BM 593 Numerical Methods & C Programming

3rd week Basic Syntax of C Language

Rules for efficient C Coding

```
/* Bad Code */
                             /* Good Code */
sum[i]=0.;
for (j=1; j<100; j++)
                              for (j=1,temp=0.; j<100; j++)
  sum[i]=a[i][j];
                                temp+=a[i][j];
                               sum[i]=temp;
for (i=1; i<100; i++)
                              for (i=1; i<100; i++)
  a[i][7]=c;
                                  a[i][7]=c;
/* rightmost index varies most rapidly */
for (i=1; i<100; i++){
                                for (i=1; i<100; i++){
                                  a=b*(x*y*z);
   a=b*x*y*z;
   c=d*y*z*x;
                                  c=d*(x*y*z);
   e=x*y+f;
                                  e=(x*y)+f;
                                  g=h*(x*y)+z;
   g=h*y*x+z;
}
                                 }
sum=0.;
                                 sum=0.;
for (i=1; i<100; i++)
                                 for (i=1; i<100; i++)
  sum+=fact*a[i];
                                     sum+=a[i];
                                 sum*=fact;
double x[100], y[100];
                                 double x[100], y[100], c;
for (i=0; i<100; i++){
                                 for (i=0; i<100; i++){
 x[i]*=i;
                                   c+=1.;
 y[i]=x[i]/2.;
                                   x[i]*=c;
}
                                   y[i]=0.5*x[i];
                                 }
```

Calling C Routines from MATLAB-mex Compilation

```
void shell(double **r, int q, double **s, int N, double **H)
/* THis is a routine to be called from the MATLAB environment */
/st shell.c calculates the electric potential for the 4 shell spherical model st/
/* r is a 2 d array with q by 3 */
/* q is the number of dipoles */
/* s is the 2 d array with N by 3 */
/* N is the number of electrodes */
/* H is the potential field matrix with */
/* N by 3*q */
/* mex file for shell.c */
/* Usage: H=matshell[r,s]; */
/* Will be stored in matshell.c */
#include "\MATLAB6p5\extern\include\mex.h"
#include "\MATLAB6p5\extern\include\matrix.h"
#include "shell.c"
void mexFunction(int nlhs, mxArray *plhs[], int nrhs, const mxArray *prhs[]){
  int i, j, k, q, N;
 double **r,**s,**H,*data1,*data2;
  if (nrhs!=2){
    mexErrMsgTxt("2 input arguments needed");
  }
  if (nlhs>1){
    mexErrMsgTxt("1 output argument needed");
  }
  q=mxGetNumberOfElements(prh[0]/3);
  /* get the number of dipoles from r which is Number of Dipoles X 3 */
 N=mxGetNumberOfElements(prh[1]/3);
  /st get the number of electrodes from s which is Number of electrodes X 3 st/
 r=(double **) mxMalloc(q*sizeof(double));
  for (i=0;i<q;i++)
```

```
r[i]=(double *) mxMalloc(3*sizeof(double));
 data1=mxGetPr(prh[0]);
 for (k=0, j=0; j<3; j++)
   for (i=0;i<q;i++,k++)
     r[i][j]=data1[k];
  s=(double **) mxMalloc(N*sizeof(double));
 for (i=0;i<q;i++)
    s[i]=(double *) mxMalloc(3*sizeof(double));
 data1=mxGetPr(prhs[1]);
 for (k=0,j=0;j<3;j++)
   for (i=0;i<N;i++,k++)
      s[i][j]=data1[k];
 H=(double **) mxMalloc(N*sizeof(double));
 for (i=0;i<q;i++)
    H[i]=(double *) mxMalloc(q*3*sizeof(double));
  shell(r,q,s,N,H);
 plhs[0]=mxCreateDoubleMatrix(N,3*q,mxREAL);
 data2=(double *) mxMalloc(N*3*q*sizeof(double));
 for (k=0,j=0;j<(3*q);j++)
   for (i=0;i<N;i++,k++)
     data2[k]=H[i][j];
 mxSetPr(plhs[0],data2);
}
More Efficient C Coding for MATLAB-mex Compilation
void shell(double *r, int q, double *s, int N, double *H)
/* This is a routine to be called from the MATLAB environment */
/st shell.c calculates the electric potential for the 4 shell spherical model st/
/* r is a 1 d array with length q*3 */
/* q is the number of dipoles */
/* s is the 1 d array with length N*3 */
/* N is the number of electrodes */
/* H is the potential field vector with length N*3*q */
/* mex file for shell.c */
/* Usage: H=matshell[r,s]; */
```

```
/* Will be stored in matshell.c */
#include "\MATLAB6p5\extern\include\mex.h"
#include "\MATLAB6p5\extern\include\matrix.h"
#include "shell.c"
void mexFunction(int nlhs, mxArray *plhs[], int nrhs, const mxArray *prhs[]){
  int i, j, k, q, N;
 double *r,*s,*H;
  if (nrhs!=2){
     mexErrMsgTxt("2 input arguments needed");
 }
  if (nlhs>1){
     mexErrMsgTxt("1 output argument needed");
  }
 q=mxGetNumberOfElements(prh[0]/3);
  /* get the number of dipoles from r which is Number of Dipoles X 3 */
 N=mxGetNumberOfElements(prh[1]/3);
  /st get the number of electrodes from s which is Number of electrodes X 3 st/
 r=mxGetPr(prh[0]);
  s=mxGetPr(prhs[1]);
  H=(double *) mxMalloc(N*3*q*sizeof(double));
  shell(r,q,s,N,H);
 plhs[0]=mxCreateDoubleMatrix(N,3*q,mxREAL);
 mxSetPr(plhs[0],H);
Passing Arrays to Numerical Recipes Routines
/* Numerical Recipes Routine for LU BACK SUBSTITUTION */
void lubksb(a,n,indx,b)
double **a,b[];
 int n,*indx;
Array addressing in NR is from 1 to N.
```

```
/* For arrays passed to NR routines allocation is done as follows */
    void main(){

        double **Matrix;
        double *Vector;
        int *Index;

        Matrix = (double **) malloc(10*sizeof(double*));
        Matrix--;
        for (i=1;i<=10;i++)
            Matrix[i]-= (double *) malloc(10*sizeof(double));

        Vector = (double *) malloc(10*sizeof(double));

        Vector--;
        Index = (int *) malloc(10,sizeof(int));
        Index--;
}</pre>
```