

```

% Define the system (original transfer function)
numerator = [1, -0.8];
denominator = conv(conv([1, -0.1], [1, -0.5]), [1, -0.94]); % Convolve denominator factors
G = tf(numerator, denominator, 1); % Transfer function with a sampling time of 1

% Generate input signal
N = 1000; % Number of data points
u = randn(N, 1); % Input signal (random Gaussian noise)

% Simulate system output
y = lsim(G, u); % Simulate the response of the system

% Split data for system identification
% Use first 80% of the data for training, rest for validation
split_idx = round(0.8 * N);
u_train = u(1:split_idx);
y_train = y(1:split_idx);
u_val = u(split_idx+1:end);
y_val = y(split_idx+1:end);

% Create iddata object for training
data_train = iddata(y_train, u_train, 1); % Sampling time = 1

% Create iddata object for validation
data_val = iddata(y_val, u_val, 1);

% Define ARX model orders for first-order, second-order, and third-order systems
orders = [
    1, 1, 1; % First-order system: [na nb nk]
    2, 1, 1; % Second-order system: [na nb nk]
    3, 1, 1; % Third-order system: [na nb nk]
];

% Loop through the model orders and estimate ARX models
for i = 1:size(orders, 1)
    na = orders(i, 1); % Denominator order
    nb = orders(i, 2); % Numerator order
    nk = orders(i, 3); % Input-output delay

    % Estimate ARX model
    model_arx = arx(data_train, [na nb nk]);

    % Display the ARX model
    fprintf('Estimated ARX model for order [%d %d %d]:\n', na, nb, nk);
    disp(model_arx);

    % Validate the model using validation data
    y_est = predict(model_arx, data_val);

    % Plot comparison between true and estimated output
    figure;
    plot(y_val, 'b'); hold on; % True output (validation data)

```

```

plot(y_est.OutputData, 'r--'); % Estimated output
legend('True Output', 'Estimated Output');
xlabel('Sample');
ylabel('Amplitude');
title(sprintf('Validation of ARX Model (Order [%d %d %d])', na, nb, nk));
grid on;
end

```

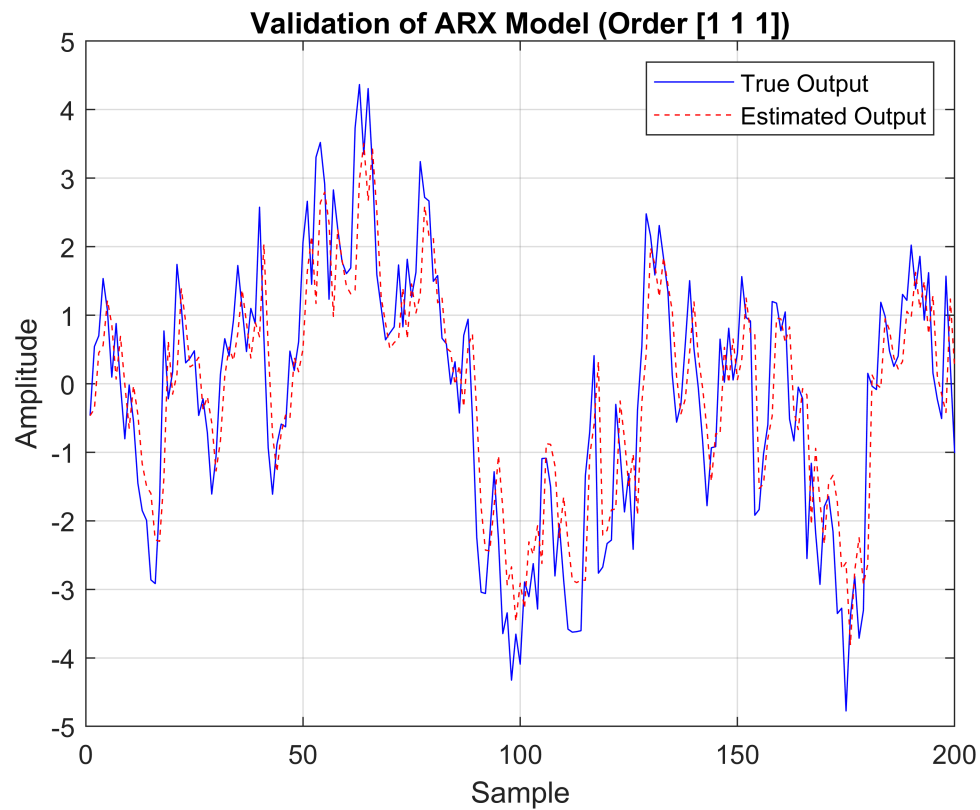
Estimated ARX model for order [1 1 1]:

idpoly with properties:

```

        A: [1 -0.7982]
        B: [0 0.0133]
        C: 1
        D: 1
        F: 1
IntegrateNoise: 0
    Variable: 'z^-1'
      IODelay: 0
    Structure: [1x1 pmodel.polynomial]
NoiseVariance: 1.0246
      Report: [1x1 idresults.arx]
    InputDelay: 0
    OutputDelay: 0
          Ts: 1
    TimeUnit: 'seconds'
    InputName: {'u1'}
    InputUnit: {''}
    InputGroup: [1x1 struct]
    OutputName: {'y1'}
    OutputUnit: {''}
    OutputGroup: [1x1 struct]
        Notes: [0x1 string]
      UserData: []
        Name: ''
SamplingGrid: [1x1 struct]

```



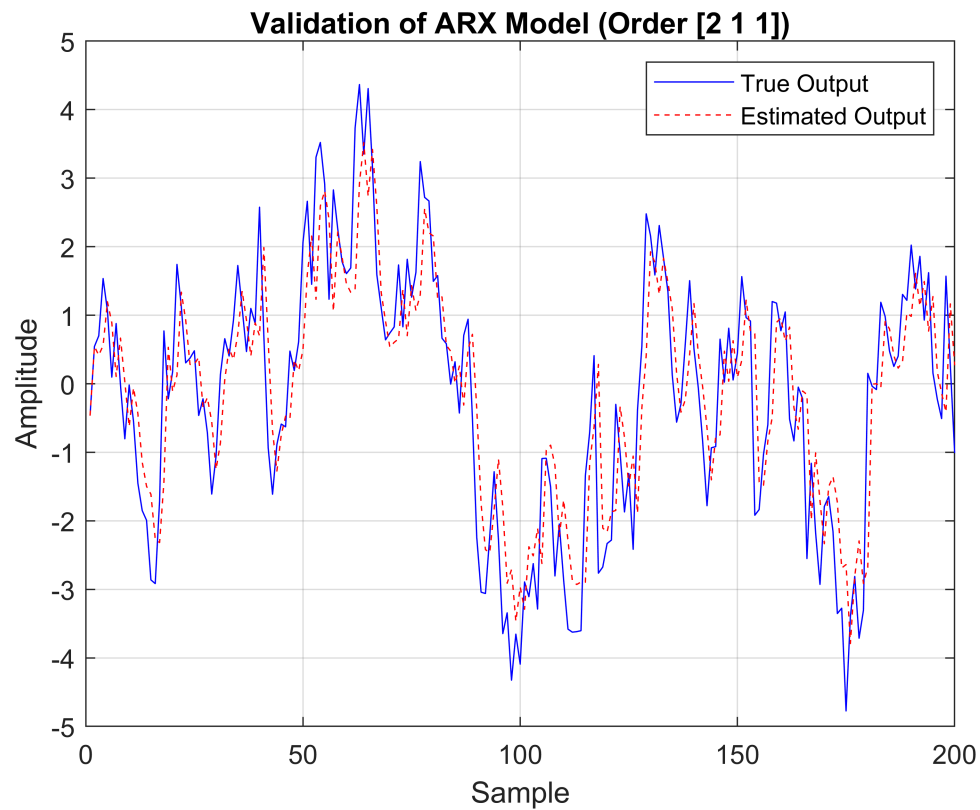
Estimated ARX model for order [2 1 1]:

idpoly with properties:

```

    A: [1 -0.7667 -0.0396]
    B: [0 0.0146]
    C: 1
    D: 1
    F: 1
IntegrateNoise: 0
  Variable: 'z^-1'
  IODelay: 0
  Structure: [1x1 pmodel.polynomial]
NoiseVariance: 1.0255
  Report: [1x1 idresults.arx]
  InputDelay: 0
  OutputDelay: 0
    Ts: 1
    TimeUnit: 'seconds'
  InputName: {'u1'}
  InputUnit: {''}
  InputGroup: [1x1 struct]
  OutputName: {'y1'}
  OutputUnit: {''}
  OutputGroup: [1x1 struct]
    Notes: [0x1 string]
  UserData: []
    Name: ''
SamplingGrid: [1x1 struct]

```



Estimated ARX model for order [3 1 1]:

idpoly with properties:

```

      A: [1 -0.7648 -0.0023 -0.0488]
      B: [0 0.0147]
      C: 1
      D: 1
      F: 1
IntegrateNoise: 0
  Variable: 'z^-1'
   IODelay: 0
  Structure: [1x1 pmodel.polynomial]
NoiseVariance: 1.0252
   Report: [1x1 idresults.arx]
  InputDelay: 0
 OutputDelay: 0
        Ts: 1
   TimeUnit: 'seconds'
  InputName: {'u1'}
  InputUnit: {''}
InputGroup: [1x1 struct]
OutputName: {'y1'}
OutputUnit: {''}
OutputGroup: [1x1 struct]
      Notes: [0x1 string]
    UserData: []
        Name: ''
SamplingGrid: [1x1 struct]

```

