})}{\sum_{\substack{\text{possible permutations}}} P_{\theta}(X_{1} = x_{\pi(1)}, \dots, X_{n} = x_{\pi(n)})}$$

$$= \frac{P_{\theta}(X_{1} = x_{1}, \dots, X_{n} = x_{n})}{n!P_{\theta}(X_{1} = x_{1}, \dots, X_{n} = x_{n})}$$

$$= \frac{1}{n!}.$$

Note that 1/n! does not depend on  $\theta$  for all  $\theta \in \Theta$ . Therefore, by definition, the vector of order statistics is sufficient for model  $P_{\theta}$ ,  $\theta \in \Theta$ .

Example.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim N\left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \right), \quad -1 < \rho < 1, \quad -\infty < x_1, x_2, < \infty$$

Suppose we have on observation  $x = (x_1, x_2)$ .

From the previous result we have  $T(x) = (x_{(1)}, x_{(2)})$  is sufficient.

We know already that  $T_1(x) = (x_1^2 + x_2^2, x_1 x_2)$  is sufficient and we just showed that  $T_2(x) = (x_{(1)}, x_{(2)})$  is also sufficient.

Then  $T_1$  is a function of  $T_2$ . So if we know  $T_2$  then we can calculate  $T_1$ , but not vice versa. This leads to the next definition.

## 7 Minimal Sufficient Statistic

**Definition.** Let  $X \sim P_{\theta}$ ,  $\theta \in \Theta$ . The sufficient statistic, S(X), is minimal sufficient if there is a function of any other sufficient statistic. This means that for any sufficient statistic T(X) there exists a function f: S(X) = f(T(X)).

We can use the following lemma to check for minimal sufficiency.

**Lemma.** Let  $X \sim P_{\theta}$ ,  $\theta \in \Theta$ . A sufficient statistic S(X) is minimal sufficient if

$$\frac{L(x;\theta)}{L(y;\theta)} \ does \ not \ depend \ on \ \theta \implies S(x) = S(y), \quad \forall \theta \in \Theta.$$

*Proof.* Let x, y be such that T(x) = T(y). Suppose the implication in the lemma holds and let T(X) be a sufficient statistic. Then

$$\frac{L(x;\theta)}{L(y;\theta)} = \frac{g(\theta,T(x))h(x)}{g(\theta,T(y))h(y)} = \frac{h(x)}{h(y)}$$

which does not depend on theta, for all  $\theta \in \Theta$ . Then this implies that S(x) = S(y).

Recall that T(x) is arbitrary. Above we showed that  $T(x) = T(y) \implies S(x) = S(y)$ . Now choose another sufficient statistic,  $T_1(X)$ . Then  $T_1(x) = T_1(y) \implies S(x) = S(y)$ . Then if follows that

$$S(x) = f(T(x)).$$

We won't write the formal proof because it will take a while.

**Remark.** (1) If S(x) = S(y) then

$$\frac{g(\theta; S(x))h(x)}{g(\theta, S(y))h(y)} = \frac{h(x)}{h(y)}$$

which does not depend on  $\theta$  for all  $\theta \in \Theta$ .

- (2)  $A \implies B$  is equivalent to  $B^c \implies A^c$ .
- (3) The meaning of the left hand side of the implication in the above lemma is

$$L(x;\theta) = c(x,y)L(y;\theta), \quad \forall \theta \in \Theta.$$

**Example.** Let  $X = (X_1, \ldots, X_n)$  where  $X_i \stackrel{iid}{\sim} N(\theta, 1)$  where  $\theta \in \Theta = \mathbb{R}$ .

# 8 Ancillary Statistic

**Definition.** Let  $X \sim P_{\theta}, \ \theta \in \Theta$ .

- (1) A statistic, A(X), whose distribution does not depend on  $\theta$  is called **ancillary**.
- (2) If  $\mathbb{E}_{\theta}(A^*(X))$  does not depend on  $\theta$  then  $A^*(X)$  is first-order ancillary.

 $\textbf{Remark.} \ \, \text{Ancillary} \implies \text{first-order ancillary, but first-order ancillary} \implies \text{ancillary.}$ 

**Example.** Let  $X_1, X_2X_n \stackrel{iid}{\sim} N(\theta, 1), \quad \theta \in \Theta = \mathbb{R}$ .

A sufficient statistic for this model is

$$S(X) = X_1 + X_2 \sim N(2\theta, 2).$$

An ancillary statistic for this model is

$$A(X) = X_1 - X_2 \sim N(0, 2).$$

Example.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim N \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \right), \quad -1 < \rho < 1$$

In this example  $\theta = \rho$ . A sufficient statistic for this model is

$$S(X) = (X_1^2 + X_2^2, X_1 X_2).$$

Note  $X_1 \sim N(0,1)$  and  $X_2 \sim N(0,1)$  are not independent.

Then two ancillary statistics are

$$A_1(X) = X_1$$
$$A_2(X) = X_2.$$

A first-order ancillary statistic is

$$A^*(X) = X_1^2 + X_2^2$$

because  $\mathbb{E}_{\theta}(A^*(X)) = 2$ .

Another ancillary statistic is

$$A(X) = I(-1 \le X_1 < 1) + I(-1 \le X_2 \le 1).$$

# 9 Scale and Location Family

### 9.1 Location Family

Let  $X \sim F$  where F is some distribution function that does not depend on any unknown parameters, e.g., N(0,1). Let  $\theta \in \Theta = \mathbb{R}$  and define

$$Y = X + \theta$$
.

Then Y is in a location family. The distribution function for Y is

$$F_Y(t) = P(Y \le t) = P(X \le t - \theta) = F_X(t - \theta).$$

**Remark.** Let  $X_1, X_2, \ldots, X_n \stackrel{\text{iid}}{\sim} F$  where F is a distribution function that does not depend on any unknown parameters. Let  $Y_1, Y_2, \ldots, Y_n$  be independent random variables from a location family.

Then

$$Y_1 - Y_2 = (X_1 + \theta) - (X + \theta)$$
  
=  $X_1 - X_2$ .

Thus,  $Y_1 - Y_2$  is an ancillary statistic. Also,

$$Y_{(j)} - Y_{(i)} = (X_{(j)} + \theta) - (X_{(i)} + \theta)$$
  
=  $X_{(i)} - X_{(i)}$ .

Thus,  $Y_{(j)} - Y_{(i)}$  is ancillary.

# 9.2 Scale Family

Let  $X \sim F$  where F is some distribution function that does not depend on any unknown parameters, e.g., N(0,1). Let  $\sigma \in \mathbb{R}_+ = \Theta$ . Then

$$Y = \sigma \cdot X$$

is in a scale family. The distribution function for Y is

$$F_Y(t) = P(Y \le t) = P(\sigma X \le t) = P\left(X \le \frac{t}{\sigma}\right) = F_X\left(\frac{t}{\sigma}\right) \quad \forall t \in \mathbb{R}.$$

**Remark.** Let  $X_1, X_2, \ldots, X_n \stackrel{\text{iid}}{\sim} F$  where F is a distribution function that does not depend on any unknown parameters. Let  $Y_1, Y_2, \ldots, Y_n$  be independent random variables from a scale family.

Then

$$\frac{Y_1}{Y_2} = \frac{\sigma X_1}{\sigma X_2} = \frac{X_1}{X_2}.$$

Thus  $\frac{Y_1}{Y_2}$  is an ancillary statistic. Also

$$\frac{Y_{(1)}}{Y_{(2)}} = \frac{\sigma X_{(1)}}{\sigma X_{(2)}}.$$

Thus  $\frac{Y_{(1)}}{Y_{(2)}}$  is an ancillary statistic.

### 9.3 Location-scale Family

Let  $X \sim F$  where F is some distribution function that does not depend on any unknown parameters, e.g., N(0,1). Let  $\sigma \in \mathbb{R}_+ = \Theta$  and  $\theta \in \mathbb{R}$ . Then

$$Y = \sigma \cdot X + \theta$$

is in a location-scale family.

**Remark.** Let  $X_1, X_2, \ldots, X_n \stackrel{\text{iid}}{\sim} F$  where F is a distribution function that does not depend on any unknown parameters. Let  $Y_1, Y_2, \ldots, Y_n$  be independent random variables from a location-scale family.

Then

$$\frac{Y_1 - Y_2}{Y_3 - Y_4}$$

does not depend on  $\sigma$  or  $\theta$ . We could also write

$$\frac{Y_1 - Y_2}{Y_2 - Y_4}.$$

# 10 Point Estimation

$$X \sim P_{\theta}, \quad \theta \in \Theta.$$

We want to estimate  $\theta$  or some function  $g(\theta)$  based on the sample X.

# 11 Maximum Likelihood

**Example.** Let  $X_1, \ldots, X_n \stackrel{iid}{\sim} uniform[0, \theta]$ . Find the MLE for  $\theta$ .