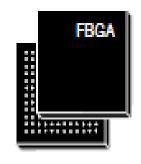
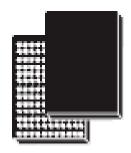
معرفي ميكروكنترلر STM32F

ریز پردازنده ۱ محمد مهدی همایون پور دانشکده مهندسی کامپیوتر، دانشگاه صنعتی امیر کبیر ۱۳۹۶







LQFP100 (14 × 14 mm) UFBGA176 (10 x 10 mm)

LQFP144 (20 × 20 mm) -

TFBGA216 (13 x 13 mm)

WLCSP180

(0.4 mm pitch)

LQFP176 (24 × 24 mm)

LQFP208 (28 x 28 mm)

کاربردهای میکروکنترلر STM32F

Suitable for a wide range of applications:

- Motor drive and application control
- Medical equipment
- Industrial applications: PLC, inverters, circuit breakers
- Printers, and scanners
- Alarm systems, video intercom, and HVAC
- Home audio appliances
- Mobile applications
- Internet of Things
- Wearable devices: smart watches

محصولات حاصل از میکروکنترلر ARM



ریزپردازنده ۱ محمد مهدی همایون پور

- Core: ARM® 32-bit Cortex®-M7 CPU with
 - DPFPU, ART AcceleratorTM and L1-cache.
 - L1-cache:
 - 16 Kbytes I/D cache,
 - allowing 0-wait state execution from embedded Flash and external memories
- DSP instructions

• The Chrom-Art AcceleratorTM (DMA2D) is a graphic accelerator

DPFPU: Double-Precision Floating Point Unit MPU: Memory Protection Unit which enhances the application security. I/D cache: I (Instruction) cache and D (Data) Cache

The memory protection unit (MPU) is used to manage the CPU accesses to memory to prevent one task to accidentally corrupt the memory or resources used by any other active task.

- up to 216 MHz, MPU,
- 462 DMIPS/2.14 DMIPS/MHz (Dhrystone 2.1),
- DSP instructions

Dhrystone MIPS (Million Instructions per Second), or DMIPS, is a measure of computer performance relative to the performance of the DEC VAX 11/780 minicomputer of the 1970s.

Internal Memories:

- Up to 2 Mbytes of Flash memory organized into two banks allowing read-while-write
- SRAM: 512 Kbytes (including 128 Kbytes of data TCM RAM for critical real-time data)
- + 16 Kbytes of instruction TCM RAM (for critical real-time routines) + 4 Kbytes of backup SRAM
- Flexible external memory controller with up to 32-bit data bus: SRAM, PSRAM, SDRAM/LPSDR SDRAM, NOR/NAND memories
- Tightly Coupled Memory and cache memory are both fast access memories.

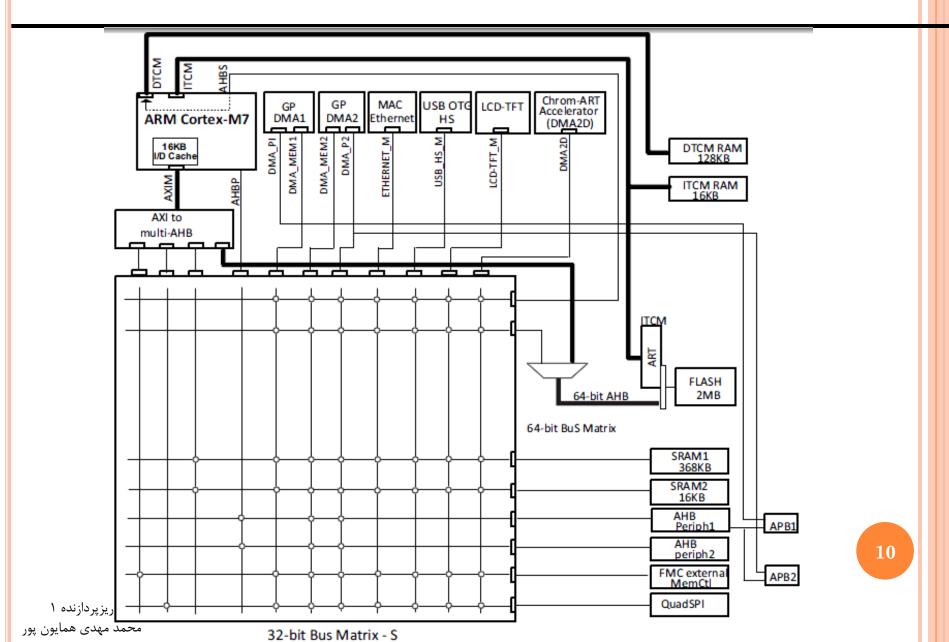
TCM: Tightly Coupled Memory interface

PSRAM: Pseudo-static random-access memory

SDRAM: Synchronous dynamic random-access memory

Extensive range of enhanced I/Os

- connected to two APB buses
- two AHB buses
- a 32-bit multi-AHB bus matrix
- a multi layer AXI interconnect supporting internal and external memories access.
- The ARM Advanced Microcontroller Bus Architecture (AMBA) is an open-standard, on-chip interconnect specification for the connection and management of functional blocks in system-on-a-chip (SoC) designs.



AXI, the third generation of AMBA interface defined in the AMBA 3 specification,

AXI is targeted at high performance, high clock frequency system designs and includes features that make it suitable for high speed submicrometer interconnect,

Advanced High-performance Bus (AHB) is a bus protocol introduced in Advanced Microcontroller Bus Architecture version 2 published by <u>ARM Ltd</u> company.

Advanced Peripheral Bus (APB) is designed for low bandwidth control accesses.

Peripherals:

- Three 12-bit ADCs
- 2 DACs
- 1 low-power RTC
- 12 general-purpose 16-bit timers including
 - two PWM timers for motor control
 - two general-purpose 32-bit timers
- 1 true random number generator (RNG),
- 1 cryptographic acceleration cell.

Standard and advanced communication interfaces:

- 4 I2Cs
- 6 SPIs
- 3 I2Ss in half-duplex mode
- 4 USARTs plus four UARTs
- 1USB OTG full-speed
- 1 USB OTG high-speed with full-speed capability

Standard and advanced communication interfaces:

- Three CANs
- Two SAI serial audio interfaces
- Two SDMMC host interfaces
- Ethernet interface
- Camera interface for CMOS sensors
- LCD-TFT display controller
- Chrom-ART AcceleratorTM
- SPDIFRX interface
- HDMI-CEC
- 1 flexible memory control (FMC) interface
- a Quad-SPI Flash memory interface
- A cryptographic acceleration cell
- -40 to +105 °C temperature range

ريزپردازنده ۱.7 to 3.6 V power supply

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- USB OTG introduces the concept of a device performing both master and slave roles whenever two USB devices are connected and one of them is a USB OTG device, they establish a <u>communication link</u>. The device controlling the link is called the master or host, while the other is called the slave or peripheral.
- For instance, a mobile phone may read from removable media as the host device, but present itself as a <u>USB</u> <u>Mass Storage Device</u> when connected to a host computer.

• S/PDIF (Sony/Philips Digital Interface Format) is a type of <u>digital audio</u> interconnect used in consumer audio equipment to output audio over reasonably short distances.

Consumer Electronics Control (CEC) is a feature of HDMI designed to allow users to command and control devices connected through HDMI[1][2] by using only one remote control.

For example, by using the remote control of a television set to control a set-top box and or DVD player.

Up to 15 devices can be controlled.

• LCD-TFT controller

- The LCD-TFT display controller provides a 24-bit parallel digital RGB (Red, Green, Blue) and delivers all signals to interface directly to a broad range of LCD and TFT panels up to XGA (1024x768) resolution with the following features:
 - 2 display layers with dedicated FIFO (64x32-bit)
 - Color Look-Up table (CLUT) up to 256 colors (256x24-bit) per layer
 - Up to 8 input color formats selectable per layer
 - Flexible blending between two layers using alpha value (per pixel or constant)
 - Flexible programmable parameters for each layer
 - Color keying (transparency color)
 - Up to 4 programmable interrupt events

Flexible memory controller (FMC)

FMC includes three memory controllers:

- The NOR/PSRAM memory controller
- The NAND/memory controller
- The Synchronous DRAM

Quad-SPI memory interface (QUADSPI)

- is a specialized communication interface targeting Single, Dual or Quad-SPI Flash memories.
- It can work in:
 - Up to 256 Mbytes external Flash are memory mapped, supporting 8, 16 and 32-bit access. Code execution is supported.

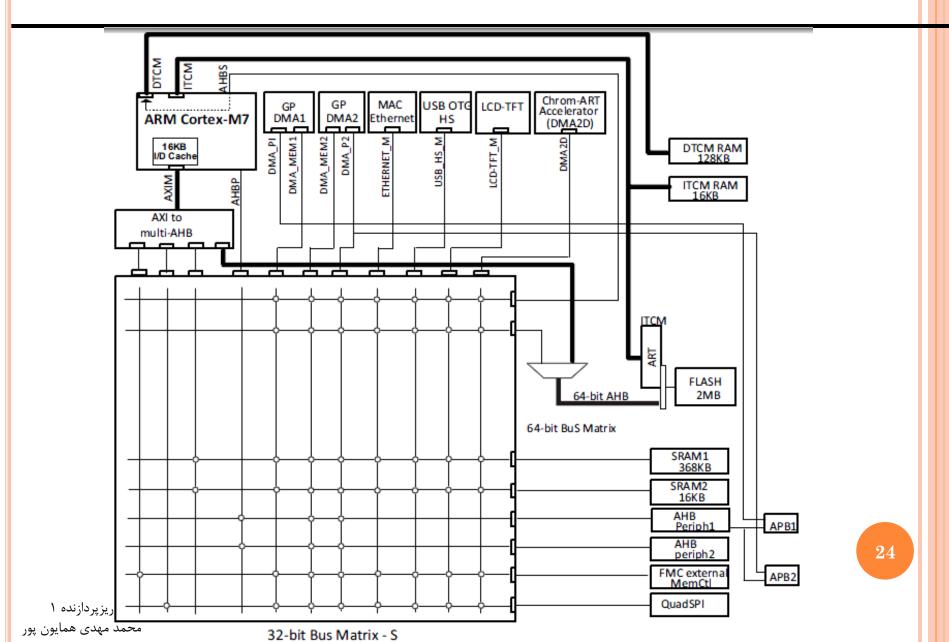
DMA controller (DMA)

- The devices feature two general-purpose dual-port DMAs (DMA1 and DMA2) with 8 streams each.
- They are able to manage memory-to-memory, peripheral-to-memory and memory-to-peripheral transfers.

AXI-AHB bus matrix:

The STM32F system architecture is based on 2 sub-systems:

- An AXI to multi AHB bridge converting AXI4 protocol to AHB-Lite protocol:
 - 3x AXI to 32-bit AHB bridges connected to AHB bus matrix
 - 1x AXI to 64-bit AHB bridge connected to the embedded Flash memory
- A multi-AHB Bus-Matrix
 - The 32-bit multi-AHB bus matrix interconnects all the masters (CPU, DMAs, Ethernet, USB HS, LCD-TFT, and DMA2D) and the slaves (Flash memory, RAM, FMC, Quad-SPI, AHB and APB peripherals) and ensures an efficient operation even when several high-speed peripherals work simultaneously.



ARM CORTEX-M7F

Key features of the Cortex-M7 core are: [6]

- 6-stage <u>pipeline</u> with <u>branch speculation</u> (پیشبینی انشعابها).
- Instruction sets:
 - Thumb-1 (entire).
 - Thumb-2 (entire).
 - 32-bit hardware integer multiply with 32-bit or 64-bit result, signed or unsigned, add or subtract after the multiply.
 - 32-bit hardware integer divide (2-12 cycles).
 - Saturation arithmetic support.
 - DSP extension: Single cycle 16/32-bit MAC, single cycle dual 16-bit MAC, 8/16-bit SIMD arithmetic.
- 1 to 240 <u>interrupts</u>, plus <u>NMI</u>.
- 12 cycle interrupt latency.
- Integrated sleep modes.
- MAC: Multiply–accumulate operation
- SIMD: Single instruction, multiple data, multiple processing elements that perform the same operation on multiple data points simultaneously.

ARM CORTEX-M7F

In <u>computer architecture</u>, a **branch predictor** is a <u>digital circuit</u> that tries to guess which way a <u>branch</u> (e.g. an <u>if-then-else structure</u>) will go before this is known definitively.

Saturation arithmetic is a version of <u>arithmetic</u> in which all operations such as addition and multiplication are limited to a fixed range between a minimum and maximum value

For example, if the valid range of values is from -100 to 100, the following operations produce the following values:

- \bullet 60 + 30 = 90
- 60 + 43 = 100
- $\bullet \quad (60+43)-(75+75)=0$
- $10 \times 11 = 100$
- $99 \times 99 = 100$
- $30 \times (5-1) = 100$
- $30 \times 5 30 \times 1 = 70$

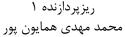
DATA SIZES AND INSTRUCTION SETS

- The ARM is a 32-bit architecture.
- When used in relation to the ARM:
 - Byte means 8 bits
 - **Halfword** means 16 bits (two bytes)
 - Word means 32 bits (four bytes)
- Most ARM's implement two instruction sets
 - 32-bit ARM Instruction Set
 - 16-bit Thumb Instruction Set
- Jazelle cores can also execute Java bytecode

Java bytecode is the instruction set of the Java virtual machine (JVM).

PROGRAM COUNTER (R15)

- When the processor is executing in ARM state:
 - All instructions are 32 bits wide
 - All instructions must be word aligned
 - Therefore the **pc** value is stored in bits [31:2] with bits [1:0] undefined (as instruction cannot be halfword or byte aligned).
- When the processor is executing in Thumb state:
 - All instructions are 16 bits wide
 - All instructions must be halfword aligned
 - Therefore the **pc** value is stored in bits [31:1] with bit [0] undefined (as instruction cannot be byte aligned).
- When the processor is executing in Jazelle state:
 - All instructions are 8 bits wide
 - Processor performs a word access to read 4 instructions at once

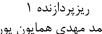


PROCESSOR MODES

- The ARM has seven basic operating modes:
 - System: privileged mode using the same registers as user mode
 - User: unprivileged mode under which most tasks run
 - FIQ: entered when a high priority (fast) interrupt is raised
 - IRQ: entered when a low priority (normal) interrupt is raised
 - Supervisor: entered on reset and when a Software Interrupt instruction is executed
 - **Abort**: used to handle memory access violations
 - **Undef**: used to handle undefined instructions

Privileged Mode: The software can use all the instructions and has access to all resources.

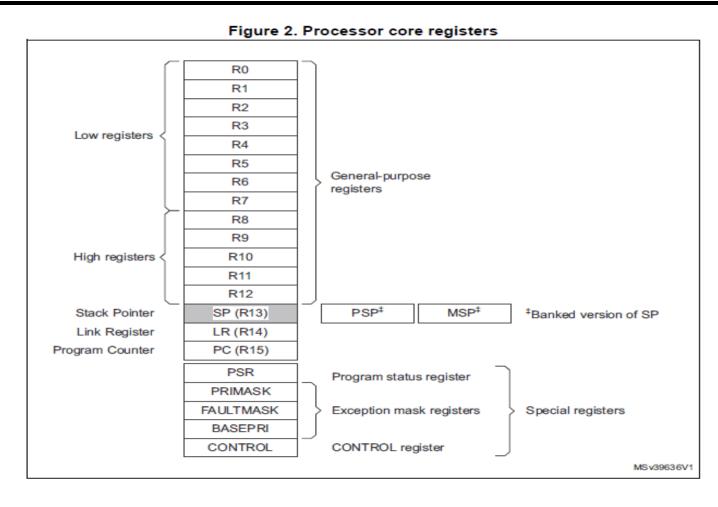
Exceptions: Bus faults, Usage Faults



THE REGISTERS

- ARM has 37 registers all of which are 32-bits long.
 - 1 dedicated program counter
 - 1 dedicated current program status register
 - 5 dedicated saved program status registers
 - 30 general purpose registers
- The current processor mode governs which of several banks is accessible. Each mode can access
 - a particular set of r0-r12 registers
 - a particular r13 (the stack pointer, sp) and r14 (the link register, lr)
 - the program counter, r15 (pc)
 - the current program status register, cpsr

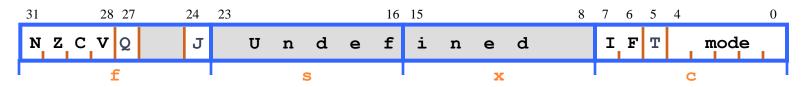
PROCESSOR CORE REGISTERS



MSP: Main Stack Pointer PSP: Process Stack Pointer

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PROGRAM STATUS REGISTERS



- Condition code flags
 - N = Negative result from ALU
 - Z = Zero result from ALU
 - C = ALU operation Carried out
 - V = ALU operation oVerflowed
- Sticky Overflow flag Q flag
 - Architecture 5TE/J only
 - Indicates if saturation has occurred
- J bit
 - Architecture 5TEJ only
 - J = 1: Processor in Jazelle state

- Interrupt Disable bits.
 - I = 1: Disables the IRQ.
 - F = 1: Disables the FIQ.
- T Bit
 - Architecture xT only
 - T = 0: Processor in ARM state
 - T = 1: Processor in Thumb state
- Mode bits
 - Specify the processor mode

CONDITION CODES

• The possible condition codes are listed below:

Suffix	Description	Flags tested
EQ	Equal	Z=1
NE	Not equal	Z=0
CS/HS	Unsigned higher or same	C=1
CC/LO	Unsigned lower	C=0
MI	Minus	N=1
PL	Positive or Zero	N=0
VS	Overflow	V=1
VC	No overflow	V=0
HI	Unsigned higher	C=1 & Z=0
LS	Unsigned lower or same	C=0 or Z=1
GE	Greater or equal	N=V
LT	Less than	N!=V
GT	Greater than	Z=0 & N=V
LE	Less than or equal	Z=1 or N=!\
AL	Always	

EXAMPLES OF CONDITIONAL EXECUTION

Use a sequence of several conditional instructions

```
if (a==0) func(1);
   CMP      r0,#0
   MOVEQ      r0,#1
   BLEQ    func
```

• Set the flags, then use various condition codes

```
if (a==0) x=0;
if (a>0) x=1;

CMP r0,#0
MOVEQ r1,#0
MOVGT r1,#1
```

Use conditional compare instructions

```
if (a==4 || a==10) x=0;
   CMP      r0,#4
   CMPNE      r0,#10
   MOVEQ      r1,#0
```

DATA PROCESSING INSTRUCTIONS

- Consist of:
 - Arithmetic: add adc sub sec rsb rsc
 - Logical: AND ORR EOR BIC
 - Comparisons: CMP CMN TST TEQ
 - Data movement: MOV
- These instructions only work on registers, NOT memory.

0

0

0

THE BARREL SHIFTER

LSL: Logical Left Shift



Multiplication by a power of 2

LSR: Logical Shift Right



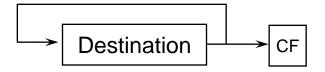
Division by a power of 2

ASR: Arithmetic Right Shift



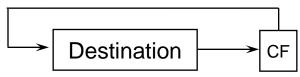
Division by a power of 2, preserving the sign bit

ROR: Rotate Right



Bit rotate with wrap around from LSB to MSB

RRX: Rotate Right Extended



Single bit rotate with wrap around from CF to MSB

