Diffusion of Vacancies in 4H-SiC

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Abstract

We demonstrate a breadth-first search (BFS) algorithm that is readily adaptable to various multicore architectures. This algorithm scales better than a naive recursive implementation for the problem of constructing probability maps for the position of a defect centers in silicon carbide (SiC) after a given number of time steps.

I. INTRODUCTION

The promise of the nitrogen-vacany (NV) center in diamond has spawned interest in similar centers in related materials such as SiC. The negatively charged silicon vacancy in 4H-SiC has been identified as having spin $S = 3/2^1$ and two distinct protocols of spin-photon interface have been proposed based on this defect². This ability to optically address the spin states, in addition to the long spin coherence, makes the particular defect very attractive. However, as little of the luminescence is generally contained in the zero-phonon line³, the transition must be amplified, potentially by placing the defect near cavities on resonance with the desired transition⁴. Positioning defects, however, is a non-trivial endeavor and the proposal is to position the negatively charged silicon vacancy defect in 4H-SiC through the probabilistic process of diffusion. Here we present results on diffusion of vacancies in 4H-SiC.

II. COMPUTATIONAL METHODS

We performed first-principles density functional theory (DFT) calculations for structural optimization using the VASP package⁵⁻⁷. For the exchange-correlation energy of electrons we use the generalized gradient approximation (GGA), as parametrized by Perdew, Burke and Erzenhof (PBE)⁸. The atomic positions were relaxed until the magnitude of Hellmann-Feynman forces was smaller than 0.01 eV/Å on each atom and the lattice parameters were concurrently relaxed. The wave functions were expanded in a plane wave basis with a cutoff energy of 500 eV and a zone-centered grid of $12 \times 12 \times 6$ points was used for integrations in k-space, for the stoichiometric primitive unit cell. The relaxed lattice parameters for the stoichiometric primitive unit cell were used for all other structures. Increasing the grid to $24 \times 24 \times 12$ causes a change in the total energy of less than 10^{-4} eV and a change in the lattice constants of less than 10^{-5} Å, while increasing the cutoff energy to 600 eV causes a change in the total energy of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and a change in the lattice constants of less than 10^{-2} eV and 10^{-2}

III. BARRIER TO DIFFUSION

Diffusion barriers for silicon vacancies are presented below as calculated using the NEB method in VASP. It is important to highlight that some silicon vacancies may be lost due to formation of $V_{\rm C}C_{\rm Si}$ complexes. The barriers for such losses are presented below as well.

TABLE I. Total energy in eV relative to the total energy of V_{Si}^- at the k site. The subscript s denotes staggered, while the subscript e denotes eclipsed.

	start point	saddle	endpoint
$0\% \text{ strain } k \to k \text{ V}_{Si}^-$	0	2.95	0
$0\% \text{ strain } (k \to h)_e \text{ V}_{\text{Si}}^-$	0	3.02	0.01
$0\% \text{ strain } (k \to h)_s \text{ V}_{\text{Si}}^-$	0	3.63	0.01
$0\% \text{ strain } h \to h \text{ V}_{\text{Si}}^-$	0.01	2.75	0.01
$-2\% \text{ strain } k \to k \text{ V}_{\text{Si}}^-$	7.89	10.69	7.89
$+2\%$ strain $k \to k \ V_{Si}^-$	15.26	18.32	15.26
$0\% \text{ strain } k \to k \text{ V}_{\text{Si}}^{-2}$	8.80	11.25	8.80
$\begin{array}{c} 0\% \text{ strain } k \to k \text{ V}_{\text{Si}}^{-2} \\ 0\% \text{ strain } h \to h \text{ V}_{\text{Si}}^{-2} \end{array}$	8.89	11.12	8.89
$-2\% \text{ strain } k \to k \text{ V}_{\text{Si}}^{-2}$	17.41	19.66	17.41
$+2\% \text{ strain } k \to k \text{ V}_{\text{Si}}^{-2}$	23.39	25.98	23.39
$0\% \text{ strain } k \to k \text{ V}_{Si}$	-8.50	-5.09	-8.50
$0\% \text{ strain } h \to h \text{ V}_{Si}$	-8.55	-5.37	-8.55
-2% strain $k \to k V_{Si}$	-1.30	1.98	-1.30
$+2\%$ strain $k \to k \ \mathrm{V_{Si}}$	7.42	10.89	7.42
$0\% \text{ strain } k\text{-V}_{Si}^- \to hk\text{-V}_{C}C_{Si}^-$	0	2.78	0.23

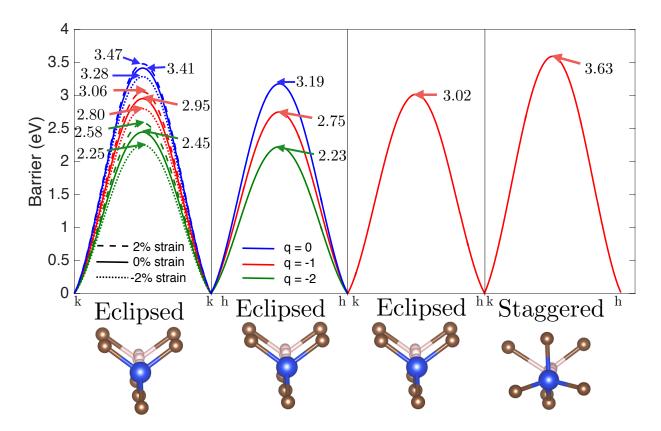


FIG. 1. Relative barriers to diffusion taking the starting point of diffusion between sites (h or k for various charge states and various strains) as the zero.

IV. TRANSITION RATES

The formula for the transition rate is,

$$r = \nu_0 e^{-\varepsilon_b/k_B T} \tag{1}$$

where $\nu_0 = 1.6 \times 10^{13} \text{ s}^{-1}$, ε_b is the energy barrier to diffusion and we take T = 1300 K.

V. APPROACH

Given the nature of the 4H-SiC crystal, there are 12 possible transitions - 3 transitions out of plane in the upwards direction, 3 transitions out of plane in the downwards direction, and 6 transitions in the plane. At any given time step, any one of these transitions is possible (with varying probabilities), so the problem at first pass grows as 12^N , where N is the number of time steps. More precisely, positions in 3 dimensions must be computed at each time step, the time must be updated and the probability must be updated for a total of 5 computations for each of the 12 transitions, we must then communicate the results of these 5 computations to the next processor, which will use the calculated values as inputs for an additional 5 units of work for every 12 transitions. Summing the geometric sequence corresponding to the total number of transitions at 0, 1, ..., N time steps, we obtain $\frac{12^{N+1}-1}{11}$, so we are dealing with a problem of size $10 \cdot \frac{12^{N+1}-1}{11}$, yielding a computational complexity of $O(12^{N+1})$. We use a set of rotation matrices as a simplification in order to calculate movement in any of the in-plane and out of plane directions. Essentially, any given in-plane transition of the six, treating the current position as the origin, can be mapped onto any other in-plane transition of the six by simply rotating the original transition, in-plane, by some multiple of 60 degrees. Similarly, any upwards (downwards) transition can be mapped onto any other upwards (downwards) transition of the three by simply rotating the original transition by some multiple of 120 degrees. Thus, we define three transitions (one in-plane and two out of the plane) and obtain the remaining transitions by using rotation matrices.

Past this point, we fill a matrix A with values corresponding to the x, y and z position shifts for a particular transition, the probability of transitioning, and the time shift for the particular transition. From here, we run a breadth-first search (BFS) through the tree with each node corresponding to a particular sequence of transitions, with corresponding particular final x, y and z positions and a given final or total time up to that point and a given final or total probability up to that point. There are N layers to this tree and each layer has 12^N nodes (for a total of $\frac{12^{N+1}-1}{11}$ nodes in the tree).

Finally, we print out the x, y and z coordinates, the probability of transitioning to that a given location, and the time passed.

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